# The Dual-Form Perceptron (leading to Kernels)

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# Machine Learning for Language Processing: Lecture 6

MPhil in Advanced Computer Science

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## **Ranking Structures with the Perceptron**

Some notation:

- Assume training data  $\{(s_i, t_i)\}$  (e.g.  $s_i$  is a sentence and  $t_i$  the correct tree for  $s_i$ )
- $\mathbf{x}_{ij}$  is the *j*th candidate for example *i* (e.g. the *j*th tree for sentence *i*)
- Assume (w.l.o.g.) that  $\mathbf{x}_{i1}$  is the correct output for input  $s_i$  (i.e.  $\mathbf{x}_{i1} = t_i$ )
- $\mathbf{h}(\mathbf{x}_{ij}) \in \mathbb{R}^d$  is the feature vector for  $\mathbf{x}_{ij}$
- $\mathbf{w} \in \mathbb{R}^d$  is the corresponding weight vector
- Output of the model on example s (train or test) is  $\operatorname{argmax}_{\mathbf{x}\in\mathcal{C}(s)}\mathbf{w}\cdot\mathbf{h}(\mathbf{x})$
- $\mathcal{C}(s)$  is the set of candidate outputs for input s

# Perceptron Training (with the new notation)

#### **Define:**

 $F(\mathbf{x}) = \mathbf{w} \cdot \mathbf{h}(\mathbf{x})$ Initialisation: Set parameters  $\mathbf{w} = 0$ For i = 1 to n $j = \operatorname{argmax}_{\{1,...,n_i\}} F(\mathbf{x}_{ij})$ If  $j \neq 1$  then  $\mathbf{w} = \mathbf{w} + \mathbf{h}(\mathbf{x}_{i1}) - \mathbf{h}(\mathbf{x}_{ij})$ Output on test sentence s:

 $\operatorname{argmax}_{\mathbf{x}\in\mathcal{C}(s)}F(\mathbf{x})$ 

- For simplicity, only showing one pass over the data and no averaging
- The argmax can be obtained just though enumeration (i.e. we have a *ranking* problem, so no need for dynamic programming)

# Perceptron Training (a dual form)

#### **Define:**

 $G(\mathbf{x}) = \sum_{(i,j)} \alpha_{i,j} (\mathbf{h}(\mathbf{x}_{i1}) \cdot \mathbf{h}(\mathbf{x}) - \mathbf{h}(\mathbf{x}_{ij}) \cdot \mathbf{h}(\mathbf{x}))$ Initialisation: Set dual parameters  $\alpha_{i,j} = 0$ For i = 1 to n $j = \operatorname{argmax}_{\{1,...,n_i\}} G(\mathbf{x}_{ij})$ If  $j \neq 1$  then  $\alpha_{i,j} = \alpha_{i,j} + 1$ Output on test sentence s:  $\operatorname{argmax}_{\mathbf{x} \in \mathcal{C}(s)} G(\mathbf{x})$ 

• Notice there is a dual parameter  $\alpha_{i,j}$  for each training example  $\mathbf{x}_{i,j}$ 

## **Equivalence of the Two Forms**

- $\mathbf{w} = \sum_{(i,j)} \alpha_{i,j} (\mathbf{h}(\mathbf{x}_{i1}) \mathbf{h}(\mathbf{x}_{ij}))$ ; therefore  $G(\mathbf{x}) = F(\mathbf{x})$  throughout training
- Why is this useful? Consider the complexity of the two algorithms

#### **Computational Complexity of the Two Forms**

- Assume T is the size of the training set; i.e.  $T = \sum_i n_i$
- Take d to be the size of the parameter vector  ${\bf w}$
- Vanilla perceptron takes O(Td) time (time taken to compute F is O(d))
- Assume time taken to compute the inner product between examples is k
- Running time of the dual-form perceptron is O(Tnk)
- Dual-form is therefore more efficient when nk << d (i.e. when time taken to compute inner products between examples is much less than O(d))

### **Computational Complexity of Inner Products**

- Can the time to calculate the inner product between two examples  $h(x) \cdot h(y)$ ever be less than O(d)?
- Yes! For certain high-dimensional feature representations
- Examples include feature representations which track all sub-trees in a tree, or all sub-sequences in a tag sequence

# **Tree Kernels**

- Tree kernels count the numbers of shared subtrees between trees  $\mathcal{T}_1$  and  $\mathcal{T}_2$ 
  - the feature-space,  $\mathbf{h}\left(\mathcal{T}_{1}\right)$  , can be defined as

$$\mathbf{h}_{i}\left(\mathcal{T}_{1}\right) = \sum_{n \in \mathcal{V}_{1}} I_{i}(n); \quad I_{i}(n) = \begin{cases} 1 & \text{if sub-tree } i \text{ rooted at node } n \\ 0 & \text{otherwise} \end{cases}$$

where  $\mathcal{V}_j$  is the set of nodes in tree  $\mathcal{T}_j$ 



# **Computation of Subtree Kernel**

• Can be made computationally efficient by recursively using a counting function:

$$k(\mathcal{T}_1, \mathcal{T}_2) = \mathbf{h}(\mathcal{T}_1)^\mathsf{T} \mathbf{h}(\mathcal{T}_2) = \sum_{n_1 \in \mathcal{V}_1} \sum_{n_2 \in \mathcal{V}_2} f(n_1, n_2);$$

- if productions from  $n_1$  and  $n_2$  differ  $f(n_1, n_2) = 0$
- for pre-terminals  $f(n_1, n_2) = \begin{cases} 1 & \text{if productions are the same} \\ 0 & \text{otherwise} \end{cases}$
- for non-pre-terminals and productions the same  $f(n_1, n_2) = \prod_{i=1}^{|\mathsf{ch}(n_1)|} (1 + f(\mathsf{ch}(n_1, i), \mathsf{ch}(n_2, i)))$

where  $ch(n_j)$  is the set of children of  $n_j$  and  $ch(n_j, i)$  is the *i*th child of  $n_j$ 

• Algorithm runs in linear time w.r.t. the size of each tree



### **Tree Kernels in Practice**

- Data-Oriented Parsing (Rens Bod) is a parsing model which uses a similar all-subtrees representation (but without the efficient computation)
- Collins and Duffy report a 0.6% absolute improvement over the generative models of Collins
- Alessandro Moschitti has done a lot of work on using various kernels (including tree kernels) for various tasks (including some parsing tasks)



# References

Michael Collins and Nigel Duffy (2002) New Ranking Algorithms for Parsing and Tagging: Kernels over Discrete Structures, and the Voted Perceptron

Rens Bod (2003) Do All Fragments Count? Natural Language Engineering, 9(4), 307-323.

Moschitti Tutorial at ACL 2012: State-of-the-Art Kernels for Natural Language Processing

