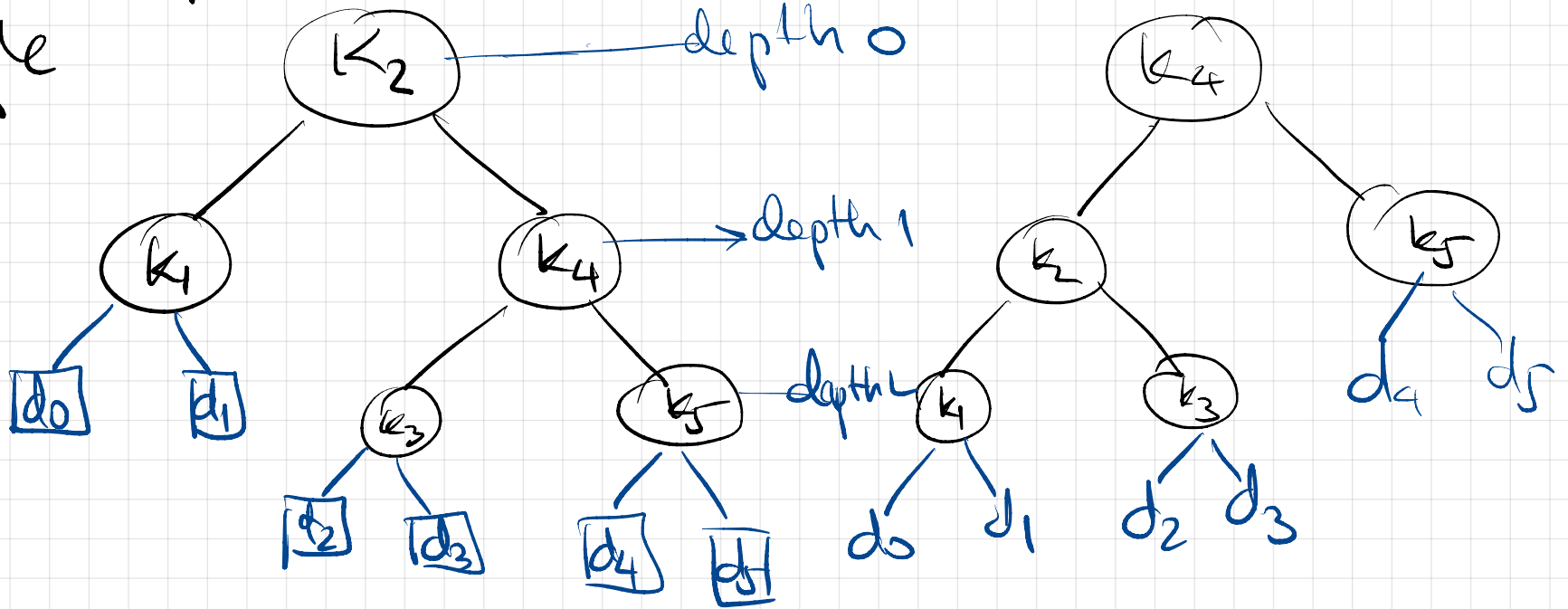


LECTURE 8 optimal BST ordered values $k_1 \leq k_2 \leq \dots \leq$

example
BST



Search probability: $\Pr(k_i) = p_i$ *not uniform*
 $\Pr(d_i) = q_i$ $d_i =$ searches for values $k_i < \text{val} < k_{i+1}$

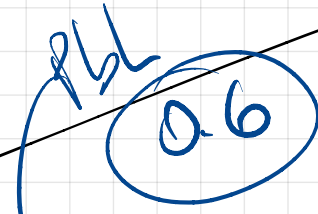
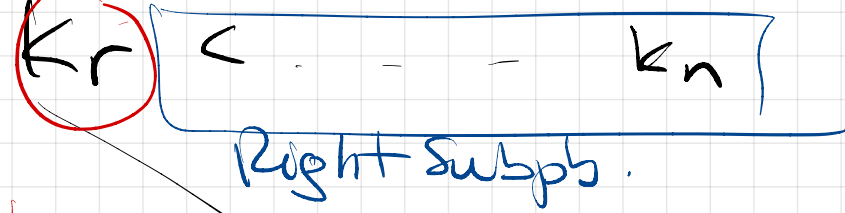
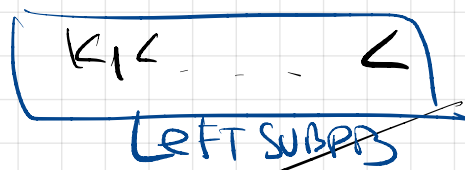
$\sum p_i + \sum q_i = 1$

depth = level

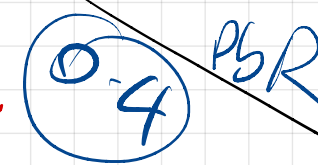
OPTIMALITY: min expected search cost

$$\sum_{i=1}^n [\text{depth}(k_i) + 1] p_i + \sum_{i=0}^n [\text{depth}(d_i) + 1] q_i$$

Step 1 OPT SOL given



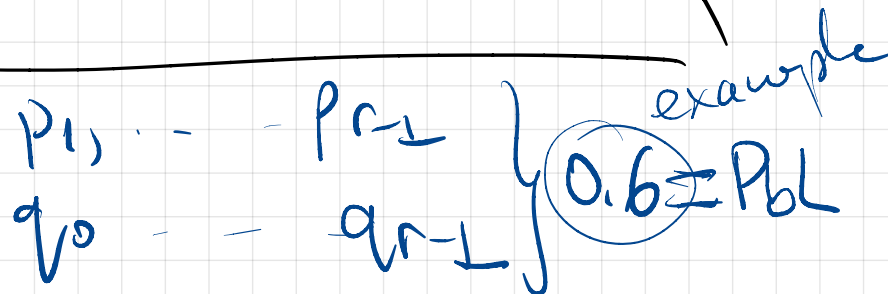
sum to $1 - p_r$
wst 1



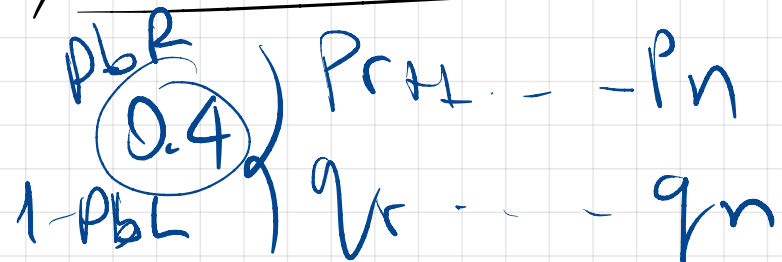
$\sum p_{1:r-1}$ all probs for
 $\sum q_{0:r-1}$ Left side

$k[1:r-1]$
 $1 \leq k \leq r-1$
 $d[0:r-1]$

$k[r+1:n]$
 $d[r:n]$



Search: $0.6 \cdot \downarrow_{root}$
best way to search ($k[1:r-1]$)



Search: $0.4 \cdot \downarrow_{root}$
best way to search ($k[r+1:n]$)

② $C[i, j] = \text{best cost for keys } k_i, k_{r+1}, \dots, k_j$
 tree (as part of overall cost)

$T[i, j] = \text{height (\# levels) of the best tree for keys } (i: j)$

$W[i, j] = \text{total prob } (i: j) = \sum_{t=i}^j p_t + \sum_{t=i+1}^j q_t$

$C[i, j] = \text{expected cost in best } [i, j] \text{ subtree} =$
 $= \text{height}(\text{subtree}[i, j]) \times \text{prob}(\text{search_subtree}[i, j]) = T[i, j] \times W[i, j]$

divide $C[i, j]$ into 3 disjoint searches:

$$= \overset{\text{cost search}}{\text{1}} \cdot \overset{\text{prob}}{p_r} + \overset{\text{cost search}}{\text{left subtree}} [i: r-1] + \overset{\text{cost search}}{\text{right subtree}} [r+1: j]$$

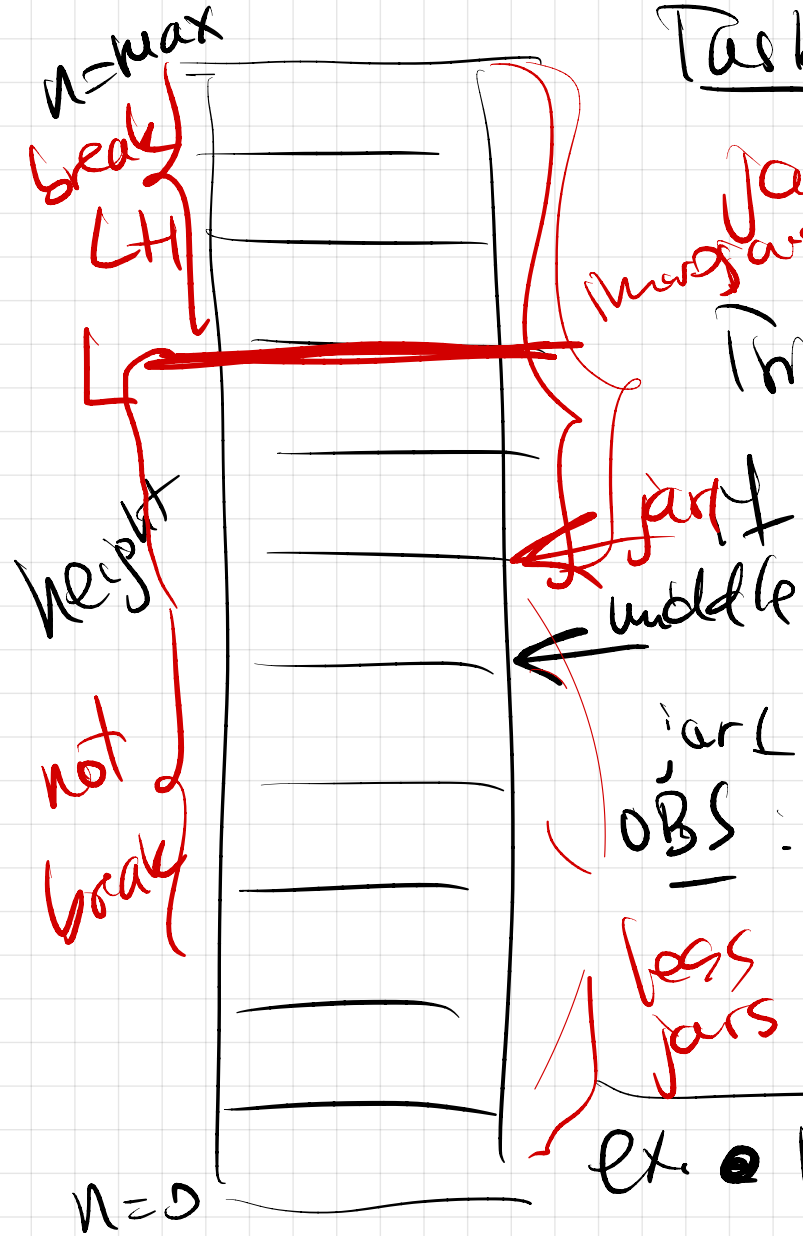
$$= \overset{\text{1 step}}{\text{1}} \cdot \overset{\text{prob}}{p_r} + \overset{\text{1 step}}{W[i: r-1]} \cdot \overset{\text{prob(left)}}{\text{prob(left)}} + \overset{\text{prob(right)}}{W[r+1: j]} \cdot \overset{\text{1 + height right-sub}}{\text{1 + height right-sub}}$$

$$= 1 \cdot p_r + W[i, r-1] (1 + T[i, r-1]) + W[r+1, j] (1 + T[r+1, j])$$

$$= \underbrace{p_r + W[i, r-1] + W[r+1, j]}_{W[i, j]} + \underbrace{W[i, r-1] \cdot T[i, r-1]}_{C[i, r-1]} + \underbrace{W[r+1, j] \cdot T[r+1, j]}_{C[r+1, j]}$$

bars on ladder n steps k jars

Task : find highest level L where jars don't break (they break at $L+1$)



That jar at level L

$L \leq L \Rightarrow$ doesn't break \Rightarrow can reuse it

$L > L+1 \Rightarrow$ jar breaks cannot reuse it

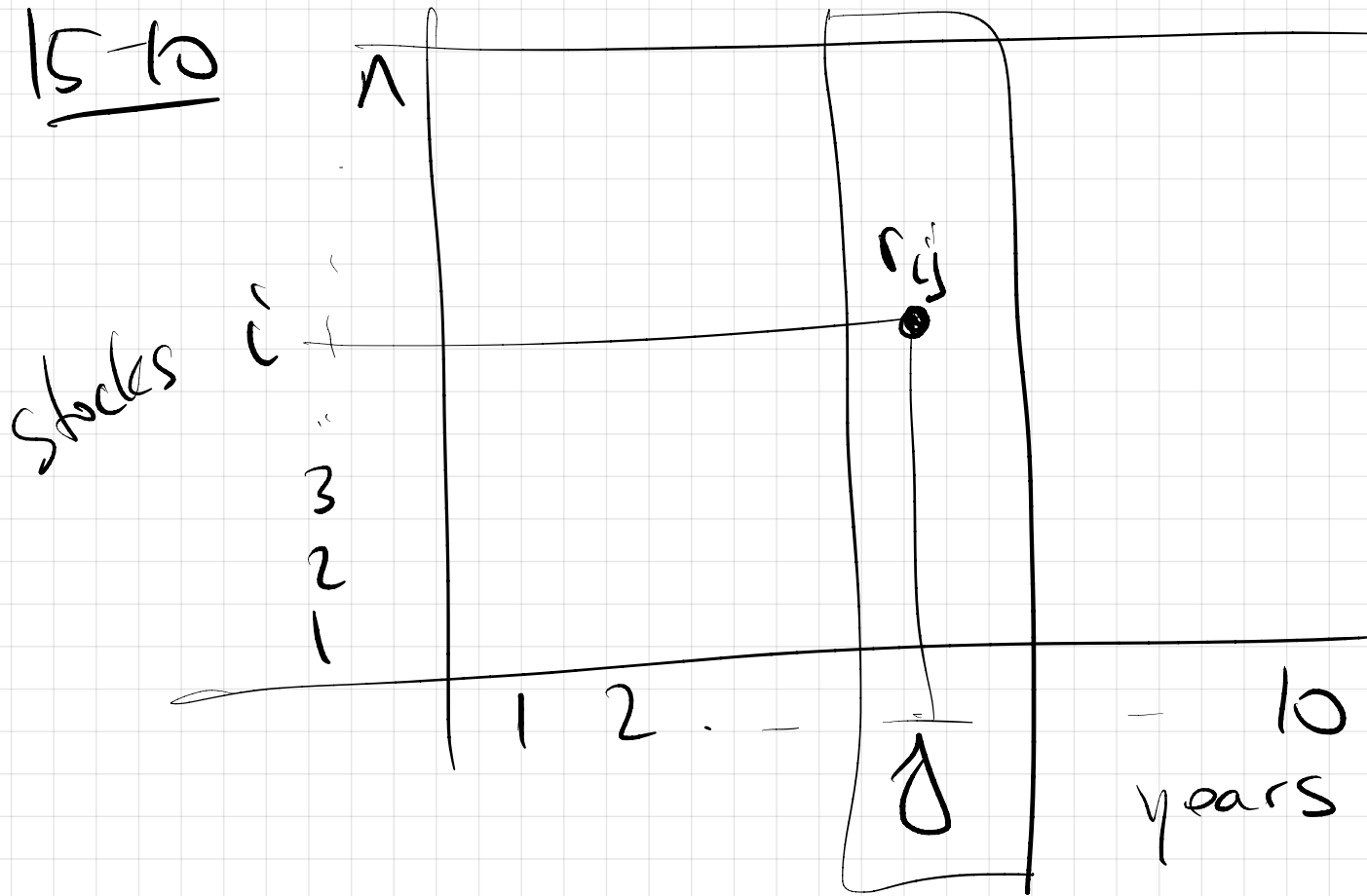
OBS : minimize # trials in worst case

You must 100% Find L

ex. $k=1 \Rightarrow$ bottom up on stairs $\Theta(n)$

$k > \log n \Rightarrow$ binary search

15-10



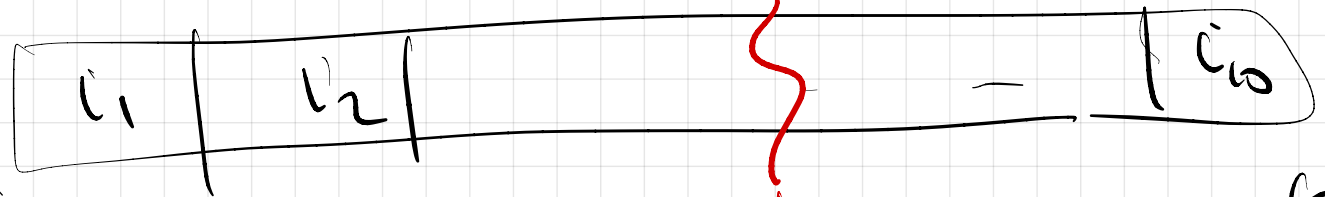
r_{ij} = return %
of stock i year j

put
 $\$N \rightarrow (\$N + \$N r_{ij})$

$\$N \rightarrow (1+r_{ij})\N

a) pick best stock that year

b) OPT sol



c) pseudocode + RT

find split
based on fee?

d) max allocation per stock \$15000
OPTIMAL character?

prev
NOT WORKING

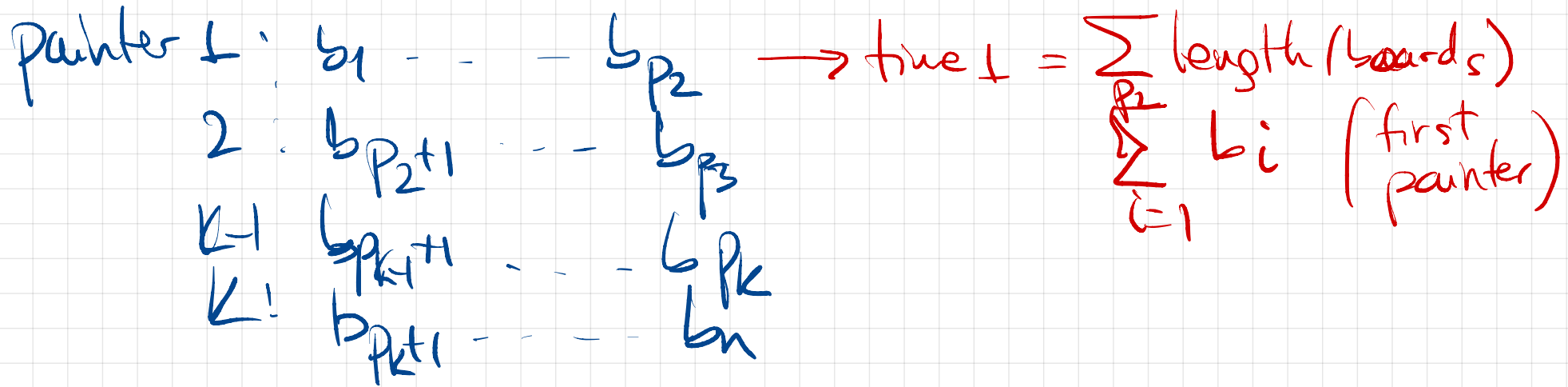
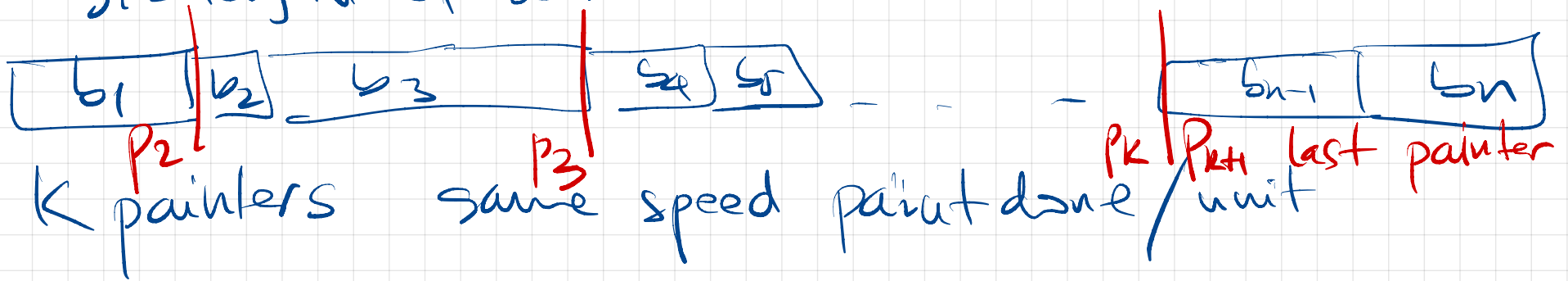
still DP?

Speculation: - DP structure works

- [C] table of
subph
has to be bounded?

Painters (fence problem)
 $b_i = \text{length of board } i$

fence = boards sequence



Task: partition boards (find p_2, p_3, \dots, p_k)

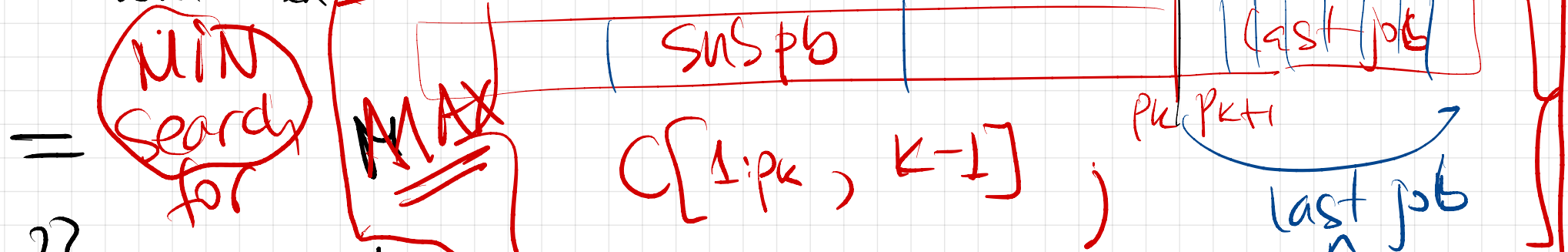
such that the longest job is minimum

(scenario: painters work in parallel ⇒

⇒ time to finish is longest job/partition)

$C[j, k]$ = best (min time in parallel) to paint boards $1:j$ with painters $1, 2, \dots, k$

$1 \leq j \leq n$
 k = #painters
 j = board index



= MIN search for

MAX $C[1:pk, k-1]$

$k-1 \leq pk \leq n-1$
 last board painted by painter $k-1$

$\Theta(n)$ Total RT. $\Theta(nk \times n)$

search in $\Theta(\log n)$ time $\rightarrow \Theta(nk \log n)$

Δ candidates $pk?$ = $C[pk, k-1]$ — $\left(\sum_{t=pk+1}^n b_t \right)$

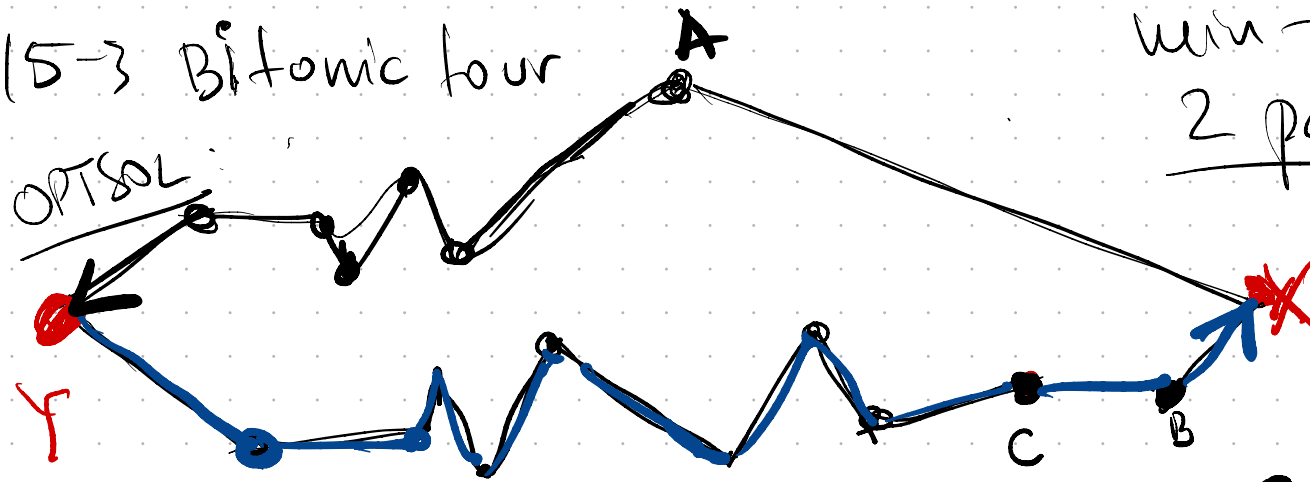
exercise

$$\sum_{t=p_k+1}^n b_t = \overset{\text{cumul}}{B_n} - \overset{\text{cumul}}{B_{p_k}} = \sum_{t=1}^n b_t - \sum_{t=1}^{p_k} b_t$$

NEXT! Selected previous midterm questions

15-3 Bitonic tour

OPT SOL



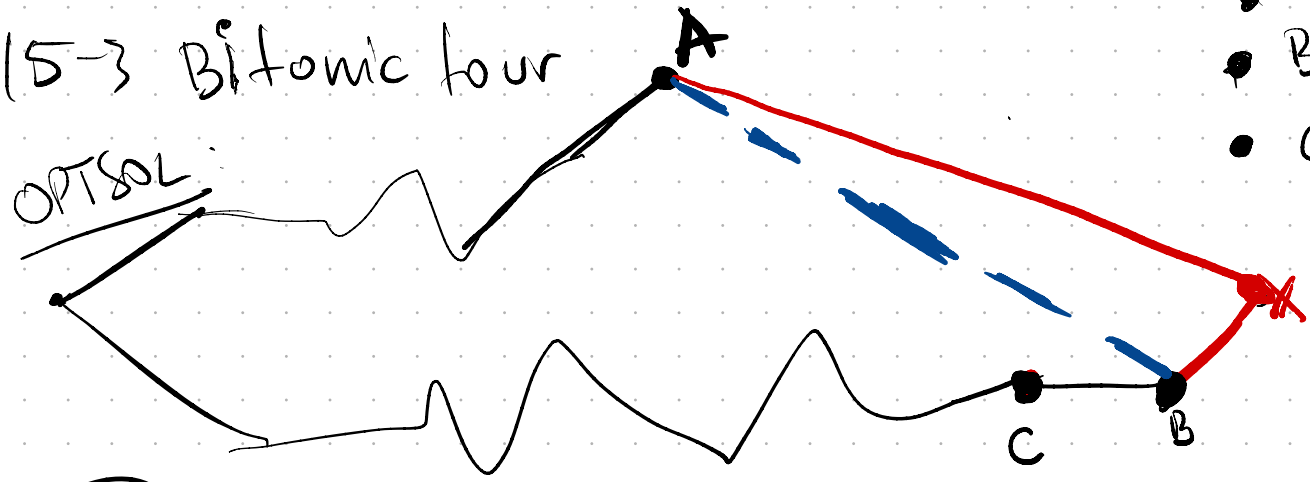
min-distance-total tour
2 paths: x, y extreme LR

- $x \rightarrow y$ upper path
- $y \rightarrow x$ lower path
- each point in one of the paths.

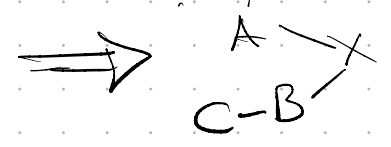
• each path strictly directional
 $L \rightarrow R$ (lower) or $R \rightarrow L$ upper.

15-3 Bitonic tour

OPTSOL



- A, B connect to X
- B closest (right most) to X
- C connects to B



$SPB = PB \cup \{x\}$ right most B

Ideal

OPTSOL $\cup \{x\}$ is optimal for $PB \cup \{x\} = SPB$? Maybe Yes.
 assume (contradict hypothesis) there is a better solution S for $SPB = PB \cup \{x\}$

Then solution is:

- eliminate x, solve $SPB = PB \cup \{x\}$ with A right-most
- then connect X either to AB or to BC, whichever is better

$$C[PB_x] = C[SPB_B] + \text{best} \left\{ \begin{array}{l} +xA + xB \\ -AB \end{array} , \begin{array}{l} +xB + xC \\ -BC \end{array} \right\}$$

idea: A, B, X closest to X 2 possibilities in OPT_{sol} (A, B, X closest)

- A, B diff paths



$$SPB = PB \setminus \{x\}$$

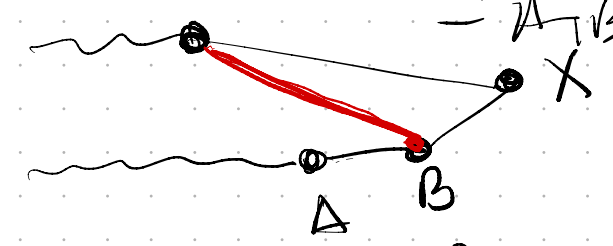
$$AB \in sol(SP B)$$

$OPT_{sol} \setminus \{AX, BX\} = sol(SP B) \setminus \{AB\}$
 or exchange argument

Solution =

$$= sol(SP B) + \underbrace{XA + AB - AB}_{connect\ X}$$

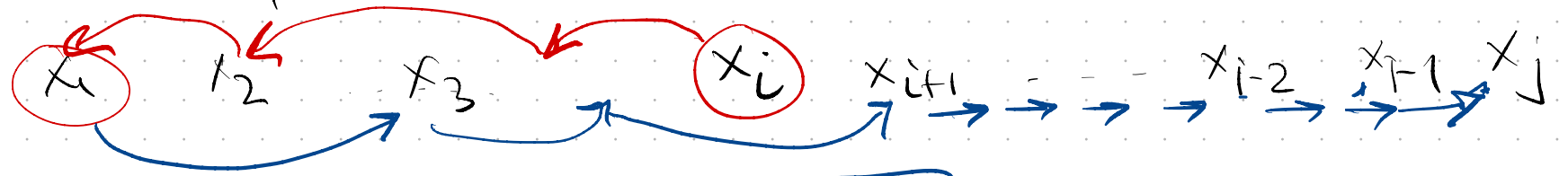
- A, B same path



$SPB = PB \setminus \{B\}$ where X is still right-most but A is closest

$$SOLUTION = sol(SP B) + \underbrace{connect\ B}_{BA + BX - XA}$$

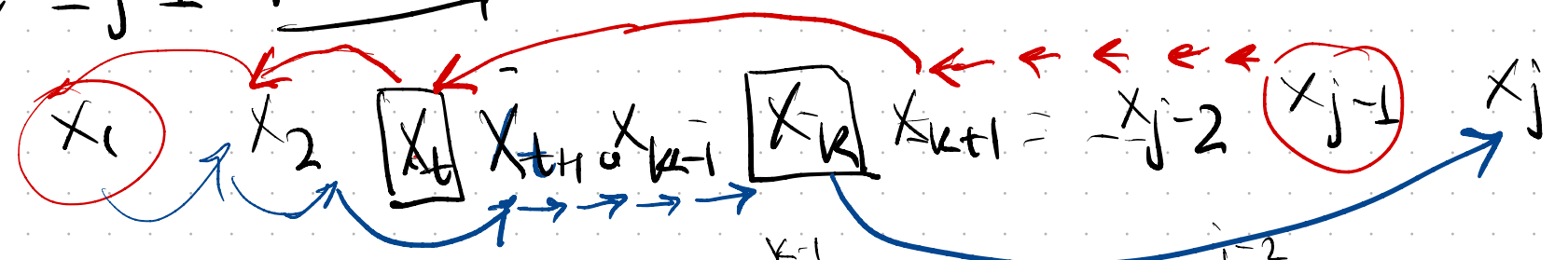
idea 3 sort x-positions 1-j. Pick x_i .



want bitonic tour $x_i \rightsquigarrow x_1$ (Left) $x_i \rightsquigarrow x_j$ (Right)

$c[i, j]$ = best bitonic path objective from x_i to x_j passing through all points $x_1, x_2, \dots, x_i, \dots, x_j$ sorted.

- if $i = j-1$ easy: $c[i, j] = c[i, j-1] + \text{dist}(x_{j-1}, x_j)$
- if $i = j-1$ not easy: search for k that right-jumps $x_k \rightarrow x_j$



$$c[j-1, j] = \text{best } t, k \left(\begin{aligned} & \sum_{l=t}^{k-1} \|x_l - x_{l+1}\| + \sum_{l=k+1}^{j-2} \|x_l - x_{l+1}\| \\ & + c[t, k] \\ & + \|x_t - x_{k+1}\| + \|x_k - x_j\| \end{aligned} \right)$$

$$C[j+1, i] = \underset{k}{\text{best}} \left(\sum_{l=k+1}^{j-1} \|x_l - x_{l+1}\| + \|x_k - x_j\| + C[k, k+1] \right)$$

\downarrow
reversed