

## CS 6140: Machine Learning — Fall 2021 — Paul Hand

Midterm 1 Study Guide and Practice Problems

Due: Never.

Names: *Sample Solutions*

This document contains practice problems for Midterm 1. The midterm will only have 5 problems. The midterm will cover material up through and including the bias-variance tradeoff, but not including ridge regression. Skills that may be helpful for successful performance on the midterm include:

1. Setting up and solving a linear regression problem with features that are nonlinear functions of the model's input.
2. Writing down the optimization problem for least squares linear regression using matrix-vector notation
3. Familiarity with matrix multiplication, in particular when multiplying by diagonal matrices
4. Evaluating the true positive rate, false positive rate, precision, and recall of a predictor for binary classification
5. Setting up a logistic regression problem and writing down the appropriate function that is being minimized
6. Computing the mean, expected value, and variance of uniform random variables
7. Explaining causes and remedies for overfitting and underfitting of ML models

# Linear Regression

Data  $\{ (x^{(i)}, y^{(i)}) \}_{i=1, \dots, n}$   $x \in \mathbb{R}^d$

Model  $y = f_{\theta}(x) + \text{noise}$

means find  $\theta$  s.t.

$$y^{(i)} \approx f_{\theta}(x^{(i)})$$

## Linear Regression

$$f_{\theta}(x) = \theta_0 + \theta_1 x_1 + \dots + \theta_n x_d$$

# Least Squares

$$x^{(i)} \in \mathbb{R}^d, \quad \theta \in \mathbb{R}^{d+1}, \quad y^{(i)} \in \mathbb{R}$$

$$X = \begin{bmatrix} 1, & -x^{(1)T} \\ \vdots & \vdots \\ 1, & -x^{(n)T} \end{bmatrix} \in \mathbb{R}^{n \times (d+1)}$$

↑ if bias is present

$$y = \begin{bmatrix} y_1 \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} y^{(1)} \\ \vdots \\ y^{(n)} \end{bmatrix} \in \mathbb{R}^n$$

$$\theta = \begin{bmatrix} \theta_0 \\ \theta_1 \\ \vdots \\ \theta_d \end{bmatrix} \in \mathbb{R}^{d+1}$$

Then

$$\min_{\theta} \frac{1}{2} \|y - X\theta\|_2^2$$

$$\equiv \min_{\theta} \frac{1}{2} \sum_{i=1}^n \left[ y^{(i)} - (\theta_0 + \theta_1 x_1^{(i)} + \dots + \theta_d x_d^{(i)}) \right]^2$$

Solution

$$\theta = (X^t X)^{-1} X^t y$$

(if  $X$  has rank  $d$ )

### Question 1.

Consider the following training data.

$x_1$	$x_2$	$y$
0	0	0
0	1	1.5
1	0	2
1	1	2.5

$X$

Suppose the data comes from a model  $y = \theta_0 + \theta_1 x_1 + \theta_2 x_2 + \text{noise}$  for unknown constants  $\theta_0, \theta_1, \theta_2$ . Use least squares linear regression to find an estimate of  $\theta_0, \theta_1, \theta_2$ .

**Response:**

$$\text{Let } X = \begin{pmatrix} 1 & 0 & 0 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \\ 1 & 1 & 1 \end{pmatrix}, \quad y = \begin{pmatrix} 0 \\ 1.5 \\ 2 \\ 2.5 \end{pmatrix}, \quad \theta = \begin{pmatrix} \theta_0 \\ \theta_1 \\ \theta_2 \end{pmatrix}$$

We solve the least squares problem

$$\min_{\theta} \|y - X\theta\|^2$$

The solution is given by

$$\theta = (X^t X)^{-1} X^t y$$

Solving  $X^t X = \begin{pmatrix} 4 & 2 & 2 \\ 2 & 2 & 1 \\ 2 & 1 & 2 \end{pmatrix}, \quad (X^t X)^{-1} = \begin{pmatrix} 3/4 & -1/2 & -1/2 \\ -1/2 & 1 & 0 \\ -1/2 & 0 & 1 \end{pmatrix}$

So  $\theta = \begin{pmatrix} 0.5 \\ 2 \\ 0.5 \end{pmatrix} \Rightarrow \begin{matrix} \theta_0 = 0.5 \\ \theta_1 = 2 \\ \theta_2 = 0.5 \end{matrix}$

## Remark

Sometimes a nonlinear model  
model can be turned  
to linear model via some  
nonlinear transformation  
of the data

Question 2.

Consider the following training data:

x	y
1	3
2	1
3	0.5

$$\log(a \cdot b) = \log(b) + \log(a)$$

$$\log e^b = b \log e$$

for  $c > 0$

Suppose the data comes from a model  $y = cx^\beta + \text{noise}$ , for unknown constants  $c$  and  $\beta$ . Use least squares linear regression to find an estimate of  $c$  and  $\beta$ .

Response:

Write  $\log y = \underbrace{\log c}_{\theta_1} + \underbrace{\beta \log x}_{\theta_2 x'} \equiv y' = \theta_1 + \theta_2 x'$

Data becomes:

$\log x$	$\log y$
0	$\log 3$
$\log 2$	0
$\log 3$	$\log 0.5$

Remark  
Assuming  $c > 0$

Let  $X = \begin{pmatrix} 1 & 0 \\ 1 & \log 2 \\ 1 & \log 3 \end{pmatrix}$ ,  $y = \begin{pmatrix} \log 3 \\ 0 \\ \log 0.5 \end{pmatrix}$ ,  $\theta = \begin{pmatrix} \log c \\ \beta \end{pmatrix}$

Solve  $\min_{\theta} \|y - X\theta\|^2$

Solution given by  $\theta = (X^t X)^{-1} X^t y$

Using numpy, we compute  $\theta = \begin{pmatrix} 0.899 \\ -0.5 \end{pmatrix}$

$\Rightarrow c = e^{0.899}$   
 $\beta = -0.5$

3

$\Rightarrow$ $c = 2.45$ $\beta = -0.5$
---

$f$  is a function of  $\theta$

Question 3.

(a) Let  $\theta^* \in \mathbb{R}^d$ , and let  $f(\theta) = \frac{1}{2} \|\theta - \theta^*\|^2$ . Show that the Hessian of  $f$  is the identity matrix.

Response:

(b) Let  $X \in \mathbb{R}^{n \times d}$  and  $y \in \mathbb{R}^n$ . For  $\theta \in \mathbb{R}^d$ , let  $g(\theta) = \frac{1}{2} \|X\theta - y\|^2$ . Show that the Hessian of  $g$  is  $X^t X$ .

Response:

a)  $(H)_{jk} = \frac{\partial^2}{\partial \theta_j \partial \theta_k} f(\theta)$

Write  $f(\theta) = \frac{1}{2} \sum_{i=1}^d (\theta_i - \theta_i^*)^2 \Rightarrow \frac{\partial}{\partial \theta_2} (\theta_3 - \theta_3^*)^2 = 0$

$\frac{\partial}{\partial \theta_k} f(\theta) = (\theta_k - \theta_k^*) \rightarrow \frac{\partial^2}{\partial \theta_j \partial \theta_k} f(\theta)$

$\frac{\partial}{\partial \theta_j} \frac{\partial}{\partial \theta_k} f(\theta) = \frac{\partial}{\partial \theta_j} (\theta_k - \theta_k^*) = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases}$

So  $H_{jk} = \begin{cases} 1 & \text{if } j=k \\ 0 & \text{if } j \neq k \end{cases} \Rightarrow H = I_d$

$$f(\theta+h) = \frac{1}{2} \|\theta+h - \theta^*\|_2^2 \quad \|v\|^2 = v^T v$$

$$= \frac{1}{2} \|\theta - \theta^* + h\|^2$$

$$= \underbrace{\frac{1}{2} \|\theta - \theta^*\|^2}_{f(\theta)} + \underbrace{(\theta - \theta^*)^T h}_{v^T h} + \underbrace{\frac{1}{2} \|h\|^2}_{\downarrow \text{Something}}$$

$$\Rightarrow \nabla f(\theta) = (\theta - \theta^*) \Rightarrow$$

$$[H(\theta)]_{j,k} = \frac{\partial}{\partial \theta_j} \left( \frac{\partial}{\partial \theta_k} f(\theta) \right) = \frac{\partial}{\partial \theta_j} [\nabla f(\theta)]_k$$

$$= \frac{\partial}{\partial \theta_j} [\theta_k - \theta_k^*] = \begin{cases} 0 & \text{if } j \neq k \\ 1 & \text{if } j = k \end{cases}$$

$$[H(\theta)]_{11} = \frac{\partial}{\partial \theta_1} [\theta_1 - \theta_1^*] = 1$$

$$f(\theta+h) = \frac{1}{2} \|(\theta+h) - \theta^*\|_2^2 \quad \|v\|^2 = v^T v$$

$$= \frac{1}{2} \|(\theta - \theta^*) + h\|^2$$

$$= \frac{1}{2} \|\theta - \theta^*\|^2 + \underbrace{(\theta - \theta^*)^T}_{\text{cross term}} h + \frac{1}{2} \|h\|^2$$

$$= f(\theta) + (\theta - \theta^*)^T h + \frac{1}{2} h^T (I) h + 0$$

$$\Rightarrow \nabla f(\theta) = \theta - \theta^*$$

$$H = I$$



$$f: \mathbb{R}^d \rightarrow \mathbb{R}$$

gradient  $\nabla f(\theta) \in \mathbb{R}^{d \times 1}$

$$[\nabla f(\theta)]_k = \frac{\partial}{\partial \theta_k} f(\theta) \quad \begin{bmatrix} \frac{\partial}{\partial \theta_1} f \\ \vdots \\ \frac{\partial}{\partial \theta_d} f \end{bmatrix}$$

or

$$f(\theta+h) = \underbrace{f(\theta)} + \underbrace{\nabla f(\theta)^T h} + o(\|h\|) \quad \begin{matrix} \nearrow \text{but} \\ \text{for } h \rightarrow 0 \\ \downarrow \end{matrix}$$

$$\left[ f(\theta+h) = f(\theta) + \underline{v}^T \underline{h} + \text{something} \right]$$

$$\lim_{h \rightarrow 0} \frac{\text{something}}{\|h\|} = 0$$

$$\Rightarrow v = \nabla f(\theta)$$

# Hessian

$$\nabla^2 f(\theta) \text{ or } H(\theta) \in \mathbb{R}^{d \times d}$$

$$[H(\theta)]_{jk} = \frac{\partial}{\partial \theta_j} \frac{\partial}{\partial \theta_k} f(\theta) = \frac{\partial}{\partial \theta_k} \frac{\partial}{\partial \theta_j} f(\theta) = [H(\theta)]_{kj}$$

or

$$J \nabla f(\theta) = \begin{bmatrix} -\nabla_{\theta} (\partial_{\theta_1} f)^T - \\ \vdots \\ -\nabla_{\theta} (\partial_{\theta_d} f)^T - \end{bmatrix} \quad \left( \begin{array}{l} \text{Derivative / Jacobian} \\ \text{of the gradient} \end{array} \right)$$

or

$$f(\theta+h) = f(\theta) + \nabla f(\theta)^T h + \frac{1}{2} h^T H(\theta) h + \underbrace{O(\|h\|^2)}_{\text{Something}}$$

$$\lim_{h \rightarrow 0} \frac{\text{Something}}{h}$$

$$b) \quad g(\theta) = \frac{1}{2} \|X\theta - y\|^2 \quad g(\theta+h)$$

By class,

$$\begin{aligned} \nabla g(\theta) &= X^t(X\theta - y) \\ &= X^tX\theta - X^ty \end{aligned}$$

Let  $M = X^tX \in \mathbb{R}^{d \times d}$ . Let  $m_k$  be  $k^{\text{th}}$  row of  $M$

$$\begin{aligned} \text{So } \frac{\partial g}{\partial \theta_k} &= (M\theta - X^ty)_k \\ &= \underbrace{m_k^t \theta}_{\uparrow} - (X^ty)_k \end{aligned}$$

$$\text{So } \frac{\partial}{\partial \theta_j} \frac{\partial g}{\partial \theta_k} = \boxed{m_{kj}}$$

$j^{\text{th}}$  entry of  $m_k$ .

Thus

$$\boxed{H = M = X^tX.}$$

$$[\nabla g(\theta)]_k = [M\theta - x^T y]_k$$

$$M\theta = \begin{bmatrix} m_1^T \theta \\ m_2^T \theta \\ \vdots \\ m_d^T \theta \end{bmatrix}$$

when  $m_j$   
j-row of  $M$

$$M = \begin{bmatrix} -m_1^T \\ -m_2^T \\ \vdots \\ -m_d^T \end{bmatrix}$$

$$g(\theta+h) = \frac{1}{2} \|X(\theta+h) - y\|_2^2$$

$$= \underbrace{\frac{1}{2} \|X\theta - y\|_2^2}_{g(\theta)} + \underbrace{\left(X^T(X\theta - y)\right)^T}_{\nabla g(\theta)} h + \frac{1}{2} h^T \underbrace{X^T X}_{H} h$$

# Matrix Multiplication

- $A \in \mathbb{R}^{d_2 \times d_1}$ ,  $B \in \mathbb{R}^{d_1 \times d_3}$

$$AB \in \mathbb{R}^{d_2 \times d_3}$$

- If you find that for  $A \in \mathbb{R}^{d_2 \times d_1}$

$$A = \underbrace{\text{Something}}_{d_2 \times d_1} + \underbrace{\text{something else}}_{d_2 \times d_1}$$

- $A \in \mathbb{R}^{d \times d}$  (SQUARE!)

and invertible  $A^{-1}A = AA^{-1}$

- $A \in \mathbb{R}^{d \times d}$  diagonal matrix if

when  $i \neq j$   $A_{ij} = 0$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Note you can still have  $A_{ii} = 0$

- Note that if  $x \in \mathbb{R}^d$  and  $A$  diagonal

$$[Ax]_i = \underline{A_{ii}} \underline{x}_i \quad [Ax]_2 = A_{22} x_2$$

- $B \in \mathbb{R}^{d \times m}$  and  $A \in \mathbb{R}^{d \times d}$  diagonal

$$\text{if } B = \begin{bmatrix} -b_1^- \\ \vdots \\ -b_d^- \end{bmatrix}$$

$b_i$   $i$ -th row

$$\underbrace{A}_{\text{diag}} \underbrace{B}_i = \begin{bmatrix} \text{---} A_{11} b_1^T \text{---} \\ \vdots \\ \text{---} A_{dd} b_d^T \text{---} \end{bmatrix}$$

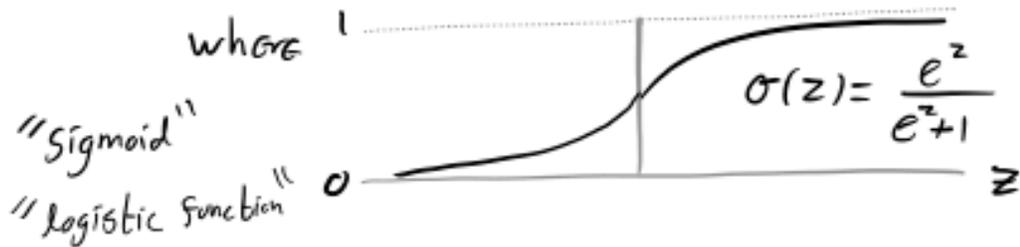
•  $C \in \mathbb{R}^{m \times d} = [C_1, \dots, C_d]$   $C_i$  i-th column

$$C A = \begin{bmatrix} A_{11} & | & C_1 & , \dots , & A_{1d} & | & C_d \\ \vdots & & \vdots & & \vdots & & \vdots \\ \vdots & & \vdots & & \vdots & & \vdots \end{bmatrix}$$

↑  
diag

# Binary Classification

Model  $y = \sigma(\theta_0 + \theta_1 x_1 + \theta_2 x_2) = \hat{y}(x; \theta)$



Solve  $\min_{\theta} \sum_{i=1}^n L(y_i, \hat{y}(x^{(i)}; \theta))$  for  $\hat{\theta}$

Predict:

For new sample  $x$ , predict

$$\begin{cases} \text{class 1 if } \hat{y} \geq \frac{1}{2} \\ \text{class 0 if } \hat{y} < \frac{1}{2} \end{cases}$$

Decision boundary  $\hat{y} = \frac{1}{2}$

$$\sigma(z) = \frac{1}{2} \quad \text{if } z = 0$$

$$\Rightarrow \text{Decision boundary: } \theta_0 + \theta_1 x_1 + \theta_2 x_2 = 0$$

#### Question 4.

Consider a binary classification problem whose features are in  $\mathbb{R}^2$ . Suppose the predictor learned by logistic regression is  $\sigma(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$ , where  $\theta_0 = 4, \theta_1 = -1, \theta_2 = 0$ . Find and plot curve along which  $P(\text{class 1}) = 1/2$  and the curve along which  $P(\text{class 1}) = 0.95$ .

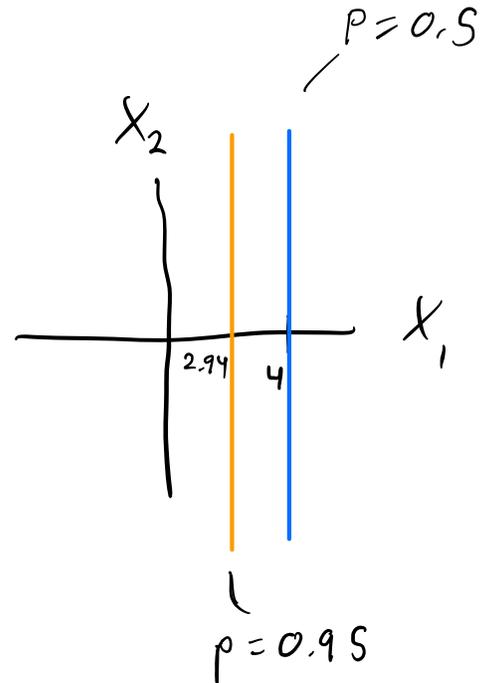
**Response:**

$$\sigma(\theta_0 + \theta_1 x_1 + \theta_2 x_2) = \frac{1}{2}$$

$$\Rightarrow \theta_0 + \theta_1 x_1 + \theta_2 x_2 = 0$$

$$\Rightarrow 4 - x_1 = 0$$

$$x_1 = 4$$



$$\sigma(\theta_0 + \theta_1 x_1 + \theta_2 x_2) = 0.95$$

Recall 
$$\sigma(z) = \frac{e^z}{e^z + 1} = \frac{1}{1 + e^{-z}}$$

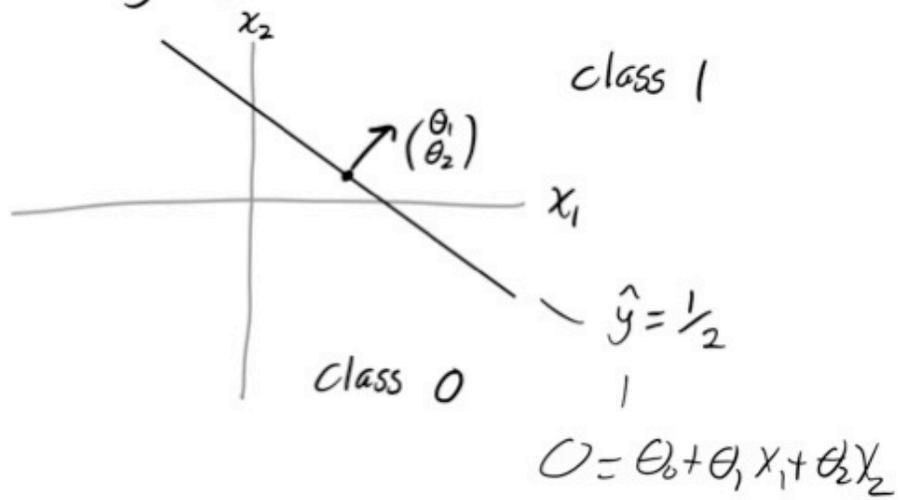
$$\text{So } \sigma(z) = 0.95 \Rightarrow \frac{1}{1 + e^{-z}} = 0.95$$

$$\Rightarrow e^{-z} = -1 + \frac{1}{0.95} = 0.0526$$

$$\Rightarrow z = 2.94$$

$$\Rightarrow \theta_0 + \theta_1 x_1 + \theta_2 x_2 = 2.94 \Rightarrow 4 - x_1 = 2.94 \Rightarrow x_1 = 1.06$$

Decision boundary is linear



## Multiclass Classification

Consider a 3 class classification problem (no bias term)

Training Data:  $\{(x^{(i)}, y^{(i)})\}_{i=1 \dots n}$

$x^{(i)} \in \mathbb{R}^d$  for all  $i$

$y^{(i)} \in \mathbb{R}^3$ ,  $y^{(i)} = \begin{cases} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} & \text{if } y^{(i)} \text{ of class 1} \\ \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} & \text{if } y^{(i)} \text{ of class 2} \\ \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} & \text{if } y^{(i)} \text{ of class 3} \end{cases}$

one-hot encoding

Model:  $y = \text{Softmax}(z_1, z_2, z_3)$

Logits  $\begin{cases} z_1 = \theta_1 \cdot x \\ z_2 = \theta_2 \cdot x \\ z_3 = \theta_3 \cdot x \end{cases}$  w/  $\begin{cases} \theta_1 \in \mathbb{R}^d \\ \theta_2 \in \mathbb{R}^d \\ \theta_3 \in \mathbb{R}^d \end{cases}$

"logits are linear in parameters of model"

$$\text{Softmax}(z_1, z_2, z_3) = \begin{pmatrix} \frac{e^{z_1}}{e^{z_1} + e^{z_2} + e^{z_3}} \\ \frac{e^{z_2}}{e^{z_1} + e^{z_2} + e^{z_3}} \\ \frac{e^{z_3}}{e^{z_1} + e^{z_2} + e^{z_3}} \end{pmatrix} \quad \text{— adds up to 1}$$

Train  $\circ$

$$\min_{\Theta} \sum_{i=1}^n L(y^{(i)}, \text{softmax}(\theta_1 \cdot x^{(i)}, \theta_2 \cdot x^{(i)}, \theta_3 \cdot x^{(i)}))$$

log loss  $\circ$

$$L(y, \hat{y}) = - \sum_{c=1}^3 y_c \log \hat{y}_c$$

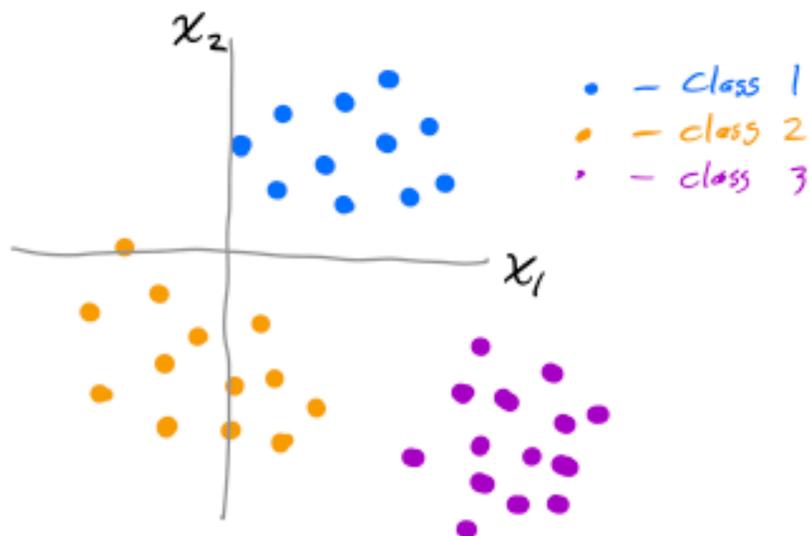
$\mathbb{R}^3$      $\mathbb{R}^3$

Prediction  $\circ$

Given  $x$ , compute  $\hat{y}(x; \hat{\theta}) \in \mathbb{R}^3$

Predict class  $\hat{c}$  w/  $\hat{c} = \underset{c}{\text{argmax}} \hat{y}_c$

What will decision boundary look like for 3-class classification?



$x_1, x_2$  is class 1

### Question 5.

Consider a 3-class classification problem. You have trained a predictor whose input is  $x \in \mathbb{R}^2$  and whose output is  $\text{softmax}(x_1 + x_2 - 1, 2x_1 + 3, x_2)$ . Find and sketch the three regions in  $\mathbb{R}^2$  that gets classified as class 1, 2, and 3.

### Response:

The predicted class corresponds to the largest component of softmax, which is the same as the largest input to softmax.

$$Z_1 = X_1 + X_2 - 1$$

$$Z_2 = 2X_1 + 3$$

$$Z_3 = X_2$$

a) where is classified as class 1?

$$X_1 + X_2 - 1 > 2X_1 + 3 \quad \& \quad X_1 + X_2 - 1 > X_2$$

$$\Rightarrow \underbrace{-X_1 + X_2 > 4}_{\text{line 1}} \quad \& \quad \underbrace{X_1 > 1}_{\text{line 2}}$$

$-x_1 + x_2 = 4$                        $x_1 = 1$

b) Where is classified as class 2 ?

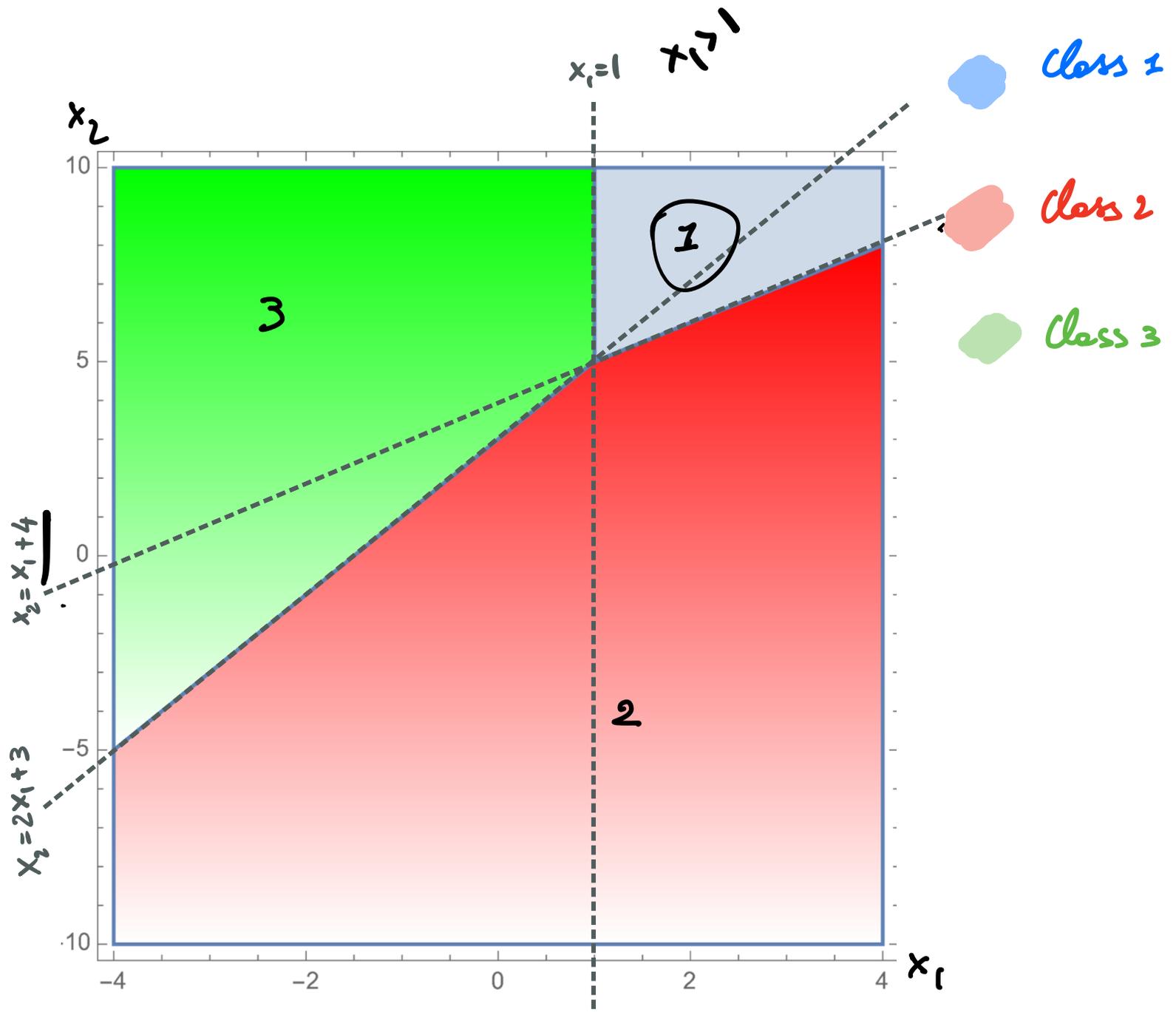
$$2X_1 + 3 > X_1 + X_2 - 1 \quad \& \quad 2X_1 + 3 > X_2$$

$$\underline{-X_1 + X_2 < 4} \quad \& \quad \underline{2X_1 - X_2 > -3}$$

c) Where is classified as class 3 ?

$$X_2 > X_1 + X_2 - 1 \quad \& \quad X_2 > 2X_1 + 3$$

$$X_1 < 1 \quad \& \quad 2X_1 - X_2 < -3$$



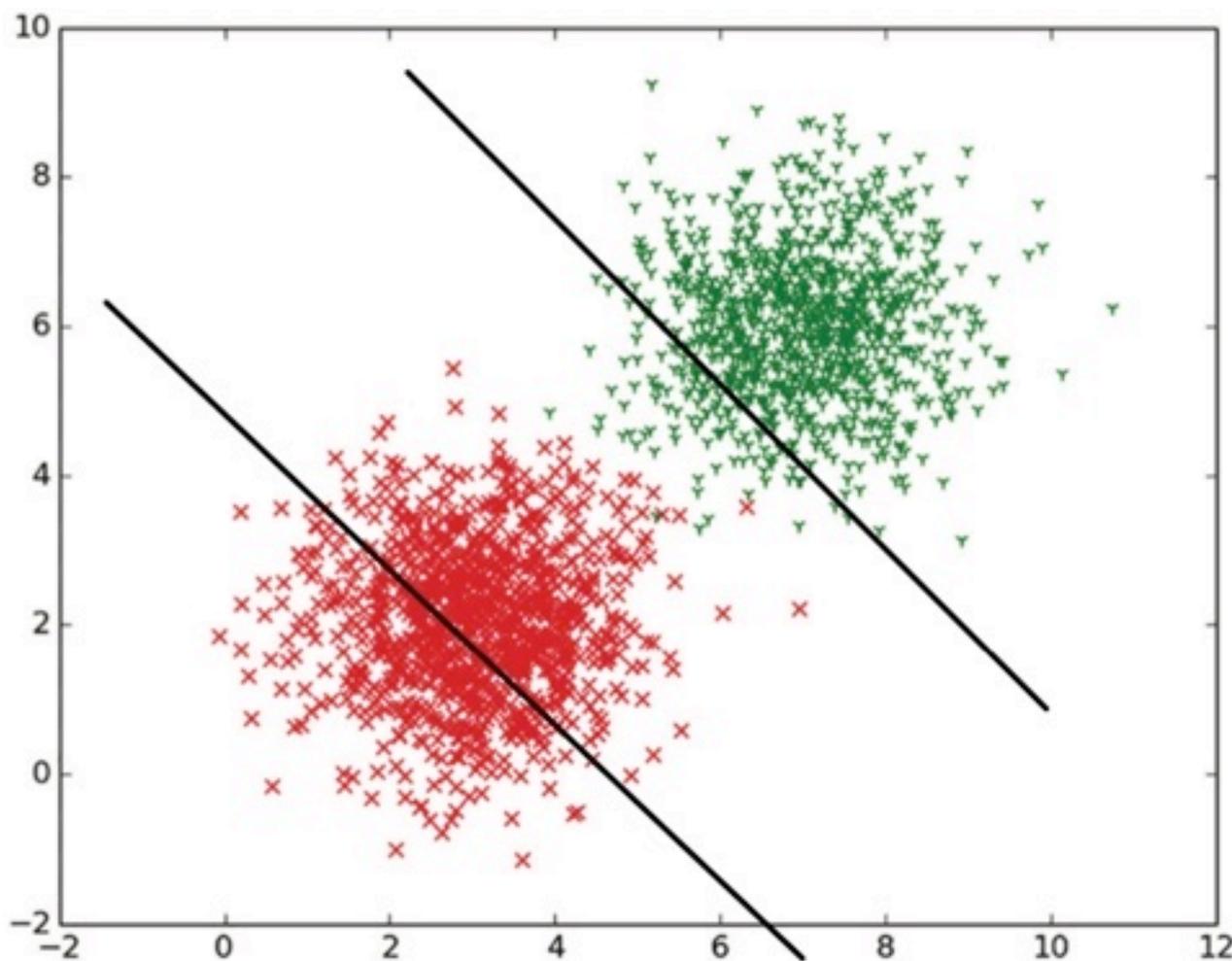
Precision %  $\frac{TP}{TP+FP}$

What fraction of predicted positives are real?

Recall %  $\frac{TP}{TP+FN}$

What fraction of positives are correctly predicted?

Want high precision & high recall



Class 1

Class 0

# RISK

•  $f: x \mapsto f(x)$  predictor

•  $l$  loss  $\Rightarrow (\quad)^2$

Risk of  $f$  is

$$R(f) = \mathbb{E}_{(x,y) \sim D} l(y, f(x))$$

But No  $S$

If  $f$  depends on some  $\theta$  then

$$R(\theta) = R(f_\theta) = \mathbb{E}_{\underline{(x,y) \sim D}} l(y, f_\theta(x))$$

Note  $\theta$  here is just a parameter fixed (constant)

Note when we study Bias-Variance:  
then  $\hat{\theta}$  is estimated from data  $\Rightarrow$  Random  
so we also take expectation over  
 $S$  = samples

$$\mathbb{E}_{S, x, y}$$

$$y = x + \varepsilon \quad \mathbb{E}_{x,y} \rightarrow \mathbb{E}_{x,\varepsilon}$$

**Question 6.**

Suppose  $x \sim \text{Uniform}([-1, 1])$  and  $y = x + \varepsilon$ , where  $\varepsilon \sim \text{Uniform}([- \gamma, \gamma])$  for some  $\gamma > 0$ . Consider a predictor given by  $f_\theta(x) = \theta_1 + \theta_2 x$ , where  $\theta \in \mathbb{R}^2$ . Evaluate the risk of  $f_\theta$  with respect to the square loss. Your answer should be a deterministic expression only depending on  $\theta_1, \theta_2$ , and  $\gamma$ .

**Response:**

$$R(\theta) = \mathbb{E}_{x,\varepsilon} \left[ |f_\theta(x) - y|^2 \right] = \mathbb{E}_{x,\varepsilon} \left[ (\theta_1 + \theta_2 x - x - \varepsilon)^2 \right]$$

$$= \mathbb{E}_{x,\varepsilon} \left[ (\theta_1 + (\theta_2 - 1)x - \varepsilon)^2 \right]$$

Note:  $\mathbb{E}[x^2] = \int_{-1}^1 x^2 \cdot \frac{1}{2} dx = \frac{1}{6} x^3 \Big|_{-1}^1 = \frac{1}{3}$

$$= \mathbb{E}_{x,\varepsilon} [\theta_1^2] + \mathbb{E}_{x,\varepsilon} [(\theta_2 - 1)^2 x^2] + \mathbb{E}[\varepsilon^2]$$

$$- 2 \mathbb{E}_{x,\varepsilon} [\theta_1 \varepsilon] - 2 \mathbb{E}_{x,\varepsilon} [\theta_1 (\theta_2 - 1)x] - 2 \mathbb{E}_{x,\varepsilon} [(\theta_2 - 1)x \varepsilon]$$

Since  $\theta_1, \theta_2$  are deterministic  $\Rightarrow \mathbb{E}[\theta_1 \varepsilon] = \theta_1 \mathbb{E}[\varepsilon]$

$\mathbb{E}[x] = \mathbb{E}[\varepsilon] = 0$  and  $x$  and  $\varepsilon$  indep.  $\Rightarrow \mathbb{E}[x \varepsilon] = \mathbb{E}[x] \mathbb{E}[\varepsilon]$

$$R(\theta) = \theta_1^2 + \frac{1}{3} (\theta_2 - 1)^2 + \frac{1}{3} \gamma^2$$

$$E[x] = \int_{-1}^1 x \text{pdf}(x) dx = \int_{-1}^1 \frac{x}{2} dx = 0$$

the reason is pdf of uniform in  $[a, b] = \frac{1}{(b-a)}$

$$E[x^2] = \int_{-1}^1 x^2 \cdot \frac{1}{2} dx =$$

$$E[\epsilon] = \int_{-\delta}^{\delta} \epsilon \frac{1}{2\delta} d\epsilon = 0$$

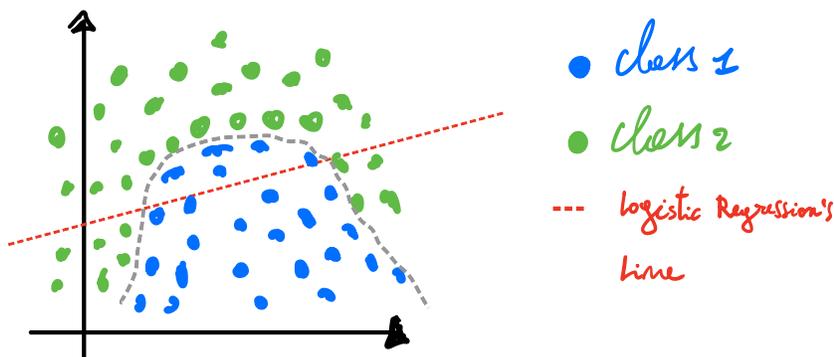
### Question 7.

You are training a logistic regression model and you notice that it does not perform well on test data.

- Could the poor performance be due to underfitting? Explain.
- Could the poor performance be due to overfitting? Explain.

Underfitting Yes, logistic regression separates the 2 classes using only a line. This might be too simple to explain the variations in the data

Consider for example the case of 2 classes separable by a curved line.

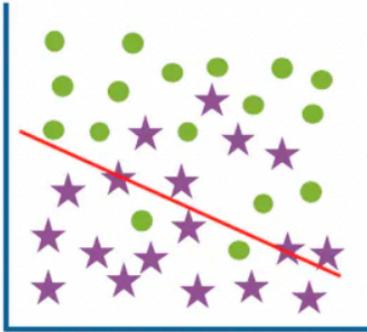


# Overfitting

Yes, if there are too many features, the data could appear to be linearly separable as a mathematical artifact. This could result in overfitting of training data.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \begin{bmatrix} x_1 \\ x_2 \\ x_1 x_2 \\ \vdots \\ x_1^{10} \end{bmatrix}$$

Underfit  
(high bias)

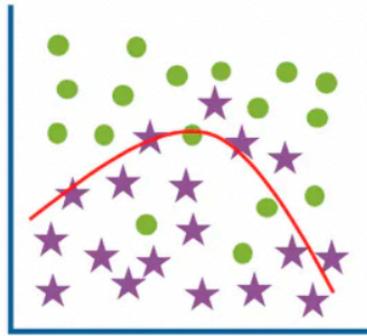


High training error  
High test error

$$G(\theta_0 + \theta_1 x_1 + \theta_2 x_2)$$

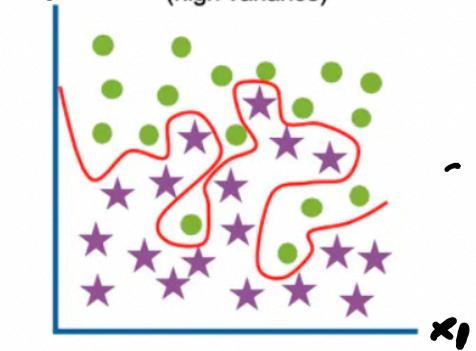
$$G(\theta_0 + \theta_1 x_1 + \theta_2 x_2 + \theta_3 x_1 x_2 + \theta_4 x_3^4 + \dots)$$

Optimum



Low training error  
Low test error

Overfit  
(high variance)



Low training error  
High test error