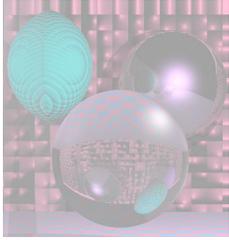


CS 4300

Computer Graphics

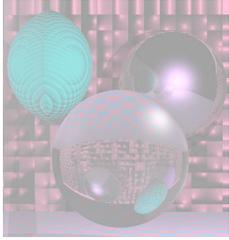
Prof. Harriet Fell
Fall 2012

Lecture 32 – November 19, 2012



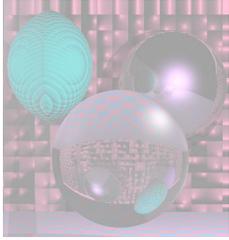
Today's Topics

- Morphing



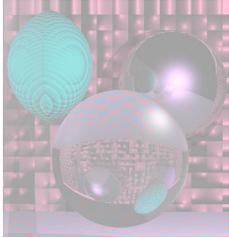
Morphing History

- *Morphing* is turning one image into another through a seamless transition.
- Early films used cross-fading picture of one actor or object to another.
- In 1985, "Cry" by Godley and Crème, parts of an image fade gradually to make a smother transition.
- Early-1990s computer techniques distorted one image as it faded into another.
 - Mark corresponding points and vectors on the "before" and "after" images used in the morph.
 - E.g. key points on the faces, such as the contour of the nose or location of an eye
 - Michael Jackson's "Black or White" (1991)
 - » <http://en.wikipedia.org/wiki/Morphing>



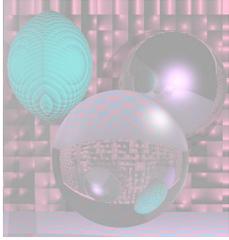
Morphing History

- 1992 Gryphon Software's “Morph” became available for Apple Macintosh.
- For high-end use, “Elastic Reality” (based on Morph Plus) became the de facto system of choice for films and earned two Academy Awards in 1996 for Scientific and Technical Achievement.
- Today many programs can automatically morph images that correspond closely enough with relatively little instruction from the user.
- Now morphing is used to do cross-fading.



Harriet George Harriet...

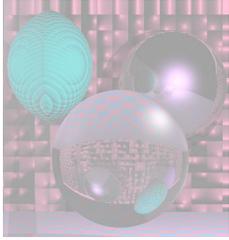




Feature Based Image Metamorphosis

Thaddeus Beier and Shawn Neely 1992

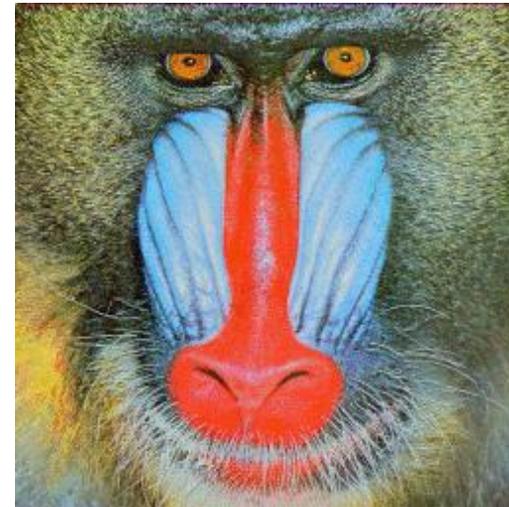
- The morph process consists
 - warping two images so that they have the same "shape"
 - cross dissolving the resulting images
- cross-dissolving is simple
- warping an image is hard



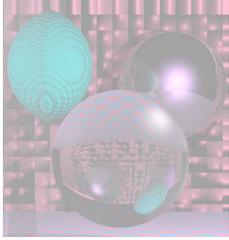
Harriet & Mandrill



Harriet 276x293



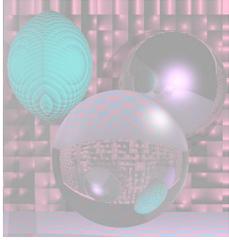
Mandrill 256x256



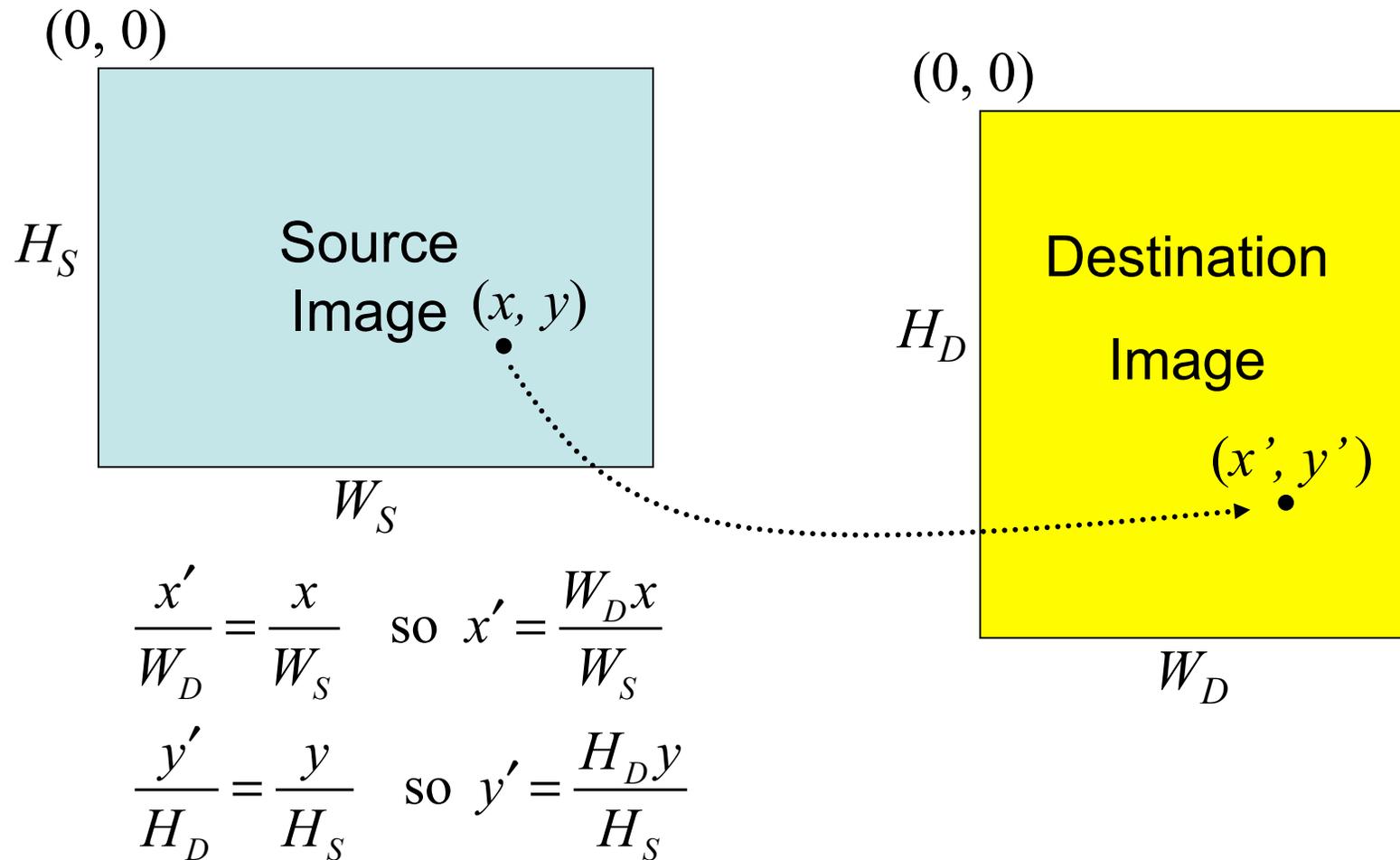
Warping an Image

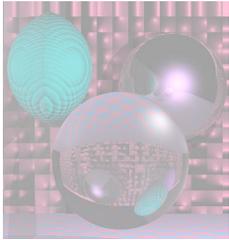
There are two ways to warp an image:

- *forward mapping* - scan through source image pixel by pixel, and copy them to the appropriate place in the destination image.
 - some pixels in the destination might not get painted, and would have to be interpolated.
- *reverse mapping* - go through the destination image pixel by pixel, and sample the correct pixel(s) from the source image.
 - every pixel in the destination image gets set to something appropriate.

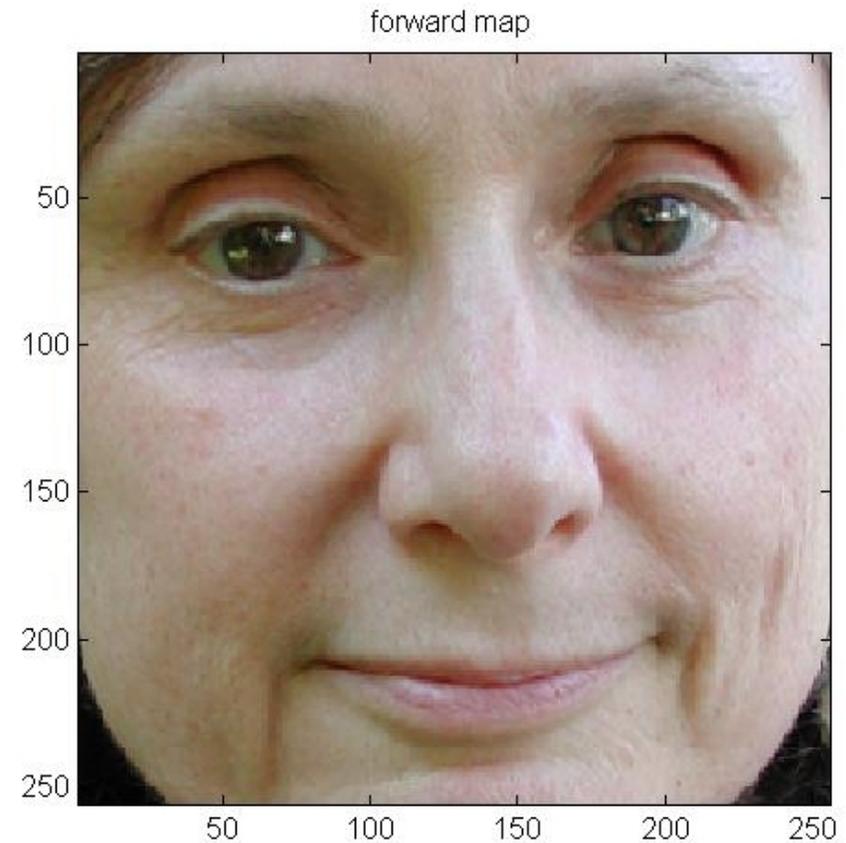
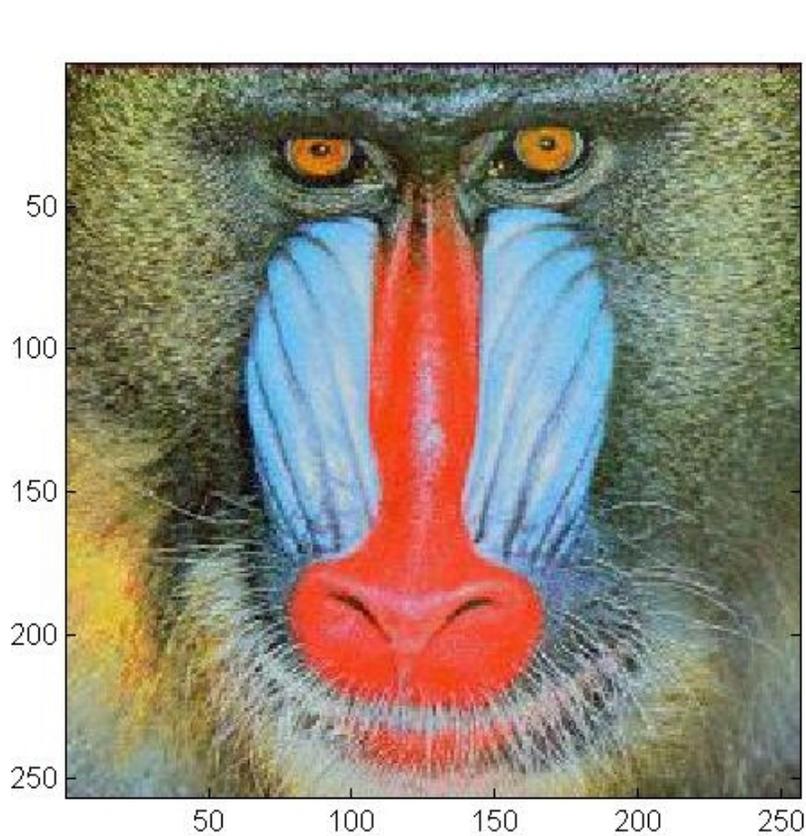


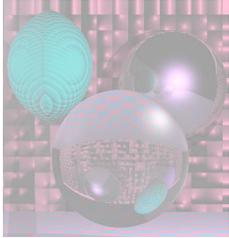
Forward Mapping



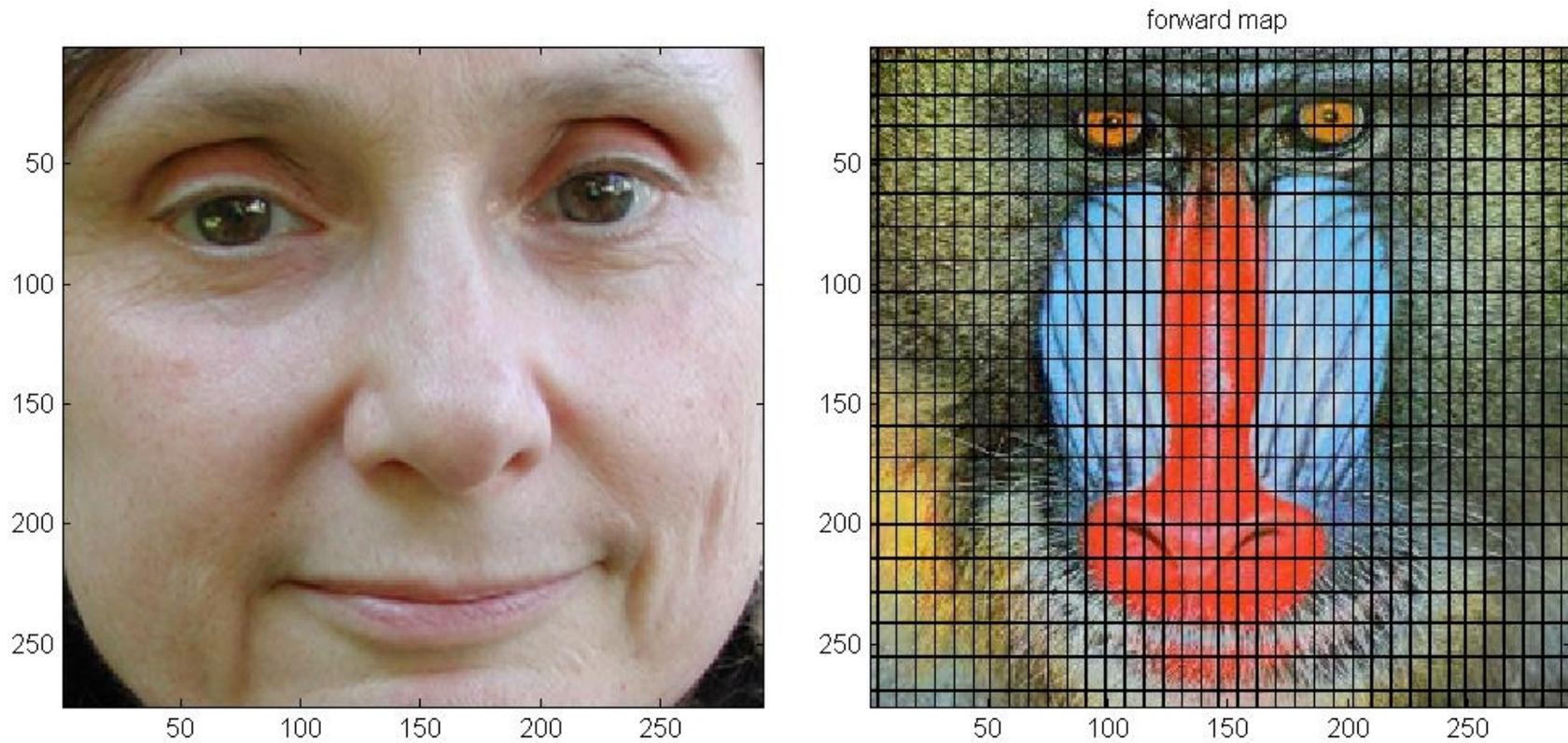


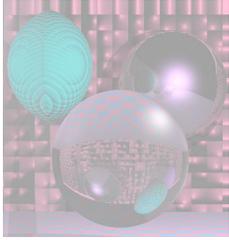
Forward Mapping Harriet → Mandrill



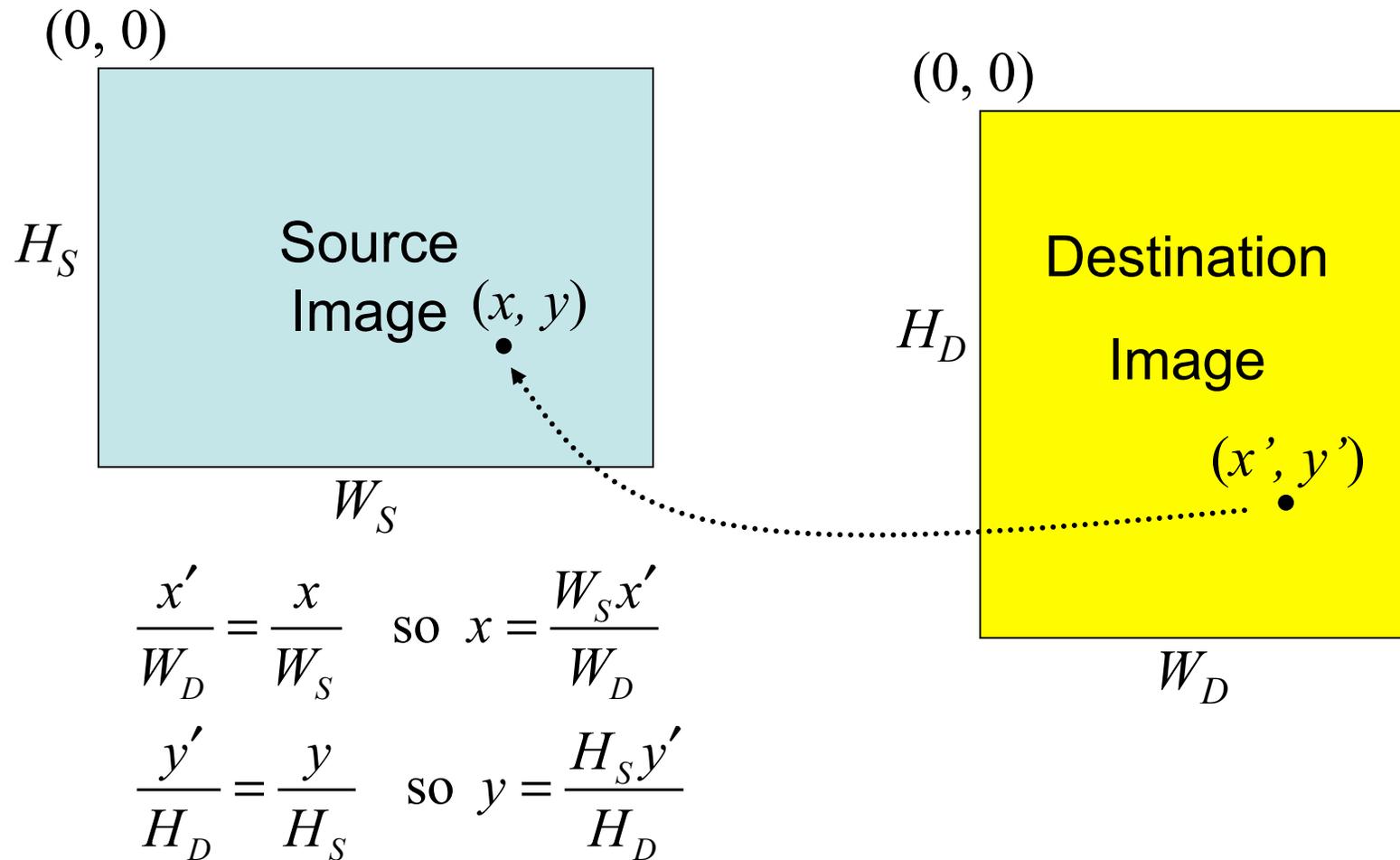


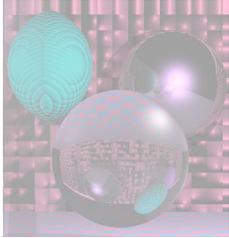
Forward Mapping Mandrill → Harriet



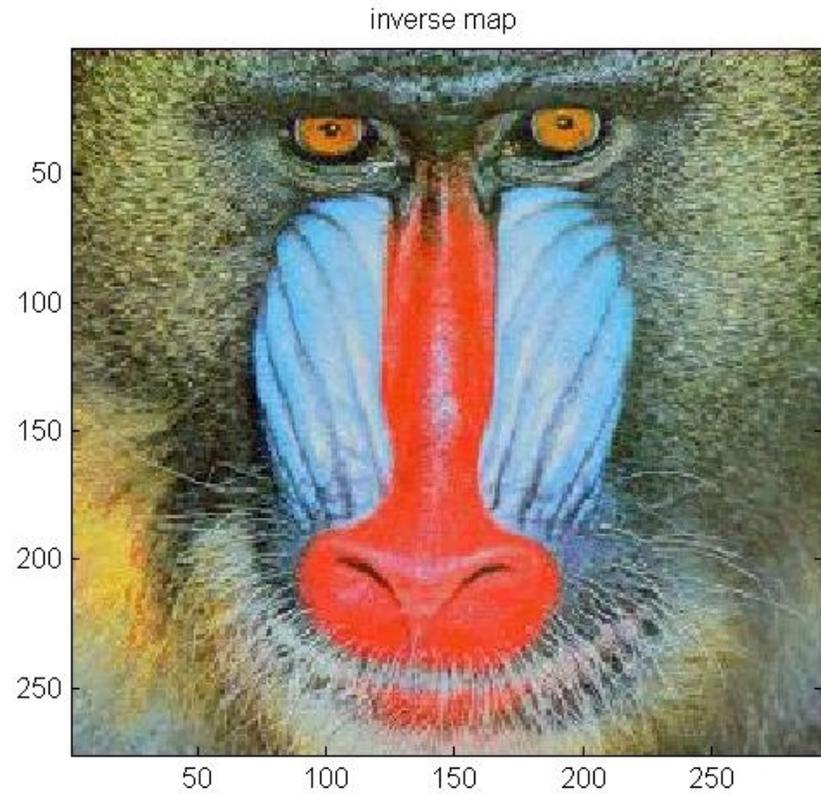
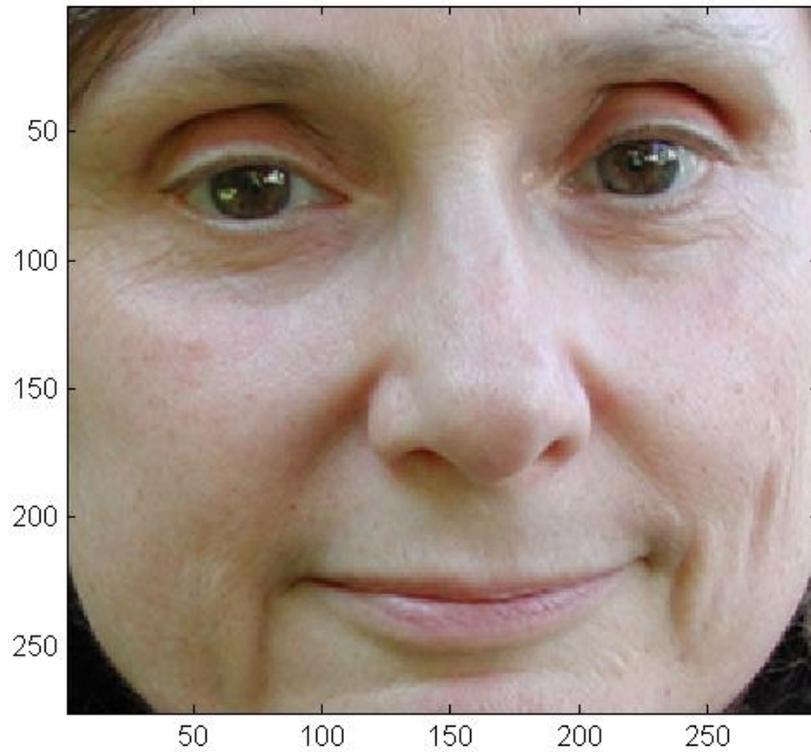


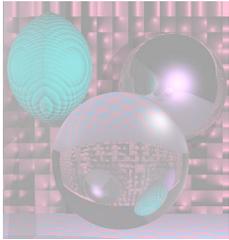
Inverse Mapping





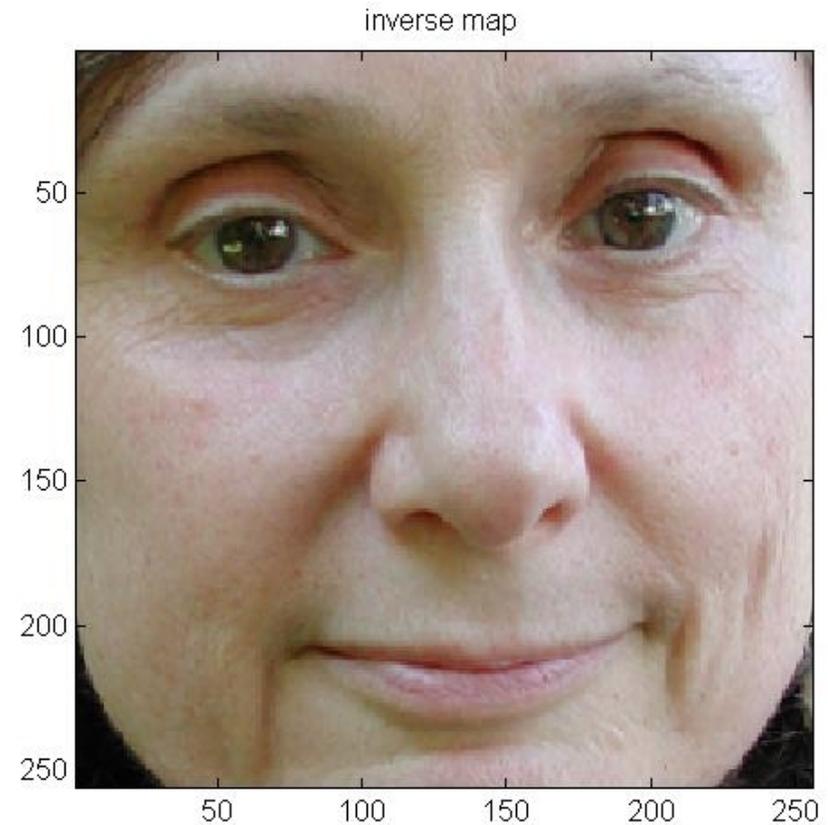
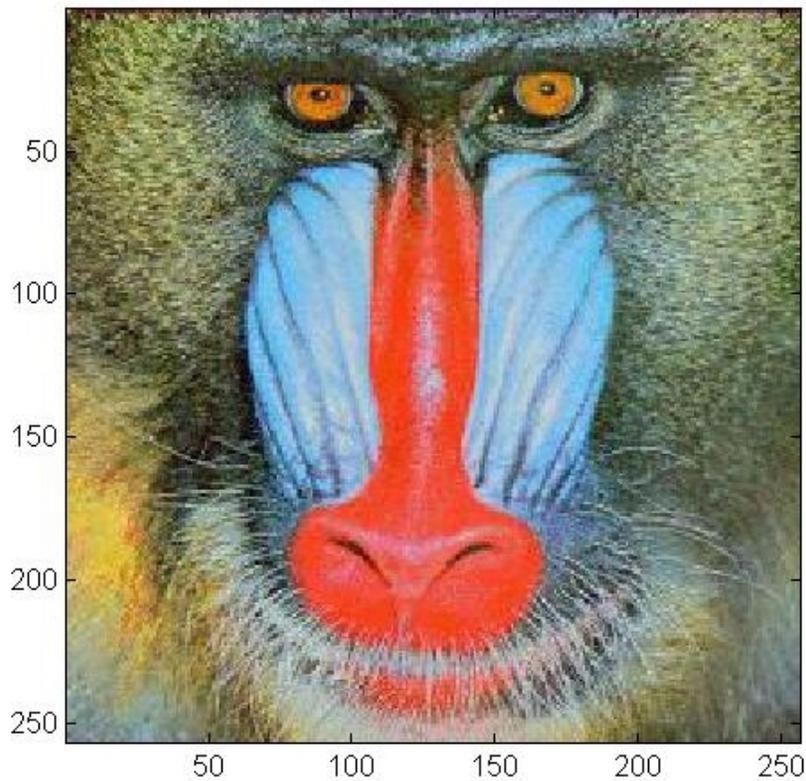
Inverse Mapping Mandrill \rightarrow Harriet

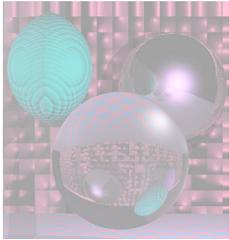




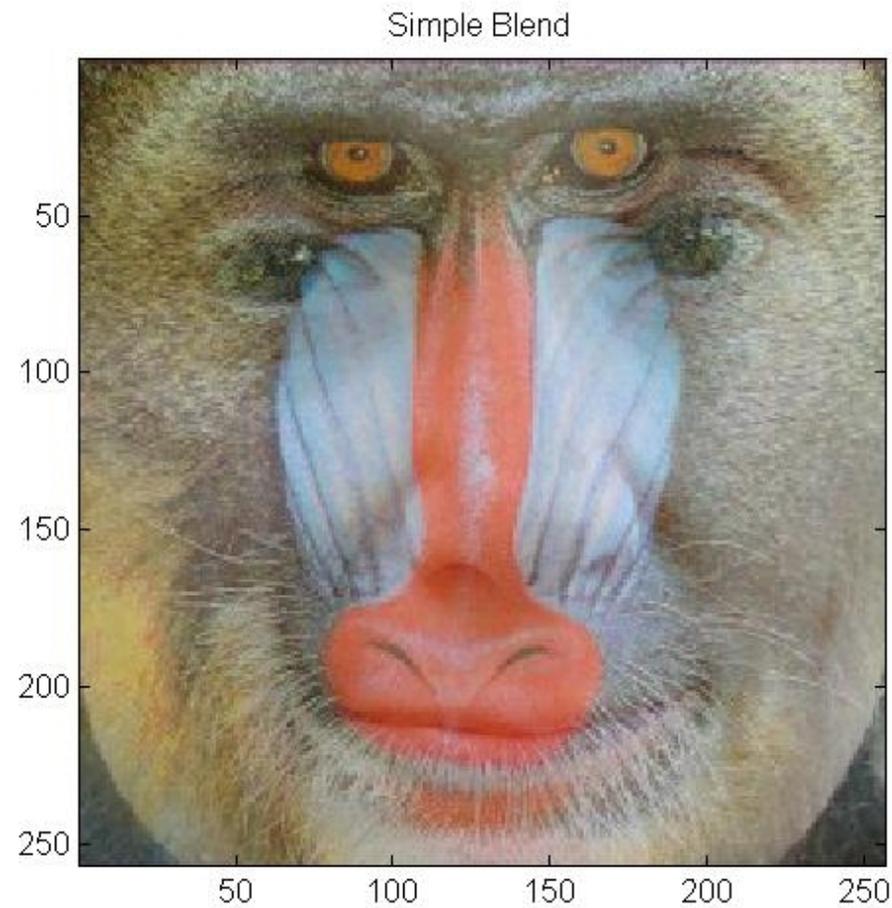
Inverse Mapping

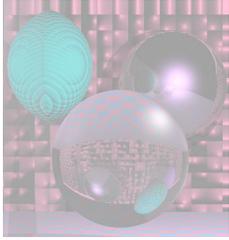
Harriet → Mandrill





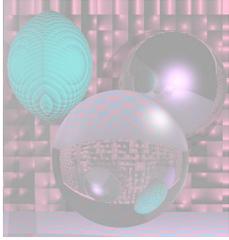
$(\text{harriet} \text{NV} + \text{mandrill}) / 2$



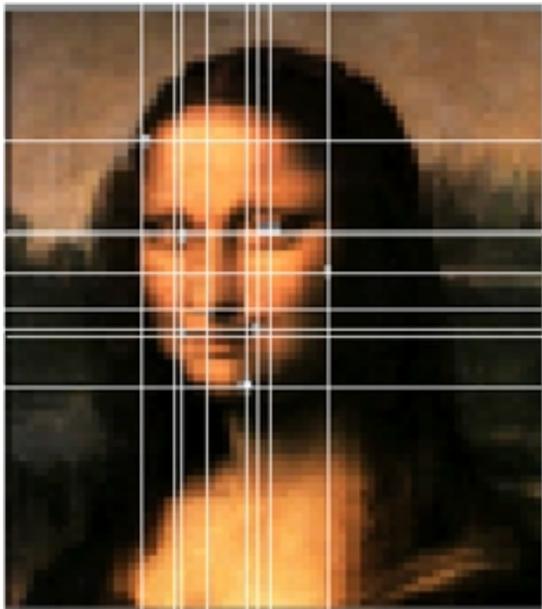


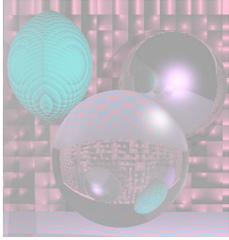
Matching Points





Matching Points Rectangular Transforms



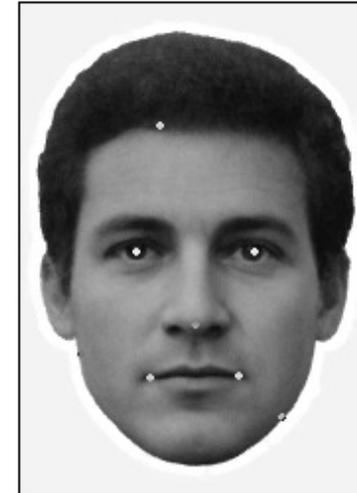


Halfway Blend

Image1

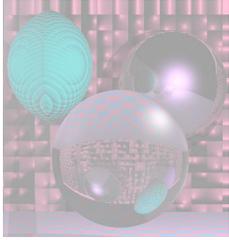


Image2



$$(1-t)\text{Image1} + (t)\text{Image2}$$

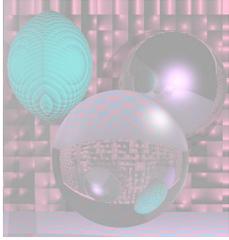
$$T = .5$$



Caricatures Extreme Blends



$t = 1.5$

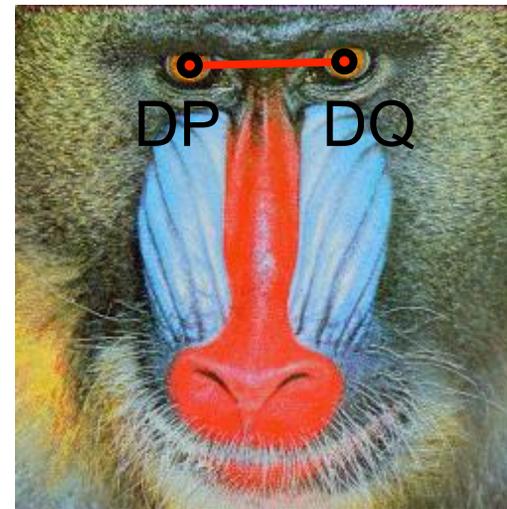


Harriet & Mandrill Matching Eyes

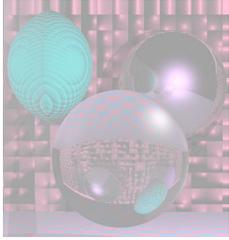
Match the endpoints of a line in the source with the endpoints of a line in the destination.



Harriet 276x293

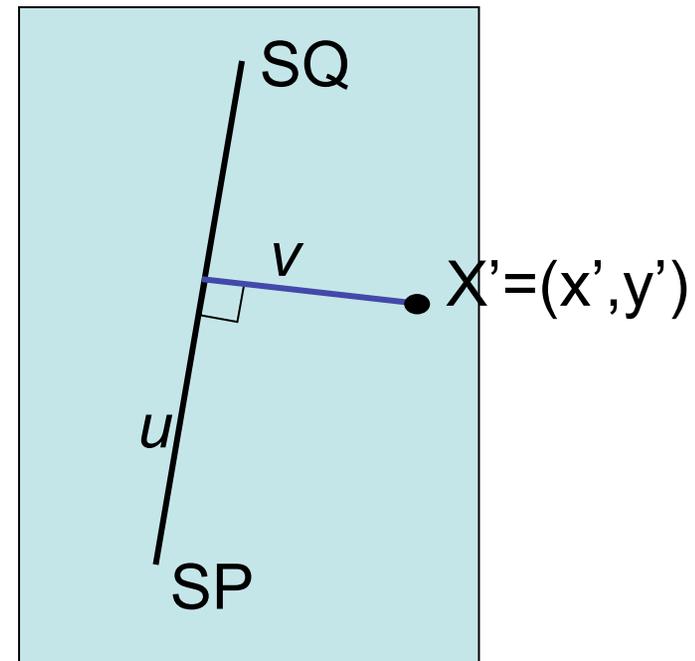
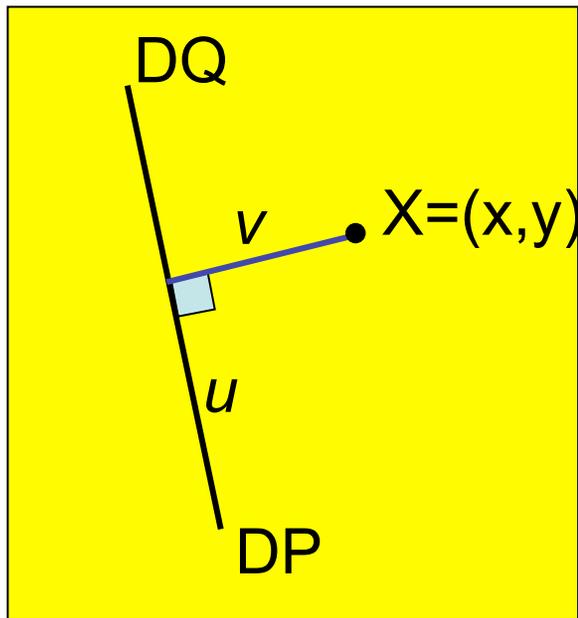


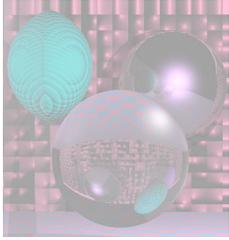
Mandrill 256x256



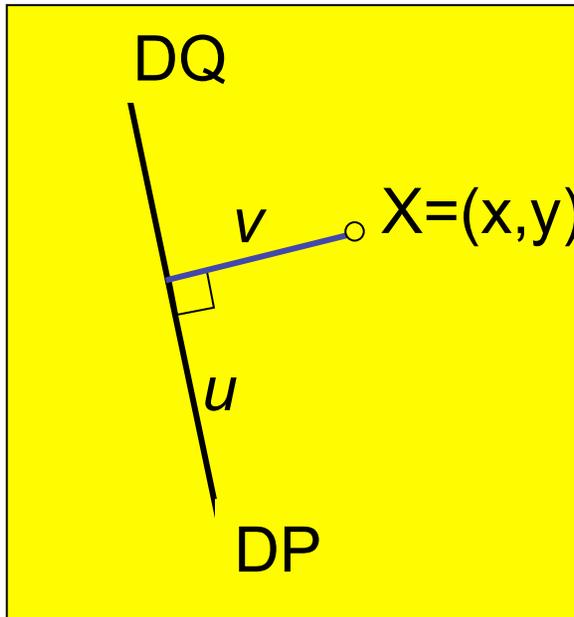
Line Pair Map

The *line pair map* takes the source image to an image the same size as the destinations and take the line segment in the source to the line segment in the destination.





Finding u and v



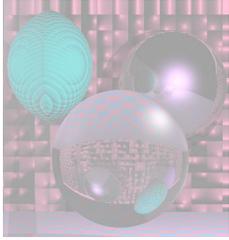
$$u = \frac{(X - DP) \cdot (DQ - DP)}{\|DQ - DP\|^2}$$

$$v = \frac{(X - DP) \cdot \text{perp}(DQ - DP)}{\|DQ - DP\|}$$

$$X' = SP + u \times (SQ - SP) + \frac{v \times \text{perp}(SQ - SP)}{\|SQ - SP\|}$$

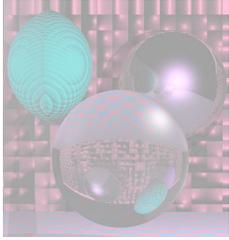
u is the proportion of the distance from DP to DQ.

v is the distance to travel in the perpendicular direction.



linePairMap.m header

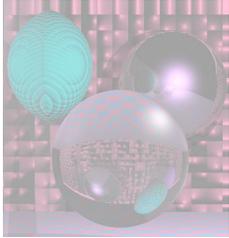
```
% linePairMap.m
% Scale image Source to one size DW, DH with line pair
mapping
function Dest = forwardMap(Source, DW, DH, SP, SQ, DP, DQ);
% Source is the source image
% DW is the destination width
% DH is the destination height
% SP, SQ are endpoints of a line segment in the Source [y, x]
% DP, DQ are endpoints of a line segment in the Dest [y, x]
```



linePairMap.m body

```
Dest = zeros(DH, DW,3); % rows x columns x RGB
SW = length(Source(1,:,1)); % source width
SH = length(Source(:,1,1)); % source height
for y= 1:DH
    for x = 1:DW
        u = ([x,y]-DP)*(DQ-DP)'/'((DQ-DP)*(DQ-DP)');
        v = ([x,y]-DP)*perp(DQ-DP)'/norm(DQ-DP);
        SourcePoint = SP+u*(SQ-SP) + v*perp(SQ-SP)/norm(SQ-SP);
        SourcePoint = max([1,1],min([SW,SH], SourcePoint));

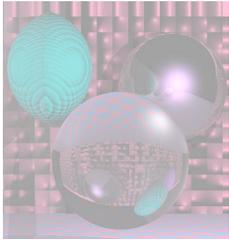
        Dest(y,x,:)=Source(round(SourcePoint(2)),round(SourcePoint(1)),:);
    end;
end;
```



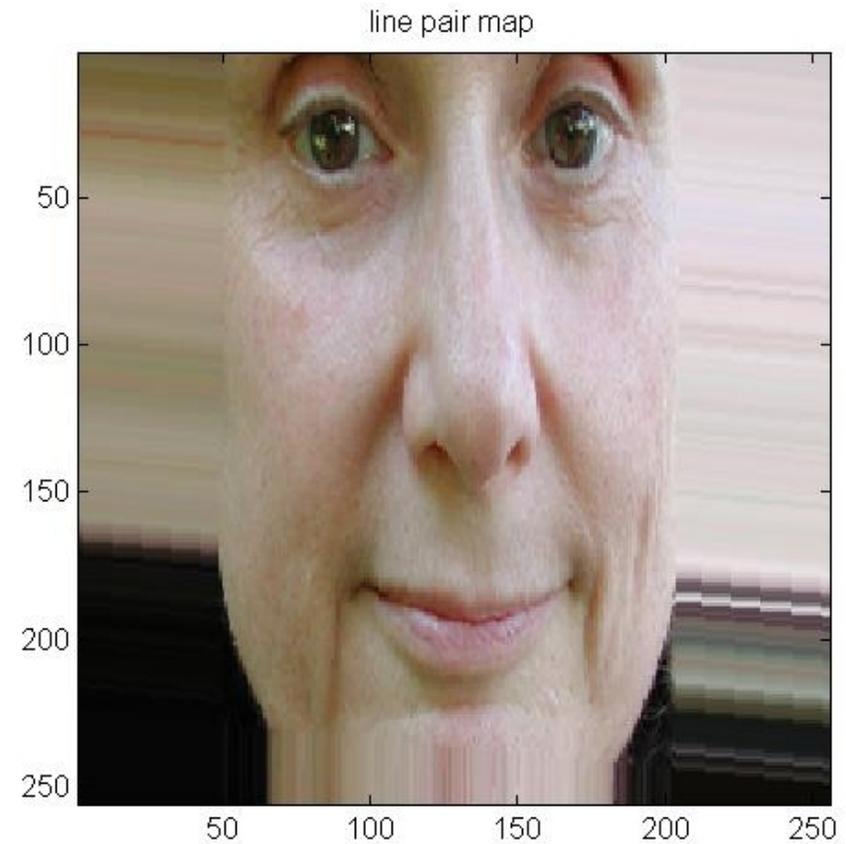
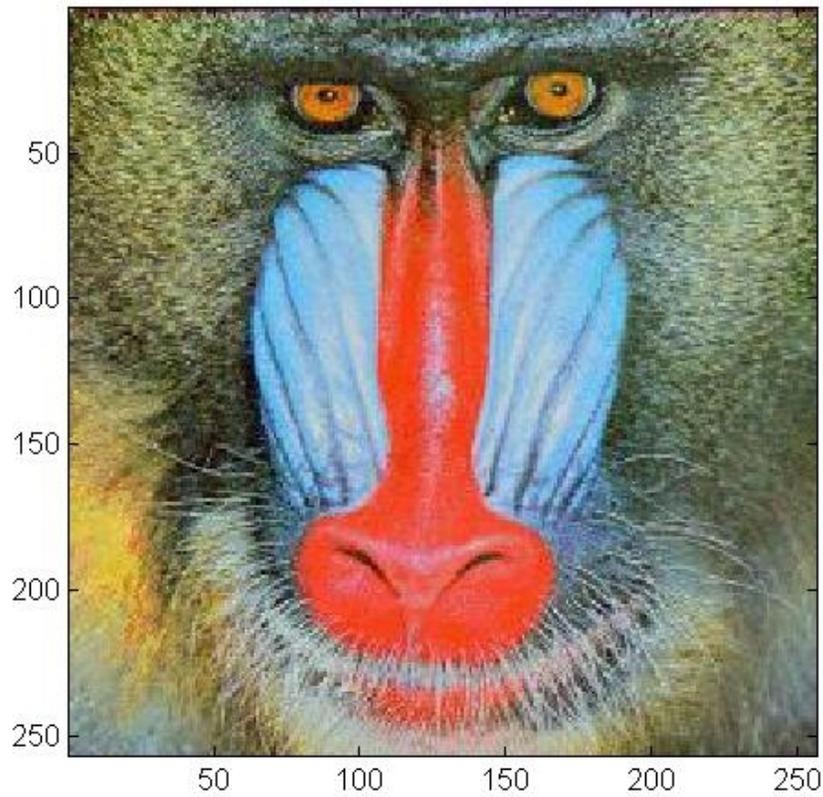
linePairMap.m extras

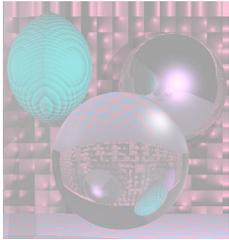
```
% display the image  
figure, image(Dest/255,'CDataMapping','scaled');  
axis equal;  
title('line pair map');  
xlim([1,DW]); ylim([1,DH]);
```

```
function Vperp = perp(V)  
Vperp = [V(2), -V(1)];
```

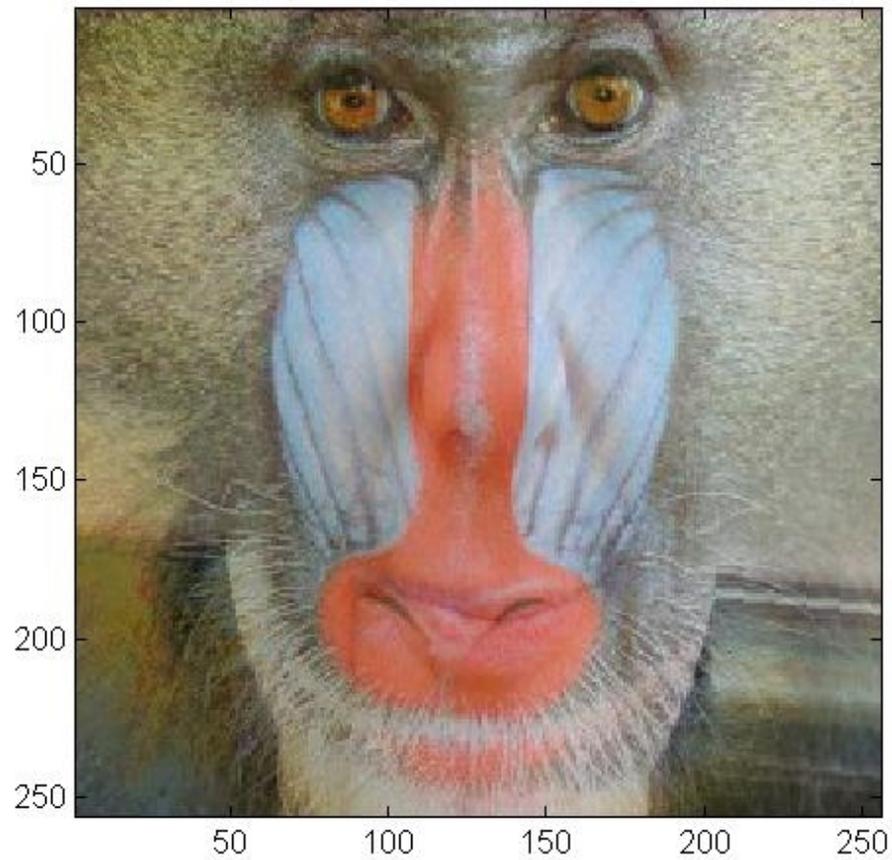


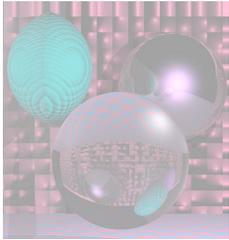
Line Pair Map



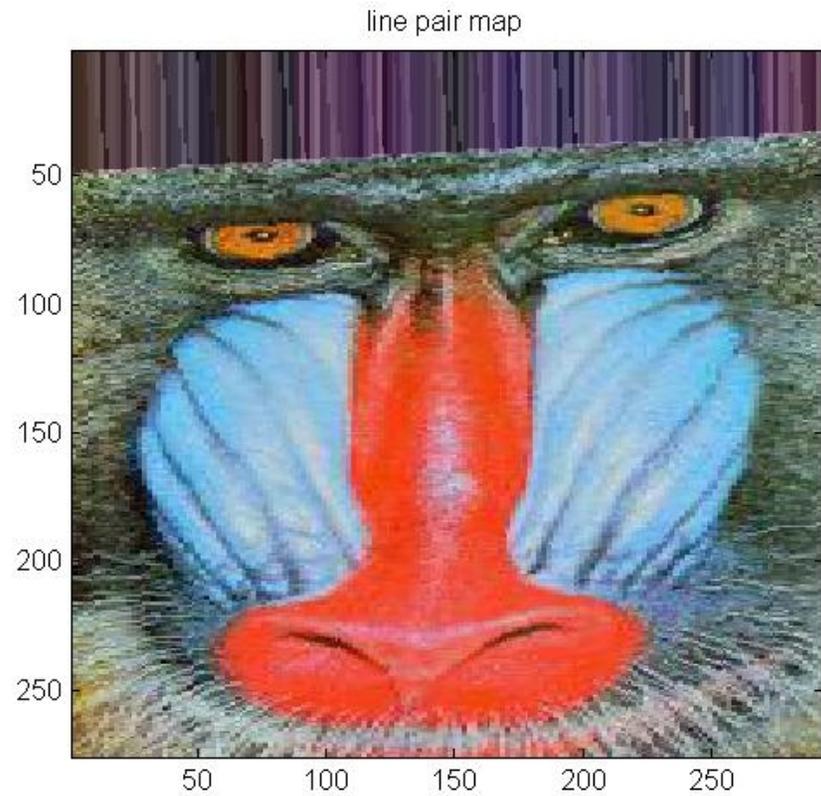
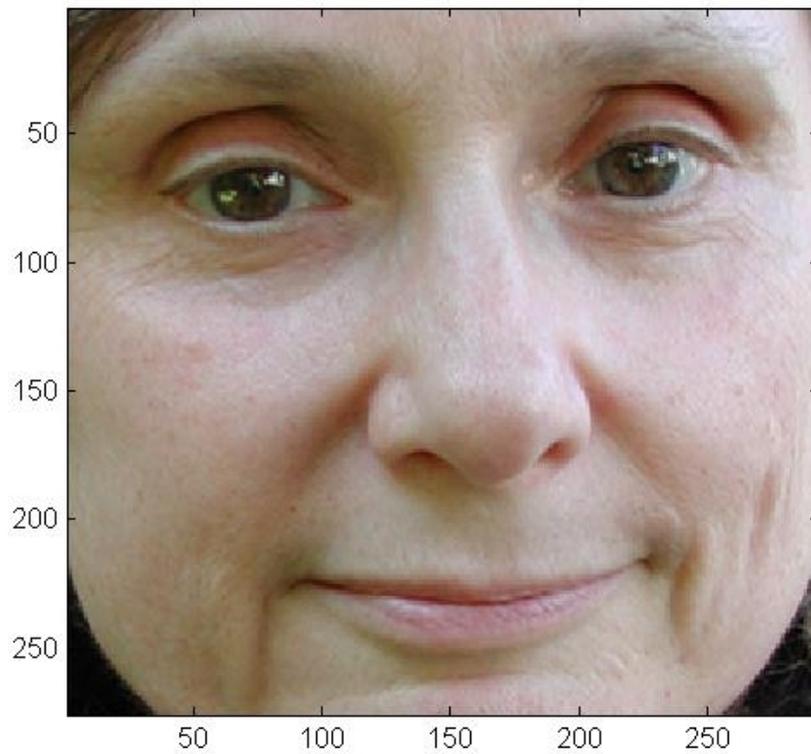


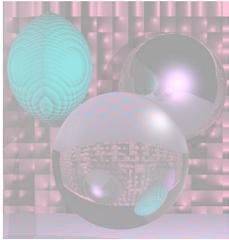
Line Pair Blend



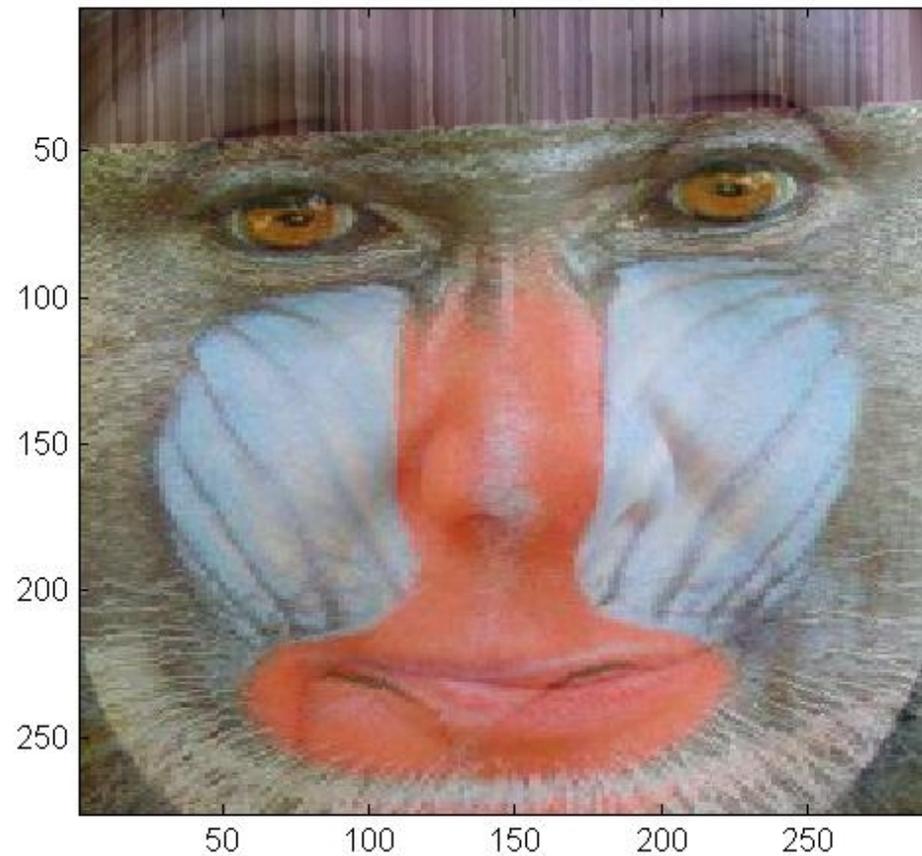


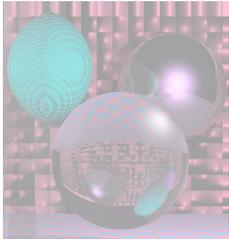
Line Pair Map 2





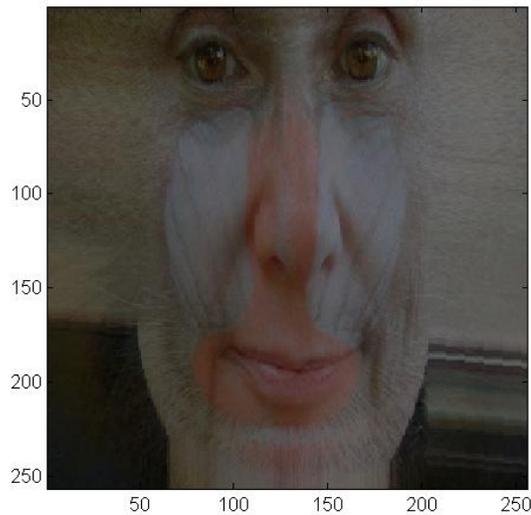
Line Pair Blend 2



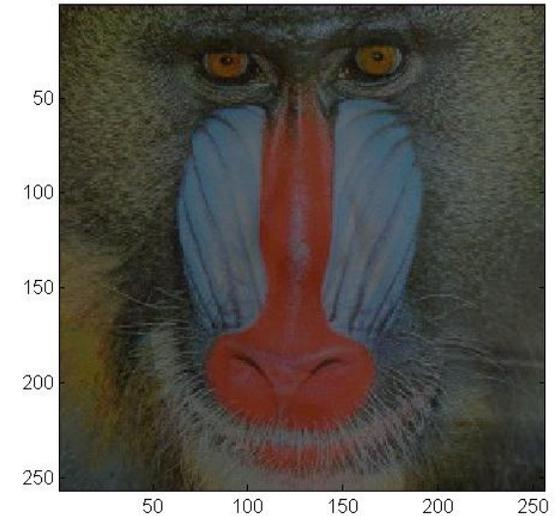
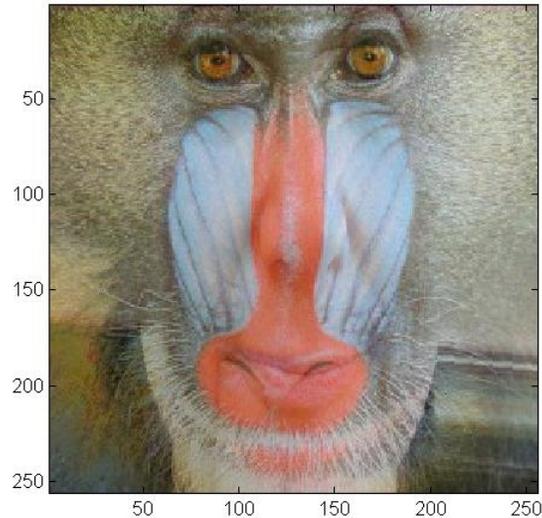


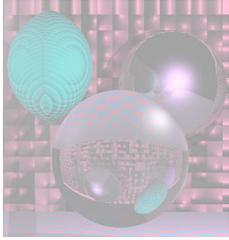
Weighted Blends

Line Pair Blend Mostly Harriet



Line Pair Blend Mostly Mandrill





Multiple Line Pairs

Find X_i' for the i th pair of lines.

$$D_i = X_i' - X$$

Use a weighted average of the D_i .

Weight is determined by the distance from X to the line.

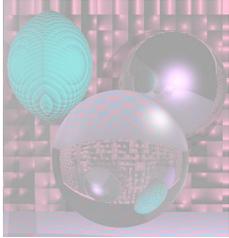
$$weight = \left(\frac{length^p}{(a + dist)} \right)^b$$

length = length of the line

dist is the distance from the pixel to the line

a , b , and p are used to change the relative effect of the lines.

Add average displacement to X to determine X' .



Let's Morph

MorphX