

# R-customizers

## Transitive Closure Simplification

## Graph Customizers and Instances

## Traversal Histories: Regularity and Similarity

Goal: define relation between graph  
and its customizers, study domains of  
adaptive programs, merging of  
interface class graphs

# Definition

- $R\text{-customizers}(I) = \{T : (T R I)\}$
- Customizer Theorem:  $(I1 R I2)$  if and only if  $R\text{-customizers}(I1) \subseteq R\text{-customizers}(I2)$  provided  $R$  is reflective and transitive
- $I1$  large graph,  $I2$  small graph
- $R$ : compatible, refinement, strong-refinement

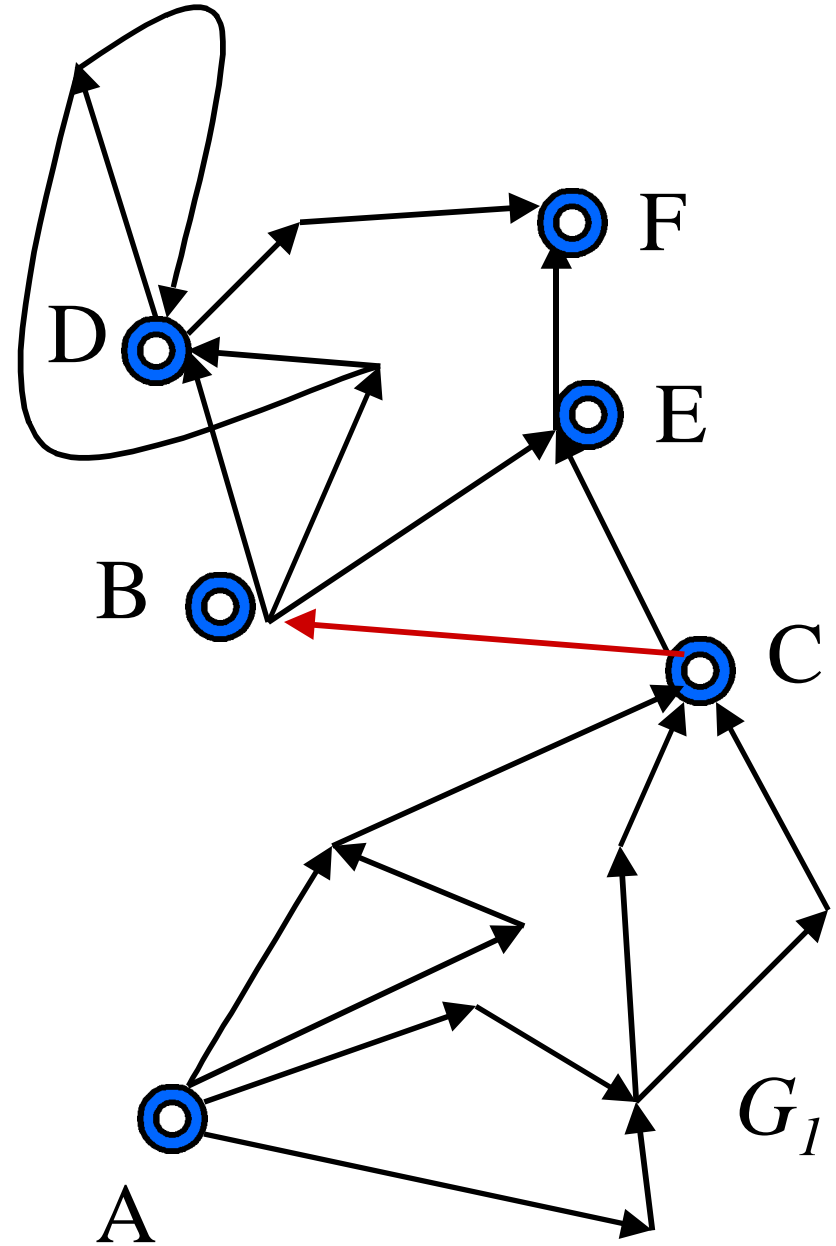
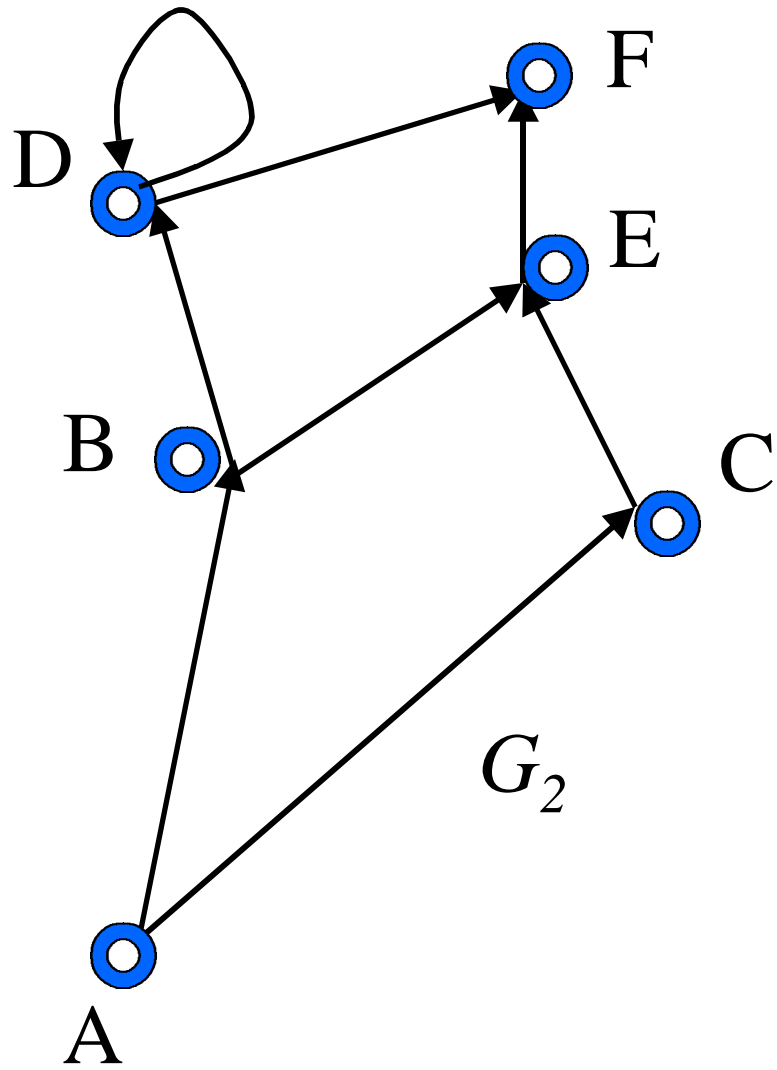
# Example for Customizer Theorem

- $I_2 : A = B.$
- $I_1 : A = B. B = C.$
- $R = \text{compatible}$
- $R\text{-customizers}(I_2) = \text{class graphs that have an A-node and a B-node with a path}$
- $R\text{-customizers}(I_1) \subseteq R\text{-customizers}(I_2)$
- $I_1$  is compatible with  $I_2$

# Key concepts: compatability

- Let  $G_1 = (V_1, E_1)$  and  $G_2 = (V_2, E_2)$  be directed graphs with  $V_2$  a subset of  $V_1$ . Graph  $G_1$  is a *compatible* with  $G_2$  if for all  $u, v$  in  $V_2$  we have that  $(u, v)$  in  $E_2$  implies that there exists a path in  $G_1$  between  $u$  and  $v$
- Polynomial.
- Motivation: All of  $G_2$  is used in  $G_1$ .

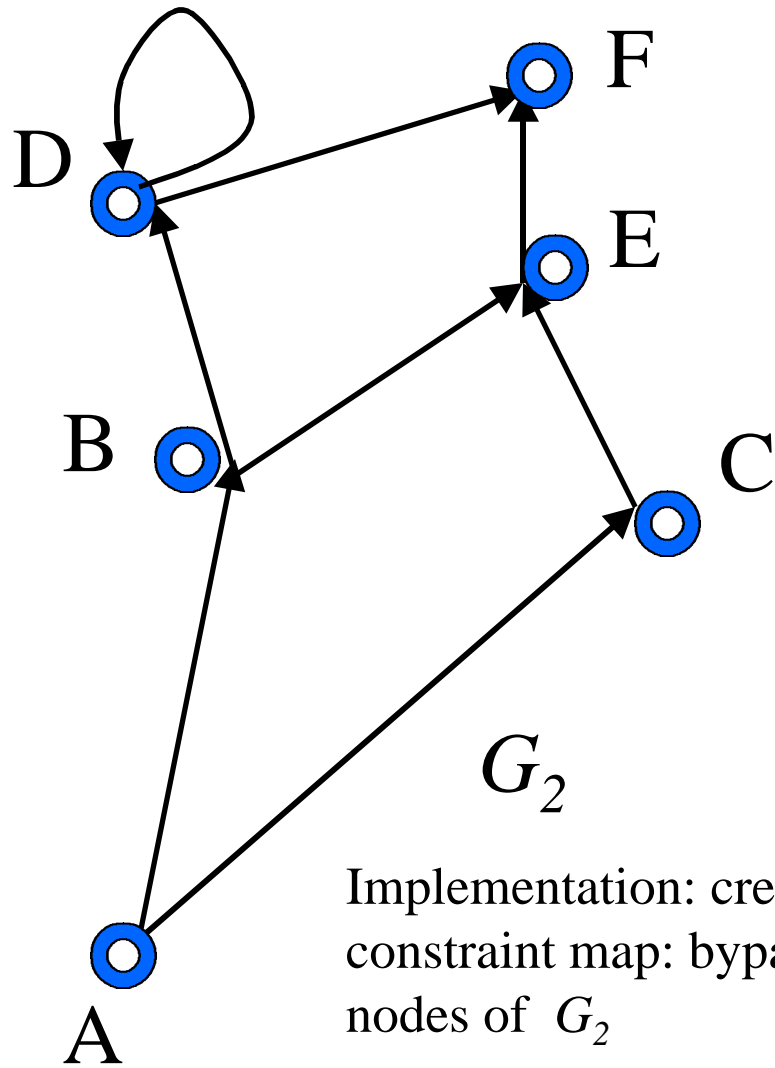
$G_1$  compatible  $G_2$



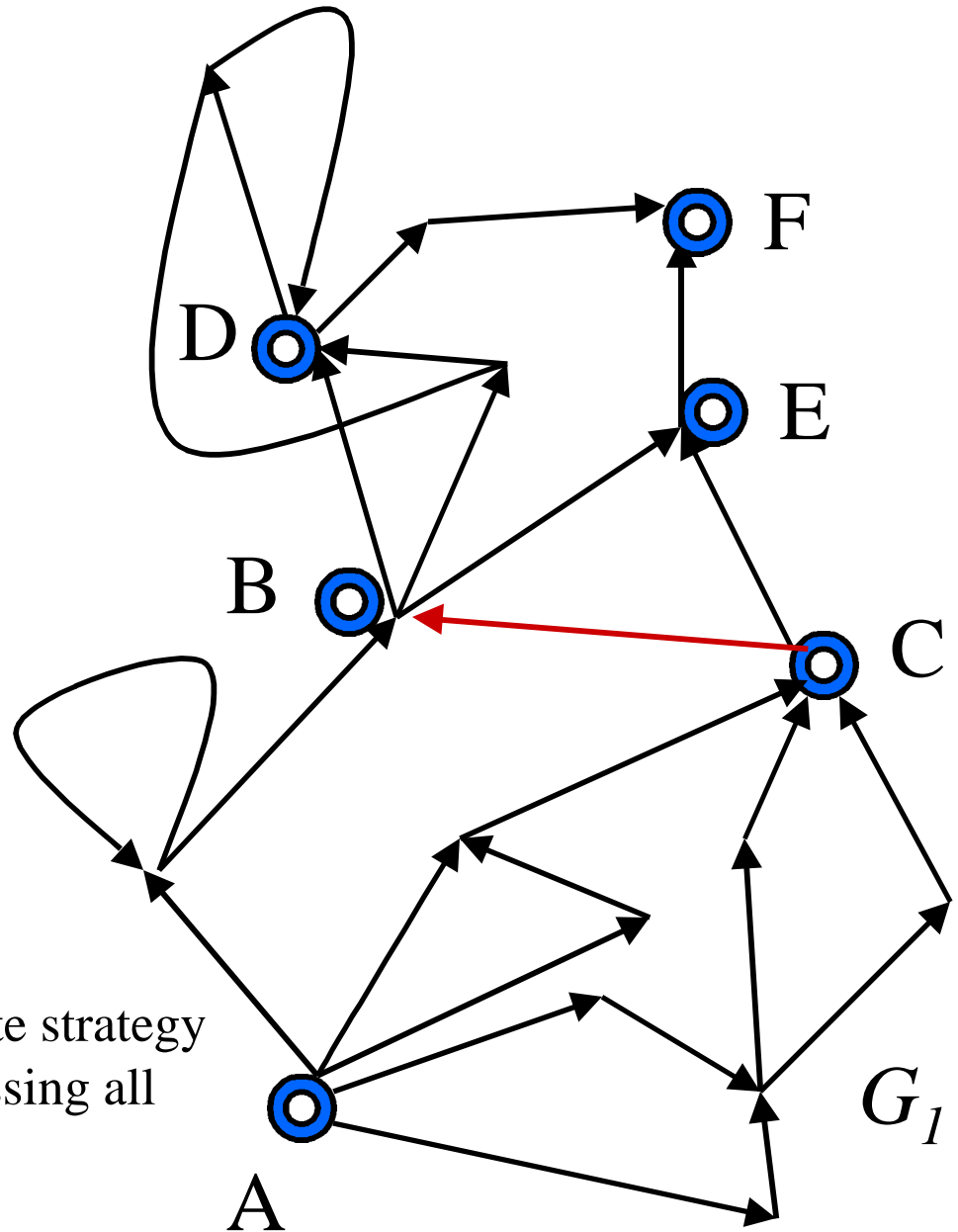
# Key concepts: refinement

- Let  $G_1=(V_1,E_1)$  and  $G_2=(V_2,E_2)$  be directed graphs with  $V_2$  a subset of  $V_1$ . Graph  $G_1$  is a *refinement* of  $G_2$  if for all  $u,v$  in  $V_2$  we have that  $(u,v)$  in  $E_2$  implies that there exists a path in  $G_1$  between  $u$  and  $v$  which does not use in its interior a node in  $V_2$ .
- Polynomial.
- Motivation: No surprises.

# $G_1$ refinement $G_2$



Implementation: create strategy constraint map: bypassing all nodes of  $G_2$



# Motivation for Refinement

- Refinement has nice implications on instances of  $G_1$  and  $G_2$  (consider the graphs to be class graphs). By contracting edges of instances of  $G_1$  without eliminating  $G_2$  nodes and by deleting parts from instances of  $G_1$  we can transform any  $G_1$  instance to a  $G_2$  instance.
- $G_1$  objects are *similar* to  $G_2$  objects.

# Motivation for Refinement

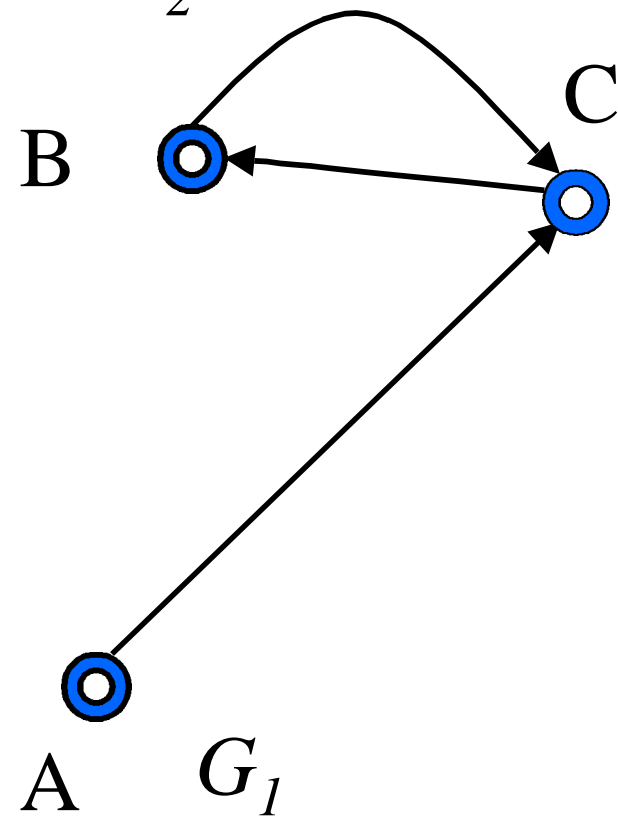
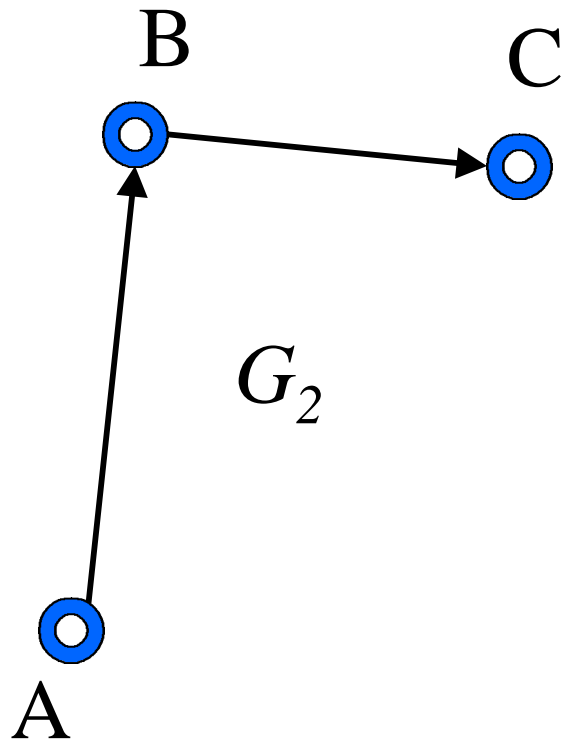
- Extra paths in  $G_1$  can be eliminated during traversal.
- Similarity between  $G_1$  and  $G_2$  objects helps to guarantee that program for  $G_2$  works correctly when applied to  $G_1$ .

Refinement means: no surprises

not  $G_1$  strong refinement  $G_2$

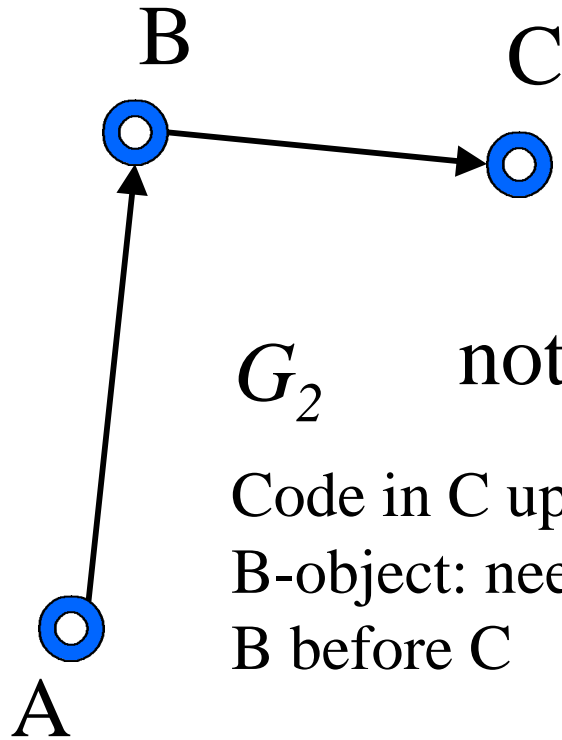
not  $G_1$  refinement  $G_2$

$G_1$  compatible  $G_2$



# No Refinement: objects are not similar

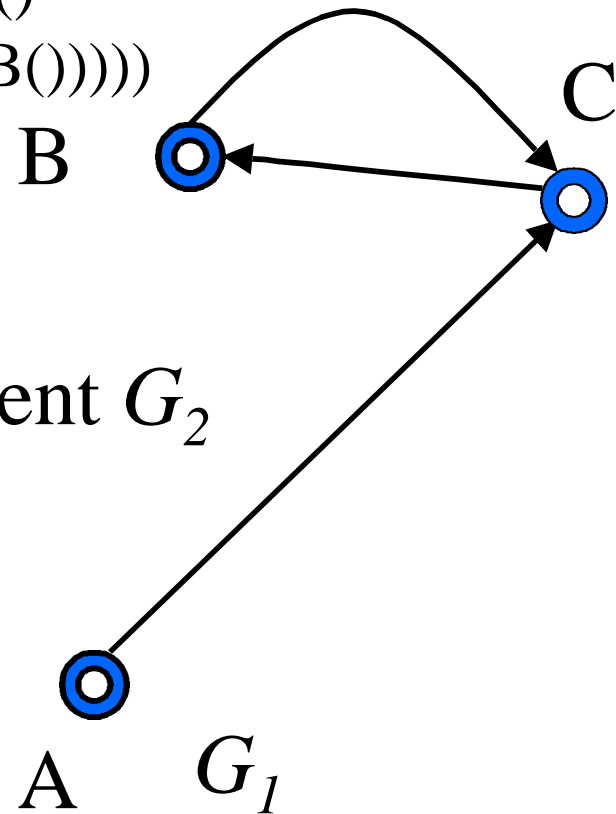
aA(  
aB(  
aC()))



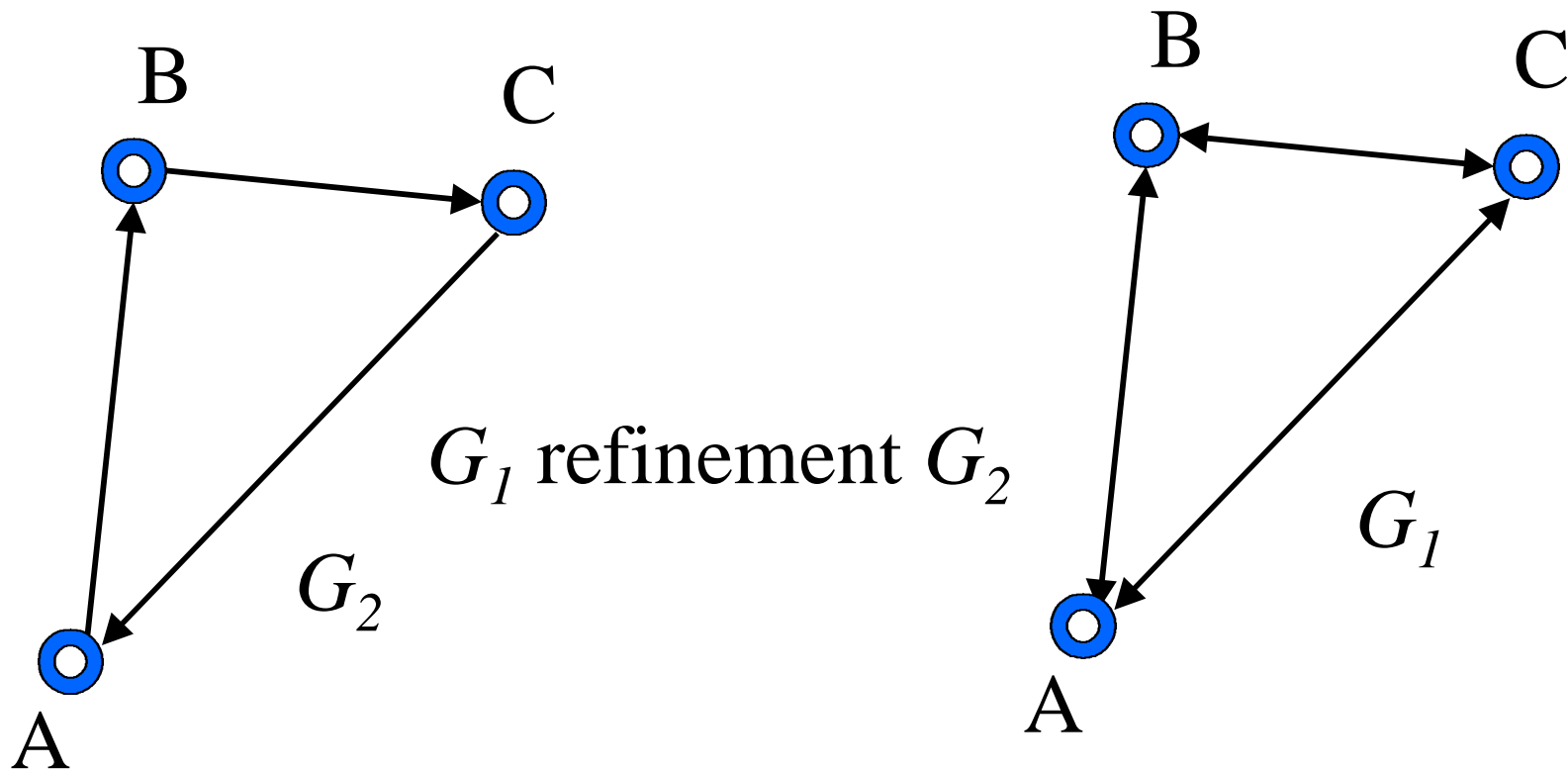
$G_2$  not  $G_1$  refinement  $G_2$

Code in C updates the  
B-object: need to visit  
B before C

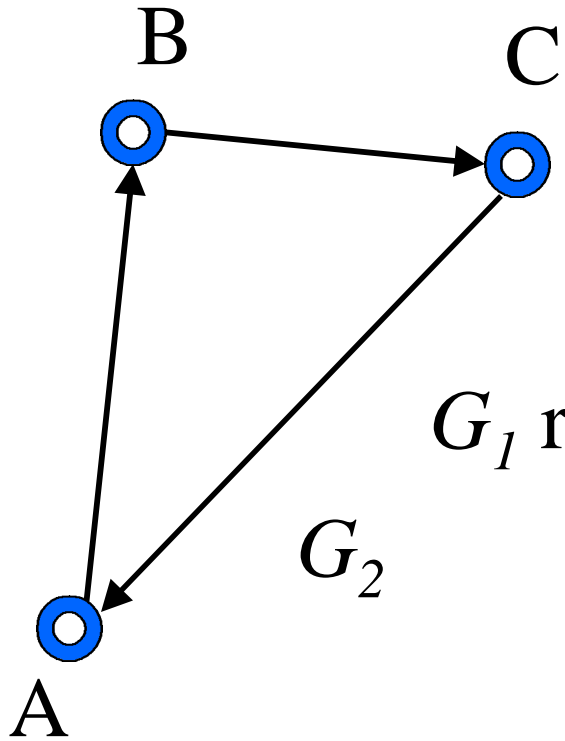
aA(  
aC(  
aB()  
aC()  
aB()))))



Refinement means: no surprises



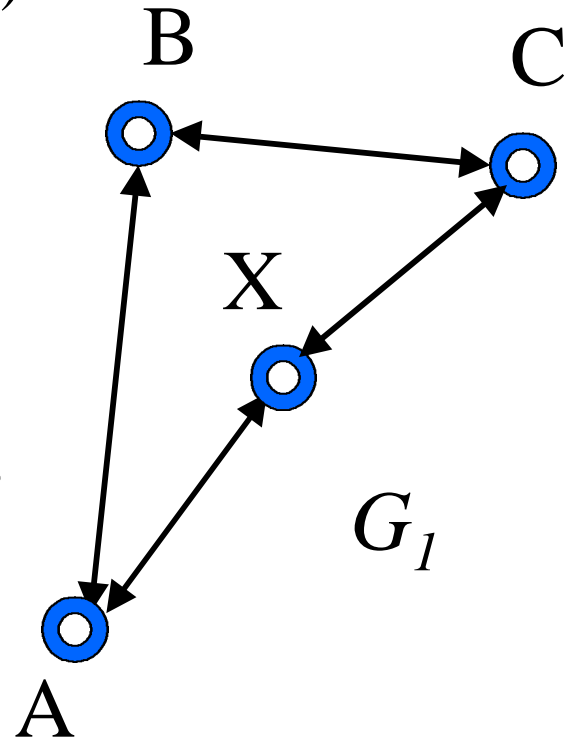
aA(  
aB(  
aC(  
aA()))))



$G_1$  refinement  $G_2$

aA(  
aB(  
aC(  
aX(  
aA())  
aB())  
aA())  
aX()))

contracting



$G_1$

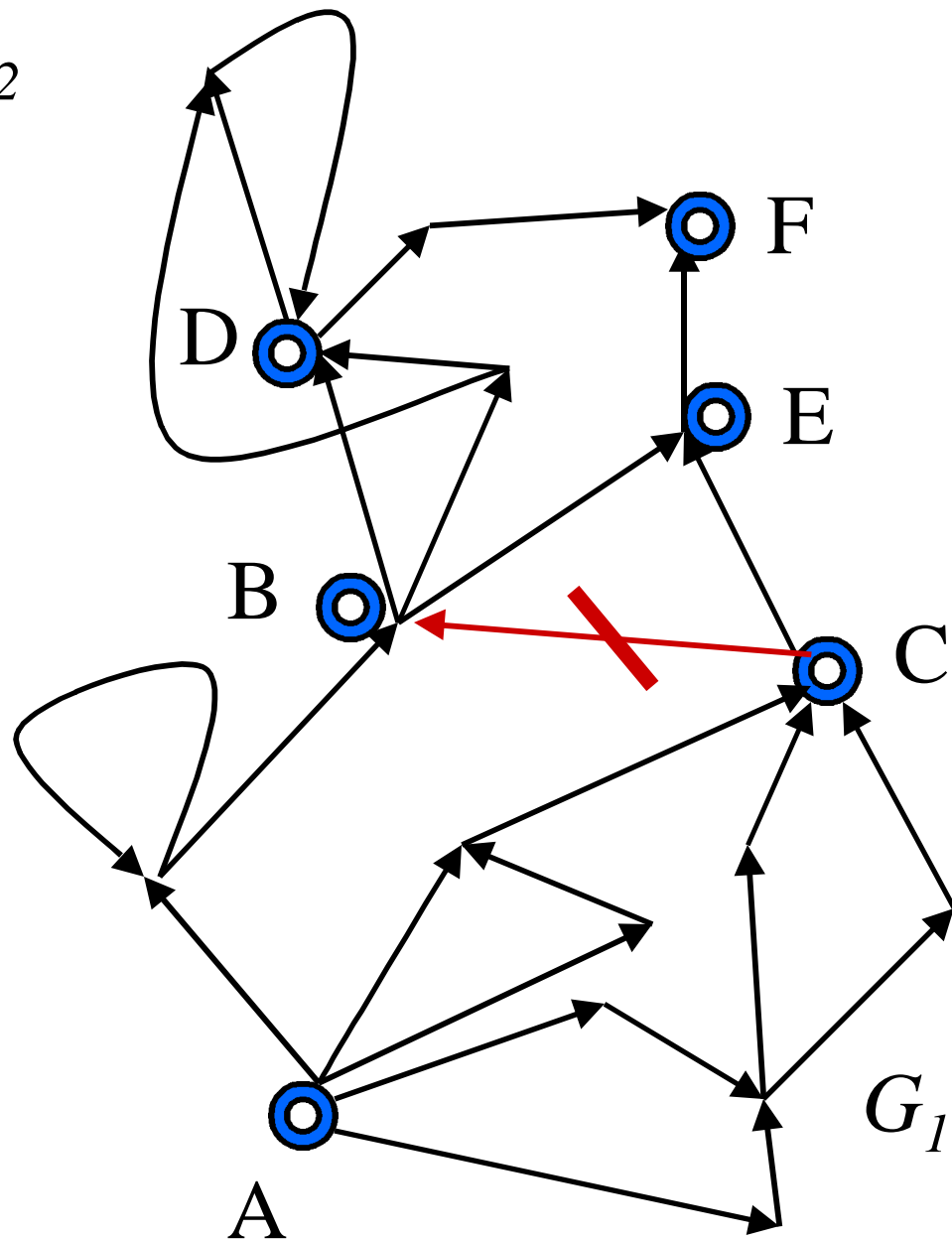
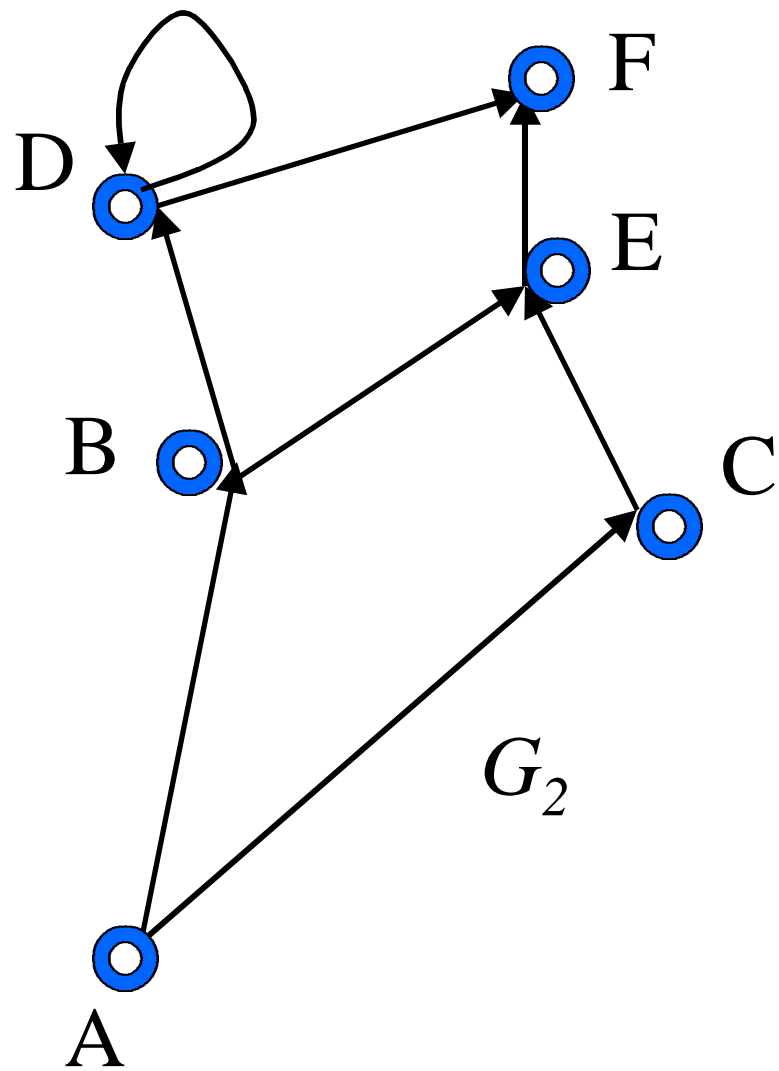
# Instantiation view

- Interface class graph: instances are class graphs
- Class graph: instances are objects
- Want objects to “conform” to interface class graph: objects of class graph and immediate objects of interface class graph must be similar

# Key concepts: strong refinement

- Let  $G_1=(V_1,E_1)$  and  $G_2=(V_2,E_2)$  be directed graphs with  $V_2$  a subset of  $V_1$ . Graph  $G_1$  is a ***strong refinement*** of  $G_2$  if for all  $u,v$  in  $V_2$  we have that  $(u,v)$  in  $E_2$  *if and only if* there exists a path in  $G_1$  between  $u$  and  $v$  which does not use in its interior a node in  $V_2$ .
- Polynomial.
- Motivation: no surprises, no extra paths

$G_1$  strong refinement  $G_2$



# Connections

- Strong refinement implies Refinement  
implies Compatible
- When do we use which relationship?

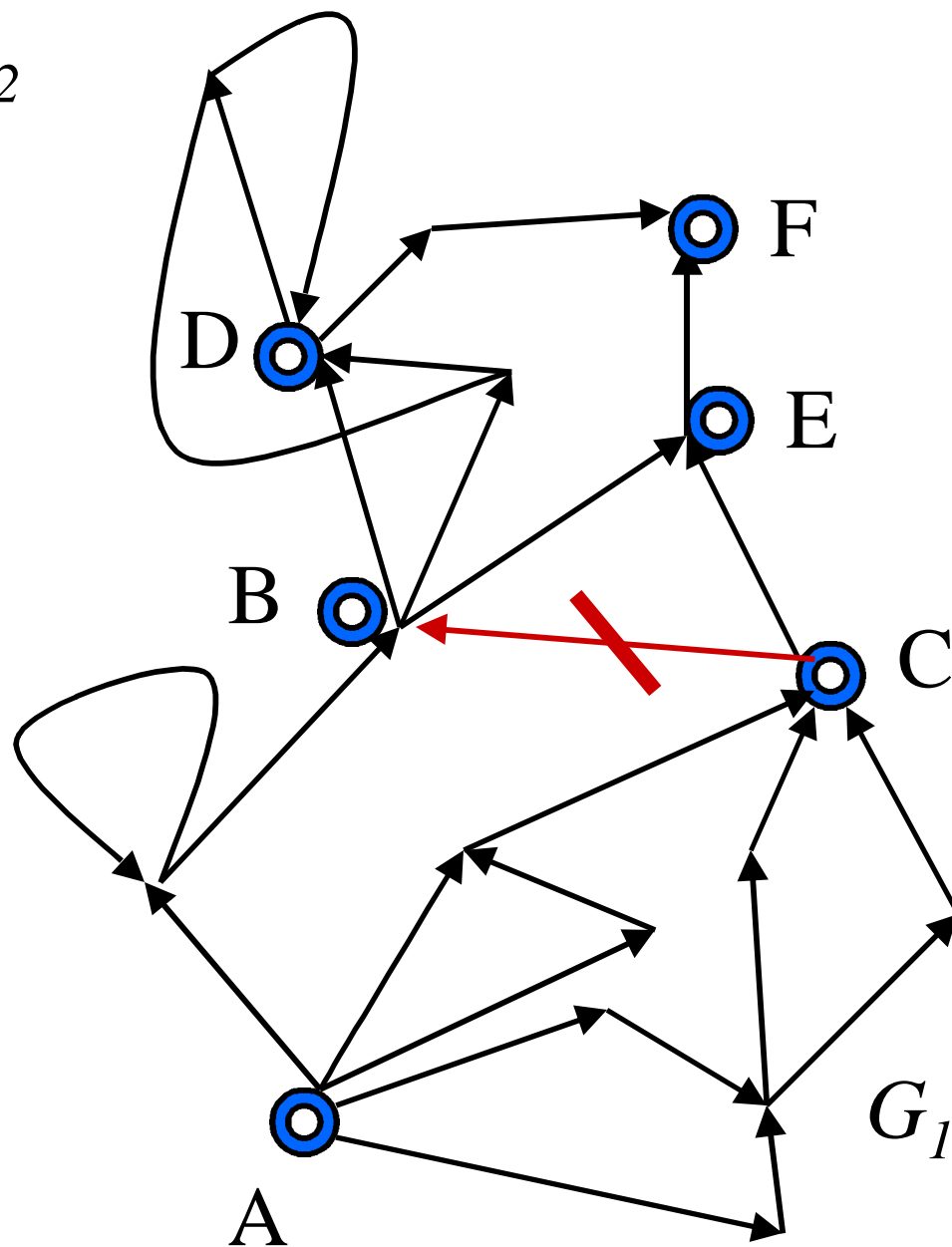
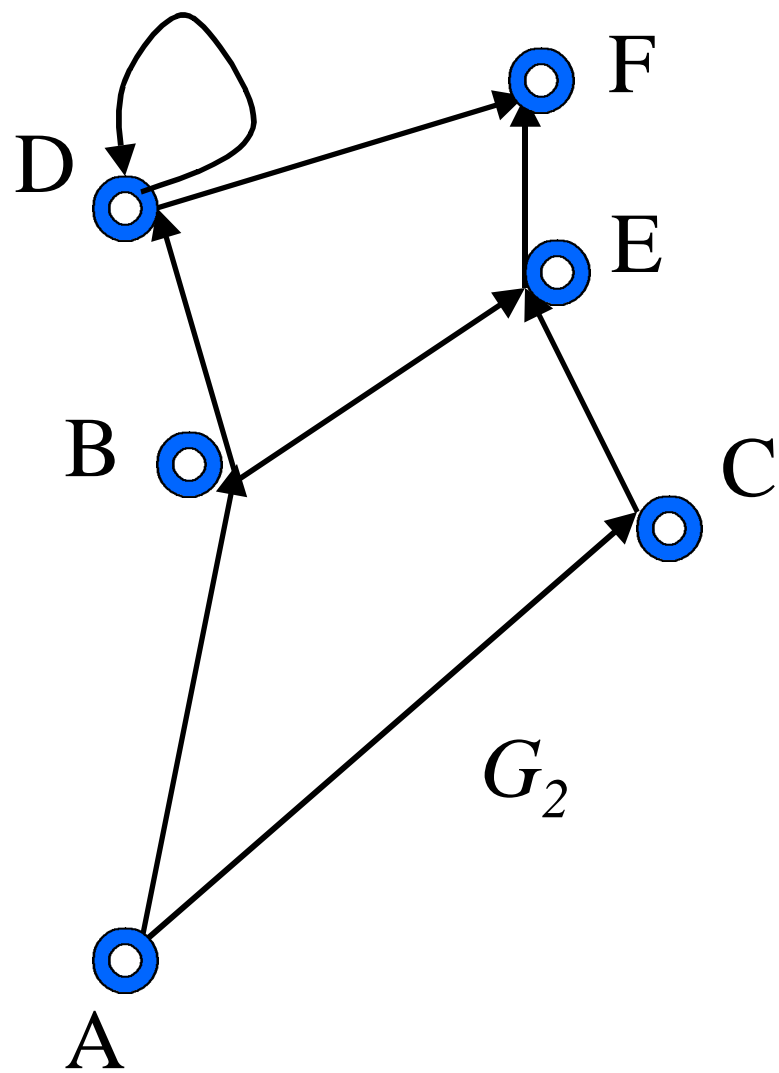
# Roles graphs play in OOD

SMALL	BIG	INTENT
CG	CG	Evolution <b>C</b>
ICG	CG	view (abstr.) <b>R</b>
CG	ICG	view (roles) <b>R</b>
ICG	ICG	Layering <b>R</b>
PSG	CG	AP <b>C</b> or <b>R</b>
PSG	ICG	Improv. AP <b>R</b>

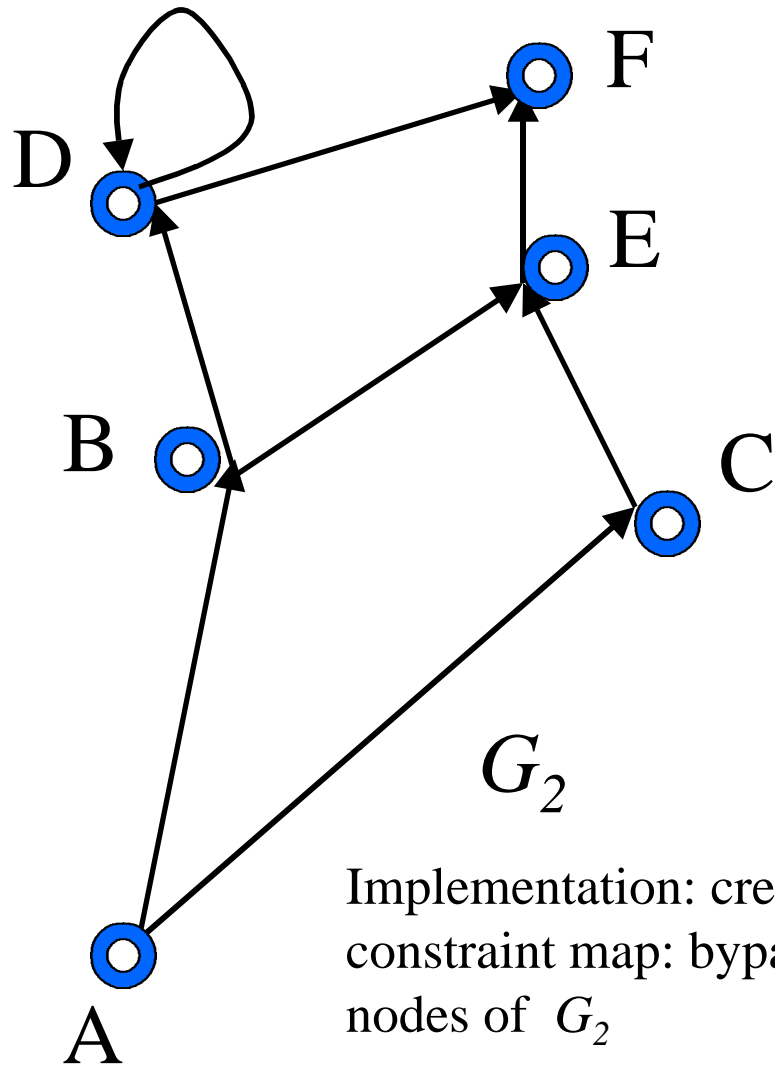
# Refinement

- For each edge in  $G_2$  there must be a corresponding pure path in  $G_1$ .
- Pure path = in interior no nodes of  $G_2$ .
- Refinement = strong refinement with “if and only if” replaced by “implies”.

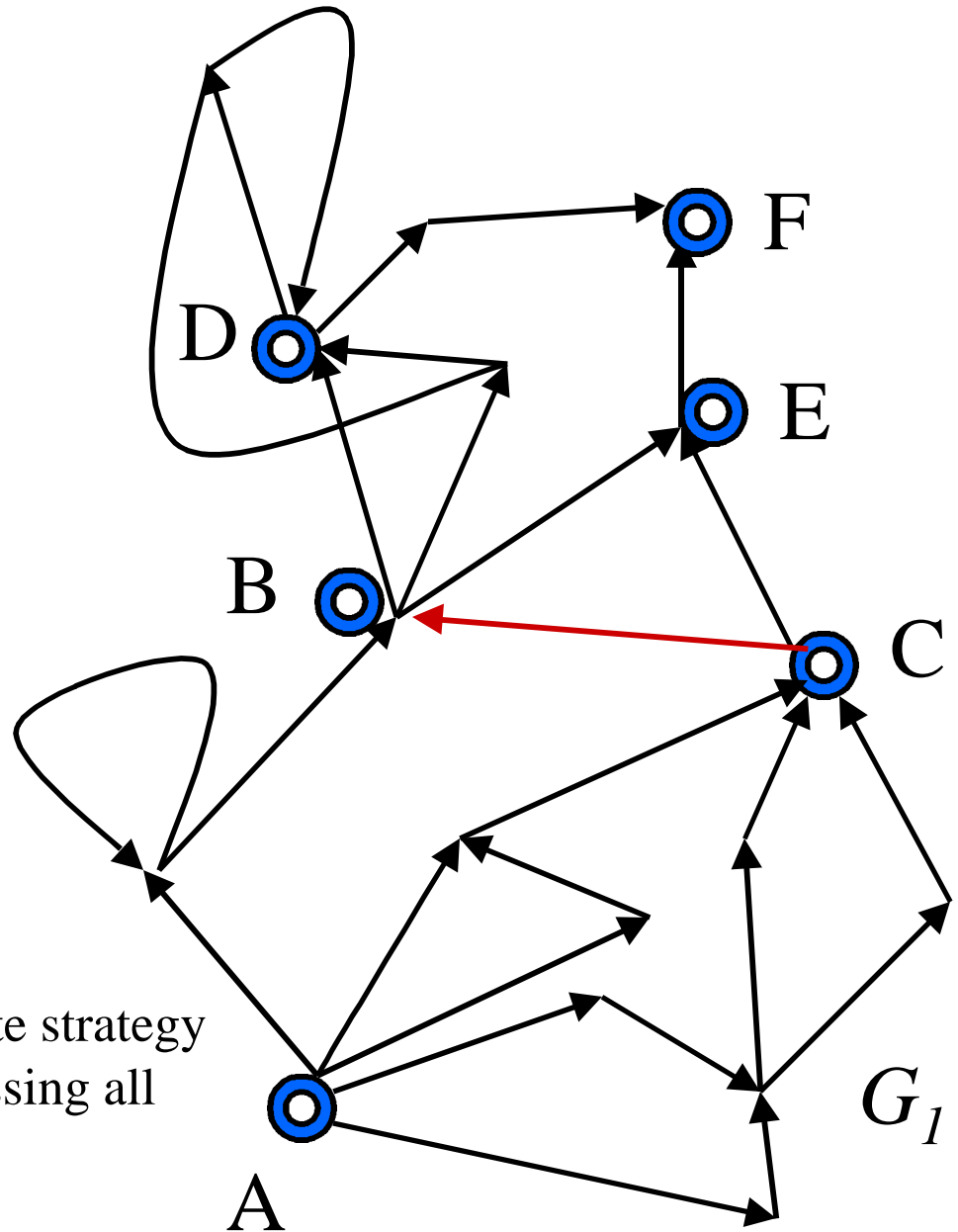
$G_1$  strong refinement  $G_2$



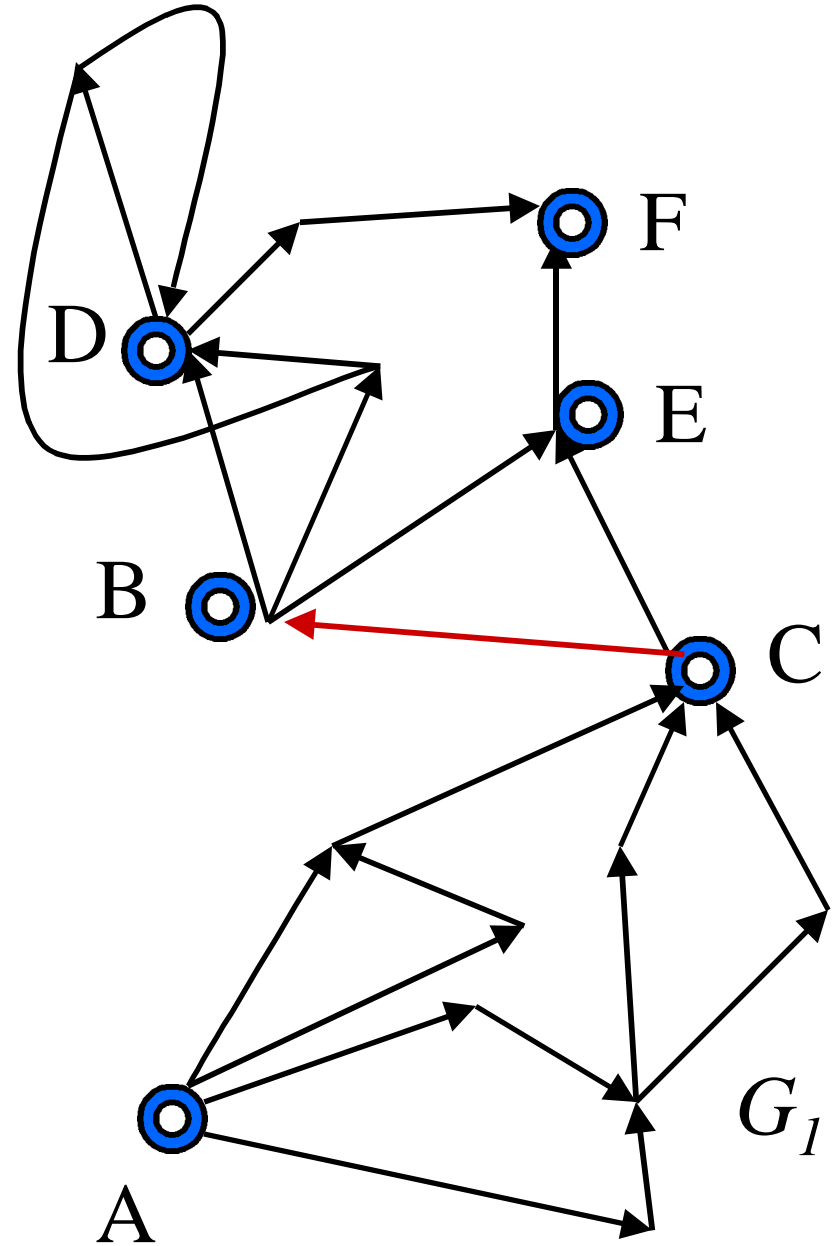
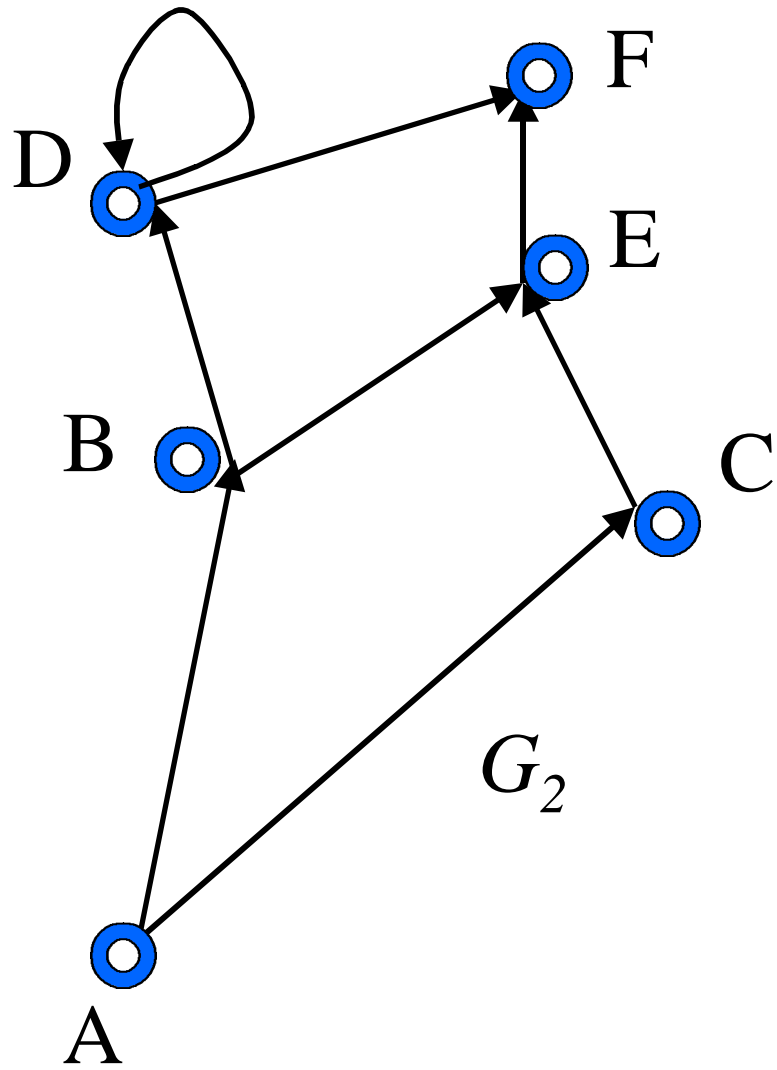
# $G_1$ refinement $G_2$



Implementation: create strategy  
constraint map: bypassing all  
nodes of  $G_2$



$G_1$  compatible  $G_2$

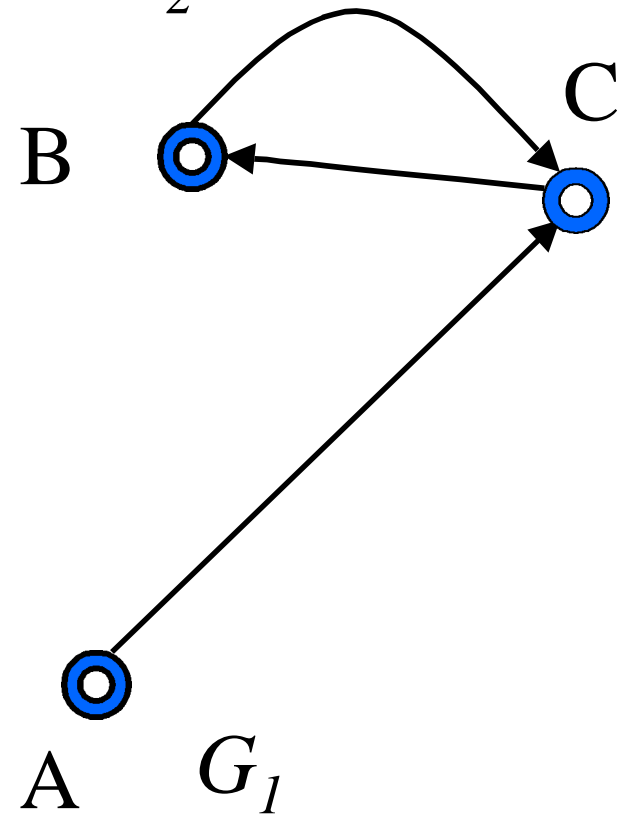
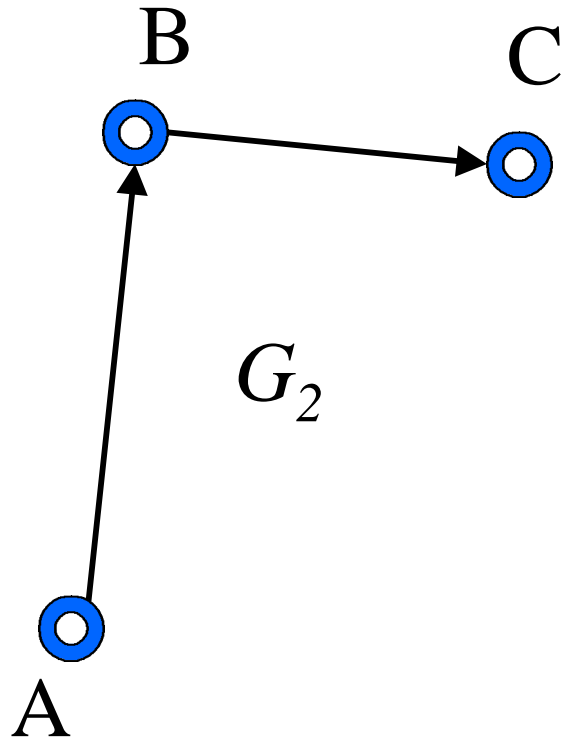


Refinement means: no surprises

not  $G_1$  strong refinement  $G_2$

not  $G_1$  refinement  $G_2$

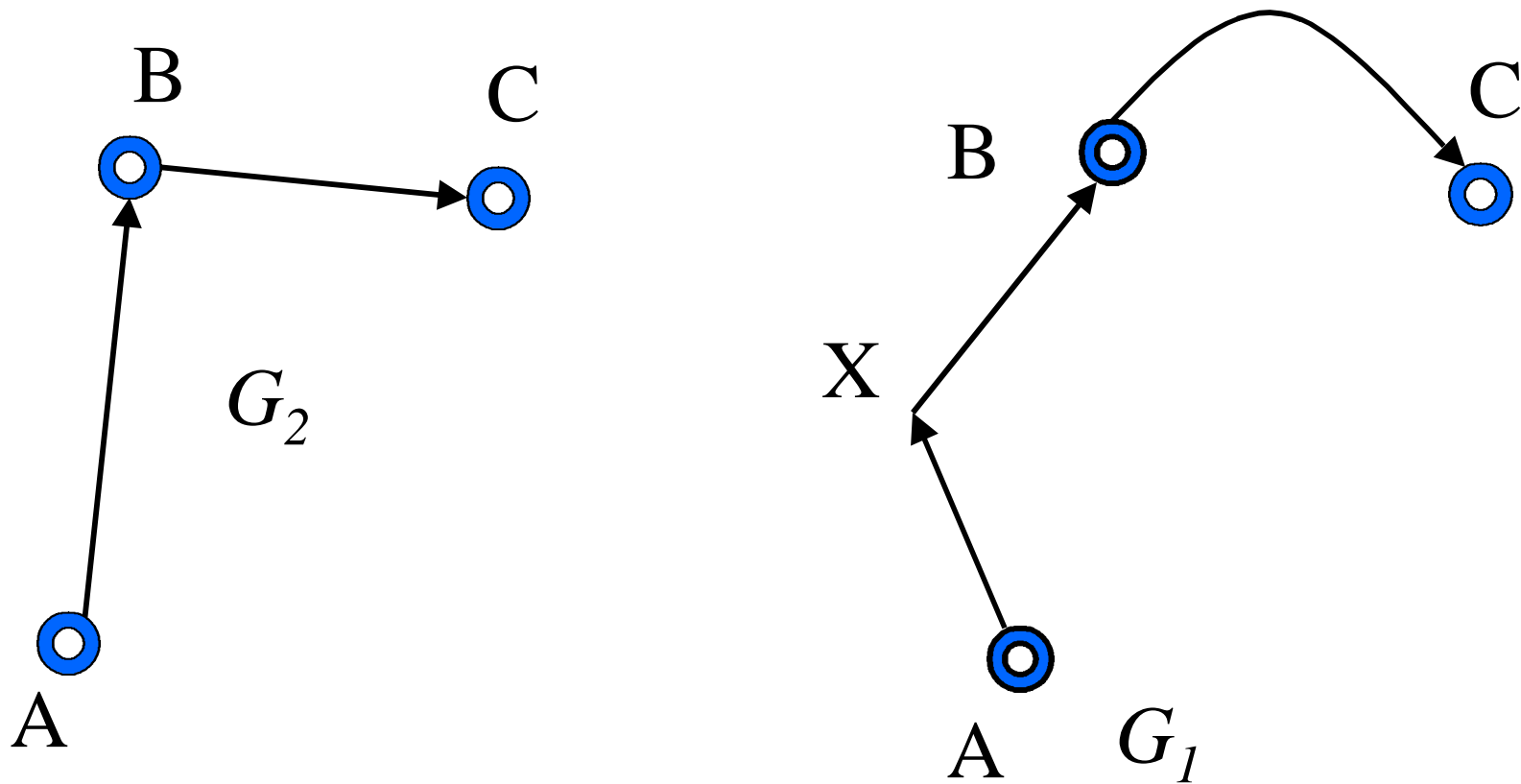
$G_1$  compatible  $G_2$



Refinement means: no surprises

$G_1$  strong refinement  $G_2$

$G_1$  refinement  $G_2$

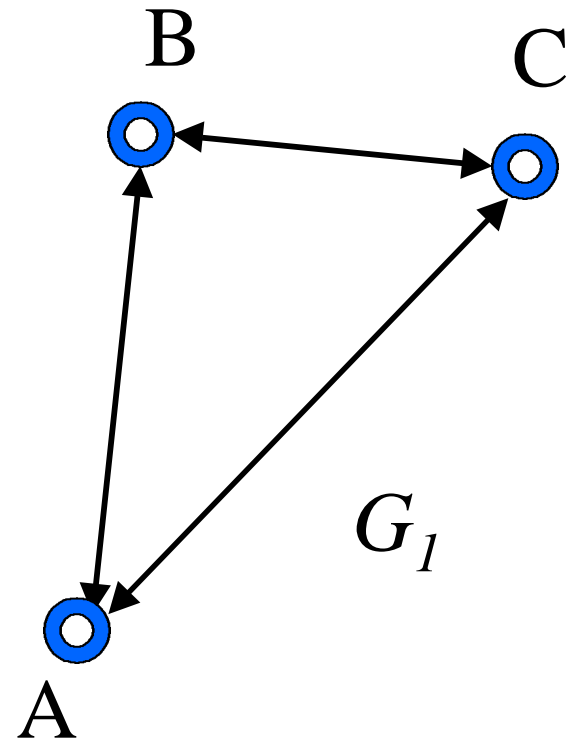
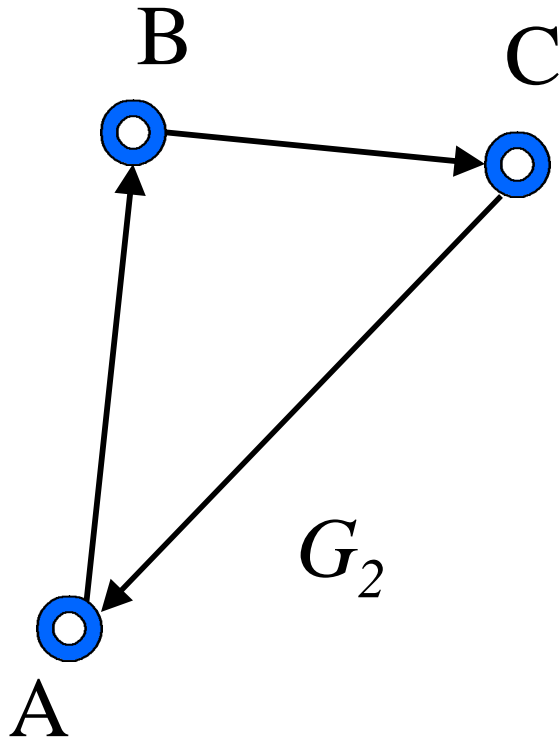


Refinement means: no surprises

$G_1$  compatible  $G_2$

not  $G_1$  strong refinement  $G_2$

$G_1$  refinement  $G_2$



# Implementation of refinement: reduce to compatability

- Translate  $G_2$  into a strategy graph  $S$  that has “bypassing all nodes” as constraint on each edge.
- Check whether  $S$  is compatible with  $G_1$ , i.e. there is a path in  $G_1$  satisfying the constraint for each edge in  $S$ .
- Reuses Traversal Graph Algorithm.

# Traversing pure paths only

- Use same strategy graph construction
- Compute traversal graph for that strategy graph
- Run-time traversals will only follow pure paths

# Intersection

R-customizers(I1) intersect R-customizers(I2)  
is always non-empty if  $R = \text{refinement}$ .  
Choose union of two graphs.

TC

## Improved strategy definition: embedded, positive strategies

- Given a graph  $G$ , a strategy graph  $S$  of  $G$  is any connected subgraph of the transitive closure of  $G$ .
- The transitive closure of  $G=(V,E)$  is the graph  $G^*=(V,E^*)$ , where  $E^*=\{(v,w): \text{there is a path from vertex } v \text{ to vertex } w \text{ in } G\}$ .



# Discussion

- Seems strange: define a strategy for a graph but strategy is independent of graph.
- Many very different graphs can have the same strategy.
- Better: A graph  $G$  is a customizer of a graph  $S$ , if  $S$  is a connected subgraph of the transitive closure of  $G$ . (call  $G$ : concrete graph,  $S$ : abstract graph).

TC

## Discussion: important is concept of instance/abstraction

- A graph  $G$  is a customizer of a graph  $S$ , if  $S$  is a connected subgraph of the transitive closure of  $G$ . (call  $G$ : concrete graph,  $S$ : abstract graph).
- A graph  $S$  is an abstraction of graph  $G$  iff  $G$  is a customizer of  $S$ .

## Improved definition

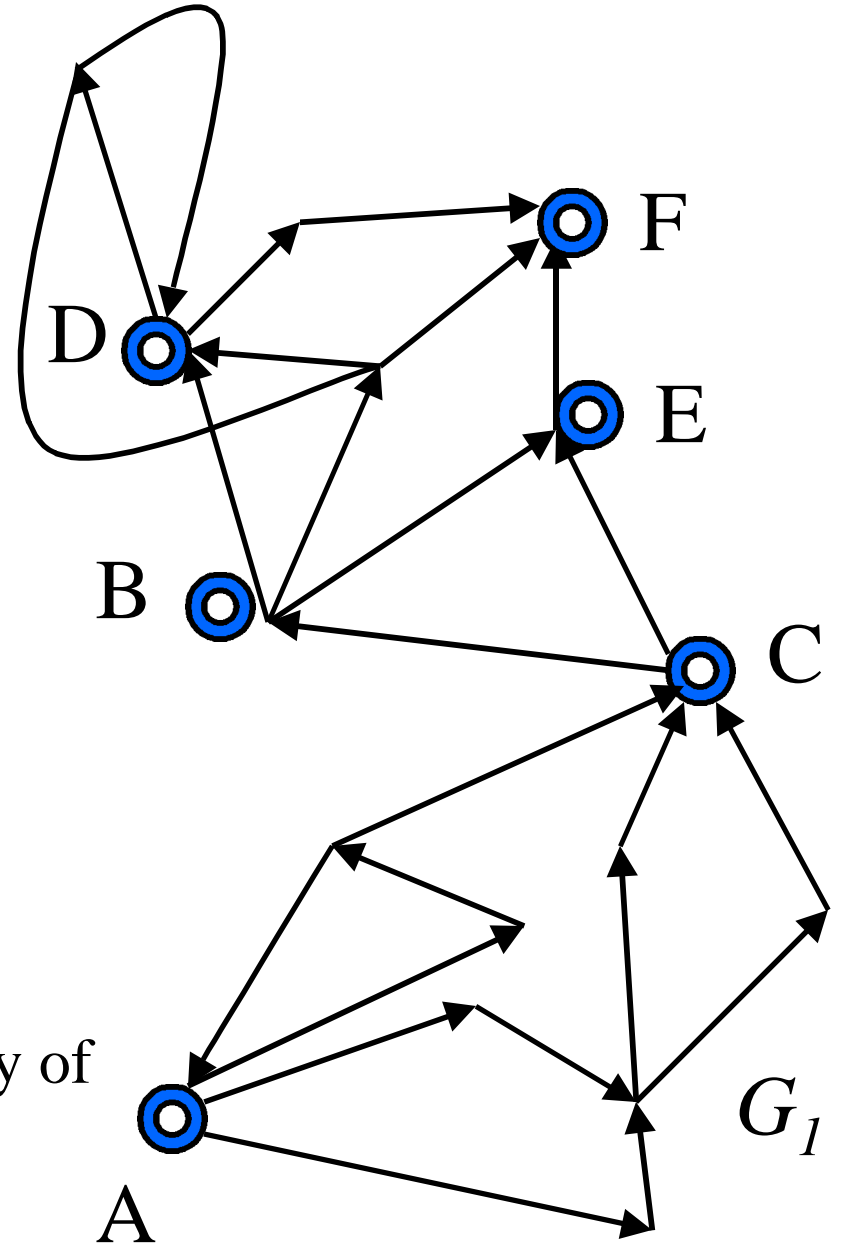
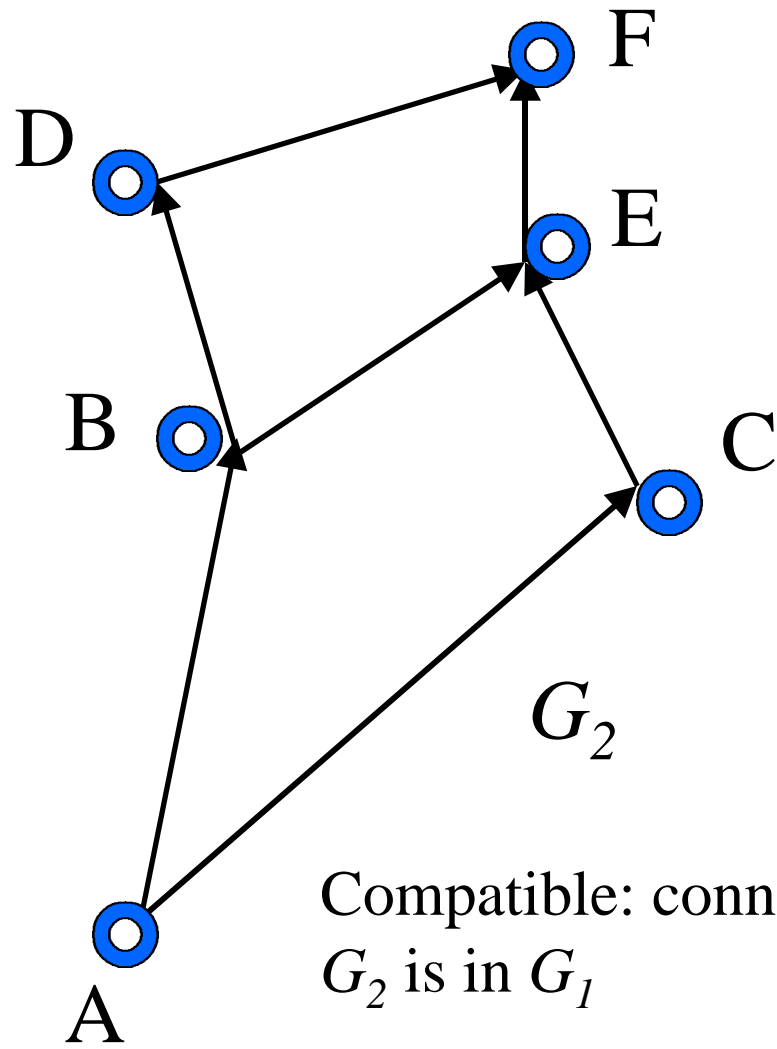
- Graph  $G$  is compatible with graph  $S$  by definition. What if we want  $G$  to be a refinement of  $S$ ?
- A graph  $G$  is a refinement-customizer of a graph  $S$ , if  $S$  is a connected subgraph of the pure transitive closure of  $G$  with respect to the node set of  $S$ .

# Pure transitive closure

- The pure transitive closure of  $G=(V,E)$  with respect to a subset  $W$  of  $V$  is the graph  $G^*=(V,E^*)$ , where  $E^*=\{(i,j): \text{there is a } W\text{-pure path from vertex } i \text{ to vertex } j \text{ in } G\}$ .
- A  $W$ -pure path from  $i$  to  $j$  is a path where  $i$  and  $j$  are in  $W$  and none of the inner nodes of the path are in  $W$ .

TC

$G_1$  compatible  $G_2$



Compatible: connectivity of  $G_2$  is in  $G_1$

# Definition of graph instance

- A vertex-labeled graph  $I$  is an instance of a graph  $G$  if
  - the vertex labels of  $I$  are nodes of  $G$
  - the labels of the successors of a node  $i$  in  $I$  with label  $g$  is a subset of the successors of node  $g$  in  $G$

# Similar instances

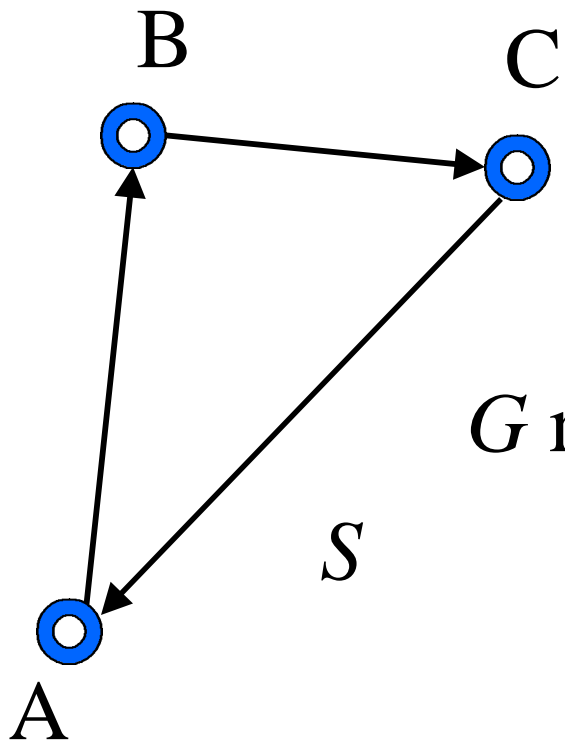
- $S$  a graph,  $G$  a refinement-customizer of  $S$
- $IG$ : instance of  $G$
- $IG$  can be turned into an instance of  $IS$  by
  - deleting parts
  - contracting edges of instances of  $G$  without eliminating  $S$  nodes

## Construct similar instance

- $S$  a graph,  $G$  a refinement-customizer of  $S$
- $IG$ : instance of  $G$ . Construct  $IS(IG)$ 
  - delete parts not covered by  $S$
  - contract edges if one end-node is not in  $S$
- Idea: The APPC/Java Beans operates on  $IS(IG)$  that is constructed in a lazy way.

aA(  
aB(  
aC(  
aA()))))

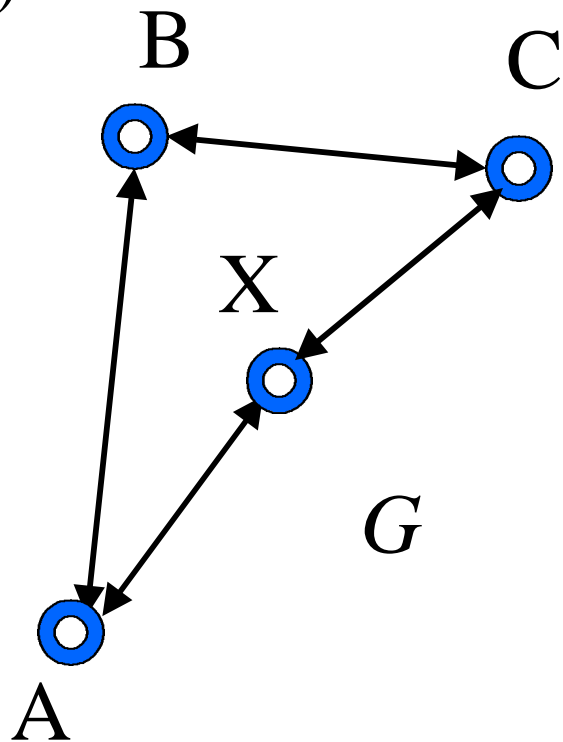
IS



aA(  
aB(  
aC(  
aX(  
aA()))))

IG

contracting



APPC

# Traversal Following a Graph

- $S \ G \ IG$
- $S$  a graph,  $G$  a customizer of  $S$ ,  $IG$  an instance of  $G$ .
- Traverse  $IG$  following  $S$ .
  - want it simpler than in TOPLAS paper
  - construct  $IS(IG)$ ?
  - traverse  $IS$  following  $S$ : all of it.
  - map traversal to  $IG$

# Classifications of Traversal Histories

- S G I
- S a graph, G a customizer of S, I an instance of G. Traverse I following S.
- Edge traversal history:
  - edge-down  $(i_1, g_1) \rightarrow (i_2, g_2)$
  - edge-up  $(i_1, g_1) \rightarrow (i_2, g_2)$ .
- Consider as language over edge-down and edge up-alphabet: Context-free? Regular?

# Classifications of Traversal Histories

- S G I
- S a graph, G a customizer of S, I an instance of G. Traverse I following S.
- Node traversal history:
  - visit (i1,g1)
- Consider as language over node visit alphabet: Regular.

# Comparison of Traversal Histories

- $S$   $G$   $IG$
- $S$  a graph,  $G$  a refinement-customizer of  $S$ ,  $IG$  an instance of  $G$ .  $IS(IG)$  instance of  $S$ . Traverse  $IG$  following  $S$ .
- Node traversal history of  $IS(IG)$  is a pure subtraversal of traversal of  $IG$ .

## Note

- In practice:  $S \supseteq ICG \supseteq CCG \supseteq I$
- ICG a refinement-customizer of S
- CCG a refinement-customizer of ICG
- I an instance of CCG
- So far we simplified:  $S=ICG$
- But same idea applies: traversal of ICG instance is a pure subtraversal of traversal of CCG instance

## Note

- Terminology is not ideal
- R-customizers sounds like refinement customizer.
- R can be: refinement-customizer
- refinement-customizer-customizers: not elegant

# What get's simpler?

- If we have refinement-customizer instead of customizer, what gets simpler besides the use of adaptive programming?
- Any of the algorithms?

Complexity

# Strategy Graph Minimization (SGM)

- Given  $G$  and a subgraph  $G'$  with vertex basis of size 1 for  $G'$  (node  $s$ ) and reversed  $G'$  (node  $t$ ), find the smallest subgraph  $S$  of the transitive closure of  $G$  so that  $\text{Graph}(\text{PathSet}_{st}(G,S))=G'$
- What if we replace “transitive closure” by “pure transitive closure with respect to node set of  $S$ ”.

Complexity

# Strategy Graph Minimization (SGM)

- SGM may have no solution.
- What is the complexity of deciding whether there is a solution?

# Complexity Relaxed Strategy Graph Minimization (RSGM)

- Given  $G$  and a subgraph  $G'$  with vertex basis of size 1 for  $G'$  (node  $s$ ) and reversed  $G'$  (node  $t$ ), find a subgraph  $S$  of the transitive closure of  $G$  so that  $G'$  is a subgraph of  $\text{Graph}(\text{PathSet}_{st}(G, S))=Q$  and size of  $S$  plus  $Q$  is minimal.
- What if we replace “transitive closure” by “pure transitive closure with respect to node set of  $S$ ”.

# Definitions

- Given  $G$  and a subgraph  $S$  of the transitive closure of  $G$ ,  $\text{PathSet}_{i,j}(G,S)$  is the set of all paths in  $G$  from  $i$  to  $j$  that are expansions of paths in  $S$  from  $i$  to  $j$ .
- $\text{Graph}(\text{PathSet}(G,S))$  = smallest subgraph of  $G$  that contains all paths in path set.

# Class graph synthesis

- Given two graphs  $S1$  and  $S2$ , find a smallest graph  $G$  such that both  $S1$  and  $S2$  are subgraphs of the transitive closure of  $G$ .
- Can take  $G$  to be a cycle.

# Class graph synthesis

- Given two graphs  $S1$  and  $S2$ , find a smallest graph  $G$  such that  $S1(S2)$  is a subgraph of the pure transitive closure of  $G$  with respect to  $S1(S2)$ , respectively.

# Hierarchical Graphs

- In the following use the definition of hierarchical graphs in the Yannakakis FSE '98 paper.
- That paper shows how to solve reachability problems efficiently for hierarchical graphs.

# Hierarchical Graphs

- Traverse according to hierarchical graph
- Is  $G$  (hierarchical) a customizer of  $S$ ?
- Is  $G$  (hierarchical) a refinement-customizer of  $S$ ?
- SGM for hierarchical graphs
- Pure SGM for hierarchical graphs
- RSGM for hierarchical graphs

# Counting argument?

- Given a graph  $G$ , how likely is it that a connected subgraph  $G'$  of  $G$  can be described by a subgraph  $S$  of the transitive closure of  $G$  so that  $S$  is smaller than  $G'$ ?
- Depends on naming of nodes. Allow regular expressions on nodes in  $S$ .
- Study classes of graphs: trees: high likelihood.

# Co-existence of multiple organizations in software systems

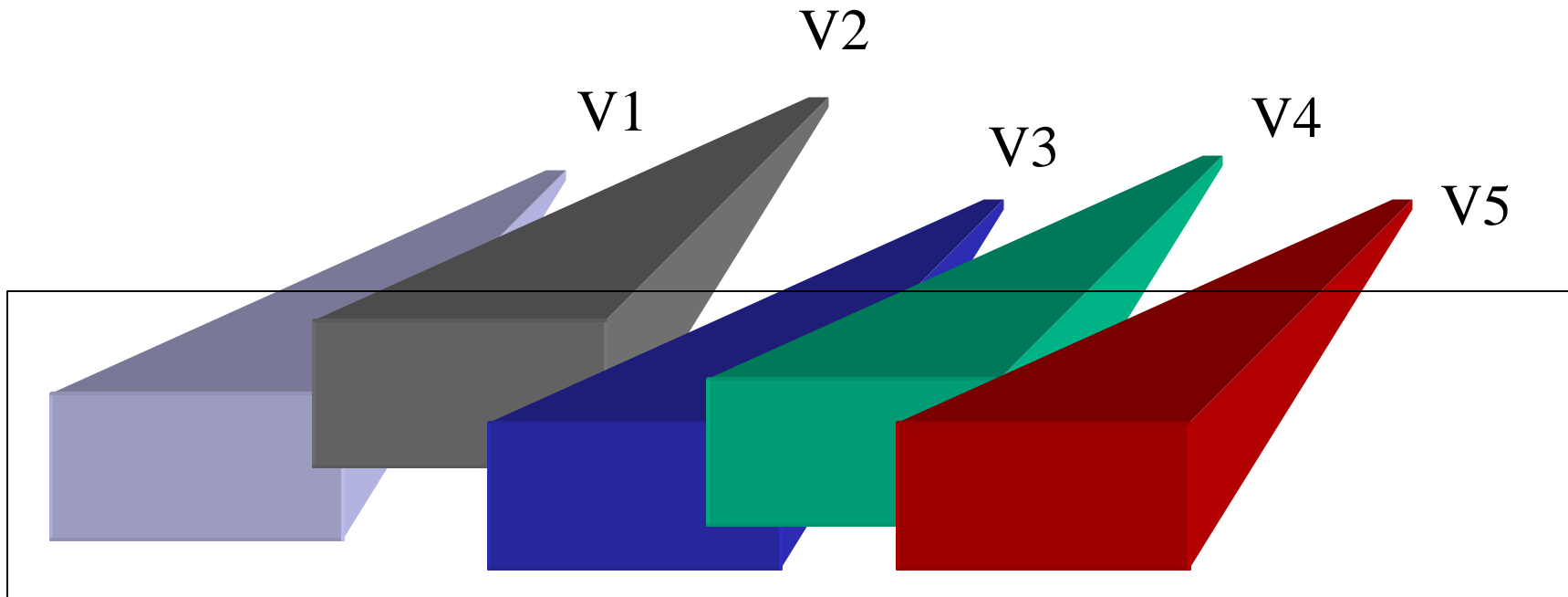
- OOP: class graph
- Many issues cross-cut the class organization: subgraph of class graph plus additional decorations on class graph
- problem: subgraph definitions are brittle with respect to class graph: change of class graphs requires changes to many subgraphs

- Lift subgraphs: define them abstractly and compose them.
- Subgraph definitions are graphs themselves: call them interface class graphs
- Set of interface class graphs: When can they be used together on a class graph. Want to automate the mapping.



View View of AP

Multiple views of the same class graph



Application class graph

In Demeter/Java: view = strategy graph

# Connection to Frameworks

- A framework is a set of cooperating classes that make up a reusable behavior
- Typical use of a framework: by subclassing
- Leads to inversion of control: “We will call you; don’t call us”

# Adaptive Programming and Frameworks

- Frameworks
  - a few big ones
  - hard to combine
  - hard to map
  - conventional technology
- APPCs
  - many small ones
  - easy to combine
  - easy to map
  - new