Boosting (ensemble)
Module 4 – Ensemble classifiers – Objectives

module 4: boosting (ensemble models)

- **BOOSTING**: combine weak/simple classifiers into a powerful one
- **Bagging**: combine classifiers by sampling training set
- **Active Learning**: select the datapoints to train on
- **ECOC for Multiclass data**: introducing the 20Newsgroups dataset of articles
- **VC dimension**: as a measure of classifier complexity
Weak Learners

- Need not to be very accurate
- Better than random guess
- Examples:
  - Decision trees/Decision stump
  - Neural Network
  - Logistic regression
  - SVM
  - Essentially any classifier
Decision Stump

- 1-Level decision tree
- A simple test based on one feature
- Eg: If an email contains the word "money", it is a spam; otherwise, it is a non-spam
- moderately accurate
- Geometry: horizontal or vertical lines
Limitation of Weak Learner

• Might not be able to fit the training data well (high bias)

• Example: no single decision stump can classifier all the data points correctly
Can weak learners combine to do better?

• Can we separate the positive data from the negative data by drawing several lines?
• Yes, we can!
Can weak learners combine to do better?

- It turns out this complicated classifier can be expressed as a linear combination of several decision stumps.

\[
H = \text{sign} \begin{pmatrix}
0.42 & + 0.65 & + 0.92
\end{pmatrix}
\]
An analogy of Committee

- A weak Learner = a committee member

- Combination of weak leaners(ensemble) = a committee

- A Weak learner's decision hypothesis = a committee member's judgement

- Ensemble's decision hypothesis = a committee's decision

- A combination of weak learners often classifies better than a single weak learner = a committee often makes better decisions than a single committee member
Idea: Generating diverse weak learners

- adaBoost picks its weak learners $h$ in such a fashion that each newly added weak learner is able to infer something new about the data.

- adaBoost maintains a weight distribution $D$ among all data points. Each data point is assigned a weight $D(i)$ indicating its importance.

- By manipulating the weight distribution, we can guide the weak learner to pay attention to different parts of the data.
Idea: Generating diverse weak leaners

- AdaBoost proceeds by rounds
- in each round, we ask the weak learner to focus on hard data points that previous weak learners cannot handle well

- Technically, in each round, we increase the weights of misclassified data points, and decrease the weights of correctly classified data points
• AdaBoost init: uniform weight distribution $D$ on datapoints

• AdaBoost loop:
  - train weak learner $h$ according to current weights $D$
  - observe error($h$, $D$); compute coefficient
    $$\epsilon_t = Pr_{i \sim D_t}[h_t(x_t) \neq y_i] \quad \alpha_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right)$$
  - store weak learner $h_t$, coefficient $\alpha_t$
  - update Distribution $D$ for next round, emphasizing misclassified points

• AdaBoost final classifier
  $$H(x) = sign \left( \sum_{t=1}^{T} \alpha_t h_t(x) \right)$$
Adaboost Algorithm

For $t = 1, \ldots, T$:

- Train weak learner using distribution $D_t$.
- Get weak hypothesis $h_t: \mathcal{X} \rightarrow \{-1, 1\}$.
- Aim: select $h_t$ to minimize the weighted error:
  \[ \epsilon_t = \Pr_{i \sim D_t} [h_t(x_i) \neq y_i] \]
- Choose $\alpha_t = \frac{1}{2} \ln \left( \frac{1 - \epsilon_t}{\epsilon_t} \right)$
- Update
  \[
  D_{t+1}(i) = \frac{D_t(i)}{Z_t} \times \begin{cases} 
  e^{-\alpha_t} & \text{if } h_t(x_i) = y_i \\
  e^{\alpha_t} & \text{if } h_t(x_i) \neq y_i 
  \end{cases} \\
  = \frac{D_t(i) \exp(-\alpha_t y_i h_t(x_i))}{Z_t}
  \]
  where $Z_t$ is a normalization factor (chosen so that $D_{t+1}$ will be a distribution).

Output the final hypothesis:

\[ H(x) = \text{sign} \left( \sum_{t=1}^{T} \alpha_t h_t(x) \right) \]
Adaboost Algorithm

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\end{array} \right.
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Output the final hypothesis:

$$
H(x) = \text{sign}\left(\sum_{t=1}^{T} \alpha_t h_t(x)\right)
$$
Adaboost: an example

\[
\begin{array}{c|c|c}
\hline
 & D_1 & h_1 \\
\hline
D_1(i) & 0.10 & 0.10 \\
e^{-\alpha_1 y_i h_1(x_i)} & 1.53 & 1.53 \\
D_1(i) e^{-\alpha_1 y_i h_1(x_i)} & 0.15 & 0.15 \\
\hline
\end{array}
\]

\[\epsilon_1 = 0.30, \alpha_1 \approx 0.42\]
\[Z_1 \approx 0.92\]
Adaboost: an example

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<td>$Z_2 \approx 0.82$</td>
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Adaboost: an example

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Adaboost: an example

\[
H = \text{sign} \left( 0.42 + 0.65 \right) = +
\]

\[
\begin{array}{ccccccccccc}
1 & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 & 10 \\
D_1(i) & 0.10 & 0.10 & 0.10 & 0.10 & 0.10 & 0.10 & 0.10 & 0.10 & \epsilon_1 = 0.30, \alpha_1 \approx 0.42 \\
e^{-\alpha_1 y_i h_1(x_i)} & 1.53 & 1.53 & 1.53 & 0.65 & 0.65 & 0.65 & 0.65 & 0.65 & D_1(i) e^{-\alpha_1 y_i h_1(x_i)} \approx 0.15 & 0.15 & 0.15 & 0.07 & 0.07 & 0.07 & 0.07 & 0.07 & 0.07 & Z_1 \approx 0.92 \\
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D_3(i) & 0.11 & 0.11 & 0.11 & 0.05 & 0.05 & 0.17 & 0.17 & 0.05 & \epsilon_3 \approx 0.14, \alpha_3 \approx 0.92 \\
e^{-\alpha_3 y_i h_3(x_i)} & 0.40 & 0.40 & 0.40 & 2.52 & 2.52 & 0.40 & 0.40 & 0.40 & D_3(i) e^{-\alpha_3 y_i h_3(x_i)} \approx 0.04 & 0.04 & 0.04 & 0.11 & 0.11 & 0.07 & 0.07 & 0.11 & Z_3 \approx 0.69
\end{array}
\]
Let $\gamma = \frac{1}{2} - \epsilon_t$, and let $D_1$ be an arbitrary initial distribution over the training set. It can be shown [7] that the weighted training error of the combined classifier $H$ with respect to $D_1$ is bounded as

$$Pr_{i \sim D_1}[H(x_i) \neq y_i] \leq \prod_{t=1}^{T} \sqrt{1 - 4\gamma_t^2} \leq \exp(-2 \sum_{t=1}^{T} \gamma_t^2)$$
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There are two possibilities for ending AdaBoost training:

1. Training error goes to 0
2. $\gamma_t=0$ (equivalent $\epsilon = 0.5$). Boosting gets stuck: the boosting weights on training set are in such a way that every weak learner has 50% error.
Adaboost Training error

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- **comments:** in practice, we usually stop boosting after certain iterations to both save time and prevent overfitting
**Adaboost Training error**

**Proof:** Define $F(x) = \sum_{t=1}^{T} \alpha_t h_t(x)$. We have

\[
D_{T+1}(i) = D_1(i) \times \frac{e^{-y_i \alpha_1 h_1(x_i)}}{Z_1} \times \cdots \times \frac{e^{-y_i \alpha_T h_T(x_i)}}{Z_T}
\]

\[
= \frac{D_1(i) \exp(-y_i \sum_{t=1}^{T} \alpha_t h_t(x_i))}{\prod_{t=1}^{T} Z_t}
\]

\[
= \frac{D_1(i) \exp(-y_i F(x_i))}{\prod_{t=1}^{T} Z_t}
\]

\[
Pr_{i \sim D_1}[H(x_i) \neq y_i] = \sum_{i=1}^{m} D_1(i) \mathbf{1}\{H(x_i) \neq y_i\}
\]

\[
\leq \sum_{i=1}^{m} D_1(i) \exp(-y_i F(x_i))
\]

\[
= \sum_{i=1}^{m} D_{T+1}(i) \prod_{t=1}^{T} Z_t
\]

\[
= \prod_{t=1}^{T} Z_t
\]
Adaboost Training error

\[
Z_t = \sum_{i=1}^{m} D_t(i) e^{-\alpha_t y_i h_t(x_i)}
= \sum_{i:y_i=h_t(x_i)} D_t(i) e^{-\alpha_t} + \sum_{i:y_i\neq h_t(x_i)} D_t(i) e^{\alpha_t}
= e^{-\alpha_t} (1 - \epsilon_t) + e^{\alpha_t} \epsilon_t
= e^{-\alpha_t} \left( \frac{1}{2} + \gamma_t \right) + e^{\alpha_t} \left( \frac{1}{2} - \gamma_t \right)
= \sqrt{1 - 4\gamma_t^2}
\]
Boosting and Margin Distribution

- **Adaboost maximizes margins**

  ![Graph showing cumulative distribution vs margin]

  \[ F(x) = \sum_t \alpha_t \cdot h_t(x) \]

  Margin(x) = \( y(x) \cdot \frac{F(x)}{\sum \alpha_t} \in [-1,1] \)

  \[ \mathbb{P}_{(x,y) \sim S} [y \cdot f(x) \leq \theta] \leq 2^T \prod_{t=1}^{T} \sqrt{\epsilon_t^{1-\theta} (1 - \epsilon_t)^{1+\theta}}. \]

- Schapire, Freund, Bartlett, Lee '98
- For any 0<\( \theta < 1 \)
Adaboost testing error based on VC dim

\[
\text{testing\_error} \leq \text{training\_error} + O \left( \sqrt{\frac{Td}{m}} \right)
\]

- \(d = \text{VC dim of classifiers (measure of complexity)}\)
- \(T = \text{number of boosting rounds}\)
  - a loose bound as \(T\) can be very large, without decreasing the testing error
Adaboost testing error based on margins

**Theorem 1** Let $D$ be a distribution over $X \times \{-1, 1\}$, and let $S$ be a sample of $m$ examples chosen independently at random according to $D$. Assume that the base-classifier space $\mathcal{H}$ is finite, and let $\delta > 0$. Then with probability at least $1 - \delta$ over the random choice of the training set $S$, every weighted average function $f \in C$ satisfies the following bound for all $\theta > 0$:

$$P_D [y f(x) \leq 0] \leq P_S [y f(x) \leq \theta] + O\left(\frac{1}{\sqrt{m}} \left(\frac{\log m \log |\mathcal{H}|}{\theta^2} + \log(1/\delta)\right)^{1/2}\right).$$

- A better bound for testing error based on margins
- Does not depend on $T = \text{number of boosting rounds}$
Deep decision trees vs Boosted decision stumps

- Deep decision trees and Boosted decision stumps look very similar. Both can easily drive the training error down to 0, and both yield similar decision boundaries. Why does boosted decision stumps often generalize better than deep decision trees?

<table>
<thead>
<tr>
<th></th>
<th>Deep Decision Tree</th>
<th>Boosted decision stumps</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Partition the space</strong></td>
<td>lines parallel to axis</td>
<td>lines parallel to axis</td>
</tr>
<tr>
<td><strong>Decision boundary</strong></td>
<td>zig-zags</td>
<td>zig-zags</td>
</tr>
<tr>
<td><strong>Bias</strong></td>
<td>low</td>
<td>low</td>
</tr>
</tbody>
</table>
## Deep decision trees vs Boosted decision stumps

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<tbody>
<tr>
<td><strong>Variance</strong></td>
<td>high</td>
<td>low</td>
</tr>
<tr>
<td><strong>Representation</strong></td>
<td>Each leaf node contains at least one example. The number of examples required to train a constant-leaves decision tree can grow exponentially with the dimension of the input space. Cannot generalize to new variations.</td>
<td>Can generalize to regions not covered by the training set. Have exponentially more efficient power than single decision trees.</td>
</tr>
<tr>
<td><strong>Power</strong></td>
<td>voting on local tiny regions among data points; more likely to overfit</td>
<td>voting among weak learners. If learners have low complexity, harder to overfit.</td>
</tr>
<tr>
<td><strong>voting schema</strong></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
Bagging Decision Trees

- Train multiple classifiers, independently
- Each classifier = Decision Tree trained on a sampled-with-replacement dataset
- Final prediction: run all classifiers, average their output
Bagging: sampling with replacement

- Trainset of size N; want sampling set of size N

- For i=1:N
  - Randomly select a point $X_i$ from Trainset
  - Do not remove this point so it can be sampled again

- Not all points will be selected
  - selected points expected count $\sim 63\% \times N$
- Some points all be selected multiple times
Bagging Decision Trees VS Boosting

• Both have final prediction as a linear combination of classifiers

• Bagging combination weights are uniform; boosting weights ($\alpha_t$) are a measure of performance for classifier at round

• Bagging has independent classifiers, boosting ones are dependent of each other

• Bagging randomly selects training sets; boosting focuses on most difficult points