

# Computer Networks: Theory, Modeling, and Analysis

Guevara Noubir  
COM3510, lecture 2

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## Outline

- Physical layer: virtual pipe
  - Brief introduction to this very large topic
- Data Link Control (DLC) layer:
  - Error detection
  - Retransmission strategies (ARQ)
  - Framing

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## Physical Layer: Modems

- Function:
  - Maps bits (from DLC) onto waveforms sent over the channel  $s(t)$
  - $s(t)$  is sent, and  $r(t)$  is received (distorted, delayed, attenuated)
  - How to recover  $s(t)$  from  $r(t)$
- We focus on digital communication for point-to-point channels

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## Basic Encoding Schemes

- NRZ (Non Return to Zero)
- NRZI (Non return to Zero Inverted)
- Manchester coding
- *Not to be confused with error-control codes*

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## Physical Transmission and Channel Effect

- Created by the system designer and by the channel
  - Focus on linear time-invariant filtering:
    - If  $s(t) \rightarrow r(t)$ , then  $s(t-\tau) \rightarrow r(t-\tau)$
    - If  $s(t) \rightarrow r(t)$ , then for any real number  $\alpha$ :  $\alpha s(t) \rightarrow \alpha r(t)$
    - If  $s(t_1) \rightarrow r(t_1)$ , and  $s(t_2) \rightarrow r(t_2)$ , then  $s(t_1) + s(t_2) \rightarrow r(t_1) + r(t_2)$
- Effect of increasing the bitrate: increased distortion  $\Rightarrow$  *inter-symbol interference (ISI)*.

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## Channel Impulse Response

- Let  $h(t)$  be the channel output corresponding to an infinitesimally narrow pulse of unit area at time 0
  - $h(t)$  is called the channel impulse response
  - $\delta s(\tau) \rightarrow s(\tau)h(t-\tau)$
  - Because of the channel linearity:  $r(t) = \int_{-\infty}^{+\infty} s(\tau)h(t-\tau)d\tau$   
*convolution integral*
  - The channel behavior is completely characterized by the impulse response
- Remarks:
  - $h(t) = 0$  for  $t < 0$ .
  - The larger the non-zero duration of  $h(t)$  the more ISI

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## Frequency Response

- Let's assume that  $s(t)$  is a complex function:
  - E.g.,  $s(\tau) = e^{j2\pi f\tau} = \cos(2\pi f\tau) + j \sin(2\pi f\tau)$  then,  
 $r(t) = H(f)e^{j2\pi ft}$  where  $H(f) = \int_{-\infty}^{+\infty} h(\tau)e^{-j2\pi f\tau}d\tau$   
 $H(f)$  is called the frequency response of the channel
  - The response of the channel to a real sinusoid input at frequency  $f$  is a sinusoid output at the same frequency:
    - Scaling factor:  $|H(f)|$
    - Phase shift:  $\angle H(f)$

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## Fourier Transforms

- Any function  $s(t)$  can be represented as a superposition of complex sinusoids of weight:  $S(f)$ 
  - Fourier transform  $S(f) = \int_{-\infty}^{+\infty} s(t)e^{-j2\pi ft} dt$
  - Inverse Fourier transform  $s(t) = \int_{-\infty}^{+\infty} S(f)e^{j2\pi ft} df$
- Since the channel is linear:  $r(t) = \int_{-\infty}^{+\infty} H(f)S(f)e^{j2\pi f\tau} df$ 
  - Then:  $R(f) = H(f)S(f)$
  - Convolution in time domain = multiplication in frequency domain

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## Sampling Theorem

- Theorem: If a waveform is low-pass limited ( $S(f) = 0$  for  $|f| > W$ ) then  $s(t)$  is completely determined by its values each  $1/2W$  seconds:

$$s(t) = \sum_{i=-\infty}^{+\infty} s\left(\frac{i}{2W}\right) \frac{\sin[2\pi W(t - i/(2W))]}{2\pi W(t - i/(2W))}$$

- Conclusion: incoming digital data can be mapped into sample values spaced by  $1/2W$  seconds. The resulting waveform is low-pass limited and can go through any ideal low-pass filter ( $W$ ) unmodified. The received waveform can be used to recover the original data.
- How many bits can we transmit per Hertz?

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## Band-pass Channels

- Low-pass channels assume that:  $|H(f)|$  nonzero only for a frequency and around  $f = 0$ .
- Most physical channels are band-pass:  $|H(f)|$  nonzero for  $f_1 < f < f_2$ ;  $H(0) = 0$ . (no dc component).
- Two solutions:
  - Direct coding into signals with no-dc component (Manchester encoding)
  - Modulation

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## Modulation

- Simplest modulation: Amplitude Modulation (AM)
  - NRZ signal is multiplied by a carrier sinusoidal signal (frequency  $f_0$ )

$$s(t) \cos(2\pi f_0 t)$$

- Signal recovery is achieved by multiplying the received signal again by the carrier frequency

$$r(t) = s(t) \cos^2(2\pi f_0 t)$$

$$r(t) = \frac{s(t)}{2} + \frac{s(t) \cos(4\pi f_0 t)}{2}$$

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## Higher Modulation Schemes

- $\cos(2\pi f t)$  and  $\sin(2\pi f t)$  are “orthogonal” then:
  - Two signals/bits of data can be transmitted simultaneously (QAM)
- Phase shift keying: QPSK, 8-PSK, 16-PSK, 64-PSK
- Frequency Shift Keying (FSK)

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## Shannon's Theorem

- The capacity of a channel (maximum achievable data rate in bps) is given by:

$$C = W \log_2 \left( 1 + \frac{S}{N_0 W} \right)$$

- $W$  is the available bandwidth,  $S$  is the signal power (seen by the receiver),  $N_0$  is the noise power per Hertz
- Signal-to-noise ratio is usually expressed in dB:  
 $10 \log_{10}(S/(N_0 W))$
- Example:  $S/N_0 W = 30$  dB  $\Rightarrow$  How many bits per Hertz?

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## Multiplexing Schemes

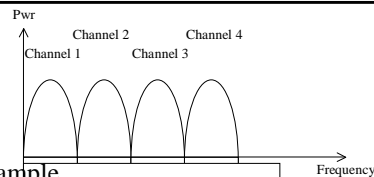
- Frequency Division Multiple
- Time Division
- Code Division
- Space Division

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## Frequency Division Multiple Access (FDMA)



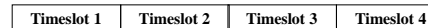
- Example**
  - FM radio set receiver: a single broadcasting station for each frequency channel
- Concept**
  - assign different frequency bands to different users
  - no sharing of a frequency band between several senders
  - user separation using band-pass filters
  - continuous flow
  - two-way: two frequency bands or Time Division Duplex (TDD)

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## Time Division Multiple Access (TDMA)



### Concept

- use the same frequency over non-overlapping periods of time

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## FDMA/TDMA: Comparing delays

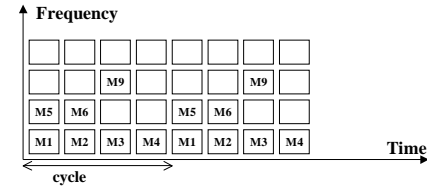
- Transmission delay in a FDMA system
  - $\text{Delay}_{\text{FD}} = T$  (transmission time in FDMA)
- Transmission delay in a TDMA system
  - $\text{Delay}_{\text{TD}} = T/M + \text{Average-waiting-time}$
  - $\text{Average-waiting-time} = (T/2) * (1-1/M)$
  - $\text{Delay}_{\text{TD}} = \text{Delay}_{\text{FD}} - (T/2) * (1-1/M)$

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## Combining FDMA and TDMA



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## Code Division Multiple Access (CDMA)

- Concept
  - use the same frequency over overlapping periods of time with different codes
  - codes generate signals with “good-correlation” properties
  - signals from another user appear as “noise”
  - signals are spread over a wideband using pseudo-noise sequences
- Techniques: Spread Spectrum
  - Direct Sequence Spread Spectrum
    - IEEE802.11 (SS no CDMA), IS-93, CDMA2000, WCDMA
  - Frequency Hopping Spread Spectrum (slow and fast)

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## CDMA

- Advantages
  - frequency diversity:
    - resistance to jamming, selective fading, multi-path fading
  - easy frequency planning
  - soft-handover (macro-diversity)
  - better performance when load is low
- Drawbacks
  - requires efficient synchronization:
    - easy on down-link, difficult on uplink
  - all users signals must reach the base-station with the same power: near-far problem
    - power-control: accurate (1dB)
  - codes allocation

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## SDMA and PDMA

- Space Division Multiple Access (resource reuse)
  - a frequency/time slot/code can be used by two different users but not at the same location
  - examples: distant cells, satellite spot beams
- Polarization Division Multiple Access
  - different antenna polarization are used
  - example: two-orthogonal antenna polarization in satellite communication

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## Digital Channels

- Several channels (wired) are designed to carry digital data directly (no need for a modem)
- When a digital repeater is used these channels provide an improved performance over channels carrying analog data.
  - The reason is that the noise is removed at each repeater in a digital channel, while it is amplified with an analog repeater.

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## Error Detection

- Assume that we when know the beginning/end of the frames. The number of data bits in the frame is  $K$  bits.
- How can we detect if one/several bits changed duration their transmission?
- Since all the frames can potentially be received then we have to add some redundancy bits ( $L$ ) to detect errors (checksum).

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## Parity Checks

- Single parity checks:
  - For every string of data bits append a single bit: parity bit
  - If the number of 1's in the string is even then the parity = 0; otherwise 1.
  - E.g., ASCII characters of 7 bits + 1 parity bit.
  - Number of 1's in an encoded string is always even.
  - This encoding allows to detect all single errors and no-two errors, etc.
  - Not sufficiently reliable specially when errors occur in bursts

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## Horizontal-Vertical Parity Checks

- Data is arranged into a two-dimensional array
  - A single parity bit is appended to each row and each column

1	1	1	0	0	0		1
0	1	0	1	1	0		1
1	0	1	0	1	1		0
1	0	0	0	0	1		0
1	1	1	1	1	0		1
0	1	1	0	1	0		1

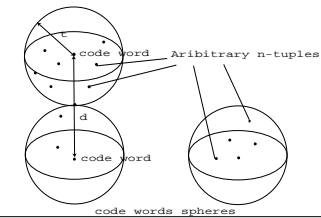
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## Hamming Distance for Block Codes

- The Hamming distance between two codewords is the number of places where they differ
- The Hamming distance of a Block code is the minimum distance between two code words



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## Example of Binary Block Code (7, 4)

- Any two different code words are different on at least three different coordinates. This code has Hamming distance 3.

Message block	Code word
(0 0 0 0)	(0 0 0 0 0 0 0)
(1 0 0 0)	(1 1 0 1 0 0 0)
(0 1 0 0)	(0 1 1 0 1 0 0)
(1 1 0 0)	(1 0 1 1 1 0 0)
(0 0 1 0)	(1 1 1 0 0 1 0)
(1 0 1 0)	(0 0 1 1 0 1 0)
(0 1 1 0)	(1 0 0 0 1 1 0)
(1 1 1 0)	(0 1 0 1 1 1 0)
(0 0 0 1)	(1 0 1 0 0 0 1)
(1 0 0 1)	(0 1 1 1 0 0 1)
(0 1 0 1)	(1 1 0 0 1 0 1)
(1 1 0 1)	(0 0 0 1 1 0 1)
(0 0 1 1)	(0 1 0 0 1 1 1)
(1 0 1 1)	(1 0 0 1 0 1 1)
(0 1 1 1)	(0 0 1 0 1 1 1)
(1 1 1 1)	(1 1 1 1 1 1 1)

- Notice that the last 4 bits of the code word are the same as the message
  - This is a systematic coding
  - The other 3 bits are redundancy bits

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## Cyclic Redundancy Checks (CRC)

- Data bits:  $s_{K-1}, s_{K-2}, \dots, s_1, s_0$
- Polynomial representation:

$$S(D) = s_{K-1}D^{K-1} + s_{K-2}D^{K-2} + \dots + s_1D + s_0$$

- The CRC is also viewed as polynomial:

$$C(D) = c_{L-1}D^{L-1} + c_{L-2}D^{L-2} + \dots + c_1D + c_0$$

- The transmitted frame can be represented as:

$$x(D) = s(D)D^L + c(D)$$

$$x(D) = s_{K-1}D^{L+K-1} + \dots + s_0D^L + c_{L-1}D^{L-1} + c_{L-2}D^{L-2} + \dots + c_1D + c_0$$

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## Generating the CRC

- The CRC is the remainder of dividing the information polynomial  $S(D)$  by a generator polynomial  $g(D)$ .

$$c(D) = \text{Remainder}\left[\frac{S(D)D^L}{g(D)}\right]$$

- Example: divide  $D^5 + D^3$  by  $D^3 + D^2 + 1$

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## Hardware Generation of the CRC

- Binary divisions can be efficiently implemented using Linear Feed-Back Shift Registers (LFSR)

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## Error Detection Capability of CRC

- All single bit errors are detected
- All errors of burst length less than  $L+1$  are detected
- Primitive polynomials allow to detect all double-errors when the frame length is less than  $2^L - 1$
- Choice of the generator polynomial:
  - Product of a primitive polynomial by  $(D+1)$
  - CRC-16:  $D^{16} + D^{15} + D^2 + 1$
  - CRC CCITT:  $D^{16} + D^{12} + D^5 + 1$

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## Non-Binary Codes

- The data is a sequence of symbols of several bits
- A symbol is in error if any of its bits has an error
- Advantages:
  - Easier to implement in software (e.g., TCP checksum)
  - Handle bursts of errors

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## Automatic Repeat reQuest (ARQ)

- Assumption:
  - The DLC knows the start/end of the frame
  - The DLC is able to detect frames with errors (e.g., using a CRC)
  - Frames that are not lost arrive in their transmission order
- ARQ retransmission strategies:
  - Stop-and-Wait ARQ
  - Go Back  $n$  ARQ
  - Selective Repeat ARQ

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## Stop-and-Wait ARQ Protocol

- Protocol for A is sending packets to B
- A simple but bogus strategy:
  - The first packet is sent in the first frame
    - If the packet is correctly received by B, B sends an Acknowledgement (Ack)
    - If the frame has errors, B send a negative ACK (Nak)
    - If the frame, Ack/Nak is lost, or a Nak is received, then A retransmits the packet.
  - When the packet is acknowledged A proceeds to the next packet
- Malfunctions can occur due to variable transmission delays or loss of Ack.
- Conclusion: it is necessary to use frame numbering.

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## Stop-and-Wait ARQ Protocol

- Algorithm at node A:
  1. Set the integer variable  $SN$  to 0
  2. Accept/wait for a packet from higher layer and assign  $SN$  to this packet
  3. Transmit the  $SN^{\text{th}}$  packet in a frame (sequence number= $SN$ )
  4. If an error-free frame is received from B with  $RN > SN$ , increase  $SN$  to  $RN$  goto 2, otherwise [within some finite delay] goto 3.
- Algorithm at node B:
  1. Set  $RN$  to 0; loop on 2 and 3
  2. On receipt of an error-free frame with  $SN = RN$  release packet to higher layer and increment  $RN$
  3. At arbitrary times (bounded delay) after receiving any error-free data from A, transmit a frame to A containing  $RN$  in the request number field

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## Correctness of Stop-and-Wait

- Safety property: never produces an incorrect result
- Liveness property: no-deadlock

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## Sequence Number Optimization for Stop-and-Wait ARQ

- The sequence number  $SN$  cannot increase without bound:
  - Loss of bandwidth, and requires a variable size  $SN$  field
- In the Stop-and-Wait protocol the uncertainty is always between:
  - $B$  side:  $SN$  received are either  $RN(t)$  or  $RN(t)-1$  ( $i+1$ , or  $i$ )
  - $A$  side:  $RN$  received are either  $SN(t)$  or  $SN(t)+1$  ( $i$ , or  $i+1$ )
- Sequence number is sent modulo 2: also called the alternating bit protocol

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## Limitation of S&W

- When the sender is waiting for the acknowledgment the channel is not used!
- Loss of bandwidth specially for channels with high round-trip-delay
  - E.g., satellite channels, channels with low-computation power nodes (buffering), etc.

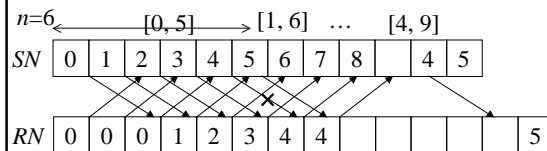
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## Go-Back $n$ ARQ Protocol

- Informal description:
  - Several successive packets are allowed to be sent: up to  $n$ .
  - The receiver accepts packets only in the correct order.
  - A request  $RN$  acknowledges all packets with  $SN < R$  and requests the transmission of packet  $RN$



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## Go-Back $n$ Algorithm

- Transmitting side:  $A$ 
  - Set  $SN_{min}$  and  $SN_{max}$  to 0.
  - Do steps 3, 4, 5 repeatedly in any order.
  - If  $SN_{max} < SN_{min} + n$ , and if a packet is available from the higher layer, accept it, assign number  $SN_{max}$  to it and increment  $SN_{max}$ .
  - If an error-free frame is received from  $B$  containing  $RN > SN_{min}$ , increase  $SN_{min}$  to  $RN$ .
  - If  $SN_{min} < SN_{max}$  (+no frame being transmitted) choose  $SN$ :  $SN_{min} \leq SN < SN_{max}$  and transmit the  $SN^{th}$  packet (generally on timeout select  $SN=SN_{min}$ )
- Receiving side:  $B$ 
  - Set  $RN$  to 0 and loop over steps 2 and 3
  - Whenever an error-free frame is received containing a sequence number equal to  $RN$ , release the packet to the higher layer and increment  $RN$
  - At arbitrary times, within a bounded delay after receiving a frame from  $A$ , transmit a frame to  $A$  containing  $RN$  in the request number field

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## Sequence Number Modulus in GBN

- If we assume that frames arrive in the their transmission order, then the GBN can use sequence number, and request numbers modulo  $m > n$ .
- *Sketch of proof* on *A* side (similar on *B* side):
  - Let  $t_1$  bet the time when a frame is generated by *A*, and  $t_2$  the time it is received by *B*. The *SN* of this frame verifies:
    - $SN_{min}(t_1) \leq SN \leq SN_{min}(t_1) + n - 1$ , and
    - $SN_{min}(t_1) \leq RN(t_2) \leq SN_{min}(t_1) + n$ ,
    - $|RN(t_2) - SN| \leq n < m$ ,
    - Thus  $RN = SN \pmod{m}$  iff  $SN = RN$  (there is no ambiguity)

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## Selective Repeat ARQ Protocol

- Go-Back-N is better than Stop-and-Wait
  - Channel usage is improved
- However, when a packet is lost, then all sub-sequent packets have to re-transmitted. This is because the receiver accepts packets only in correct order
- Idea behind Selective Repeat (SR) ARQ:
  - The receiver accepts all error-free frames in the range of  $RN$  to  $RN+n-1$ . Even if they are out-of-order.
  - The receiver sends  $RN$  and also sends the  $SN$  of other correctly received frames (with  $SN > RN$ ).

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## GBN vs. SR

- Use GBN:
  - Some channels are subject to errors in bursts. There is a high probability that when a frame is lost, the following frames will also be lost.
  - Some communication nodes are limited in memory and processing. They cannot store packets that are out-of-order, or they cannot re-order them.
- Otherwise, use SR.

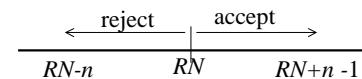
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## Sequence Numbers in SR

- If we assume that frames arrive in the their transmission order, then the GBN can use sequence number, and request numbers modulo  $m \Rightarrow 2n$ .
- *Sketch of proof* (*A* side):
  - $RN(t_2) - n \leq SN \leq RN(t_2) + n - 1$



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## Two-way communication

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- SN and RN can be piggy-backed in the exchanged frames
- To avoid blocking one-direction when then other one is idle, it is necessary to permit frames containing only request. These frames are activated by a timer.

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## Error Recovery at Transport Layer

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- Difference between a link layer, and transport layer communications:
  - In transport layer: numbering of session packets. In link layer numbering of all link packets
  - Packets may arrive out-of-order in transport layer
  - Timers setup is much more critical at the transport layer because of congestion problems
- ARQ protocols:
  - Same basic protocols as in the link layer
  - If packets can arrive out-of-order: numbering packets modulus a number is no more possible

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## Error Recovery at Transport Layer

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- Solutions to the order problem:
  - Require that the network delivers packets in order (e.g., fixed routing). However, this is generally not realistic since links may break and routing path will have to change.
  - Use a very large modulus.
  - Use a mechanisms that destroys packets after a limited time, and use a modulus large enough so that a wraparound does not happen during the lifetime of a packet.

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## Framing

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- The physical layer provide a mean to transmit a sequence of bits.
- How can one determine the beginning/end of a frame?
- Solutions:
  - Character-based framing (use special control characters)
  - Bit-oriented framing with flags
  - Length counts

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## Character-Based Framing

- We can use a character code such the ASCII (American Standard Code for Information Interchange): sequence of 7 bits (usually with a parity bit).

SYN	SYN	STX	Header	Packet	ETX	CRC	SYN	SYN
-----	-----	-----	--------	--------	-----	-----	-----	-----

- SYN: Synchronous idle, STX: Start of text, ETX: End of text
- Problem 1: if control characters appear within the header, or CRC.
  - These are known location, one can skip control characters in these fields
- Problem 2: if CTRL characters appear in the packet.
  - Use a Data Link Escape (DLE) character before STX (for start frame), and before ETX (for end frame), but not when it appears within the packet.
  - If DLE appears within the packet replace it with DLE DLE.
    - Example: DLE STX => start of frame, DLE ETX => end of frame,
    - DLE DLE STX => binary sequence DLE STX

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## Character-based Framing (Cont'd)

- Disadvantages:
  - Excessive overhead: DLE STX and DLE ETX for each frame, for each DLE within the packet and additional character has to be inserted (potentially doubling the size of the frame)
  - The frame has to contain an integral number of characters
- Potential errors:
  - Error in the DLE ETX => undetected end of frame
  - Error leading to the appearance of a DLE ETX

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## Bit-Oriented Framing: Flags

- Use a flag to indicate the end of a frame. The appearance of the flag within the frame is masked through a technique called bit stuffing (e.g., High-level DLC).
- A bit-oriented frame can have any length.
- Example:
  - Flag: 01111110 (= 01<sup>6</sup>0) (other flags could be used).
  - Rule of bit stuffing: insert a 0 after any sequence of five 1's
- Expected number of insertions =  $(E(K)-j+3)2^j$ .
  - $K$  is frame length, bit  $j-1$  counts twice.
  - Optimal  $j = \lfloor \log_2 E\{K\} \rfloor$

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## Length Fields

- SYN + Length field in the frame header
  - E.g., DECNET
- Can an encoding method require a smaller expected number of bits? Answer Shannon's source coding theorem of information theory.
- The minimum expected number of bits is at least the entropy of the distribution:
 
$$H = \sum_K P(K) \log_2 \frac{1}{P(K)}$$
- Idea: map more likely values of  $K$  into shorter bit strings
- Example the unary-binary encoding ( $j = \lfloor \log_2 E\{K\} \rfloor$ ):
  - $K=i2^j+r$  is encoded as  $0^i1r$

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## Framing with Errors

- Lost flag (the receiver will stop at the next flag). Detection through CRC ( $2^{-L}$ ).
- Error within the frame to change a bit into a flag (e.g., 01<sup>6</sup>0). Detection through CRC.
- Error in the length field. Detection through CRC or header CRC.

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## Frequency Division Multiple Access (FDMA)

- Advantages: simple receivers
  - longer symbol duration: no-need for equalization
    - low inter-symbol interference
    - e.g., 50kb/s QPSK  $\Rightarrow$  40  $\mu$ s  $\gg$  1-10 $\mu$ s delay spread
- Drawbacks
  - frequency guard bands, costly tight band-filters
  - long fading duration: need slow frequency hopping

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## Time Division Multiple Access (TDMA)

- Advantages
  - simple filters (window)
  - possibility to transmit and receive over the same frequency channel
- Drawbacks
  - users must be synchronized
  - guard times
  - short symbol duration: need for equalization, training sequences...
    - high inter-symbol interference
    - e.g., 50Kbps, QPSK, 8 users:
      - 5  $\mu$ s symbol duration
      - delay spread: 1 $\mu$ s (cordless), upto 20 $\mu$ s for cellular

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