Question 1. Vector algebra. In the figure below, the triangle a,b,c sits symmetrically near the origin, with its outer surface directed away from the origin, towards "you". What you are to compute is the inner product of the unit normal, N, to the triangle, with the vector \( \mathbf{L} = [1,0,0] \). When you compute the unit normal, make sure that its magnitude and direction make sense to you -- does your unit normal have the values it should, given the figure? This type of computation is used in calculating the amount of illumination to a surface. In such a case, the vector \( \mathbf{L} \) would be a vector directed toward the light source.

You should know that the normal is computed using the cross product of edge vectors and you should know how to normalize a vector to create one of unit length, then how to compute the inner product (by components).

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Question 2. Geometric transforms in two dimensions. The figure below, shows a line A,B in its original position and the line with corresponding points, A',B' obtained by a pair of
transforms, one a rotation and the other a translation.

Your task it to create the translation and rotation matrices required, T and R. The transformations can be designed to be applied in one order or designed with different values to be applied in the other order, giving the same result. (But you'll find that one order is simpler to design than the other.) Do the following:

a. Write out the your choice of T and R, indicating why you chose the values you did as well as what order they must be applied in.

b. Apply the first matrix to be used to the two points A,B and draw the resulting diagram.

c. Starting with that result, apply the second matrix and explain why it results in the answer, A',B'.

d. Multiply the two matrices together in the proper order to produce a result M. Apply M to the original points A,B and show that it results in A',B'.

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**Question 3. Scan-fill of polygons.** The figure below, shows the triangle A,B,C. To the right of it is the structure of one of the edge data elements. Do the following two tasks:

a. Build and draw the bucket-sorted edge table for the triangle, starting with y=0.

b. Show the active edge table (AET) for each of the y values 1 through 7, seven drawings total. In each AET update the Xmin value to the value at the corresponding value of y.
Question 4. Clipping polygons. The figure below, shows a polygon that is to be clipped against a rectangular window. The four cases are illustrated to the right of the polygon figure. Explain how each works. Clip the polygon in the order: bottom, top, right, and left for the window edges. Draw the successive clipping steps as separate figures.

Question 5. Midpoint line algorithm for scan conversion. The Java code below is an excerpt from a working version of the Bresenham midpoint algorithm for scan converting lines. You are to do the following:

a. Write out the sequence of x,y pixel values that two calls to the bres() method would draw. The first would be with arguments 0,0,5,5 and the second call would be with arguments 1,1,5,2. Include a comment or two, in addition to just writing out the numbers.

b. Compute the x,y points that would be generated for the two lines by using the standard formula \( y = mx + b \) and rounding the y values you get for each x. Do not use a calculator, since all the values will be simple fractions. Did your results agree with the values from the Bresenham algorithm? (If there's an ambiguity in rounding, go with the Bresenham value.)
public void dobres(int x0, int y0, int x1, int y1){
    int y = y0;
    int d = 2*(y0 - y1)*(x0 + 1) + (x1 - x0)*(2*y0 + 1) +
            2*x0*y1 - 2*x1*y0;

    for (int x = x0; x <= x1; x++) {
        draw(x,y);
        if (d < 0)
            { y++;
              d += 2*(x1 - x0) + 2*(y0 - y1);}
        else
            d += 2*(y0 - y1);
    }
} // dobres()