



CS5310

Graduate Computer Graphics

Prof. Harriet Fell
Spring 2011
Lecture 3 – February 2, 2011



Today's Topics

- From 3D to 2D
- 2 Dimensional Viewing Transformation

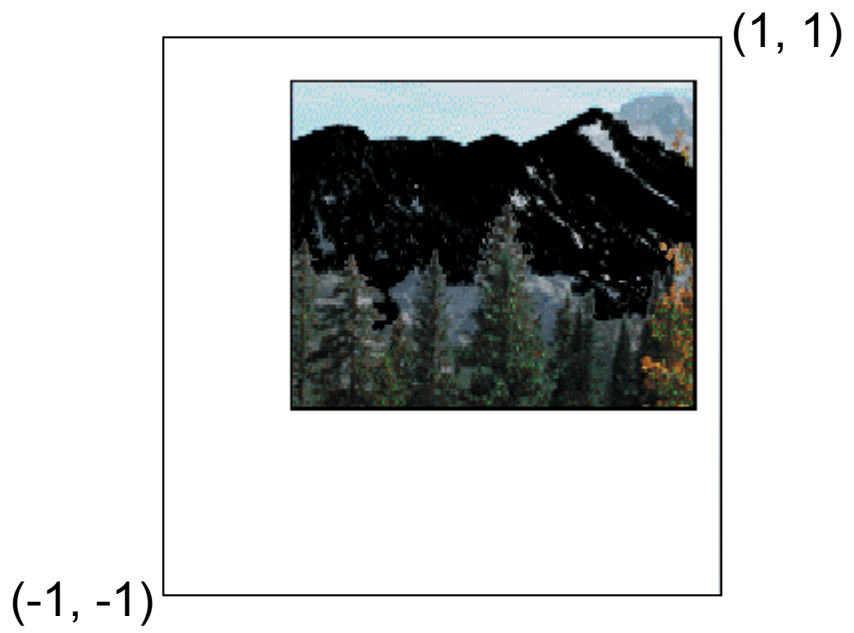
<http://www.siggraph.org/education/materials/HyperGraph/viewing/view2d/2dview0.htm>

- Viewing – from Shirley *et al.* Chapter 7
- Recursive Ray Tracing
 - Reflection
 - Refraction





Scene is from my photo of Estes Park – Harriet Fell
Kitchen window from <http://www.hoagy.org/cityscape/graphics/cityscapeAtNight.jpg>

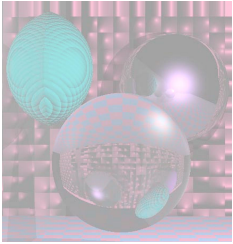




from a 3D World to a 2D Screen

When we define an image in some world coordinate system, to display that image we must somehow map the image to the physical output device.

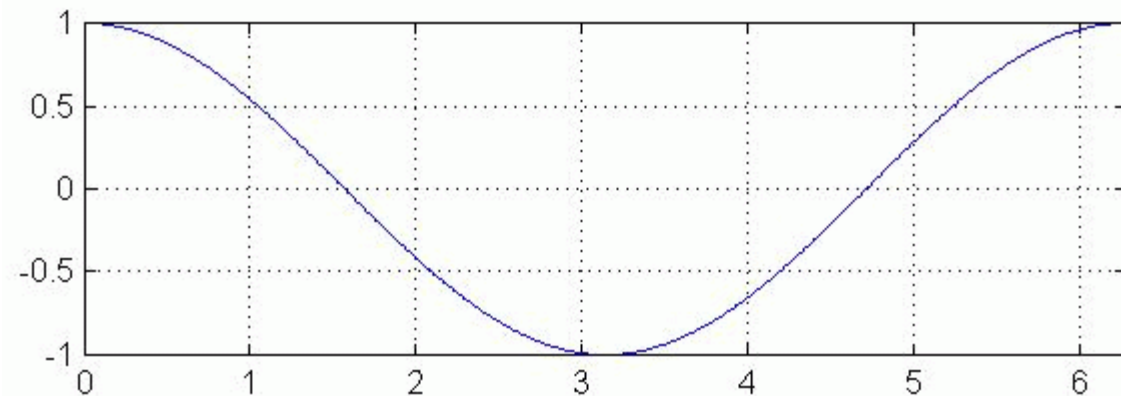
1. Project 3D world down to a 2D window (WDC).
2. Transform WDC to a Normalized Device Coordinates Viewport (NDC).
3. Transform (NDC) to 2D physical device coordinates (PDC).



2 Dimensional Viewing Transformation

<http://www.siggraph.org/education/materials/HyperGraph/viewing/view2d/2dview0.htm>

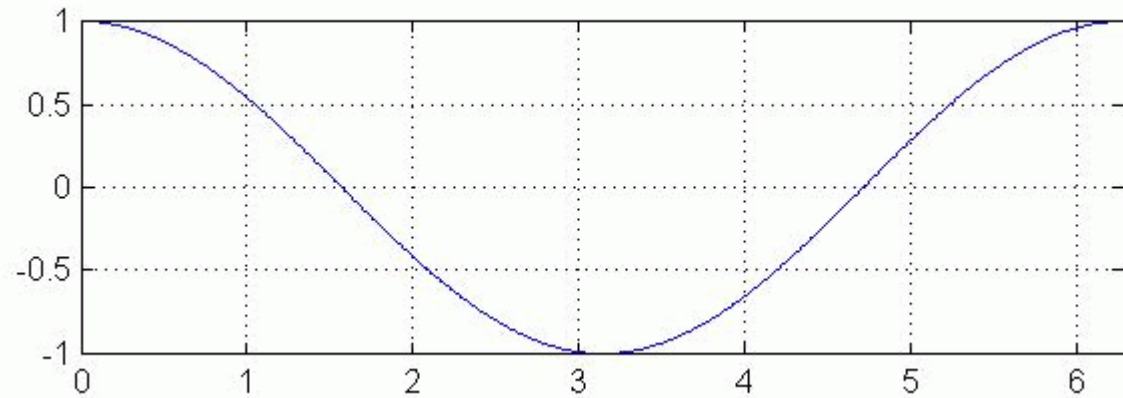
- Window
 - Example: Want to plot x vs. $\cos(x)$ for x between 0.0 and 2π . The values of $\cos x$ will be between -1.0 and $+1.0$. So we want the window as shown here.



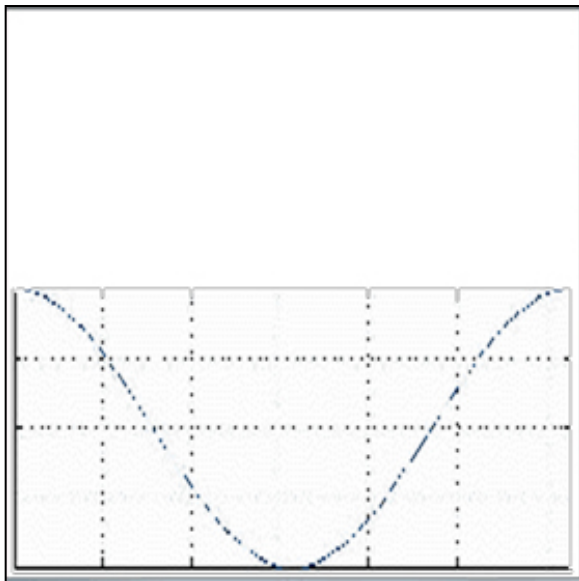


2D Viewing Transformation

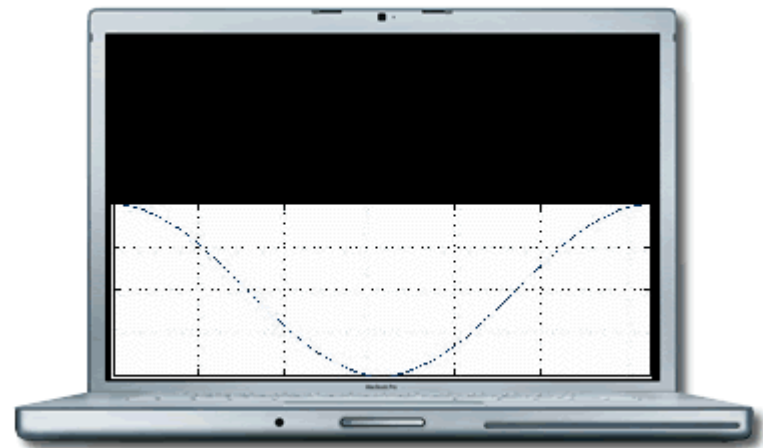
World

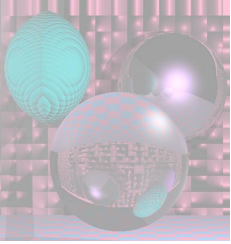


Viewport

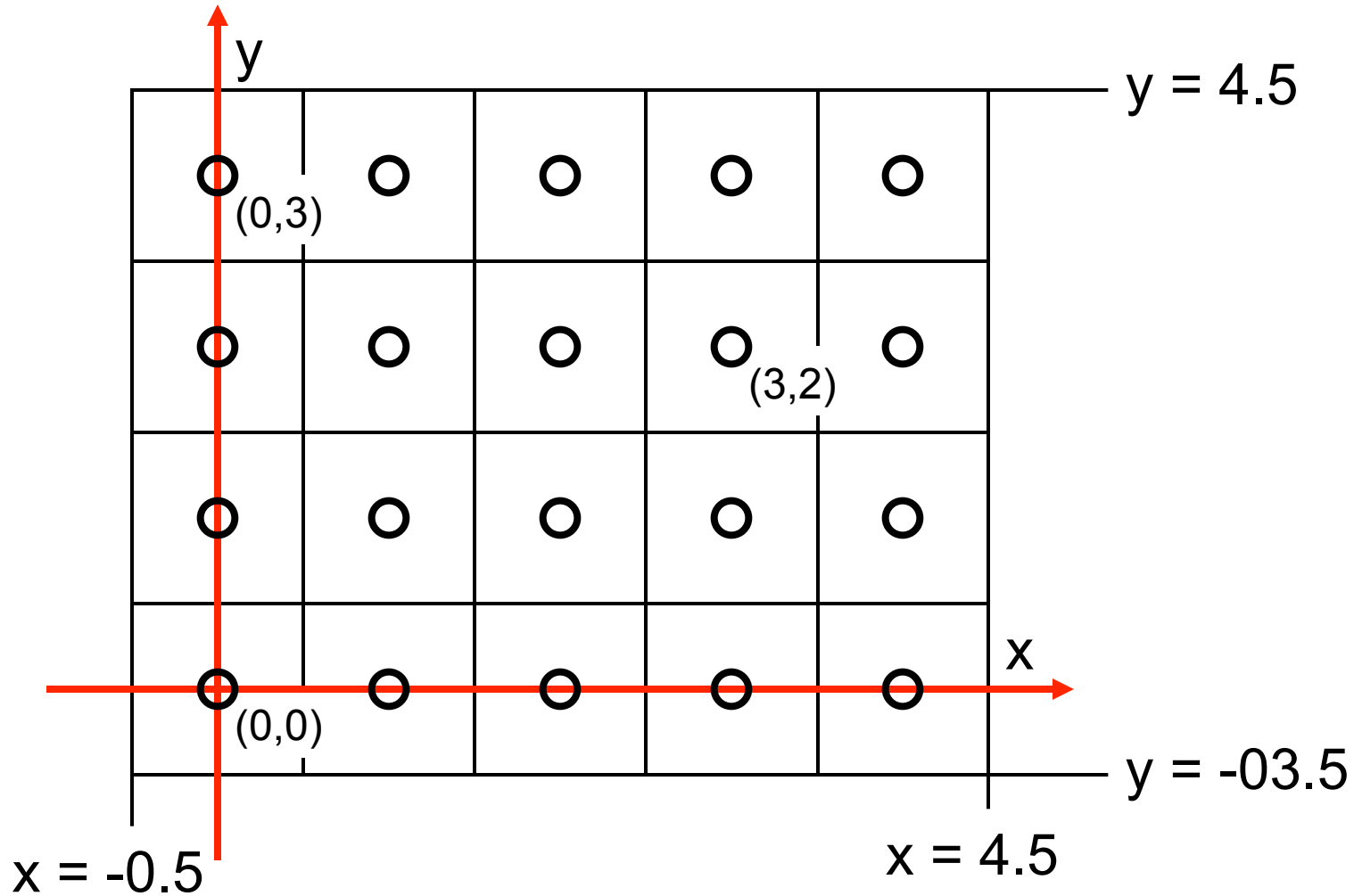


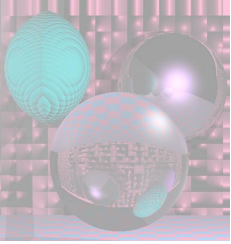
Device



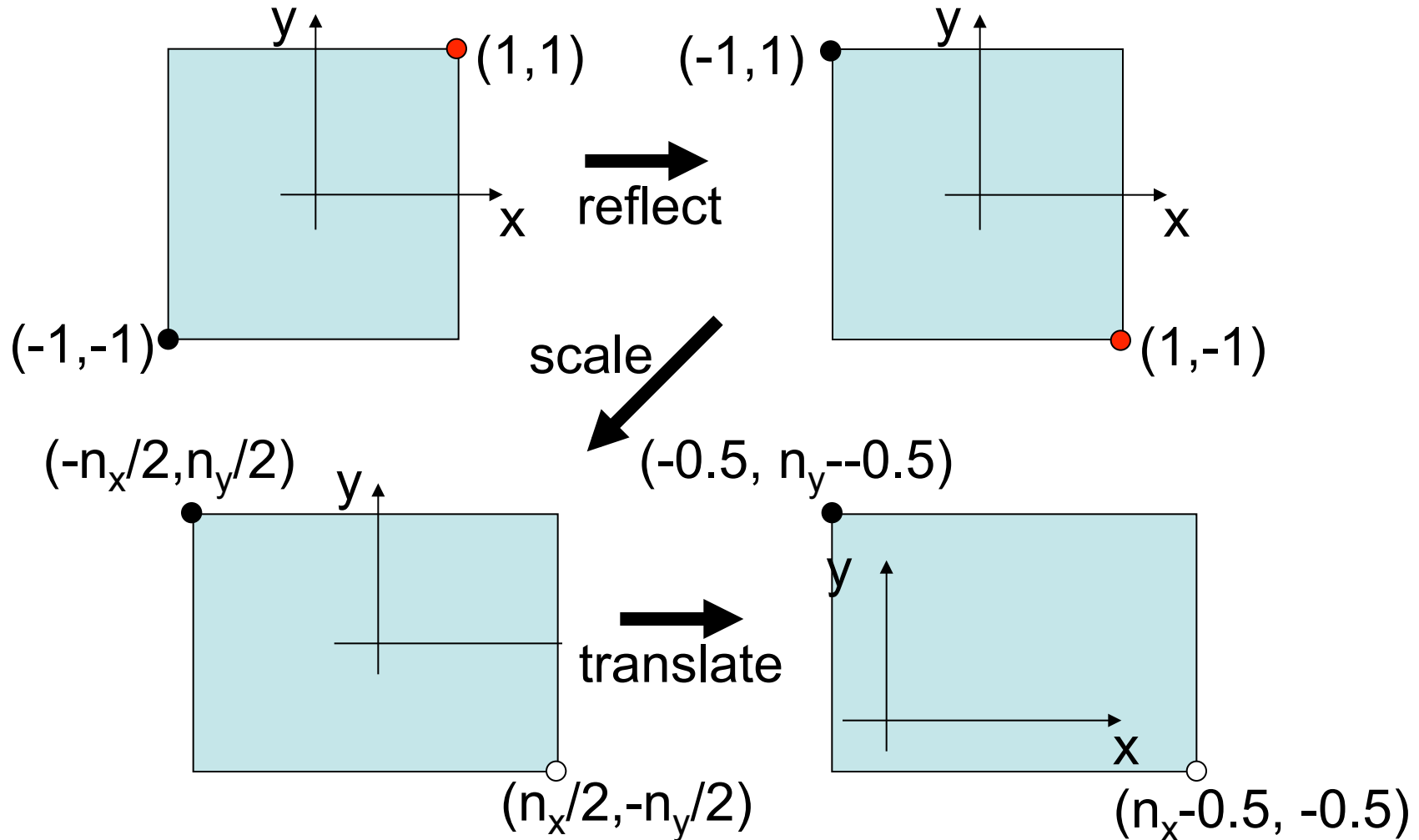


Pixel Coordinates



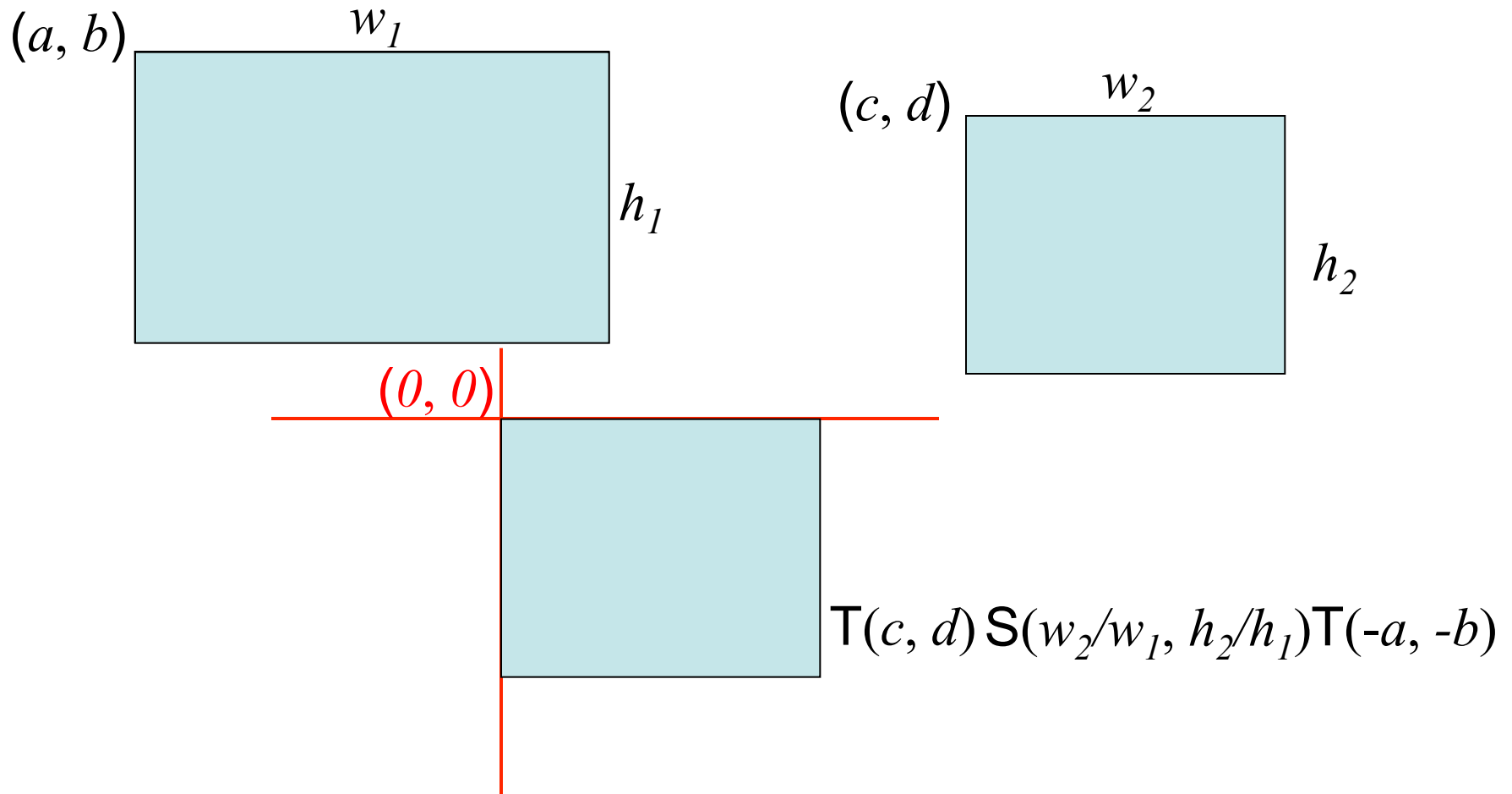


Canonical View to Pixels



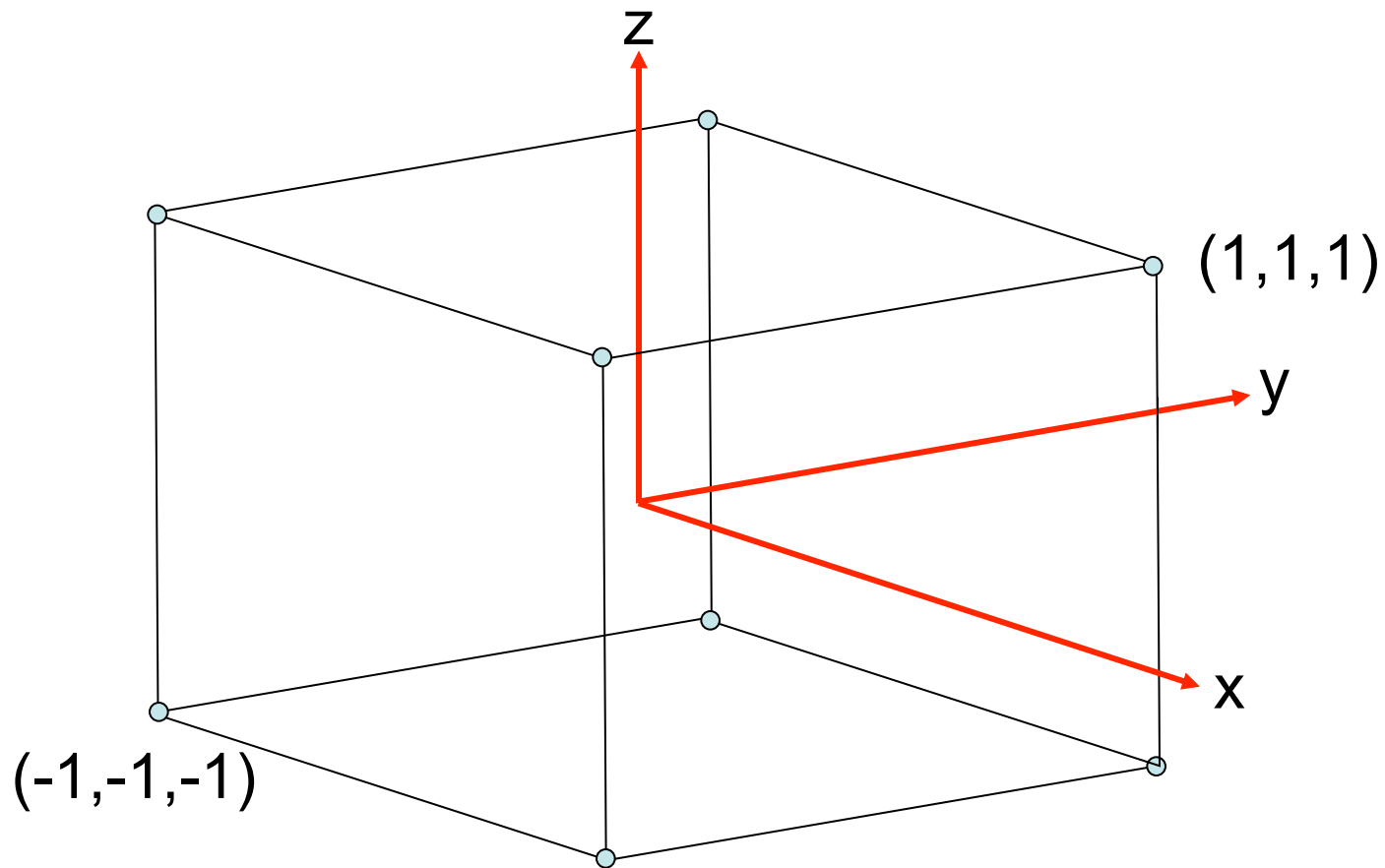


2D Rectangle to Rectangle



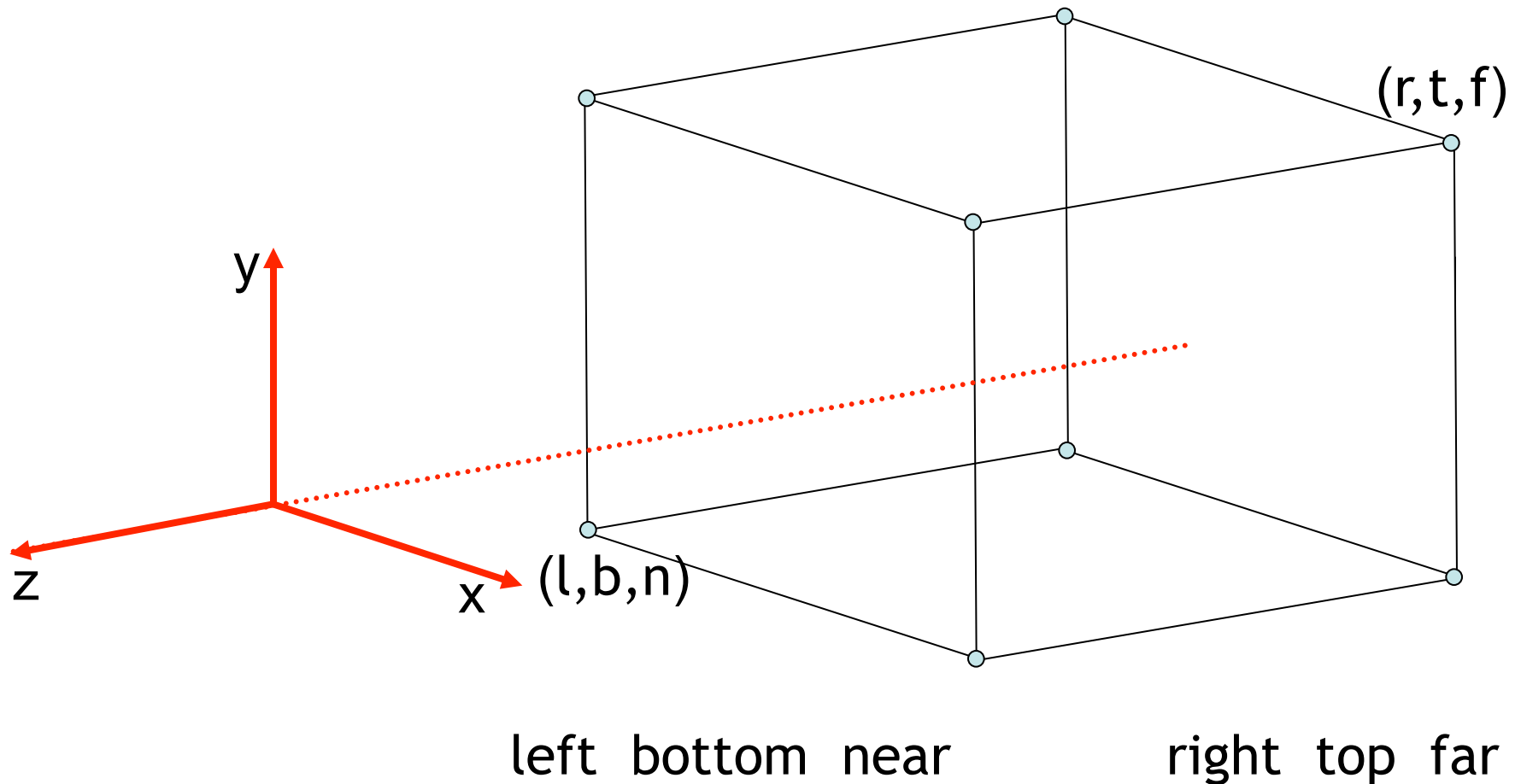


Canonical View Volume





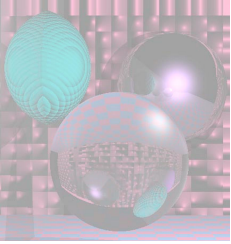
Orthographic Projection





Orthographic Projection Math

$$\begin{bmatrix} x_{canonical} \\ y_{canonical} \\ z_{canonical} \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2}{t-b} & 0 & 0 \\ 0 & 0 & \frac{2}{n-f} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -\frac{l+r}{2} \\ 0 & 1 & 0 & -\frac{b+t}{2} \\ 0 & 0 & 1 & -\frac{n+f}{2} \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$



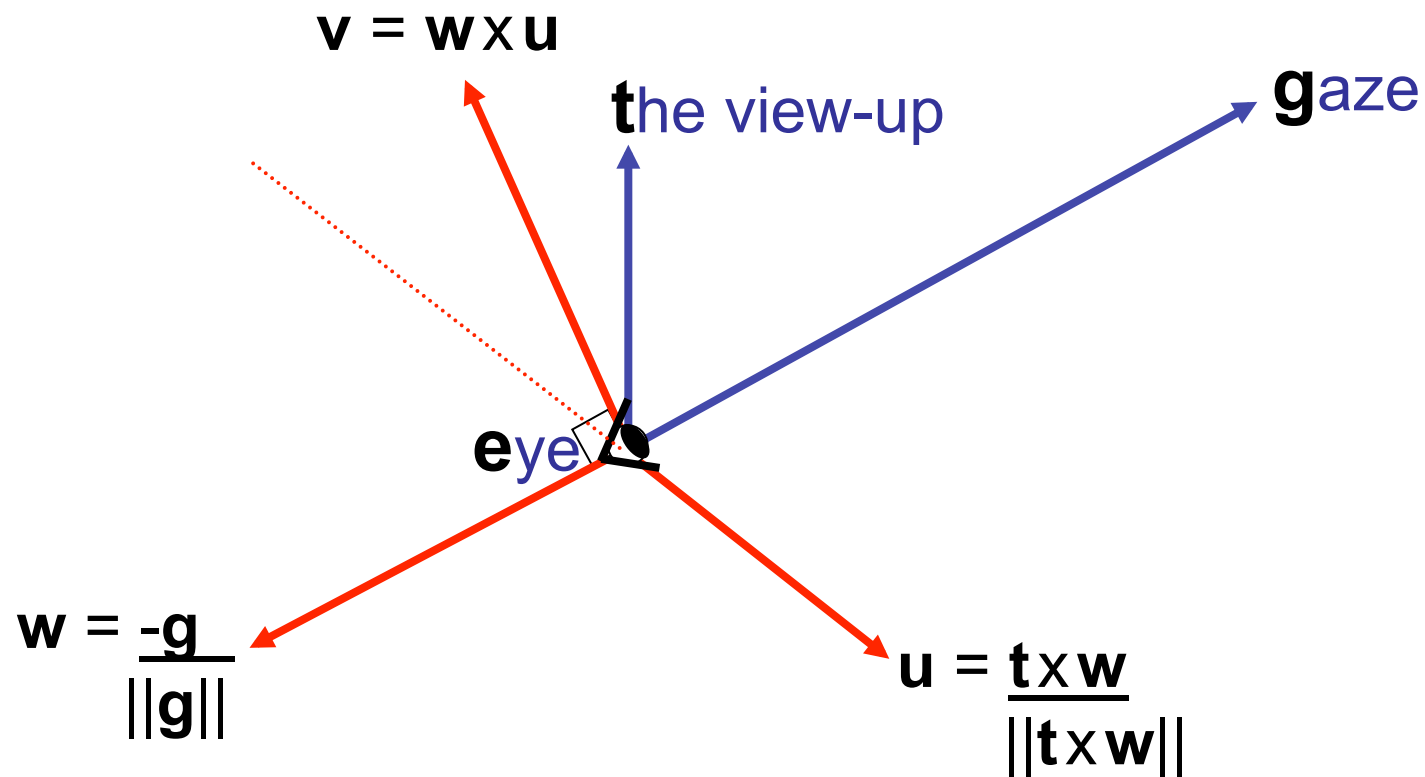
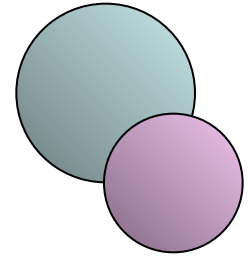
Orthographic Projection Math

$$M_o = \begin{bmatrix} \frac{n_x}{2} & 0 & 0 & 0 \\ 0 & \frac{n_y}{2} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} \frac{2}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2}{t-b} & 0 & 0 \\ 0 & 0 & \frac{2}{n-f} & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -\frac{l+r}{2} \\ 0 & 1 & 0 & -\frac{b+t}{2} \\ 0 & 0 & 1 & -\frac{n+f}{2} \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} x_{pixel} \\ y_{pixel} \\ z_{canonical} \\ 1 \end{bmatrix} = M_o \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix}$$

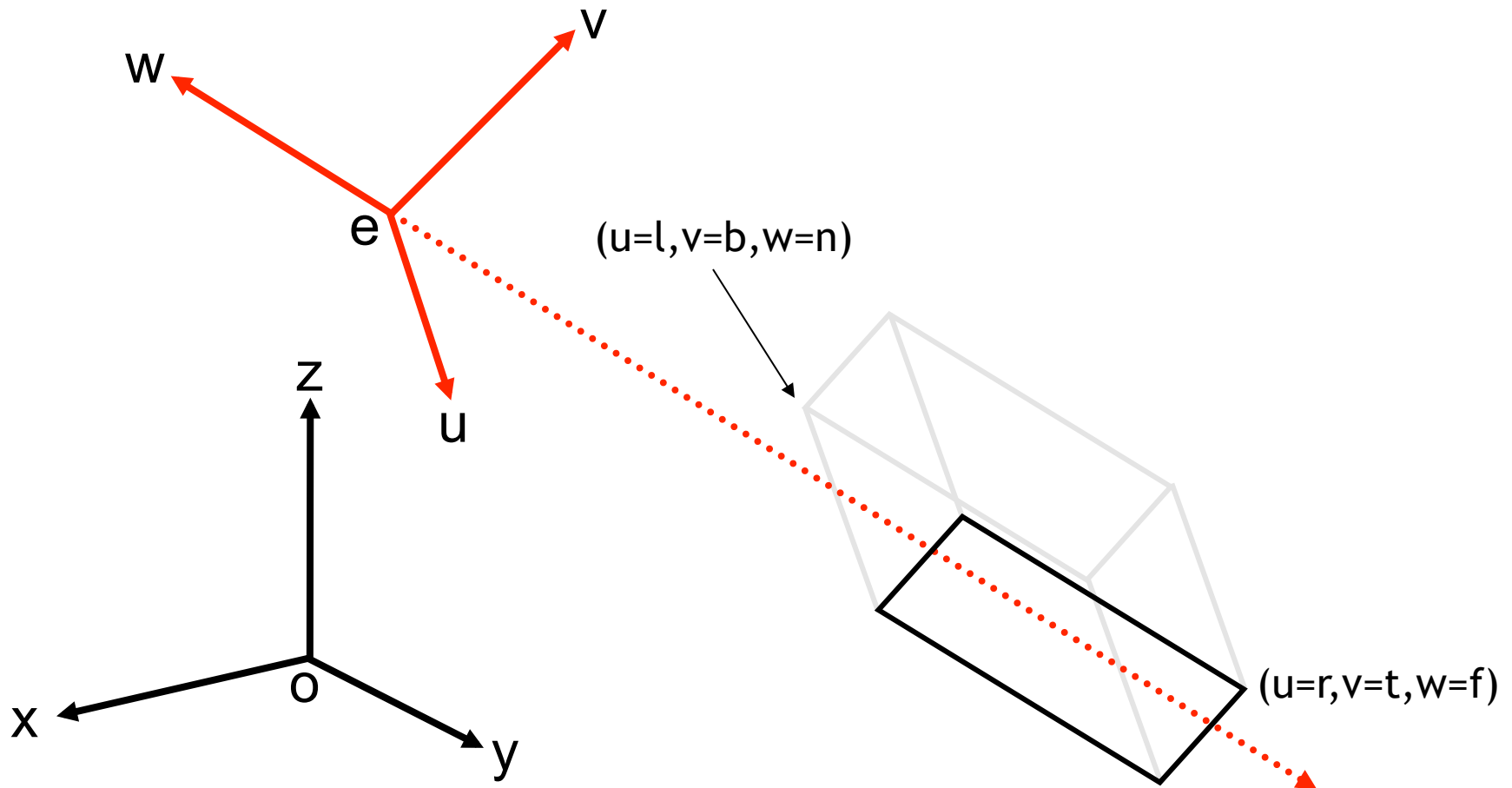


Arbitrary View Positions





Arbitrary Position Geometry





Arbitrary Position Transformation

Move e to the origin and align (u, v, w) with (x, y, z) .

$$M_v = \begin{bmatrix} x_u & y_u & z_u & 0 \\ x_v & y_v & z_v & 0 \\ x_w & y_w & z_w & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 & -x_e \\ 0 & 1 & 0 & -y_e \\ 0 & 0 & 1 & -z_e \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

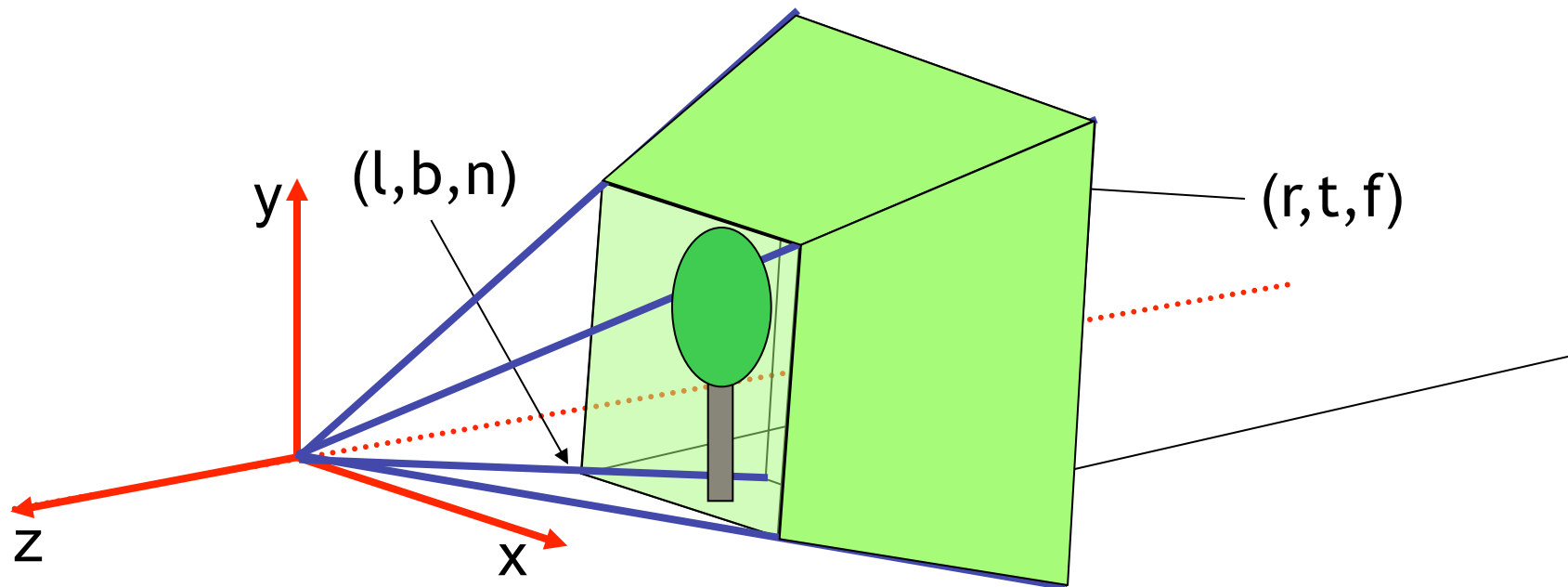
Compute $M = M_o M_v$.

For each line segment (a, b)

$$p = Ma, q = Mb, \text{ drawline}(p, q).$$

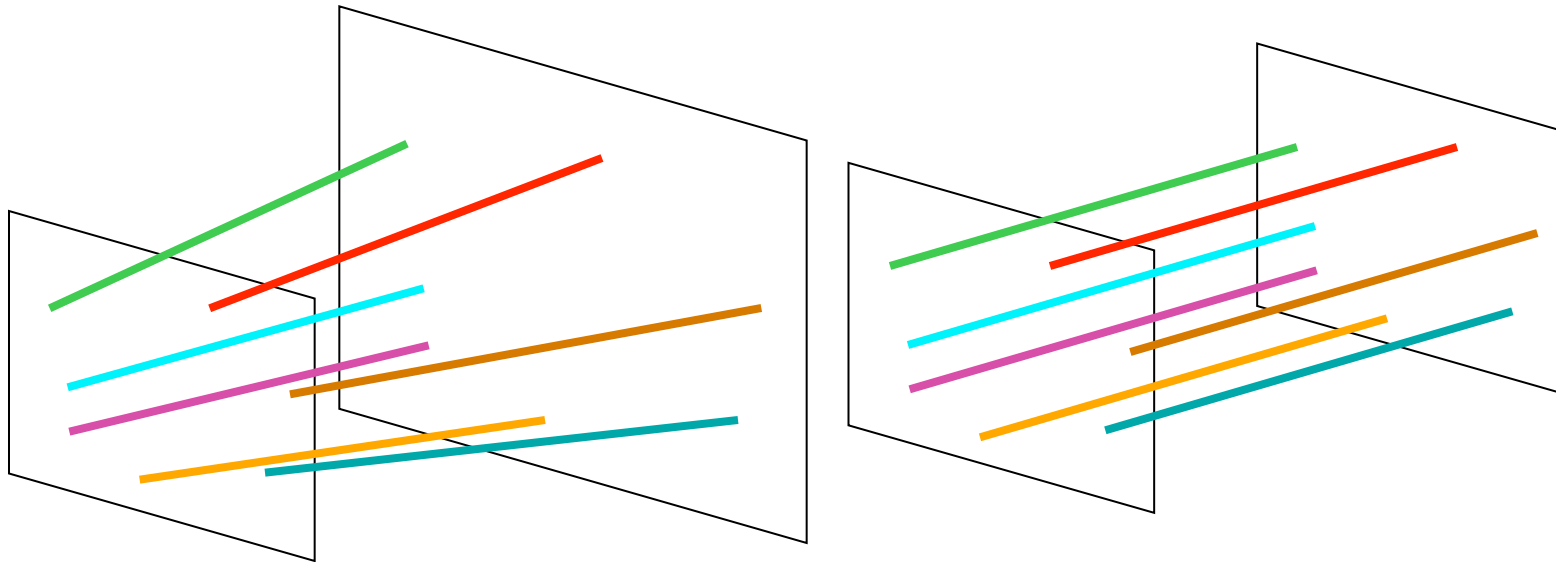


Perspective Projection



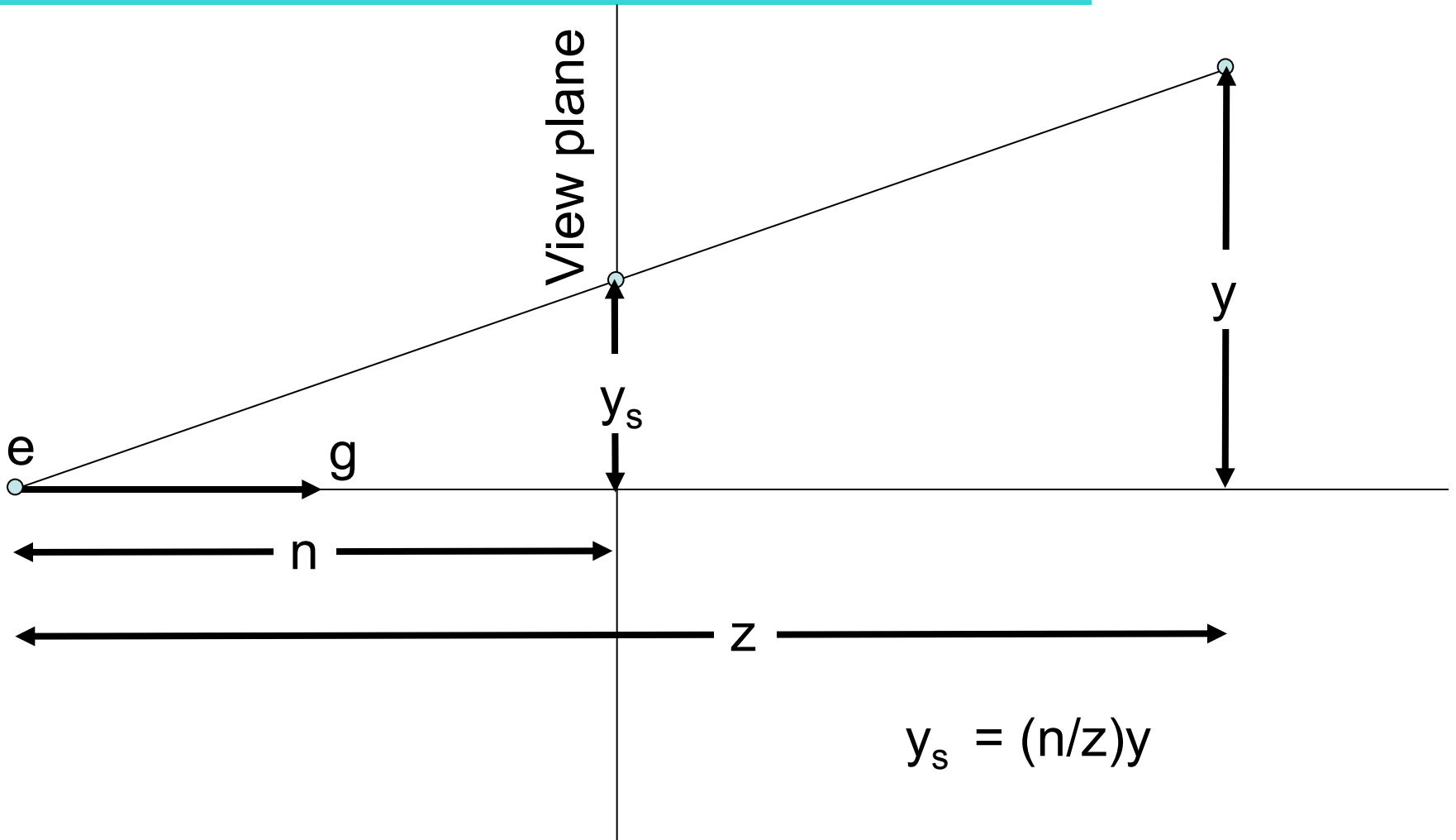


Lines to Lines





Perspective Geometry





Perspective Transformation

The perspective transformation should take

$$\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} nx / z \\ ny / z \\ p(z) \\ 1 \end{bmatrix}$$

Where

$$p(n) = n$$

$$p(f) = f$$

and

$$n \ll z_1 > z_2 \ll f$$

implies $p(z_1) > p(z_2)$.

$P(z) = n + f - fn/z$ satisfies these requirements.



Perspective Transformation

$$\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} nx/z \\ ny/z \\ n + f - fn/z \\ 1 \end{bmatrix} \text{ is not a linear transformation.}$$

$$\begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} nx \\ ny \\ nz + fz - fn \\ z \end{bmatrix} \text{ is a linear transformation.}$$



The Whole Truth about Homogeneous Coordinates

$$\begin{bmatrix} x \\ y \end{bmatrix} \leftrightarrow \left\{ \begin{bmatrix} hx \\ hy \\ h \end{bmatrix} \mid h \neq 0 \right\}$$

A point in 2-space corresponds to a line through the origin in 3-space minus the origin itself.

A point in 3-space corresponds to a line through the origin in 4-space minus the origin itself.



Homogenize

$$\begin{bmatrix} 6 \\ 14 \\ 2 \end{bmatrix} \xrightarrow{\text{homogenize}} \begin{bmatrix} 3 \\ 7 \\ 1 \end{bmatrix} \leftrightarrow \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 27 \\ 63 \\ 9 \end{bmatrix} \xrightarrow{\text{homogenize}} \begin{bmatrix} 3 \\ 7 \\ 1 \end{bmatrix} \leftrightarrow \begin{bmatrix} 3 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 22 \\ 121 \\ 77 \\ 11 \end{bmatrix} \xrightarrow{\text{homogenize}} \begin{bmatrix} 2 \\ 11 \\ 7 \\ 1 \end{bmatrix} \leftrightarrow \begin{bmatrix} 2 \\ 11 \\ 7 \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ 5.5 \\ 3.5 \\ .5 \end{bmatrix} \xrightarrow{\text{homogenize}} \begin{bmatrix} 2 \\ 11 \\ 7 \\ 1 \end{bmatrix} \leftrightarrow \begin{bmatrix} 2 \\ 11 \\ 7 \end{bmatrix}$$



Perspective Transformation Matrix

$$M_p = \begin{bmatrix} n & 0 & 0 & 0 \\ 0 & n & 0 & 0 \\ 0 & 0 & n+f & -fn \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad M_p \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} \rightarrow \begin{bmatrix} nx \\ ny \\ nz + fz - fn \\ z \end{bmatrix}$$

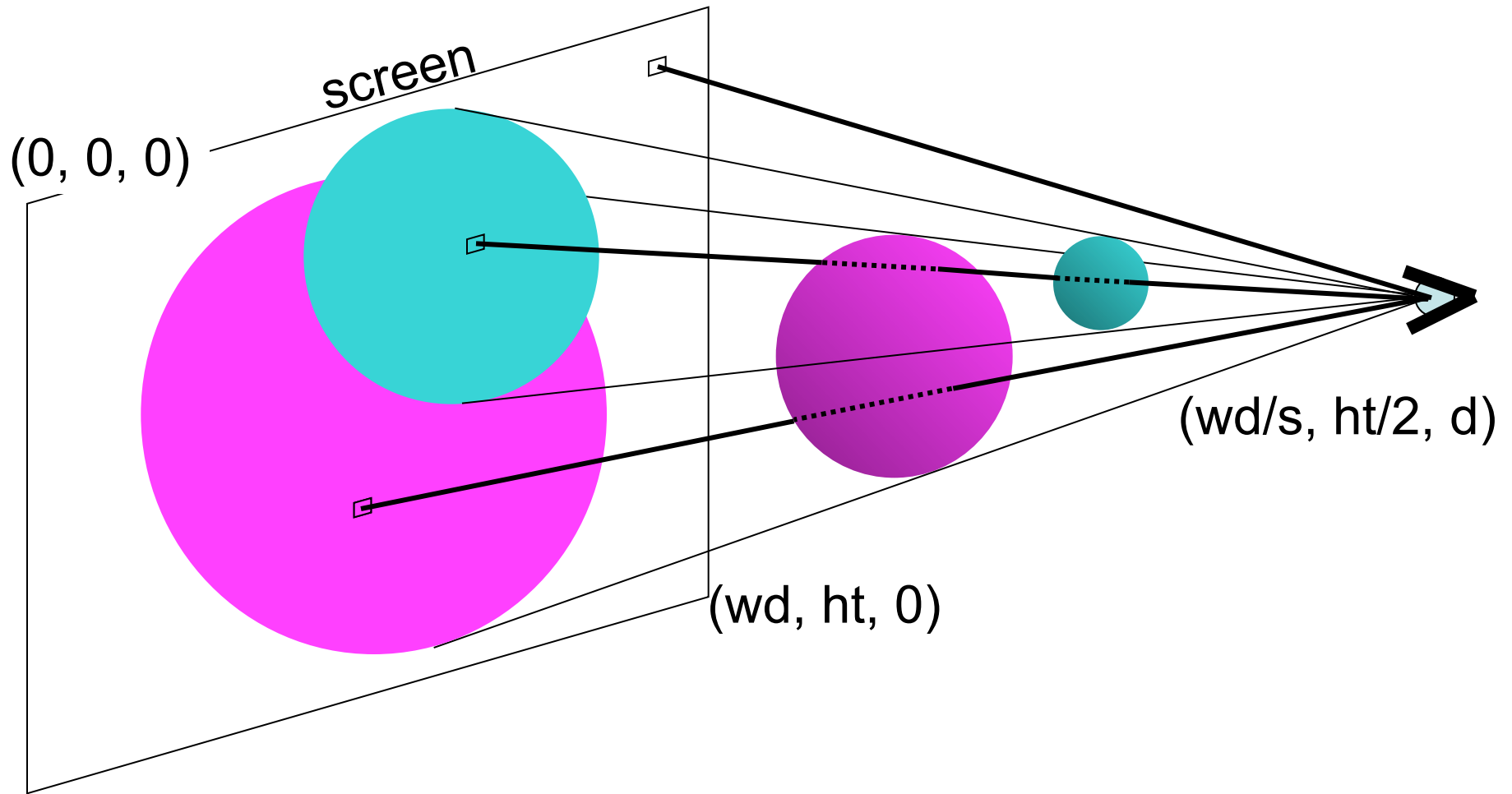
Compute $M = M_o M_p M_v$.

For each line segment (a, b)

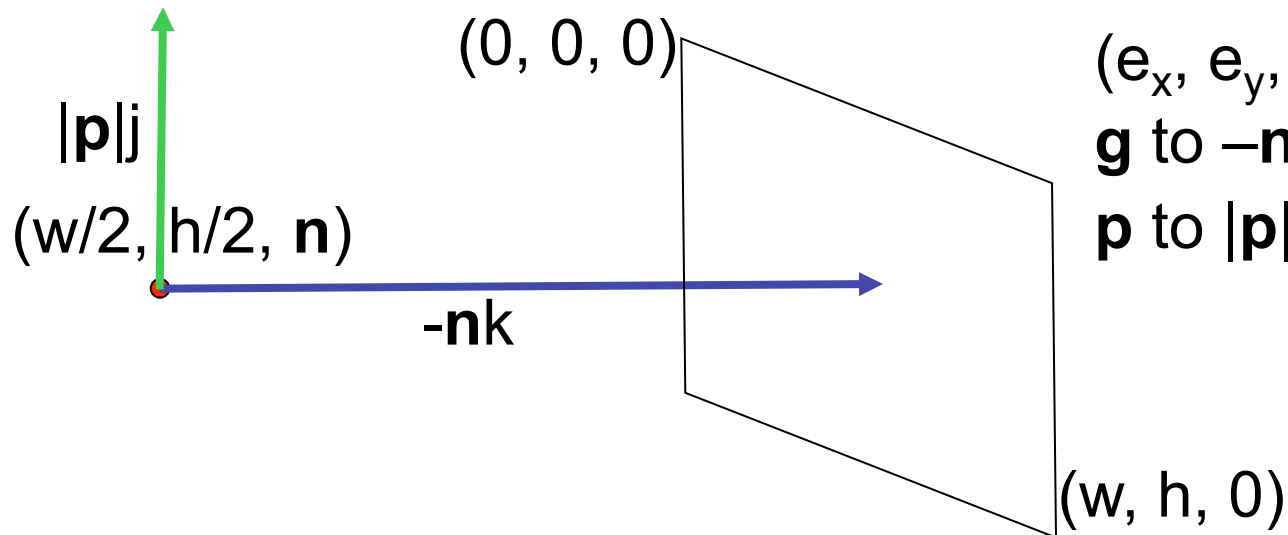
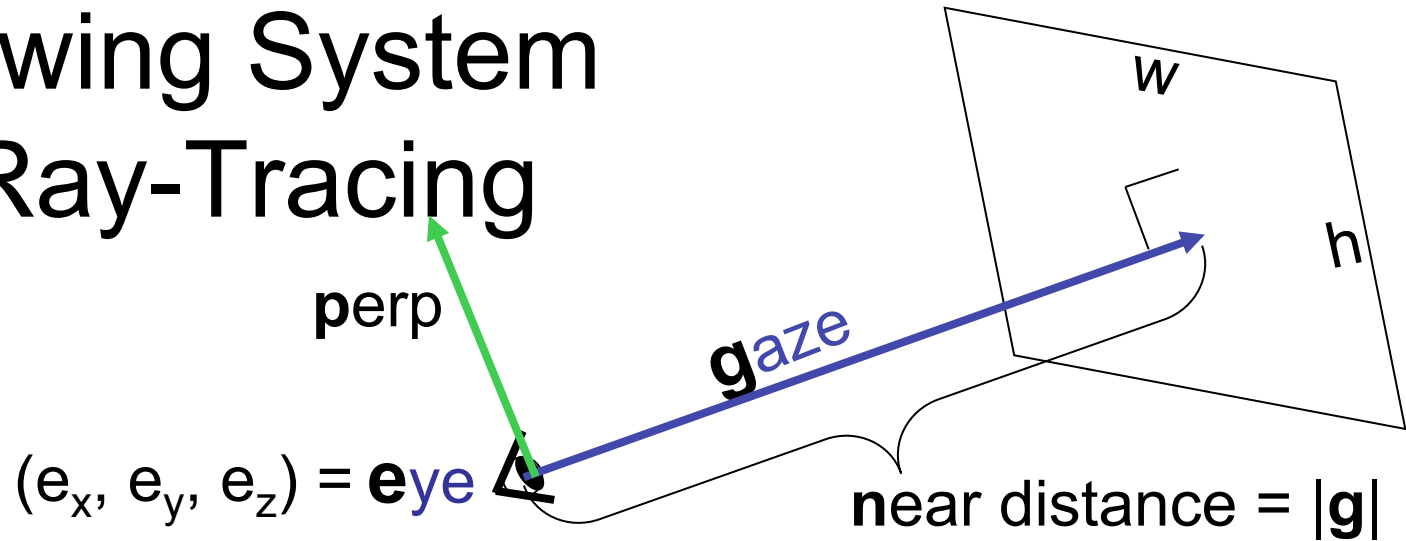
$$p = Ma, q = Mb, \text{ drawline}(\text{homogenize}(p), \text{homogenize}(q)).$$



Viewing for Ray-Tracing Simplest Views



A Viewing System for Ray-Tracing



You need a transformation that sends

(e_x, e_y, e_z) to $(w/2, h/2, n)$

g to $-nk$

p to $|p|j$



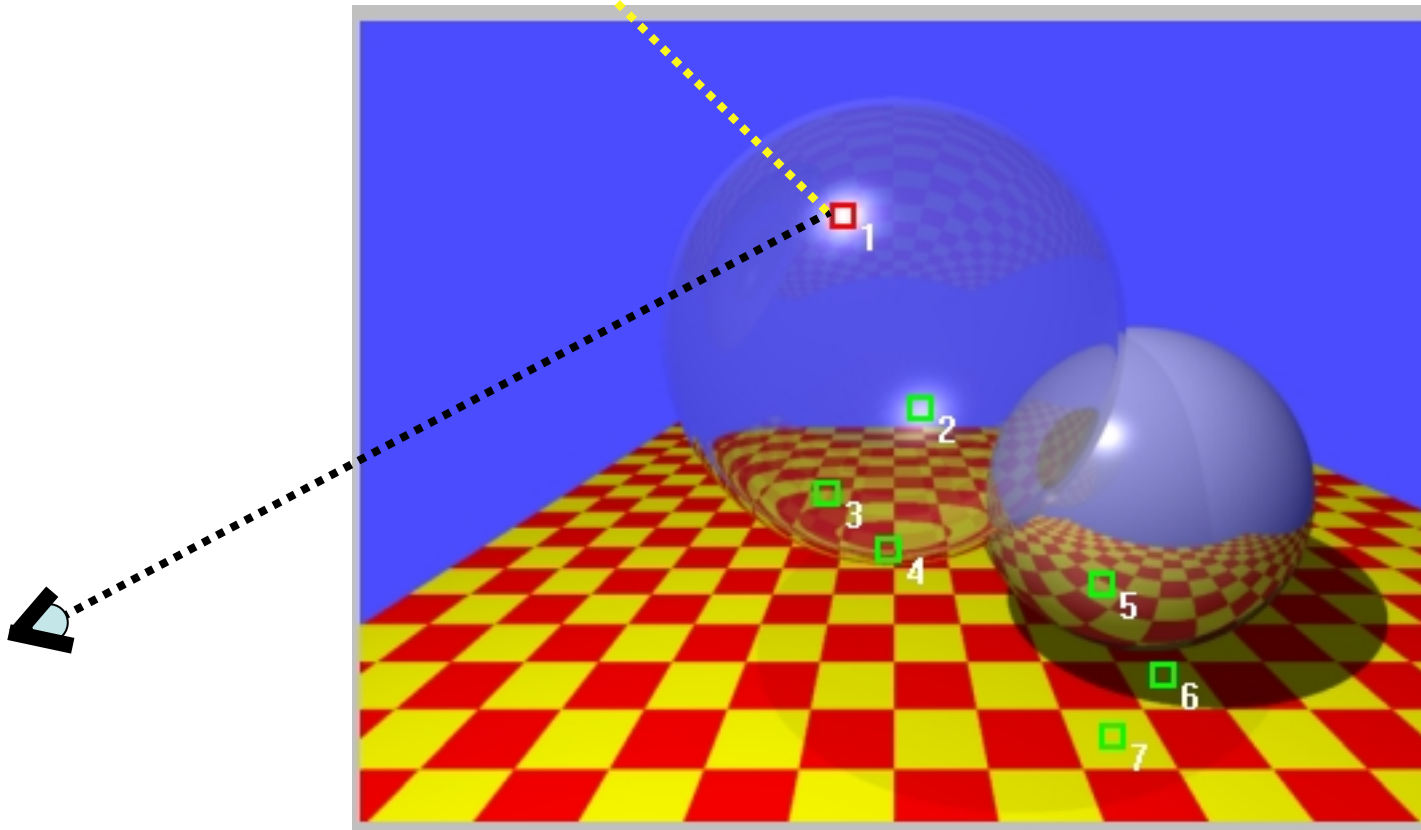
Time for a Break





Recursive Ray Tracing

Adventures of the 7 Rays - Watt

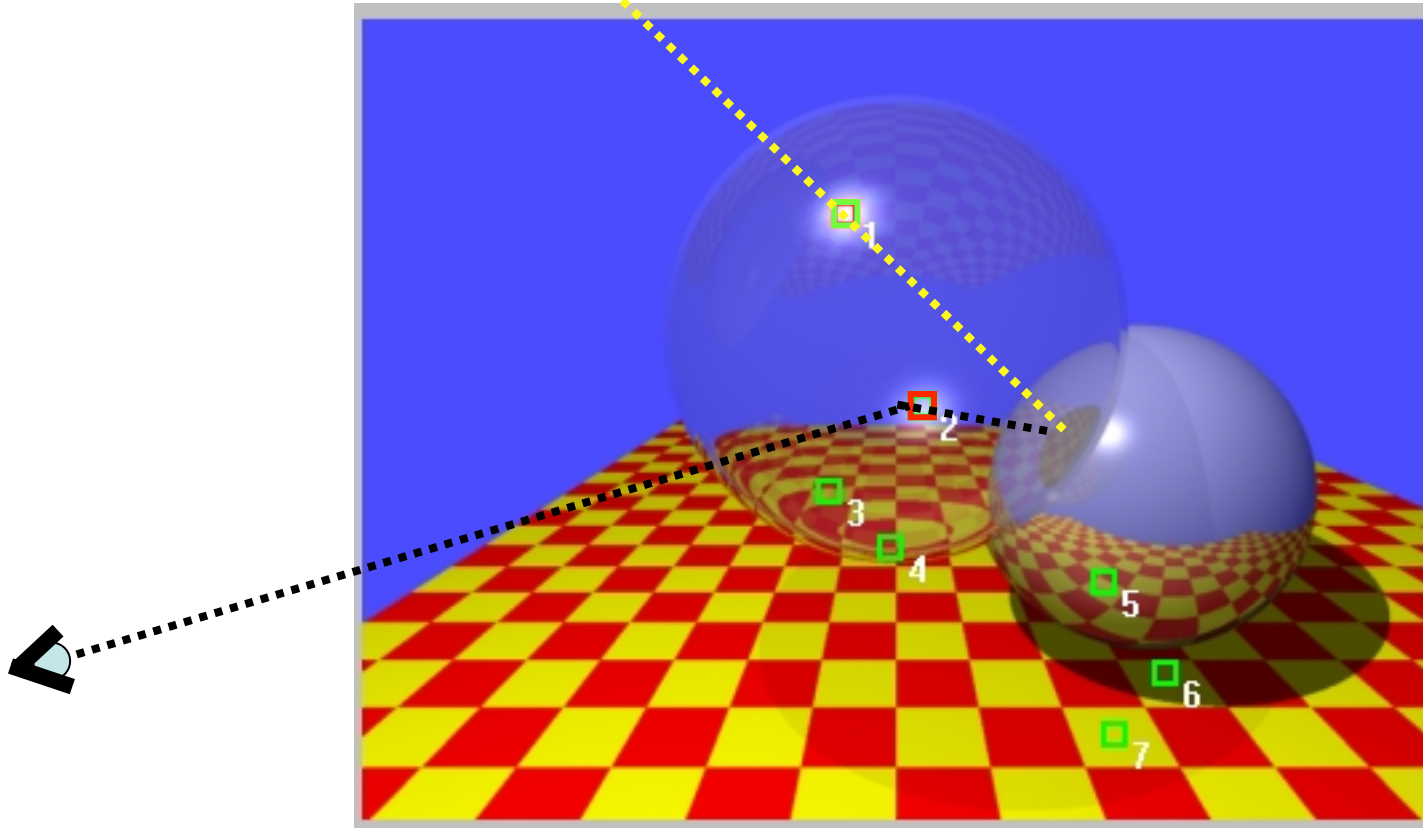


Specular Highlight on Outside of Sphere



Recursive Ray Tracing

Adventures of the 7 Rays - Watt

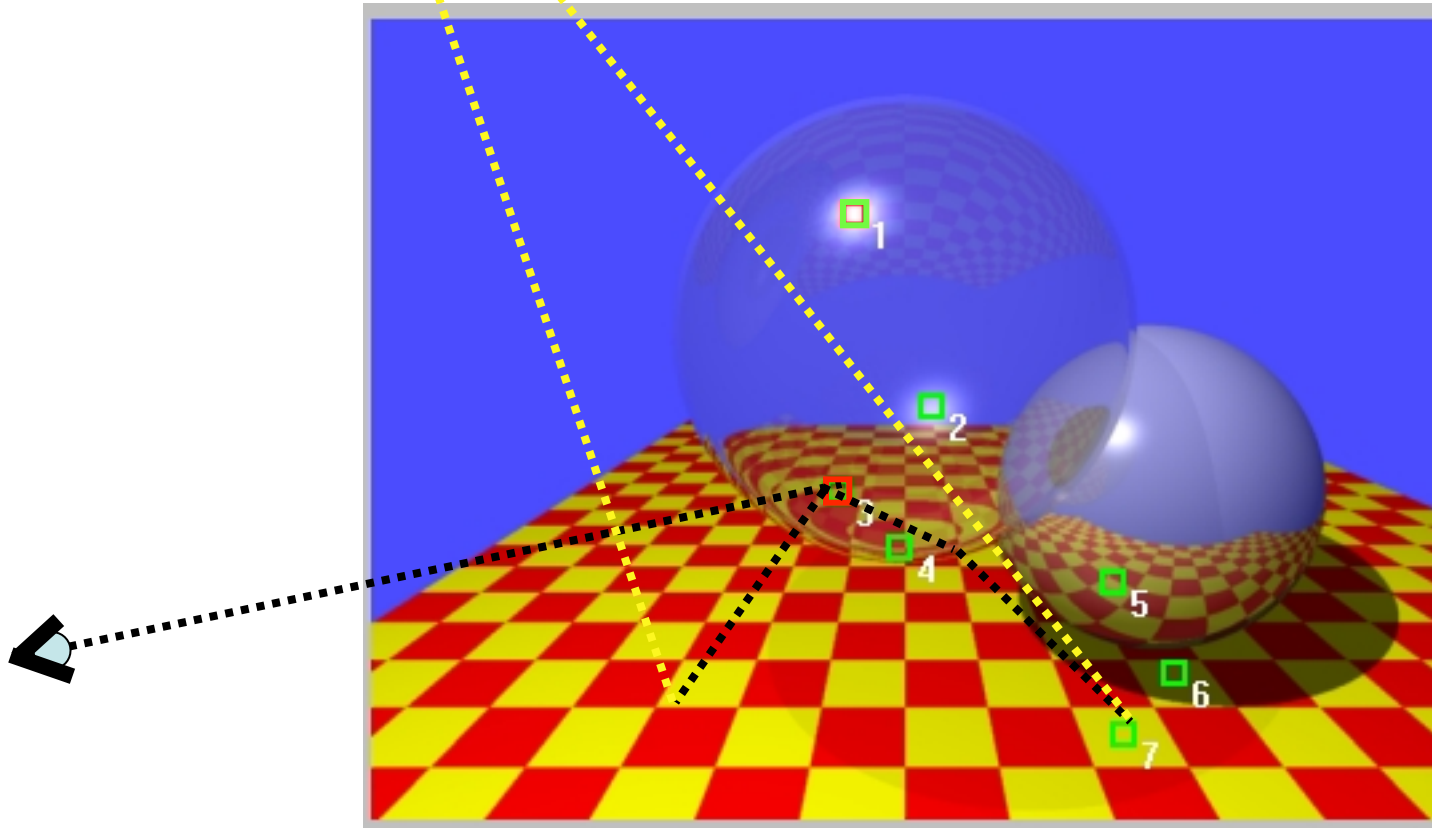


Specular Highlight on Inside of Sphere

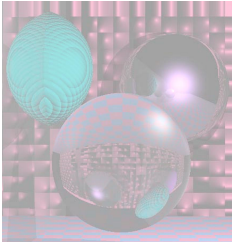


Recursive Ray Tracing

Adventures of the 7 Rays - Watt

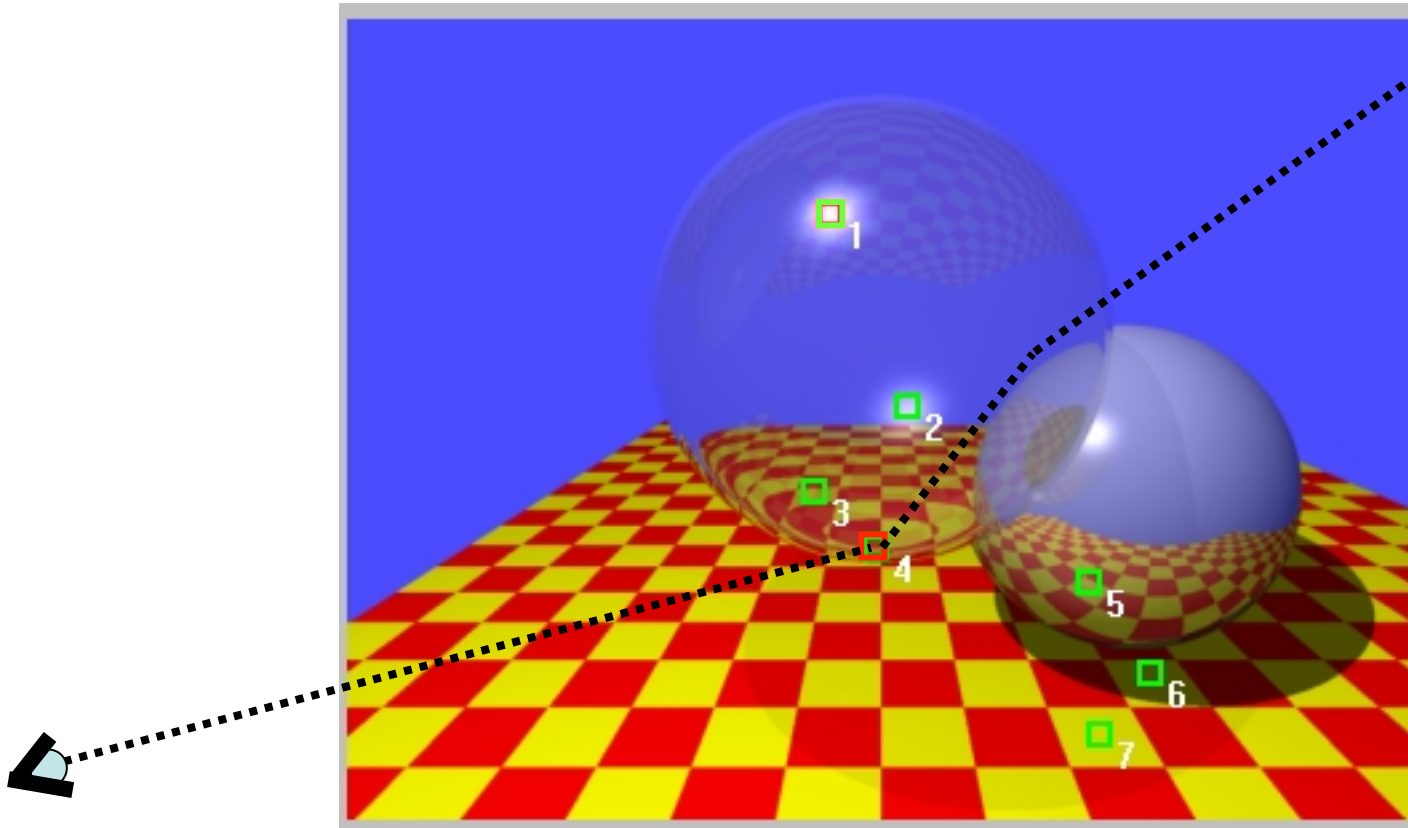


Reflection and Refraction of Checkerboard



Recursive Ray Tracing

Adventures of the 7 Rays - Watt

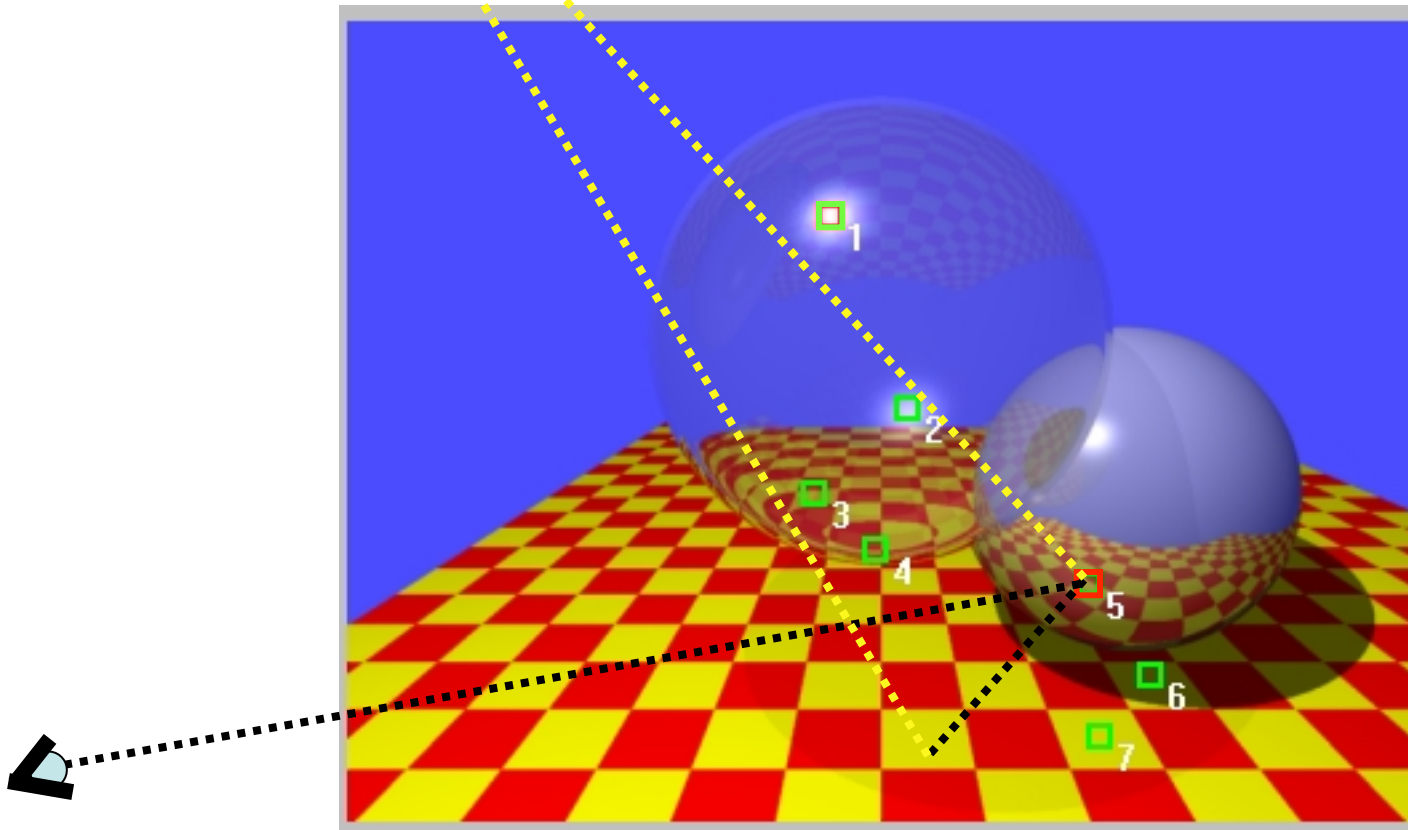


Refraction Hitting Background



Recursive Ray Tracing

Adventures of the 7 Rays - Watt

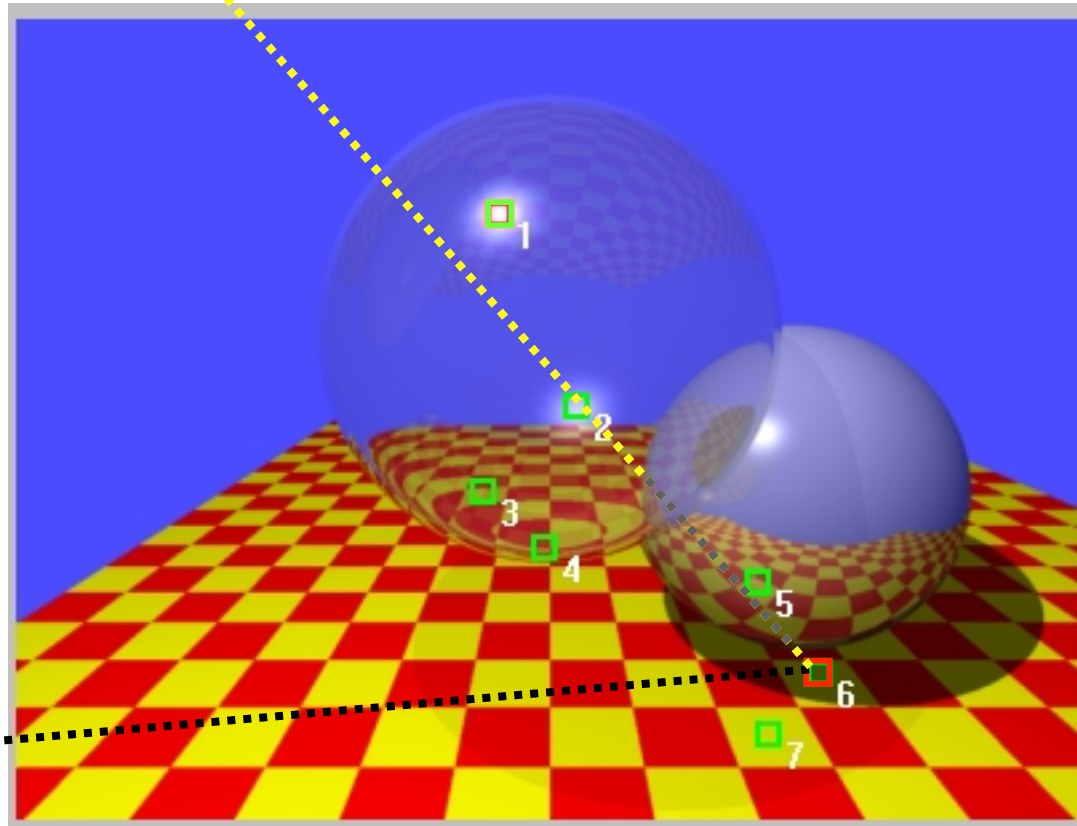


Local Diffuse Plus Reflection from Checkerboard



Recursive Ray Tracing

Adventures of the 7 Rays - Watt

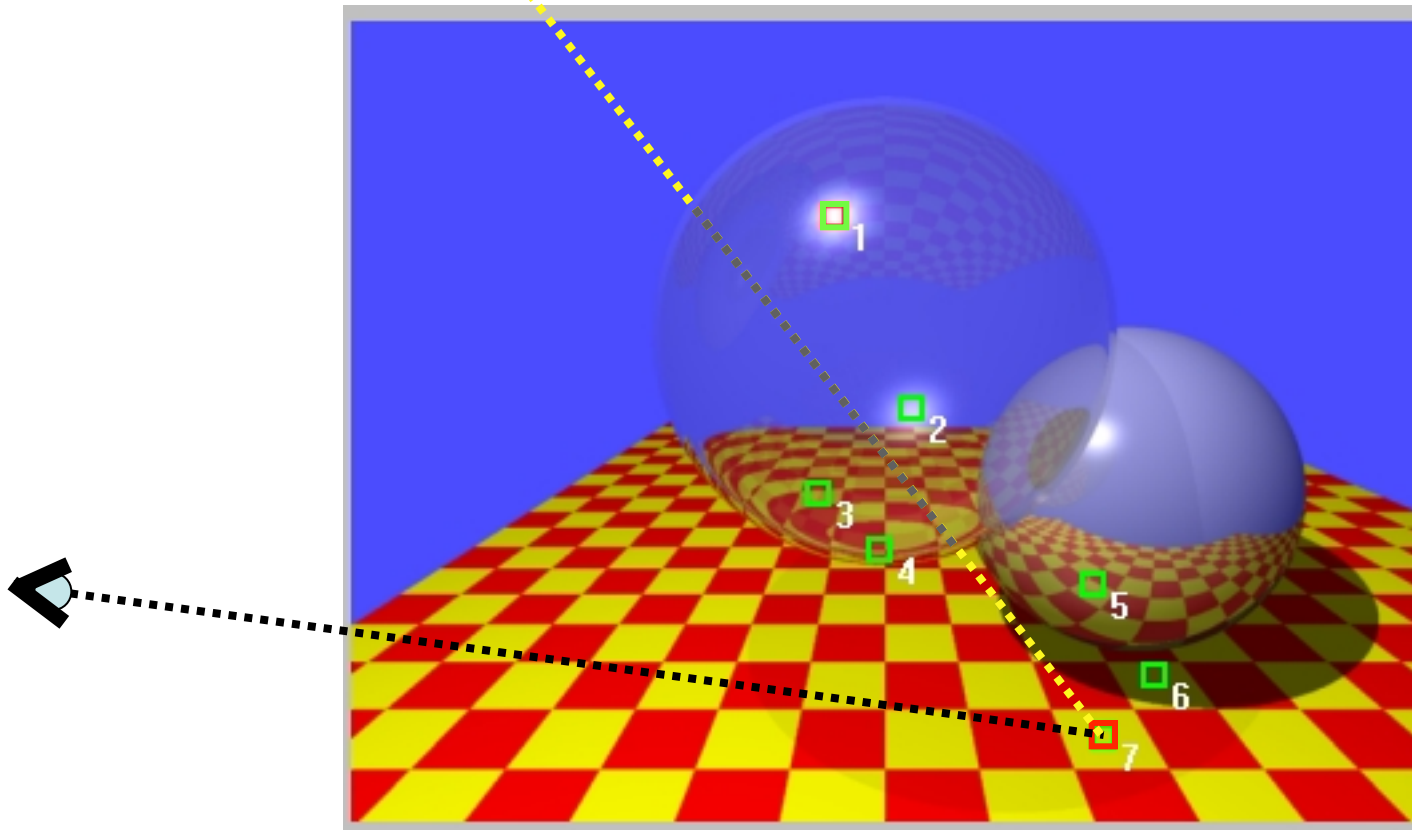


Local Diffuse in Complete Shadow

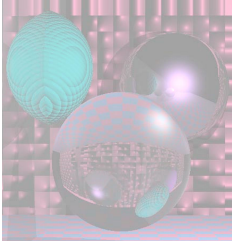


Recursive Ray Tracing

Adventures of the 7 Rays - Watt



Local Diffuse in Shadow from Transparent Sphere



Recursive Ray-Tracing

- How do we know which rays to follow?
- How do we compute those rays?
- How do we organize code so we can follow all those different rays?

```
select center of projection(cp) and window on view plane;  
for (each scan line in the image ) {  
    for (each pixel in scan line ) {  
        determine ray from the cp through the pixel;  
        pixel = RT_trace(ray, 1);}}
```

```
// intersect ray with objects; compute shade at closest intersection  
// depth is current depth in ray tree
```

```
RT_color RT_trace (RT_ray ray; int depth){  
    determine closest intersection of ray with an object;  
    if (object hit) {  
        compute normal at intersection;  
        return RT_shade (closest object hit, ray, intersection, normal,  
                        depth);}  
    else  
        return BACKGROUND_VALUE;  
}
```

```

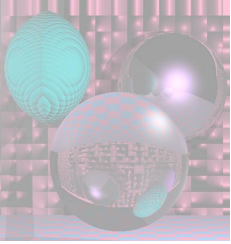
// Compute shade at point on object,
// tracing rays for shadows, reflection, refraction.
RT_color RT_shade (
    RT_object object, // Object intersected
    RT_ray ray,       // Incident ray
    RT_point point,   // Point of intersection to shade
    RT_normal normal, // Normal at point
    int depth )      // Depth in ray tree
{
    RT_color color; // Color of ray
    RT_ray rRay, tRay, sRay; // Reflected, refracted, and shadow ray
    color = ambient term ;
    for ( each light ) {
        sRay = ray from point to light ;
        if ( dot product of normal and direction to light is positive ){
            compute how much light is blocked by opaque and
            transparent surfaces, and use to scale diffuse and specular
            terms before adding them to color;}}
    }
}

```

```

if ( depth < maxDepth ) { // return if depth is too deep
    if ( object is reflective ) {
        rRay = ray in reflection direction from point;
        rColor = RT_trace(rRay, depth + 1);
        scale rColor by specular coefficient and add to color;
    }
    if ( object is transparent ) {
        tRay = ray in refraction direction from point;
        if ( total internal reflection does not occur ) {
            tColor = RT_trace(tRay, depth + 1);
            scale tColor by transmission coefficient
            and add to color;
        }
    }
}
return color; // Return the color of the ray
}

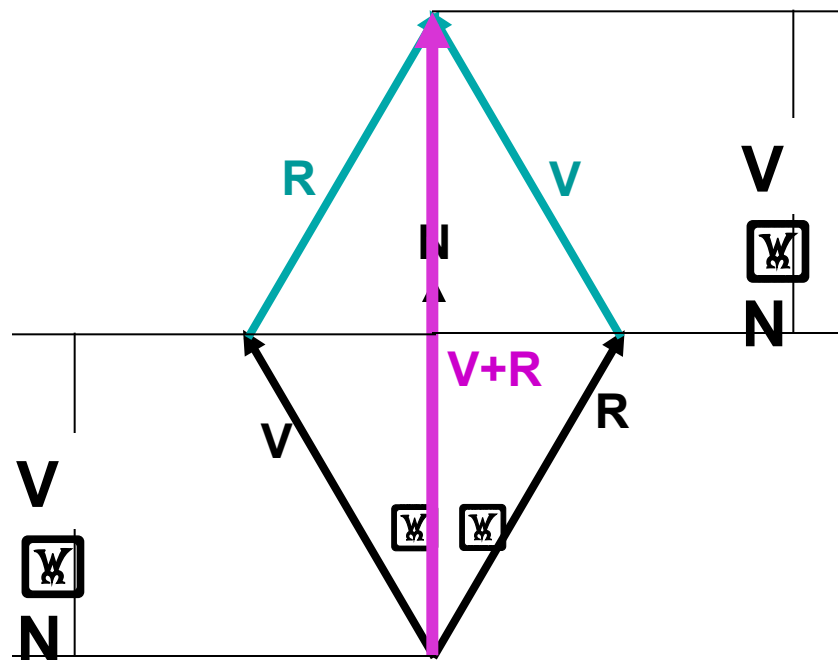
```

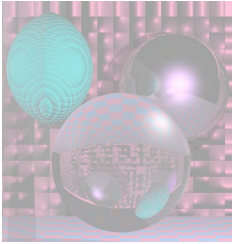



Computing R

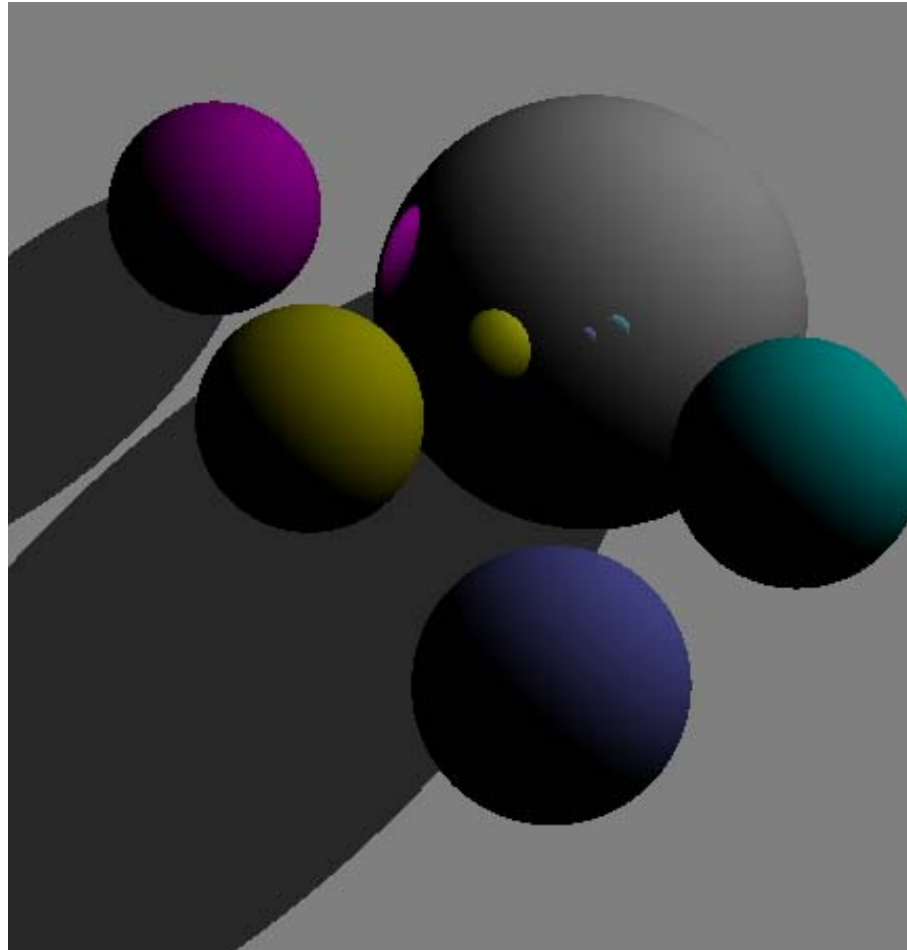
$$V + R = (2 V \cdot N) N$$

$$R = (2 V \cdot N) N - V$$



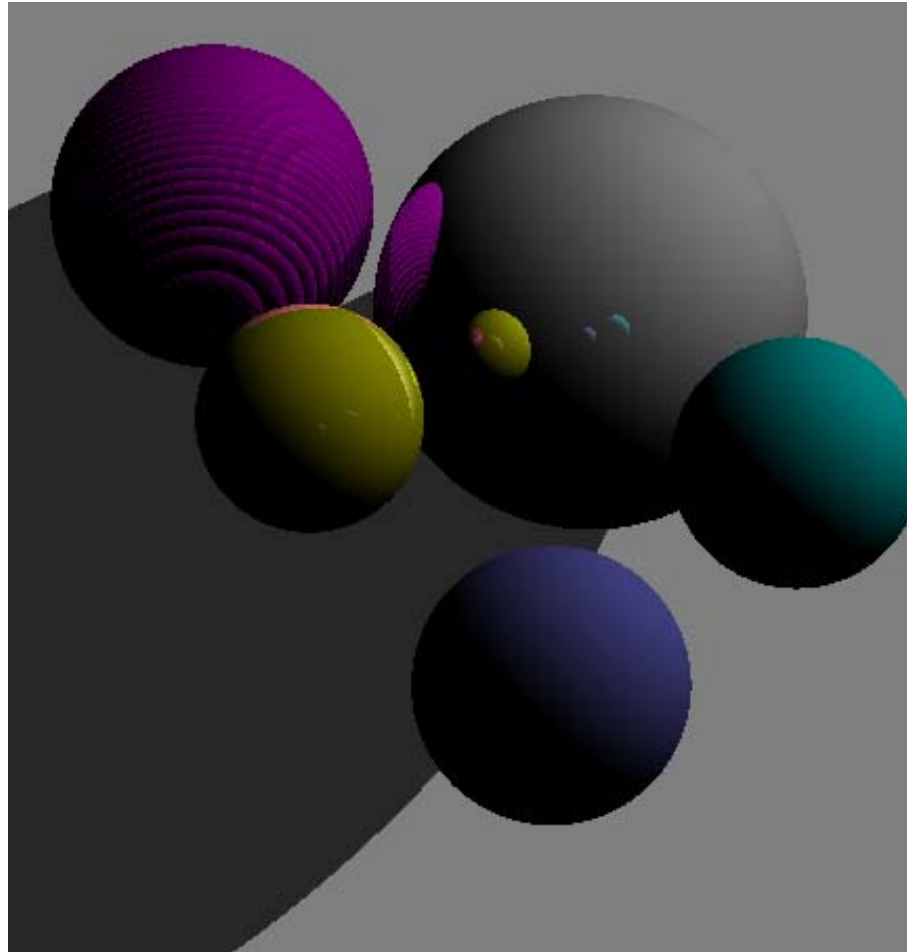


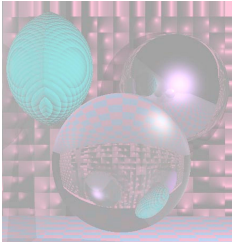
Reflections, no Highlight



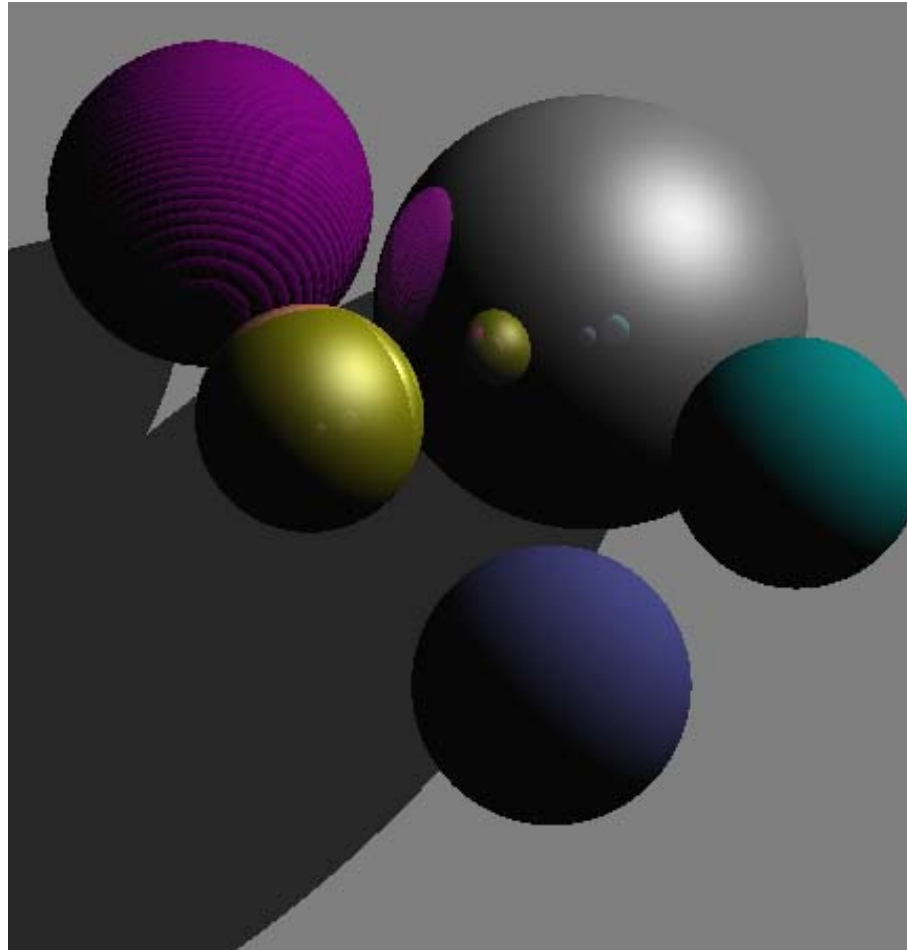


Second Order Reflection



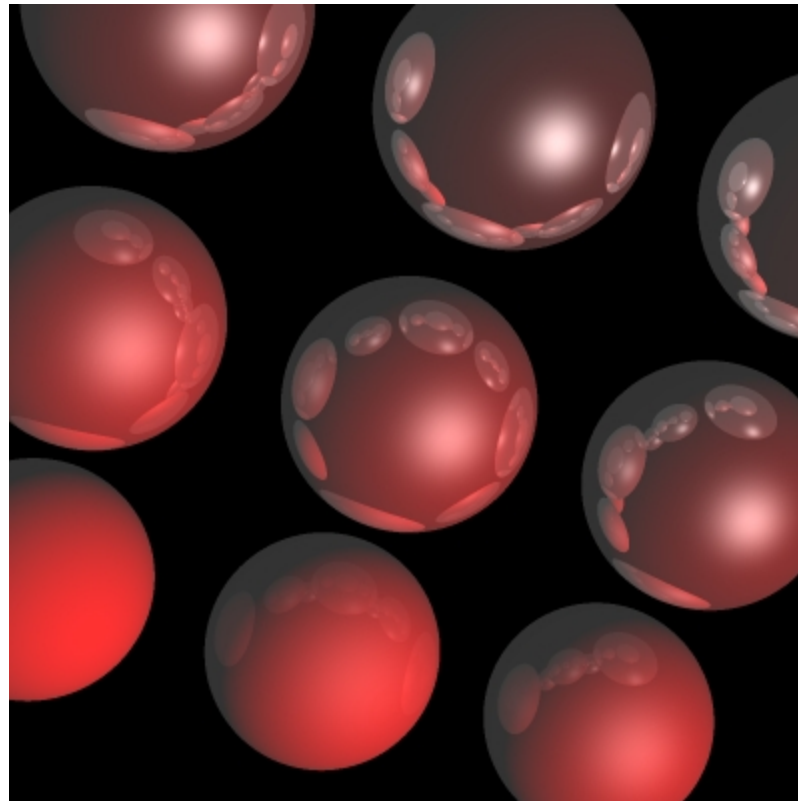


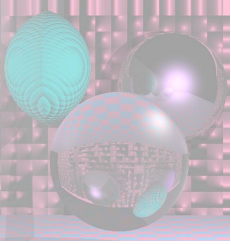
Refelction with Highlight





Nine Red Balls

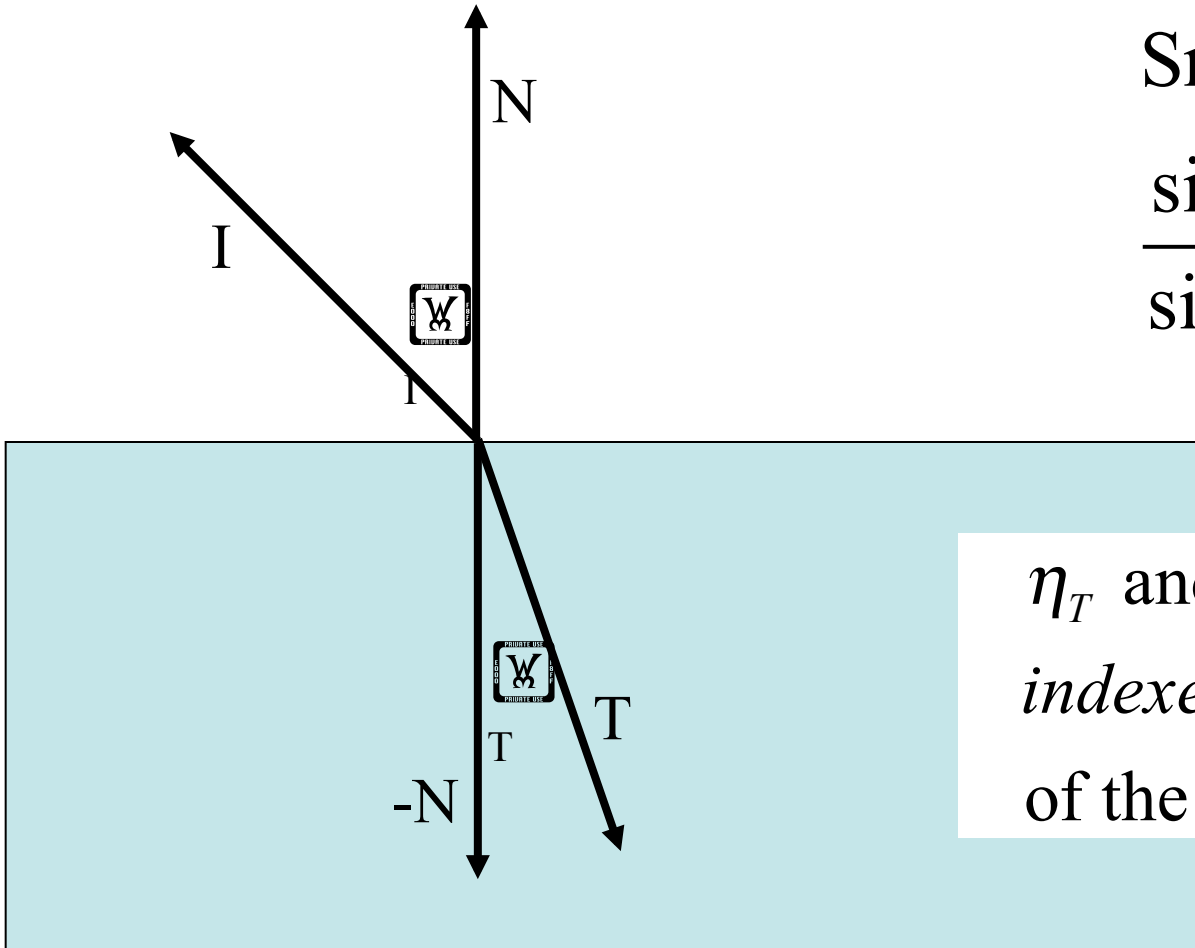




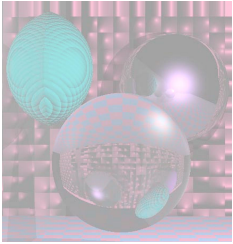
Refraction

Snell's Law

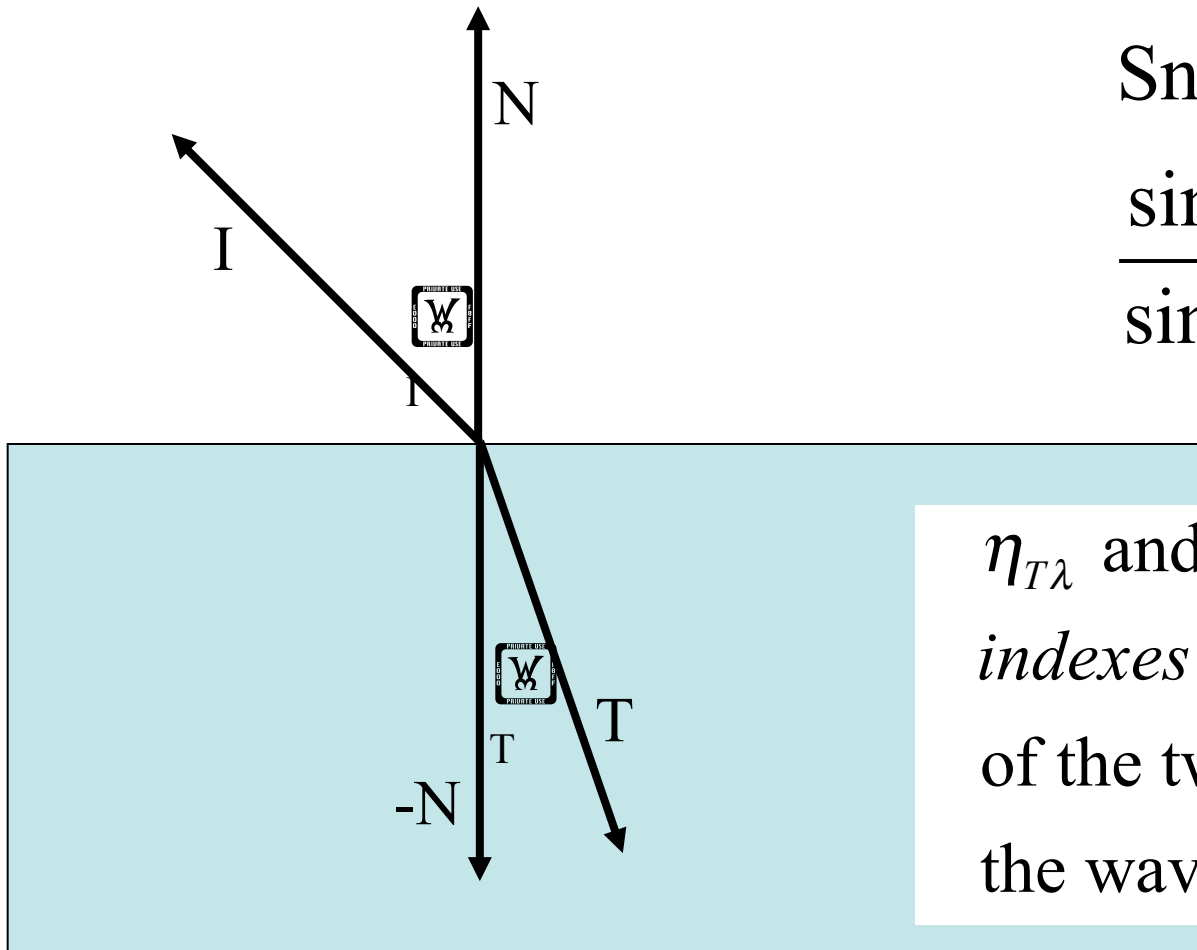
$$\frac{\sin(\theta_I)}{\sin(\theta_T)} = \frac{\eta_T}{\eta_I}$$



η_T and η_I are the
indexes of refraction
of the two mediums.



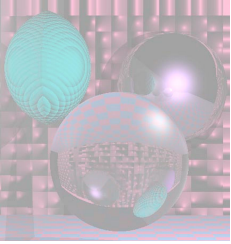
Refraction and Wavelength



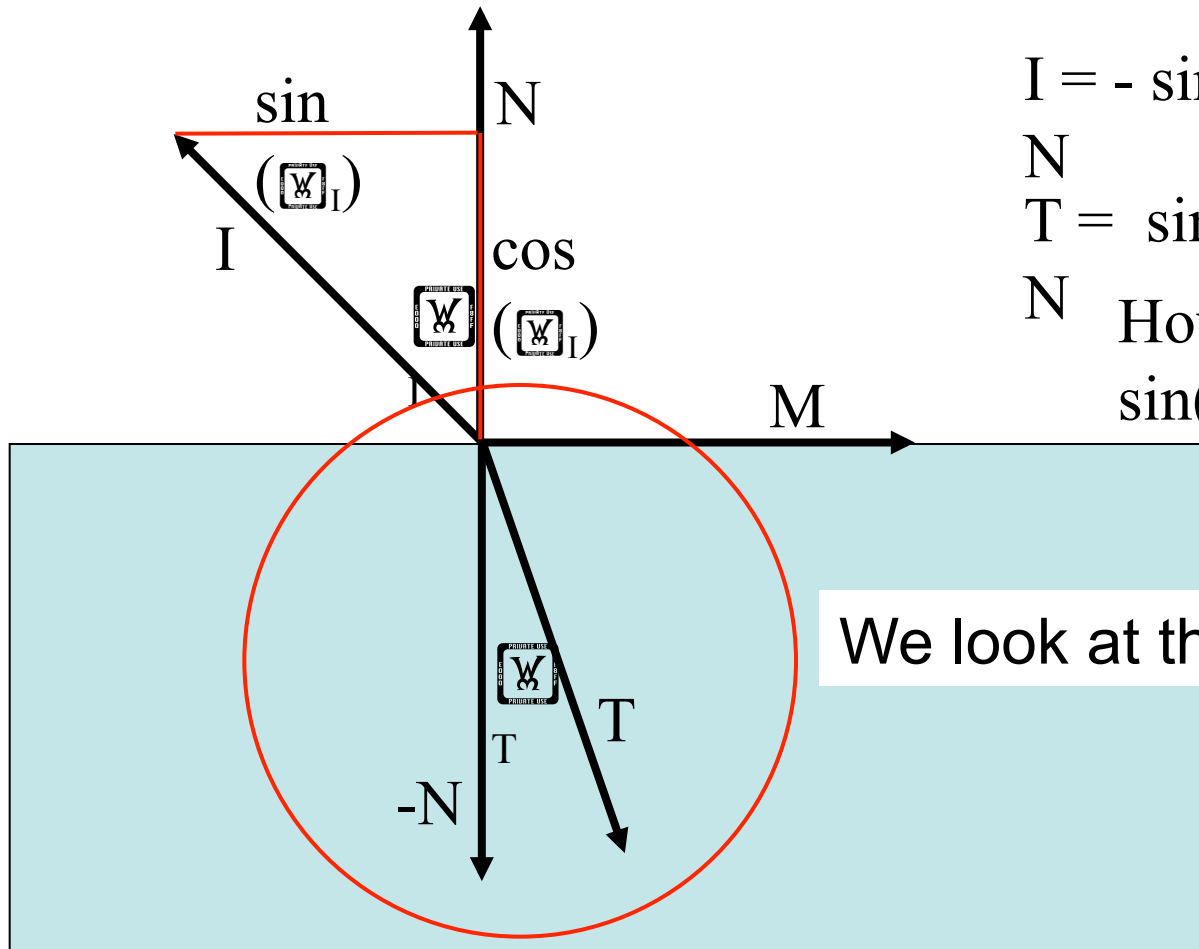
Snell's Law

$$\frac{\sin(\theta_I)}{\sin(\theta_T)} = \frac{\eta_{T\lambda}}{\eta_{I\lambda}}$$

$\eta_{T\lambda}$ and $\eta_{I\lambda}$ are the
indexes of refraction
of the two mediums for
the wavelength of light λ .



Computing T



$$I = -\sin(\Psi_I)M + \cos(\Psi_I)N$$

N

$$T = \sin(\Psi_T)M - \cos(\Psi_T)N$$

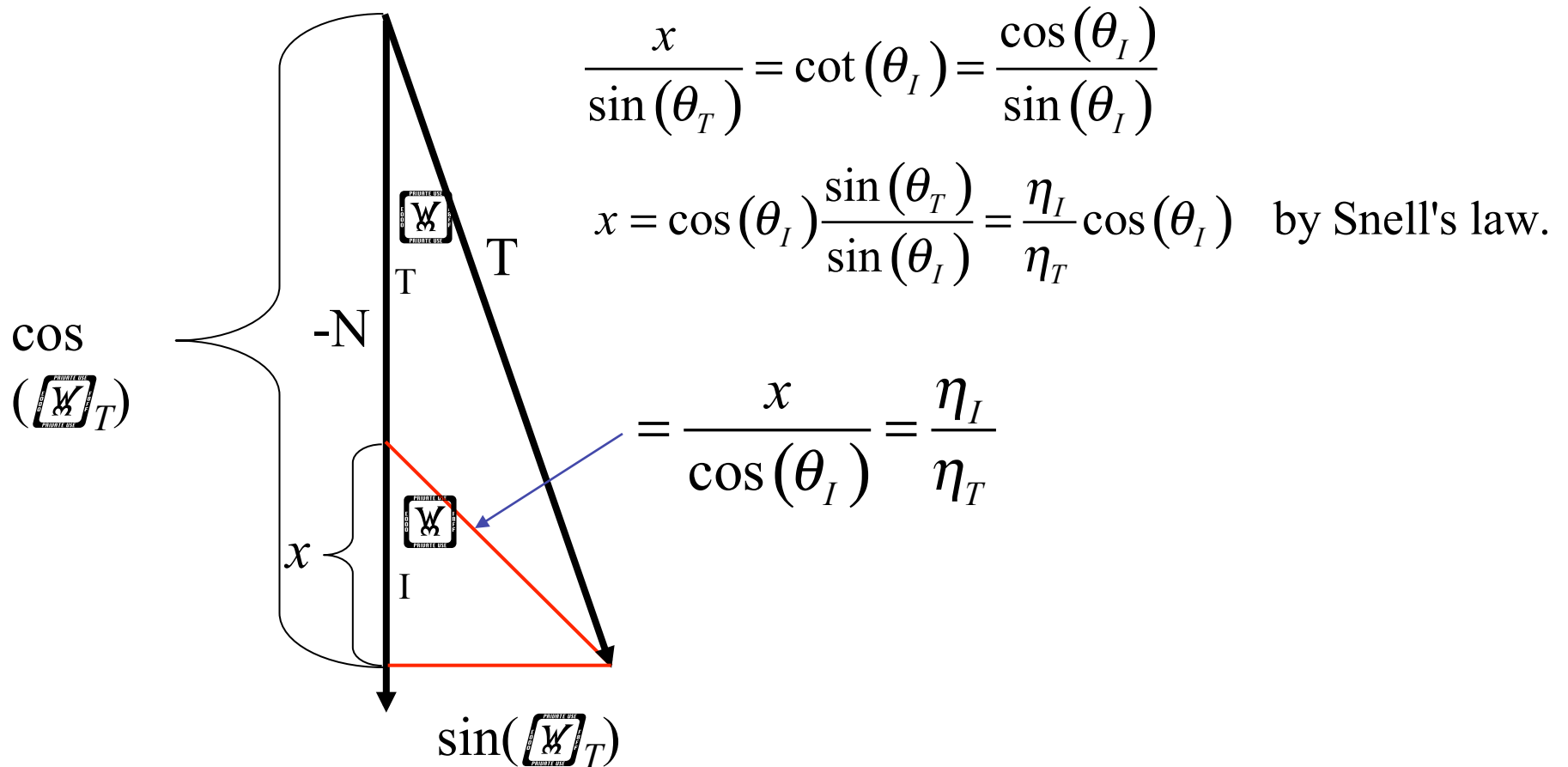
N

How do we compute M, $\sin(\Psi_T)$, and $\cos(\Psi_T)$?

We look at this in more detail



Computing T



Computing T

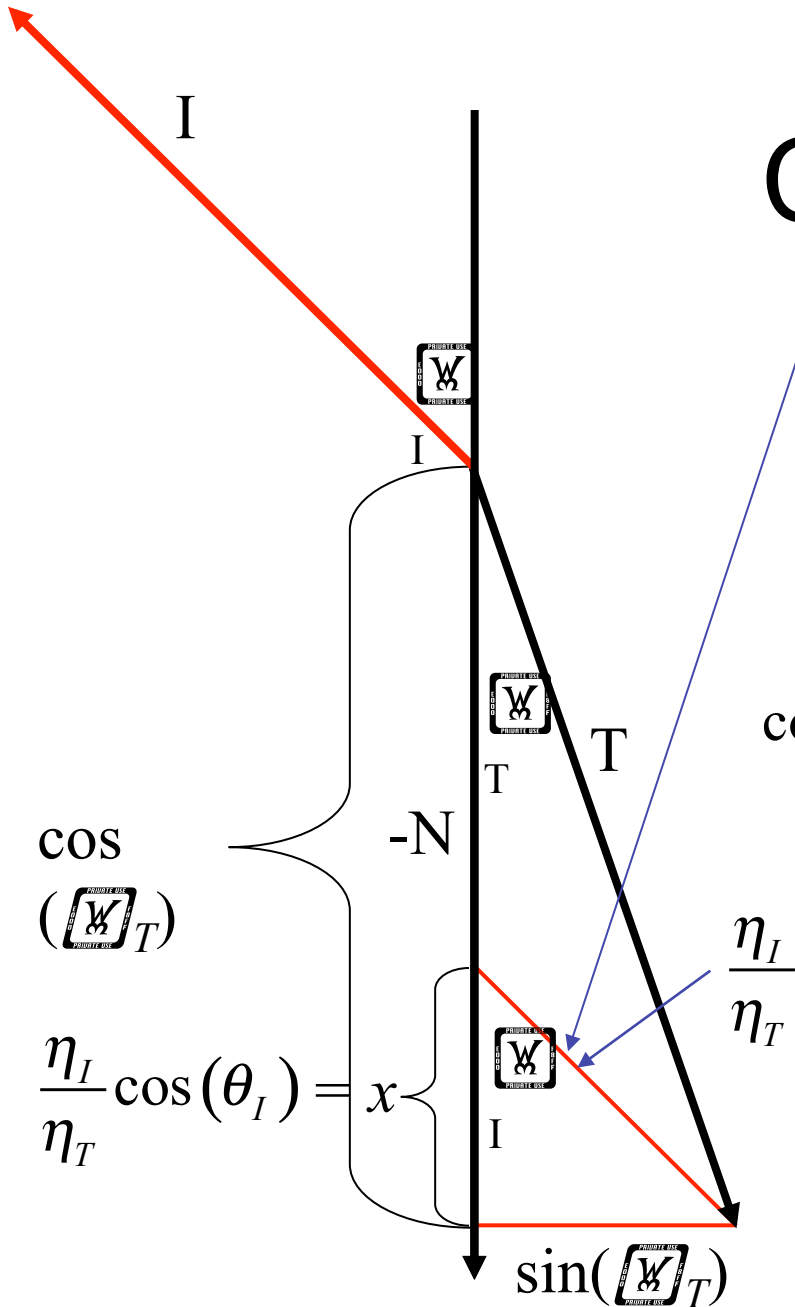
Parallel to I

$$T = - \left(\cos(\theta_T) - \frac{\eta_I}{\eta_T} \cos(\theta_I) \right) N - \frac{\eta_I}{\eta_T} I$$

$$\cos(\theta_T) = \sqrt{1 - \sin^2(\theta_T)} = \sqrt{1 - \left(\frac{\eta_I}{\eta_T} \right)^2 \sin^2(\theta_I)}$$

$$= \sqrt{1 - \left(\frac{\eta_I}{\eta_T} \right)^2 (1 - \cos^2(\theta_I))}$$

$$= \sqrt{1 - \left(\frac{\eta_I}{\eta_T} \right)^2 (1 - (N \cdot I)^2)}$$





Total Internal Reflection

$$\cos(\theta_T) = \sqrt{1 - \left(\frac{\eta_I}{\eta_T}\right)^2 (1 - (N \cdot I)^2)}$$

When is $\cos(\theta_T)$ defined?

$$\text{When } 1 - \left(\frac{\eta_I}{\eta_T}\right)^2 (1 - (N \cdot I)^2) \geq 0.$$

If $\eta_I > \eta_T$ and $N \cdot I$ is close to 0, $\cos(\theta_T)$ may not be defined.

Then there is no transmitting ray and we have

total internal reflection.



Index of Refraction

The speed of all electromagnetic radiation in vacuum is the same, approximately 3×10^8 meters per second, and is denoted by c . Therefore, if v is the phase velocity of radiation of a specific frequency in a specific material, the refractive index is given by

$$\eta = \frac{c}{v}$$

http://en.wikipedia.org/wiki/Refractive_index



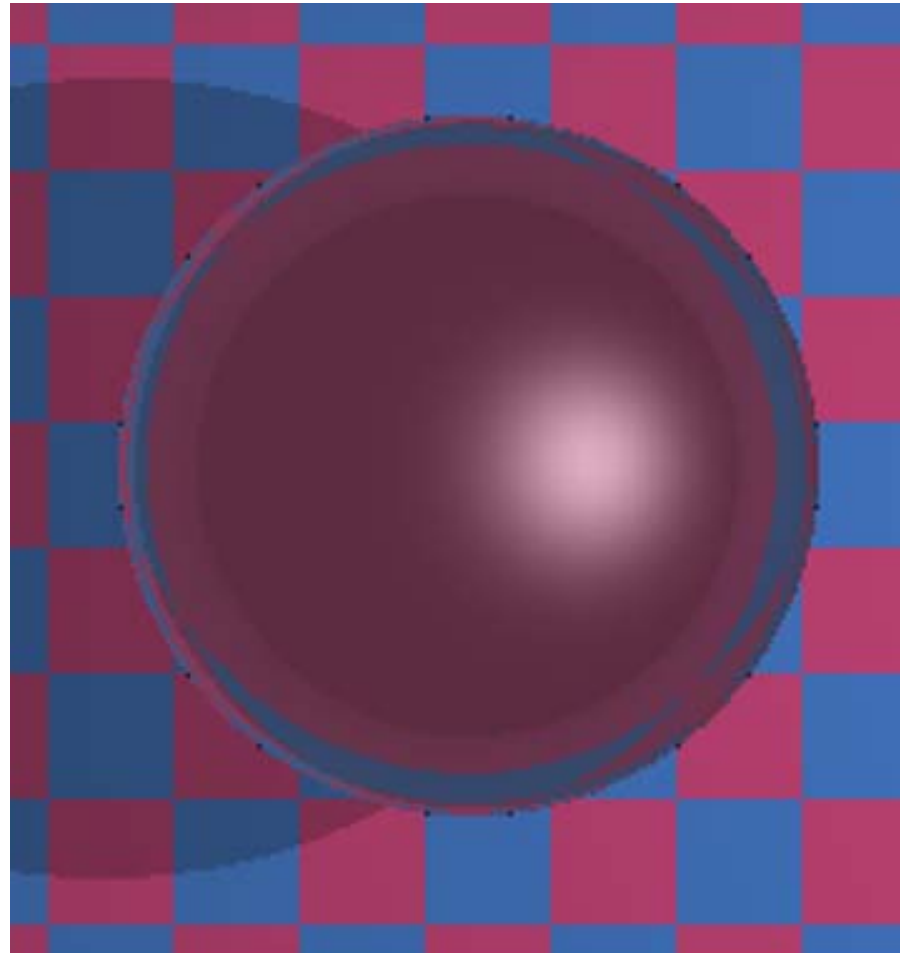
Indices of Refraction

Material	n_D at $\lambda=589.3$ nm
vacuum	1 (exactly)
helium	1.000036
air at STP	1.0002926
water ice	1.31
liquid water (20°C)	1.333
ethanol	1.36
glycerine	1.4729
rock salt	1.516
glass (typical)	1.5 to 1.9
cubic zirconia	2.15 to 2.18
diamond	2.419

http://en.wikipedia.org/wiki/List_of_indices_of_refraction

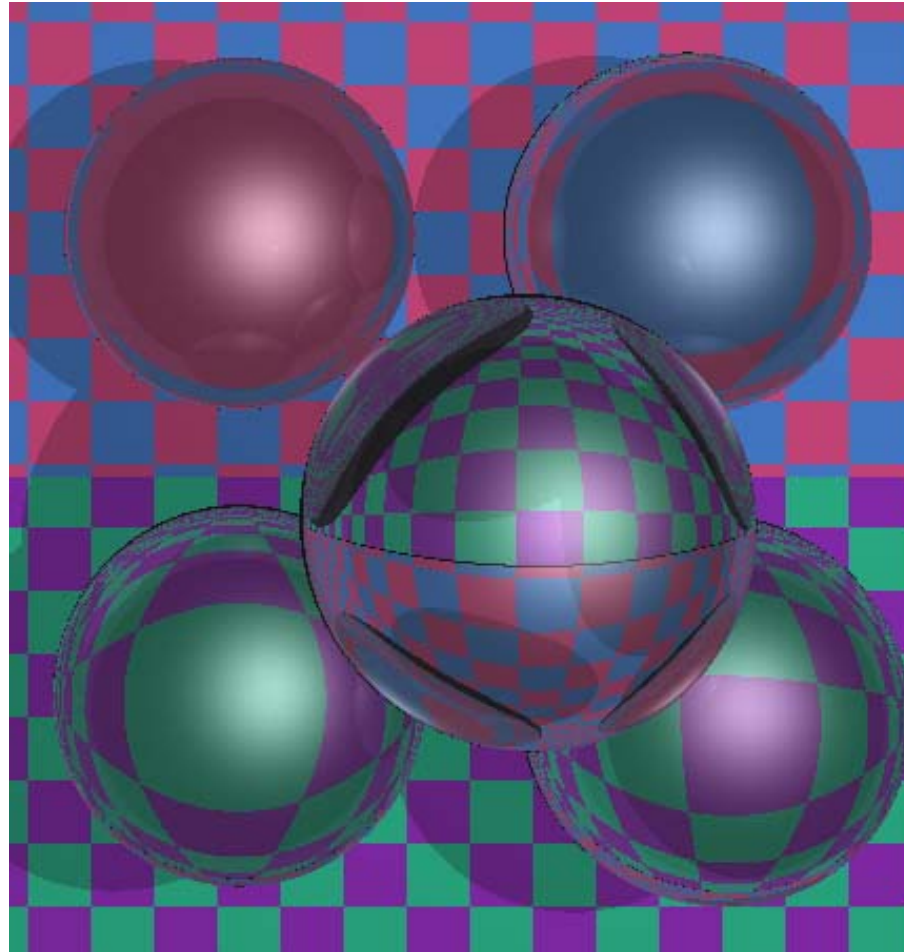


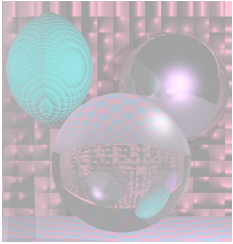
One Glass Sphere



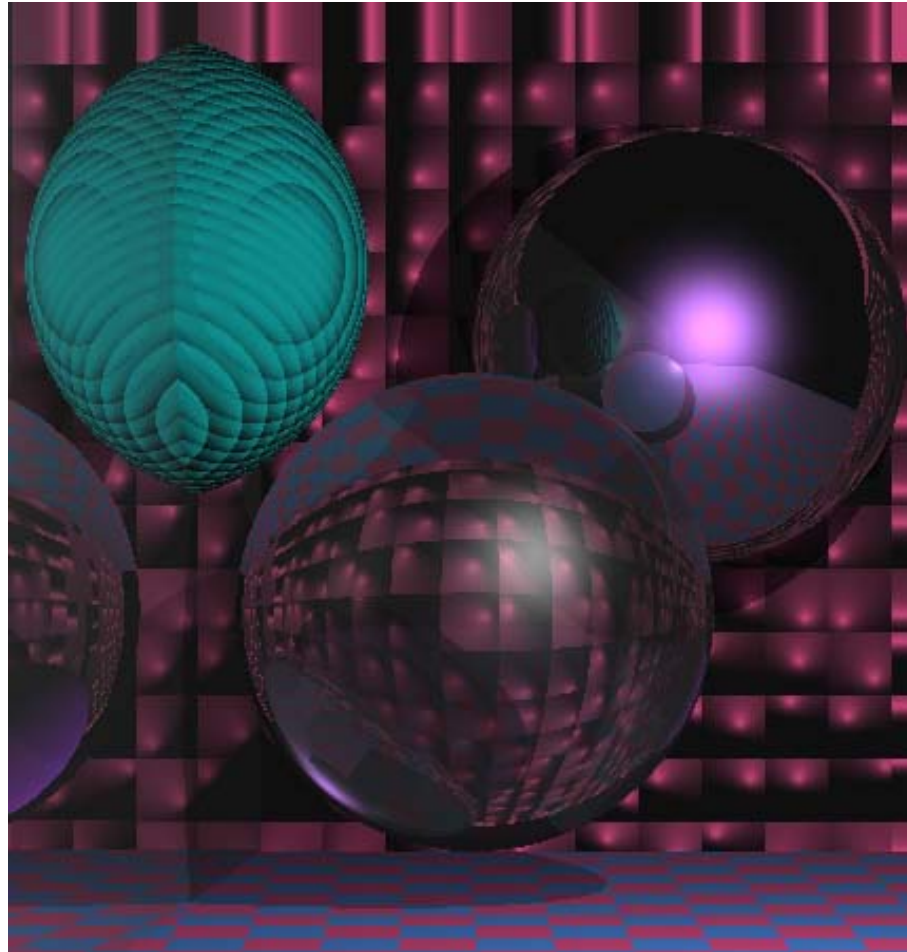


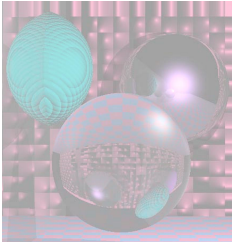
Five Glass Balls



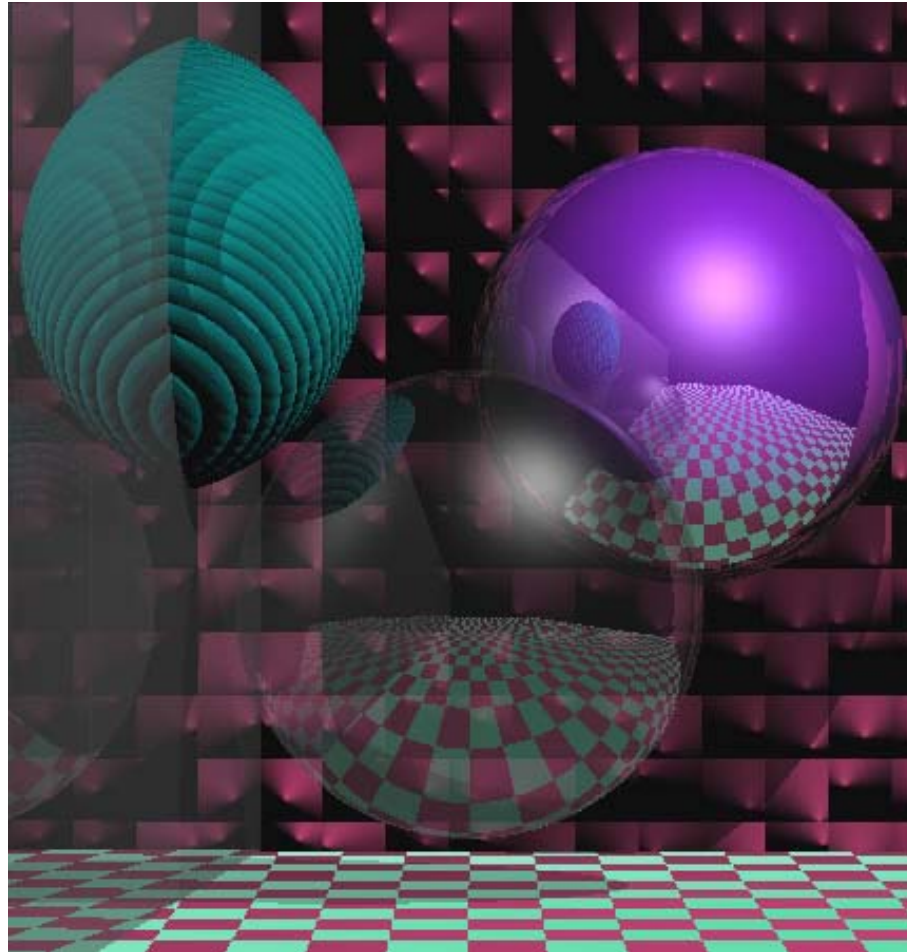


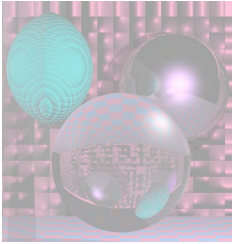
A Familiar Scene



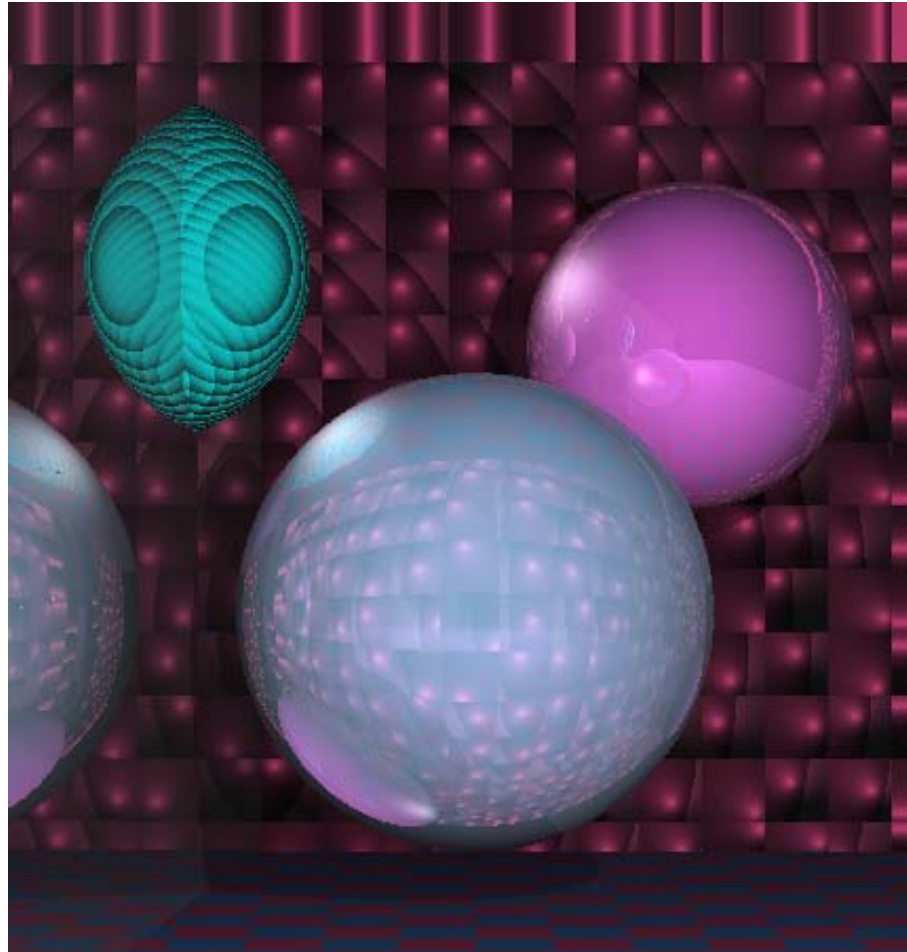


Bubble





Milky Sphere





Lens - Carl Andrews 1999

