

What Program Analysis Can and Cannot Do for You

David Van Horn

with support from NSF, CRA, Google.



A Formulae-as-Types Notion of Control

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Abstract

The programming language Scheme contains the control construct `call/cc` that allows access to the current continuation (the current control context). This, in effect, provides Scheme with first-class labels and jumps. We show that the well-known formulae-as-types correspondence, which relates a constructive proof of a formula α to a program of type α , can be extended to a typed Idealized Scheme. What is surprising about this correspondence is that it relates *classical* proofs to typed programs. The existence of computationally interesting “classical programs” — programs of type α , where α holds classically, but not constructively — is illustrated by the definition of conjunctive, disjunctive, and existential types using standard classical definitions. We also prove that

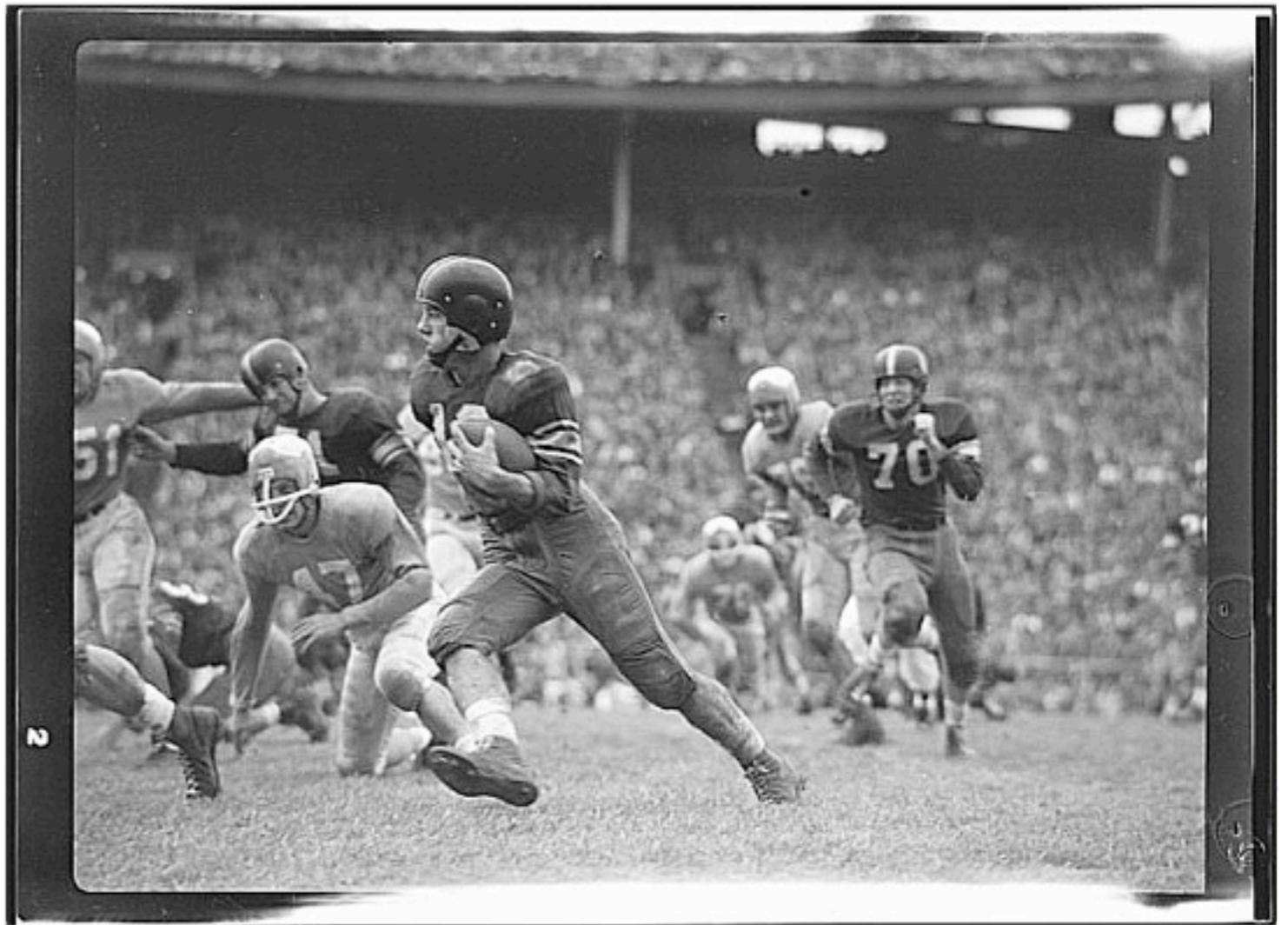
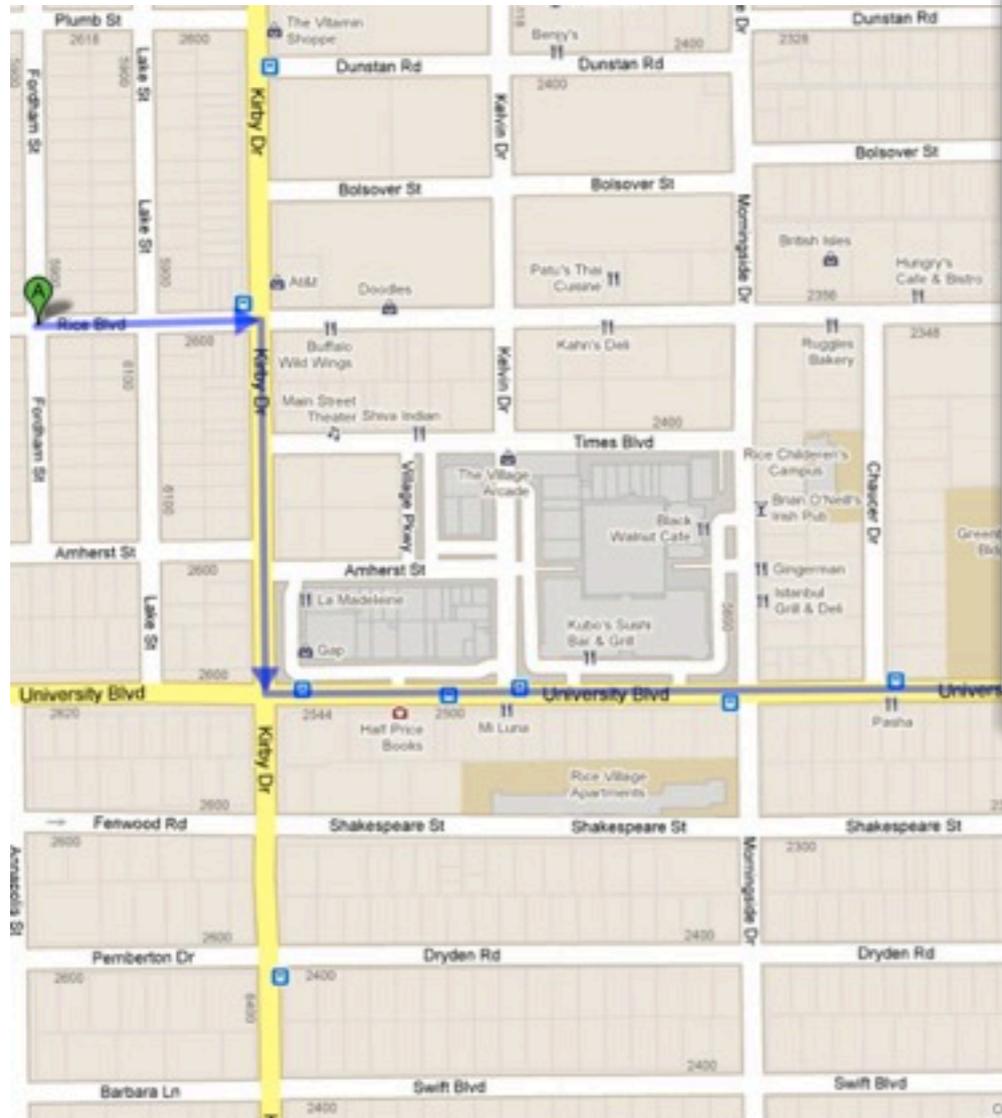
in general, classical proofs lack computational content. This paper shows, however, that the formulae-as-types correspondence *can* be extended to classical logic in a computationally interesting way. It is shown that classical proofs possess computational content when the notion of computation is extended to include explicit access to the current control context.

This notion of computation is found in the programming language Scheme [16], which contains the control construct `call/cc`¹ that provides access to the current continuation (the current control context). This, in effect, provides Scheme with first-class labels and jumps, and allows for programs that are more efficient than purely functional programs. The formulae-as-types correspondence presented in this paper is based on a typed version of *Idealized Scheme* — a typed ISWIM containing an operator



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What Program Analysis Can and Cannot Do for You

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Higher-order Program Analysis is Dead.

(I should know, I killed it.)

it's hard to write

it's slow

it's imprecise

it's awful

Higher-order Program Analysis is Alive and Well.

(I have a way forward.)

it's easy to write

it's fast

it's precise

it's great

So what?

**Modern software is
higher-order.**

**We need reasonable
software.**

So you should care.

**Modern software is
higher-order.**

Modern software is higher-order.

Q: What are higher-order languages?

Modern software is higher-order.

Q: What are higher-order languages?

A: Languages in which computations are values.

Modern software is higher-order.

Python

```
#  $(\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$   
def deriv(f):  
    def fp(x):  
        return ((f(x+e) - f(x-e)) / (2*e));  
    return fp
```

Modern software is higher-order.

Java

```
//  $(\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$ 
public Func<Double, Double>
deriv(final Func<Double, Double> f) {
    return new Func<Double, Double>() {
        public Double apply(Double x) {
            return ((f.apply(x+ε) - f.apply(x-ε)) / (2*ε));
        }
    };
}
```

Modern software is higher-order.

C#

```
//  $(\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$   
static Func<double, double>  
deriv(Func<double, double> f) {  
    return (x)  
        => (f(x+ε) - f(x-ε)) / (2*ε);  
}
```

Modern software is higher-order.



```
// (ℝ → ℝ) → (ℝ → ℝ)
function deriv(f) {
  return function (x) {
    return (f(x+ε) - f(x-ε)) / (2*ε);
  };
}
```

Modern software is higher-order.

X10

```
//  $(\mathbb{R} \rightarrow \mathbb{R}) \rightarrow (\mathbb{R} \rightarrow \mathbb{R})$   
def deriv(f: (Double) => Double) {  
  val fp = (x: Double) =>  
    (f(x+ε) - f(x-ε)) / (2*ε);  
  return fp;  
}
```

An Introduction To Programming With X10

DRAFT

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Bard Bloom, bardb@us.ibm.com

Cal Swart, cal@us.ibm.com

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December 2, 2010

```
1 public class IntRange {
2     val low: Int;
3     var high: Int;
4     public def this(low: Int, high: Int) {
5         this.low = low; this.high = high;
6     }
7     public def includes(n:Int) = low <= n && n <= high;
8     public static def isDigitFcn() {
9         val digit = new IntRange(0,9);
10        return (n: Int) => digit.includes(n);
11    }
12    public def inMeTester() {
13        return (n: Int) => low <= n && n <= high;
14    }
15 }
```

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```





window.setTimeout



« [Gecko DOM Reference](#)

Summary

Executes a code snippet or a function after specified delay.

Syntax

```
var timeoutID = window.setTimeout(func, delay, [param1, param2, ...]);  
var timeoutID = window.setTimeout(code, delay);
```

where

- `timeoutID` is the ID of the timeout, which can be used later with [window.clearTimeout](#).
- `func` is the [function](#) you want to execute after `delay` milliseconds.
- `code` in the alternate syntax, is a string of code you want to execute after `delay` milliseconds. (Using this syntax is not recommended for the same reasons as using [eval\(\)](#))
- `delay` is the number of milliseconds (thousandths of a second) that the function call should be delayed by. Note that the actual delay may be longer, see Notes below.

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 - Minimum delay and timeout nesting
- Specification

TAGS FILES

Page Notifications Off



XMLHttpRequest

1. Introduction

This section is non-normative.

The [XMLHttpRequest](#) object implements an interface to perform HTTP client functionality, such as sending and receiving XMLHttpRequests using the ECMAScript HTTP API.

The name of the object is [XMLHttpRequest](#) for historical reasons. The name is potentially misleading. First, the object can be used to make requests over both HTTP and HTTPS, but that function is not "requests" in a broad sense of the term as it does not return requests or responses for the defined HTTP methods.

Some simple code to do something with XMLHttpRequest:

```
function test(data) {
  // taking care of data
}

function handler() {
  if(this.readyState == 4 && this.status == 200) {
    // so far so good
    if(this.responseXML != null && this.responseXML.documentElement != null) {
      // success!
      test(this.responseXML.getElementsByTagName("data"));
    } else {
      test(null);
    }
  } else if (this.readyState == 4 && this.status != 200) {
    // fetched the wrong page or network error...
    test(null);
  }
}

var client = new XMLHttpRequest();
client.onreadystatechange = handler;
client.open("GET", "unicorn.xml");
client.send();
```

Download
ChangeLog
About
v0.4.1 docs

Wiki

nodeJS

Evented I/O for V8 JavaScript.

An example of a web server written in Node which responds with "Hello World" for every request.

```
var http = require('http');
http.createServer(function (req, res) {
  res.writeHead(200, {'Content-Type': 'text/plain'});
  res.end('Hello World\n');
}).listen(8124, "127.0.0.1");
console.log('Server running at http://127.0.0.1:8124/');
```

To run the server, put the code into a file `example.js` and execute it with the node program:

```
% node example.js
Server running at http://127.0.0.1:8124/
```

java.util

Class Observable

[java.lang.Object](#)

└─ [java.util.Observable](#)

```
public class Observable  
extends Object
```

This class represents an observable object, or "data" in the model-view paradigm. It can be subclassed to represent an object that the application wants to have observed.

An observable object can have one or more observers. An observer may be any object that implements interface `Observer`. After an observable instance changes, an application calling the `Observable`'s `notifyObservers` method causes all of its observers to be notified of the change by a call to their `update` method.

The order in which notifications will be delivered is unspecified. The default implementation provided in the `Observable` class will notify `Observers` in the order in which they registered interest, but subclasses may change this order, use no guaranteed order, deliver notifications on separate threads, or may guarantee that their subclass follows this order, as they choose.

Note that this notification mechanism is has nothing to do with threads and is completely separate from the `wait` and `notify` mechanism of class `Object`.

When an observable object is newly created, its set of observers is empty. Two observers are considered the same if and only if the `equals` method returns true for them.

Since:

JDK1.0

See Also:

[notifyObservers\(\)](#), [notifyObservers\(java.lang.Object\)](#), [Observer](#),
[Observer.update\(java.util.Observable, java.lang.Object\)](#)

java.util
Class Observable

[java.lang.Object](#)
└─ [java.util.Observable](#)

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public class Observable  
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```

This class represents an observable object, or "data" in the model-view paradigm, that the application wants to have observed.

An observable object can have one or more observers. An observer may be any object that implements the `Observer` interface. After an observable instance changes, an application calling the `Observable`'s `notifyObservers` method will cause the `update` method of each registered observer to be called.

Constructor Summary

[Observable\(\)](#)
Construct an `Observable` with zero `Observer`s.

Method Summary

| | |
|----------------|---|
| void | addObserver(Observer o) Adds an observer to the set of <code>Observer</code> s for this object. If the object is already in the set. |
| protected void | clearChanged() Indicates that this object has no longer changed since its most recent change, so that the <code>hasChanged</code> method will return <code>false</code> . |
| int | countObservers() Returns the number of <code>Observer</code> s of this <code>Observable</code> . |
| void | deleteObserver(Observer o) Deletes an observer from the set of <code>Observer</code> s of this <code>Observable</code> . |
| void | deleteObservers() Clears the observer list so that this object no longer has any <code>Observer</code> s. |
| boolean | hasChanged() Tests if this object has changed. |
| void | notifyObservers() If this object has changed, as indicated by the <code>hasChanged</code> method, then call the <code>clearChanged</code> method to indicate that this object has no longer changed. |
| void | notifyObservers(Object arg) If this object has changed, as indicated by the <code>hasChanged</code> method, then call the <code>clearChanged</code> method to indicate that this object has no longer changed. Then call the <code>update</code> method of each registered observer, passing the argument. |
| protected void | setChanged() Marks this <code>Observable</code> object as having been changed; the <code>hasChanged</code> method will return <code>true</code> . |

Programming Ruby

The Pragmatic Programmer's Guide

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Object-Oriented Design Libraries

One of the interesting things about Ruby is the way it blurs the distinction between design and implementation. Ideas that have to be expressed at the design level in other languages can be implemented directly in Ruby.

To help in this process, Ruby has support for some design-level strategies.

- **The Visitor pattern** (Design Patterns,) is a way of traversing a collection without having to know the internal organization of that collection.
- **Delegation** is a way of composing classes more flexibly and dynamically than can be done using standard inheritance.
- **The Singleton pattern** is a way of ensuring that only one instantiation of a particular class exists at a time.
- **The Observer pattern** implements a protocol allowing one object to notify a collection of objects.

Normal
implem
and tra

Library: observer

The Observer pattern, also known as Publish/Subscribe, provides a simple mechanism for one object to inform a set of interested third-party objects when its state changes.

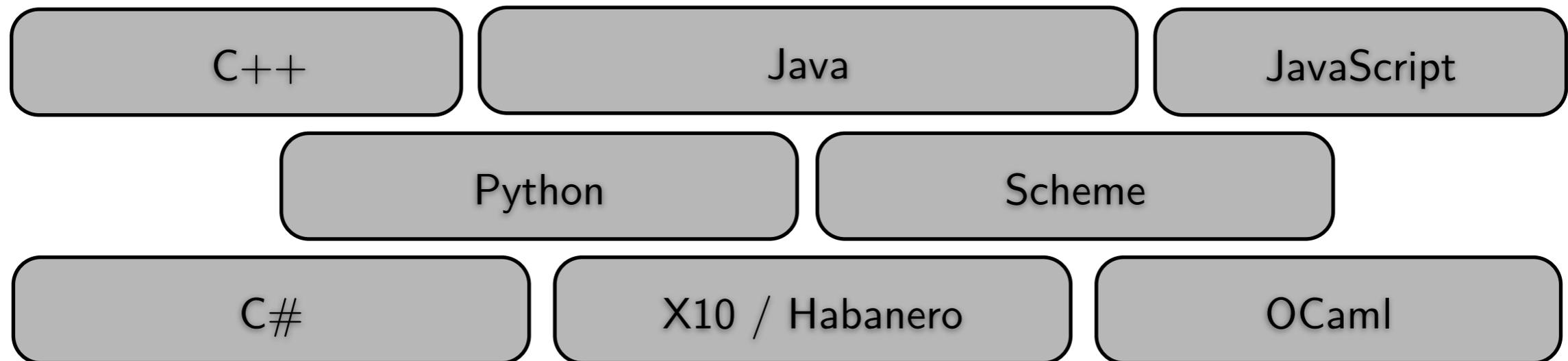
In the Ruby implementation, the notifying class mixes in the `Observable` module, which provides the methods for managing the associated observer objects.

`add_observer(obj)` Add `obj` as an observer on this object. `obj` will now receive notifications.

`delete_observer(obj)` Delete `obj` as an observer on this object. It will no longer receive notifications.

`delete_observers` Delete all observers associated with this object.

Modern software is higher-order.



...and many more

Modern software is higher-order.

C++

Java

JavaScript

Python

Scheme

C#

X10 / Habanero

OCaml

...and many more

Higher order

Modern software is higher-order.

C++ (360)

Java (201,211,215,310,402)

JavaScript (327)

Python (140,182,327)

Scheme (211,311)

C# (160,402,410,460)

X10 / Habanero (322)

OCaml (311,411)

...and many more

Higher order

**We need reasonable
software.**

We need reasonable software.

Q: What does it mean to reason about software?

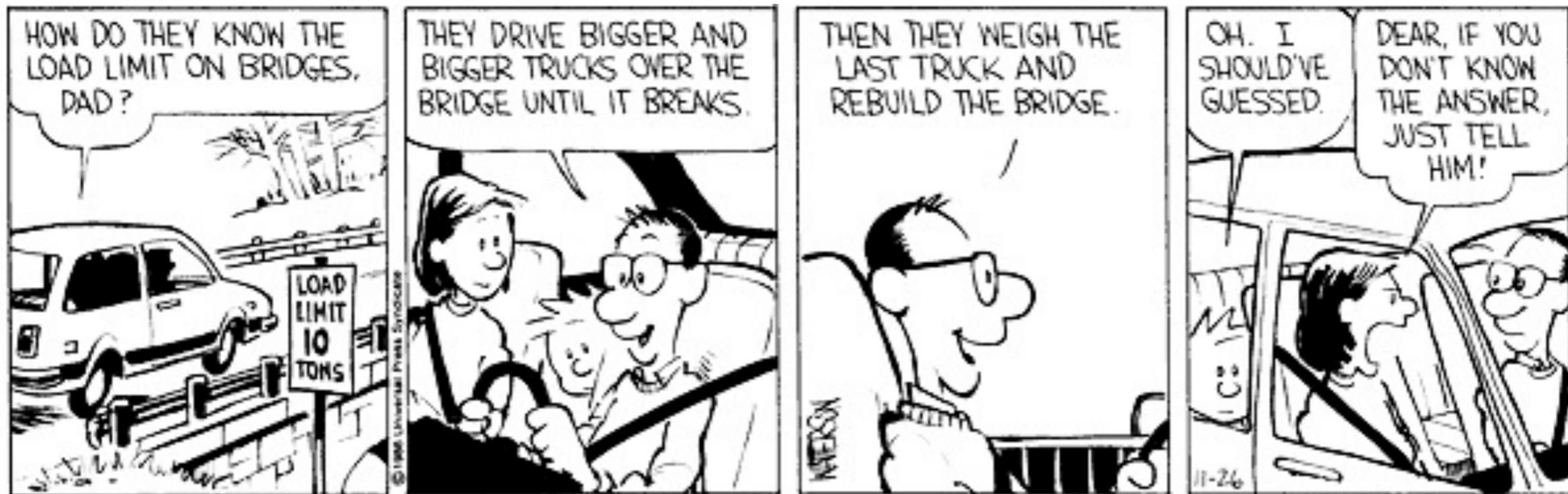
We need reasonable software.

Q: What does it mean to reason about software?

A: It means predicting the future.

**We need reasonable
software.**

We need reasonable software.



We need reasonable software.

```
public void f(XYZ x) {  
    x.m();  
}
```

Optimizing Java compiler:
prove `x` is always an `X`, inline method definition.

We need reasonable software.

`first(x)`

Puzzled ML programmer:
prove `x` is always a non-empty list: no problem.

We need reasonable software.

`first(x)`

Puzzled ML programmer:
prove `x` is *maybe* the empty list: fix.

We need reasonable software.

`checkPrivilege(R);`

Security analyzer:
prove enable(R) is on the stack.

We need reasonable software.

Optimizing compilers

Parallelizing compilers

Software construction

Security analysis

Program understanding

Static debugging

Termination analysis

Model checking

...and many more

We need reasonable software.

Optimizing compilers

Parallelizing compilers

Software construction

Security analysis

Program understanding

Static debugging

Termination analysis

Model checking

...and many more

Program analysis

Higher-order program analysis

Scalability



- Complexity
- Maintenance
- Verification
- Expressivity
- Modularity

Q: What is program analysis?

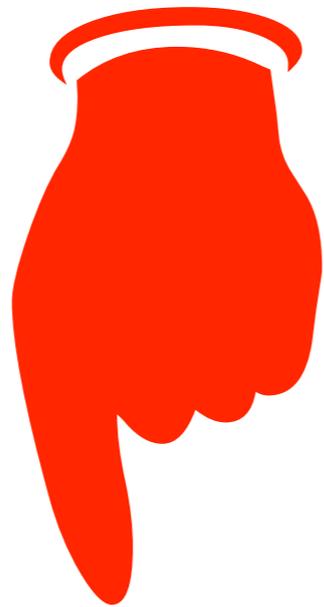
Q: What is program analysis?

A: Prediction of which values show up
at which program sites.

$f(x+\epsilon)$



Where does data go to?

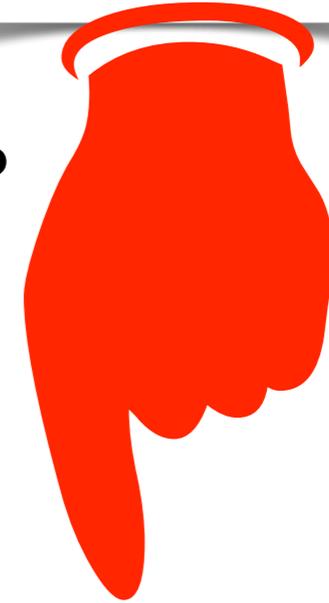


Where does control go to?

$f(x + \epsilon)$

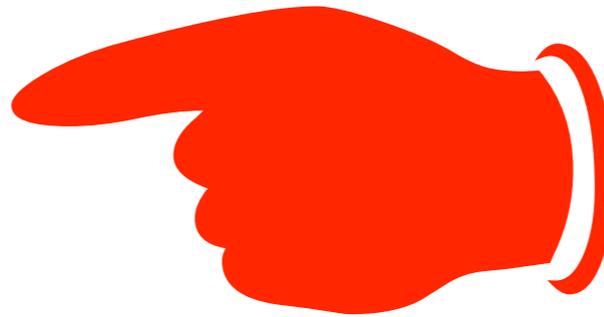
C#

Who calls deriv?

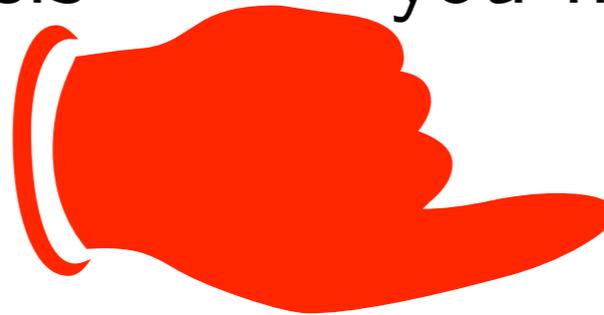


```
deriv(Func<double, double> f) {  
    return (x)  
        => (f(x+ε) - f(x-ε)) / (2*ε);  
}
```

To do control-flow analysis,
you need data-flow analysis



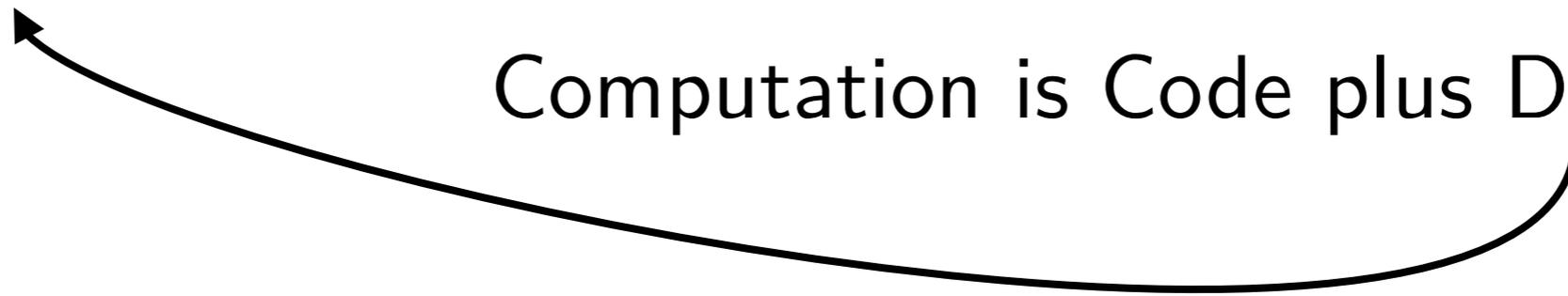
To do data-flow analysis,
you need control-flow analysis



Why so tangled up?

Values include Computations

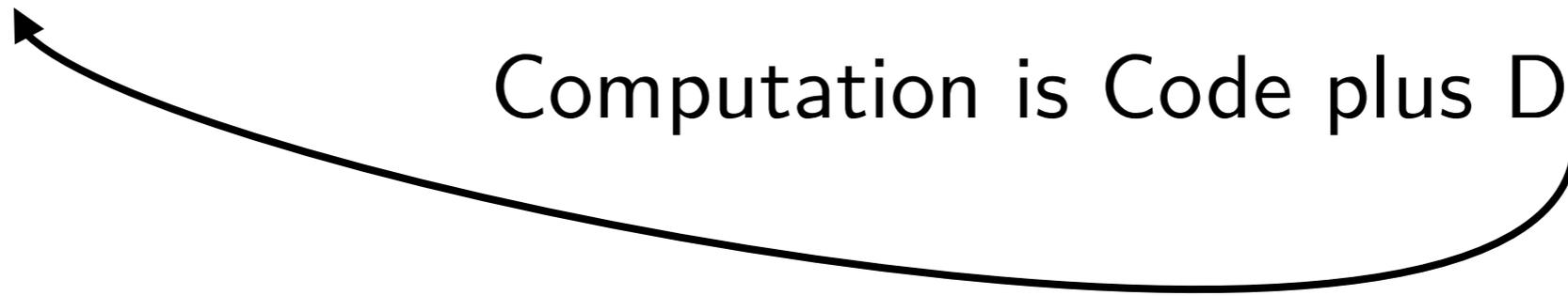
Computation is Code plus Data



Why so tangled up?

Values include Computations

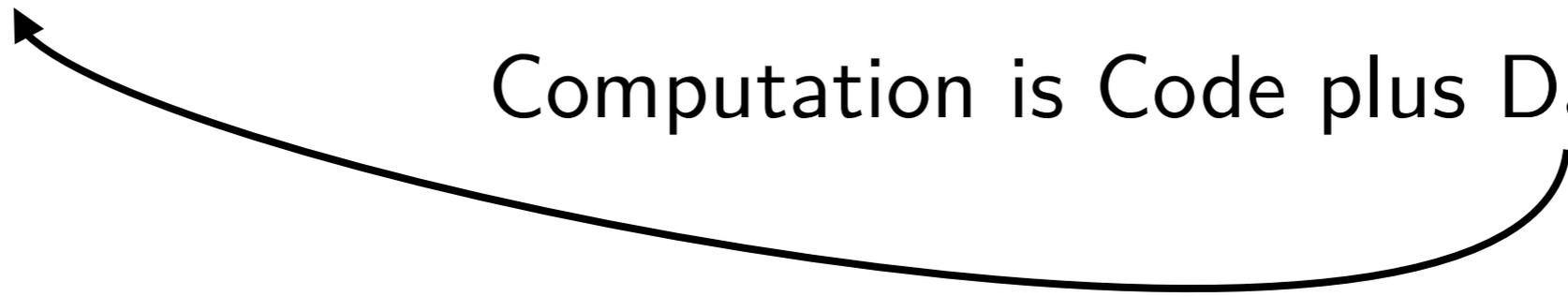
Computation is Code plus Data



Why so tangled up?

Values include Computations

Computation is Code plus Data



**Computable predictions
about run-time behavior**

Why so tangled up?

Values include Computations

Computation is Code plus Data

**Computable predictions
about run-time behavior**

So what's their complexity?

Existing analyses and their complexity

OCFA

```
function app(f,x) { return f(x); };
```

```
app(sqr,4);
```

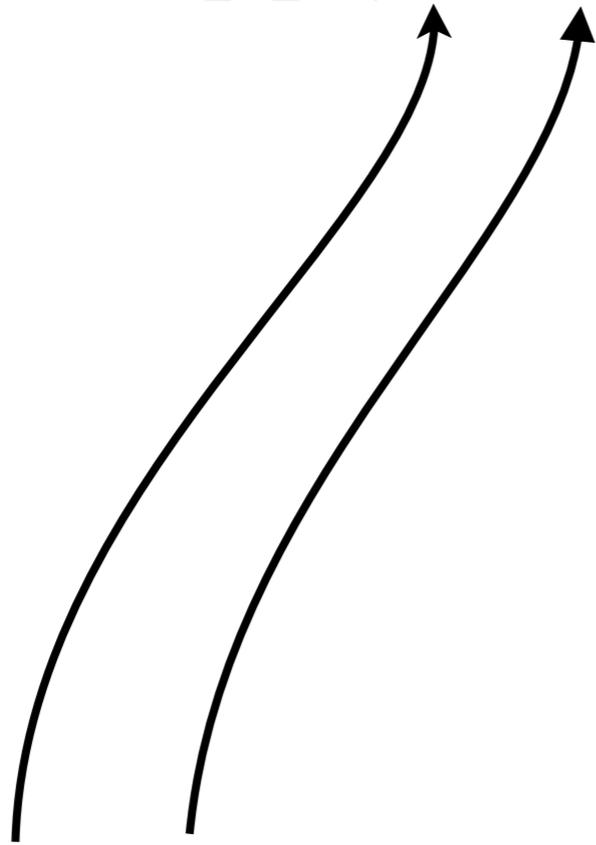
```
app(db1,5);
```

OCFA

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OCFA

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OCFA

```
function app(f, x) { return f(x); }
```

{sqr}

```
app(sqr, 4);
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```
app(db1, 5);
```

OCFA

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function app(f, x) { return f(x); };
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app(db1, 5);
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{sqr}

{4}

OCFA

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function app(f, x) { return f(x); };
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{4}

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app(sqr, 4);
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{sqr(4)}

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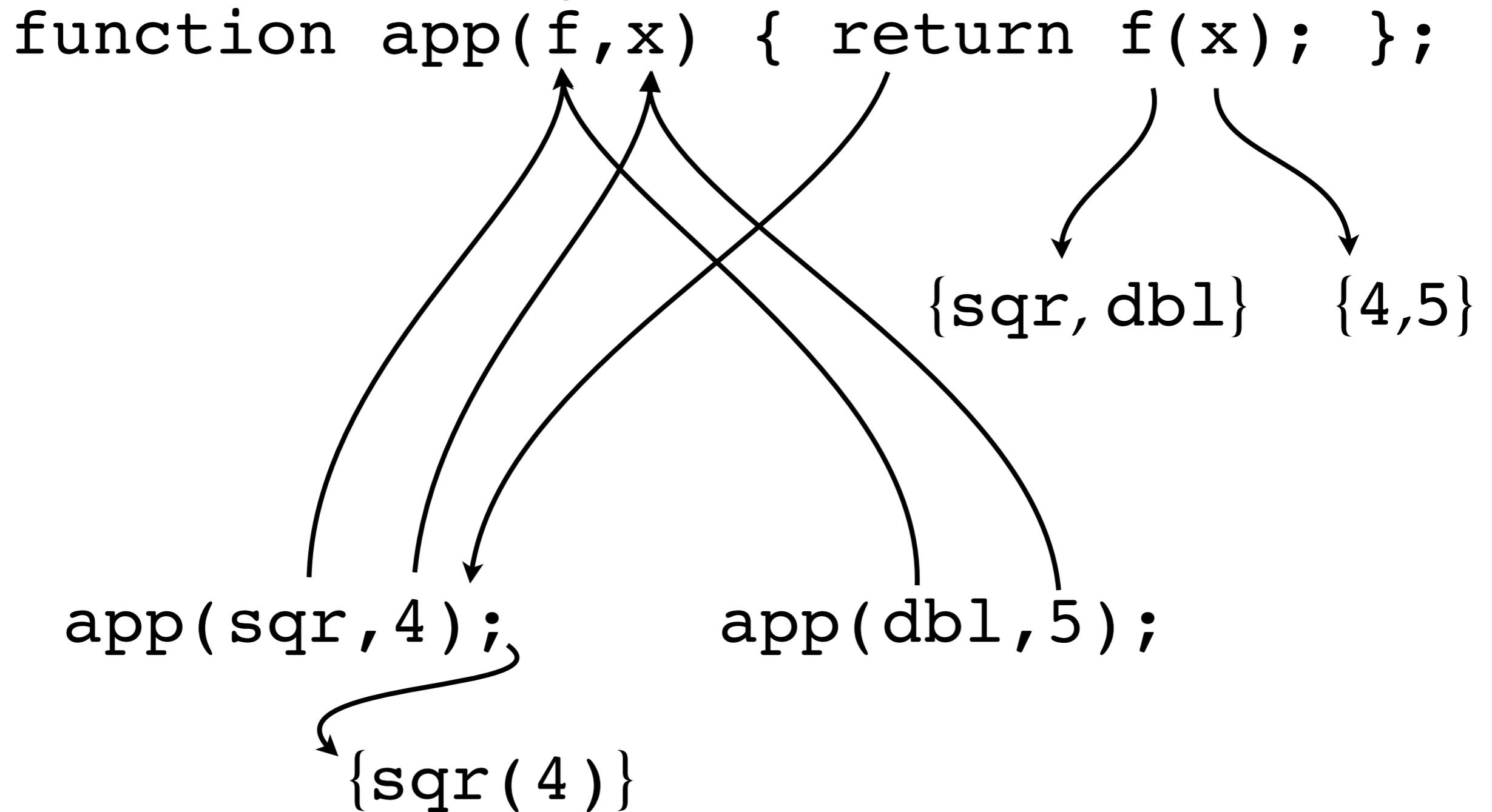
{sqr, dbl} {4}

```
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```

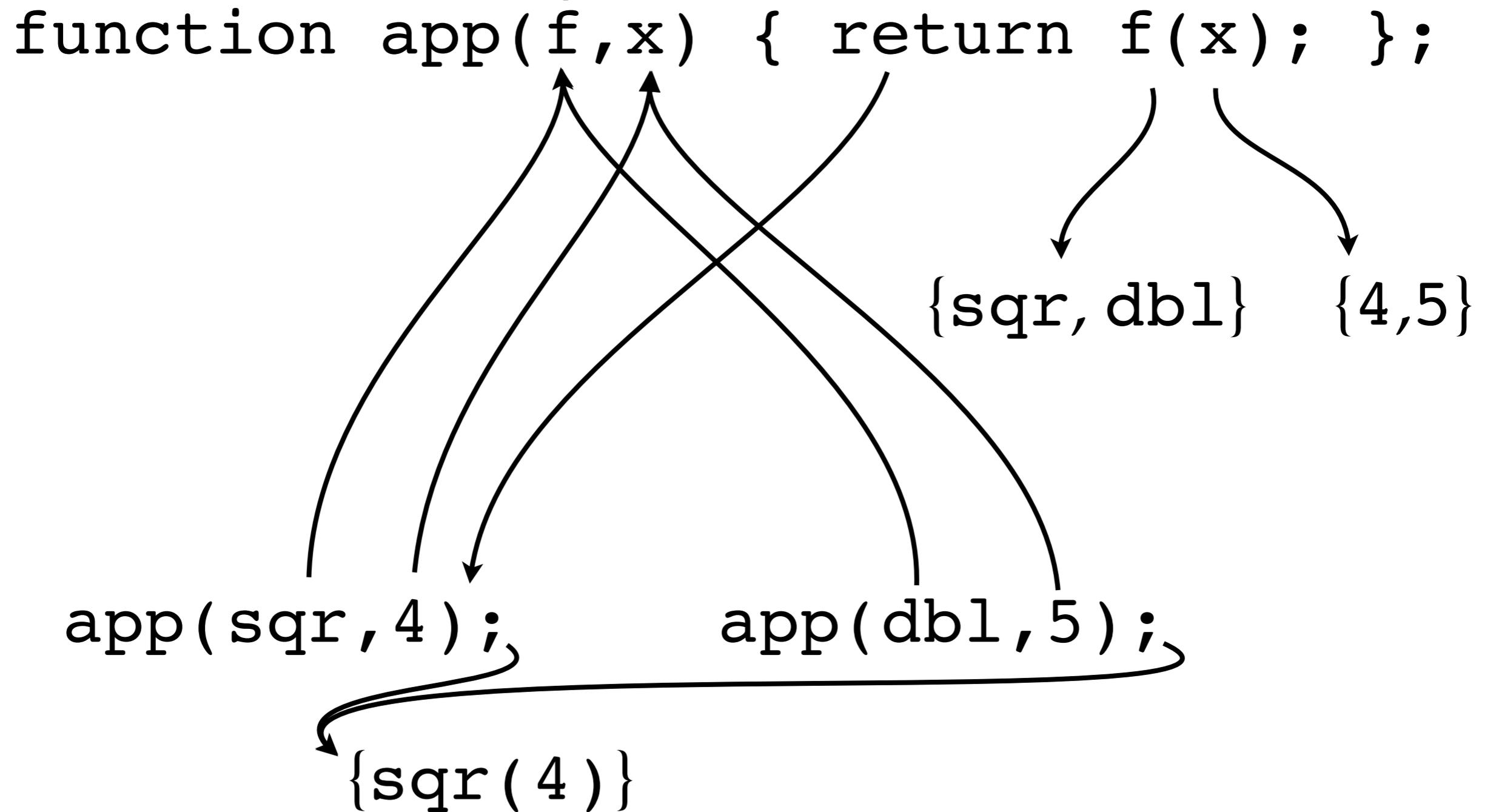
```
app(dbl, 5);
```

{sqr(4)}

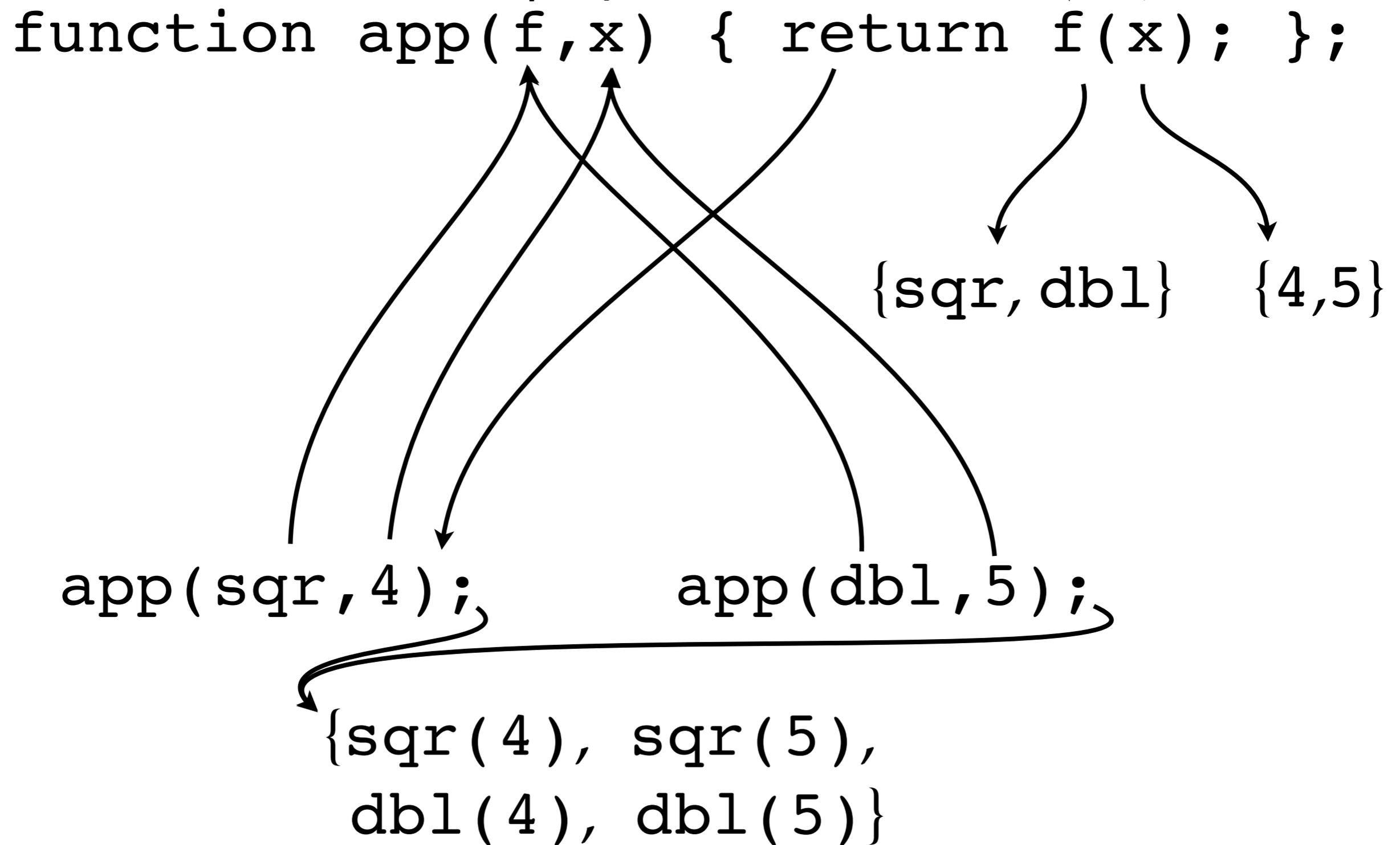
OCFA



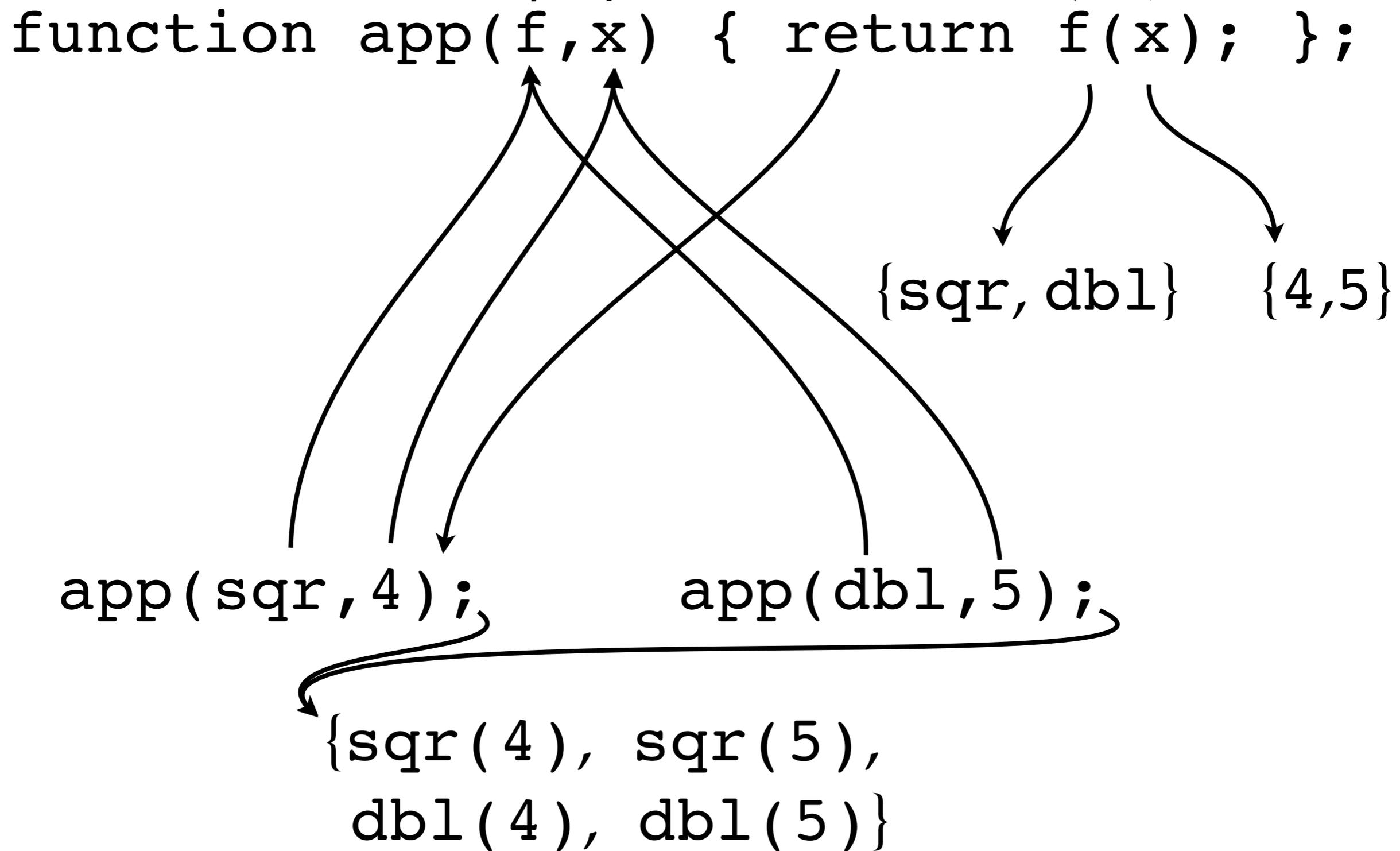
OCFA



OCFA



OCFA



```
function app(f, x) { return f(x); };
```

Theorem: 0CFA is complete for PTIME.

{4,5}

app(sqr, 4);

app(dbl, 5);

{sqr(4), sqr(5),
dbl(4), dbl(5)}

Precision



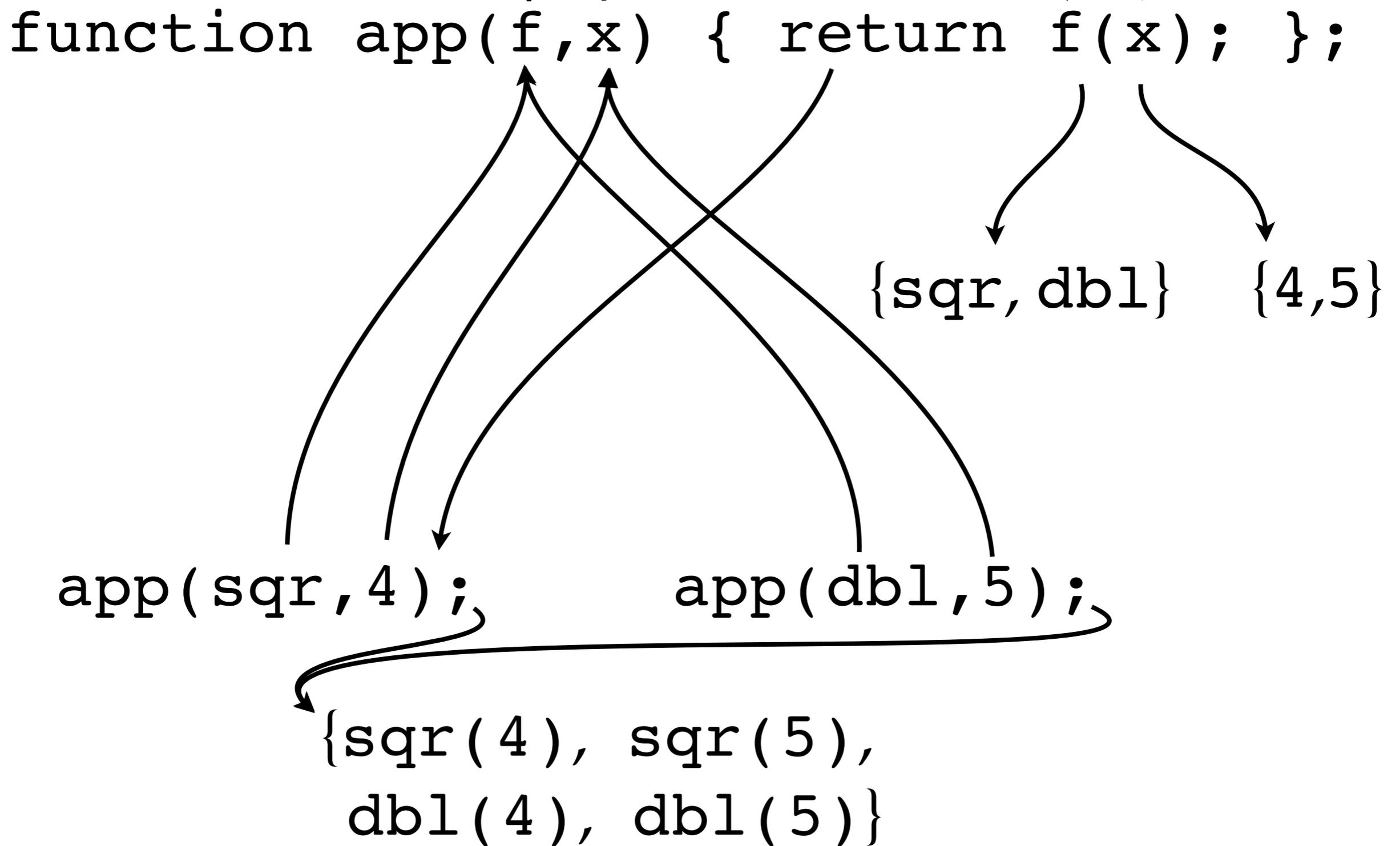
0CFA

Precision

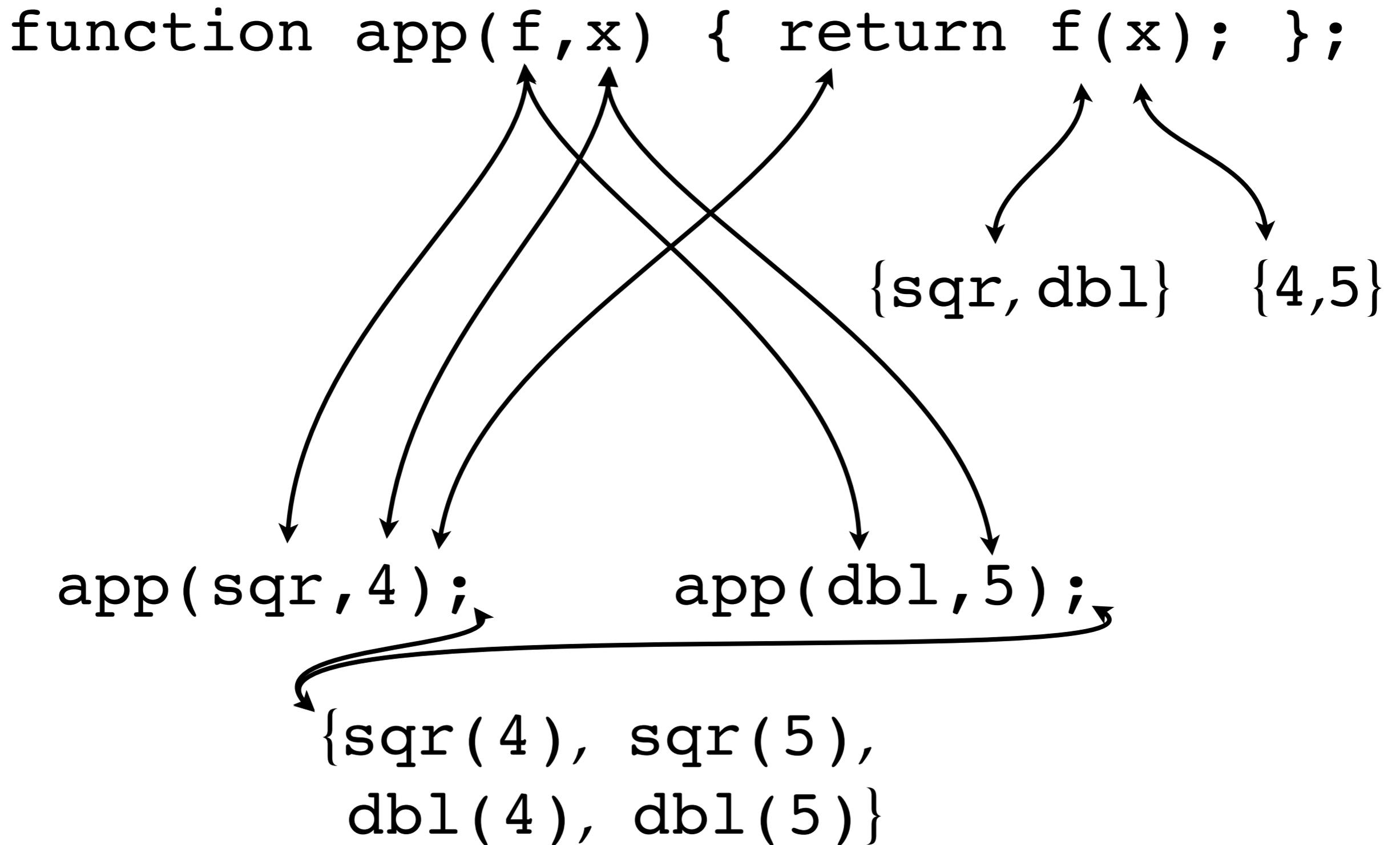


0CFA
Simple closure

Simple closure



Simple closure



Simple closure

```
function app(f, x) { return f(x); };
```

{sqr, dbl} {4, 5}

```
app(sqr, 4);
```

```
app(dbl, 5);
```

```
{sqr(4), sqr(5),  
dbl(4), dbl(5)}
```

```
function app(f, x) { return f(x); };
```

Theorem: Simple closure is complete for PTIME.

```
app(sqr, 4);      app(dbl, 5);
```

{sqr(4), sqr(5),
dbl(4), dbl(5)}

Precision



0CFA
Simple closure

Precision



0CFA

Simple closure

Sub0CFA

Sub0CFA

```
function app(f, x) { return f(x); };
```

{sqr}

{4}

```
app(sqr, 4);
```

```
app(db1, 5);
```

{sqr(4)}

Sub0CFA

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{4}

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app(sqr, 4);
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{sqr(4)}

Sub0CFA

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```

```
{sqr(4)}
```

?

```
{4}
```

Sub0CFA

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function app(f, x) { return f(x); };
```

```
app(sqr, 4);
```

```
app(db1, 5);
```

```
{sqr(4)}
```

?

?

Sub0CFA

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```
app(db1, 5);
```

```
{sqr(4)}
```

?

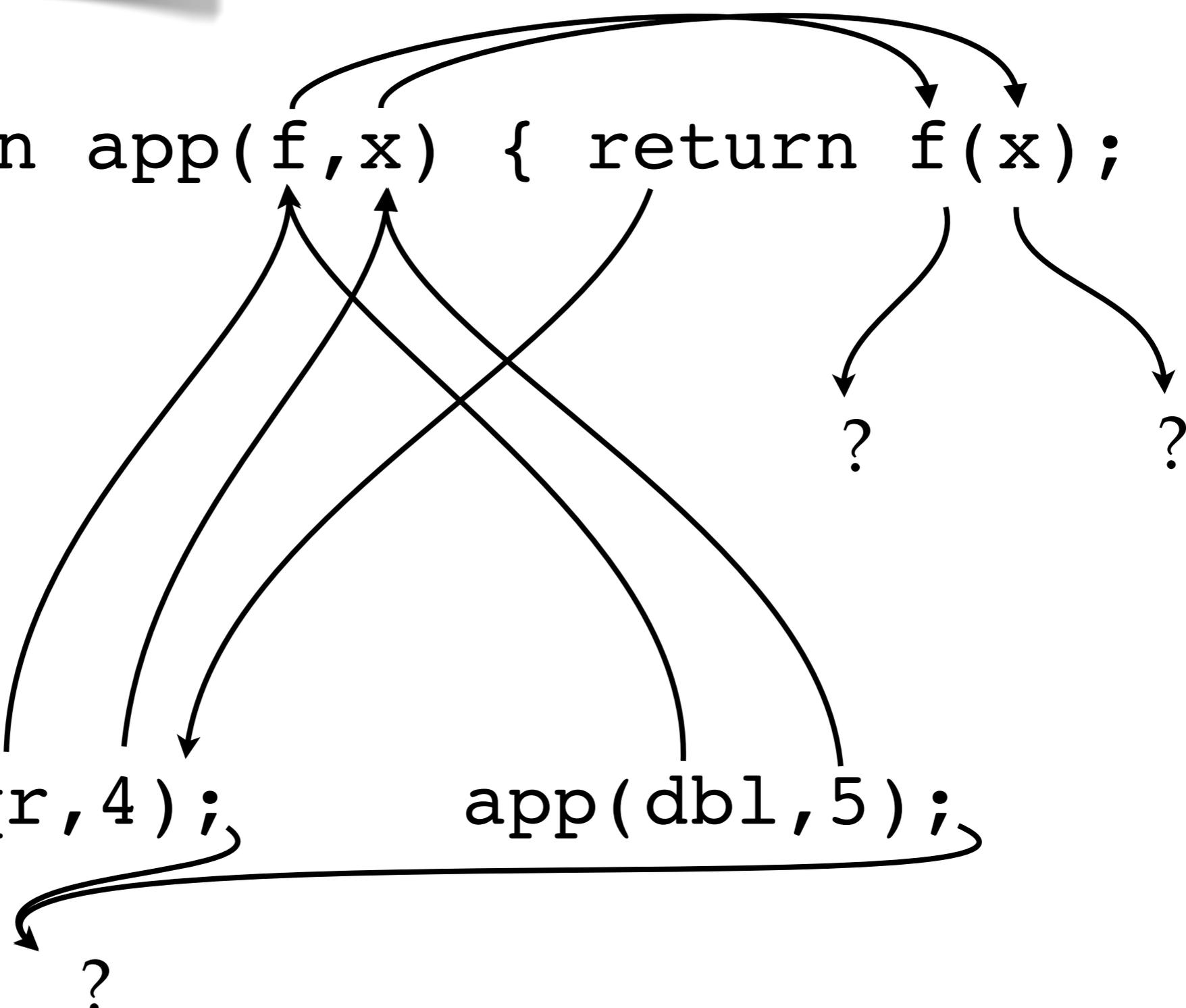
?

Sub0CFA

```
function app(f, x) { return f(x); };
```

```
app(sqr, 4);
```

```
app(db1, 5);
```

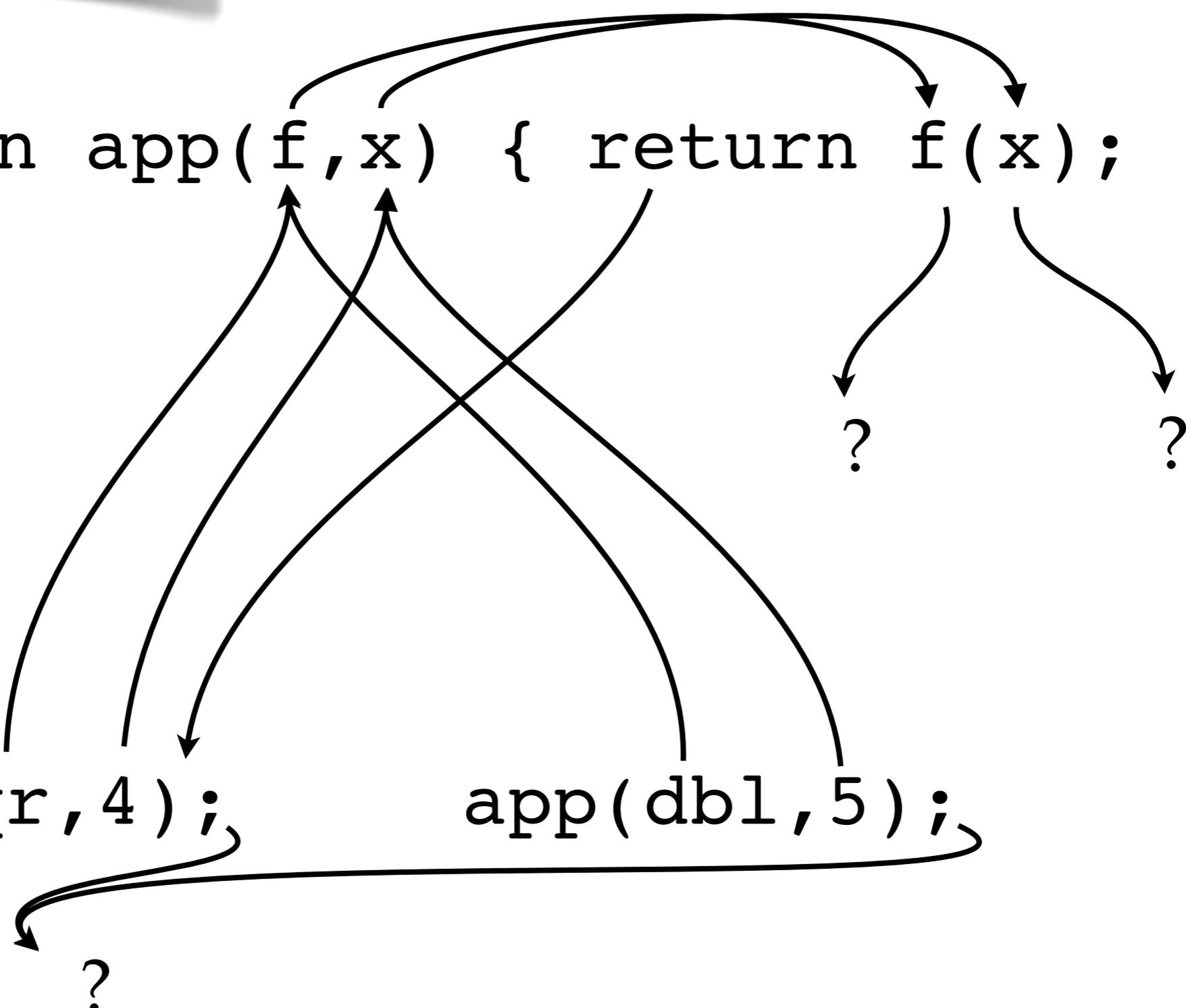


Sub0CFA

```
function app(f, x) { return f(x); };
```

```
app(sqr, 4);
```

```
app(db1, 5);
```



```
function app(f, x) { return f(x); };
```

Theorem: Sub0CFA is complete for PTIME.

```
app(sqr, 4);
```

```
app(db1, 5);
```

?

Precision



0CFA

Simple closure

Sub0CFA

Precision



0CFA

Simple closure

Sub0CFA

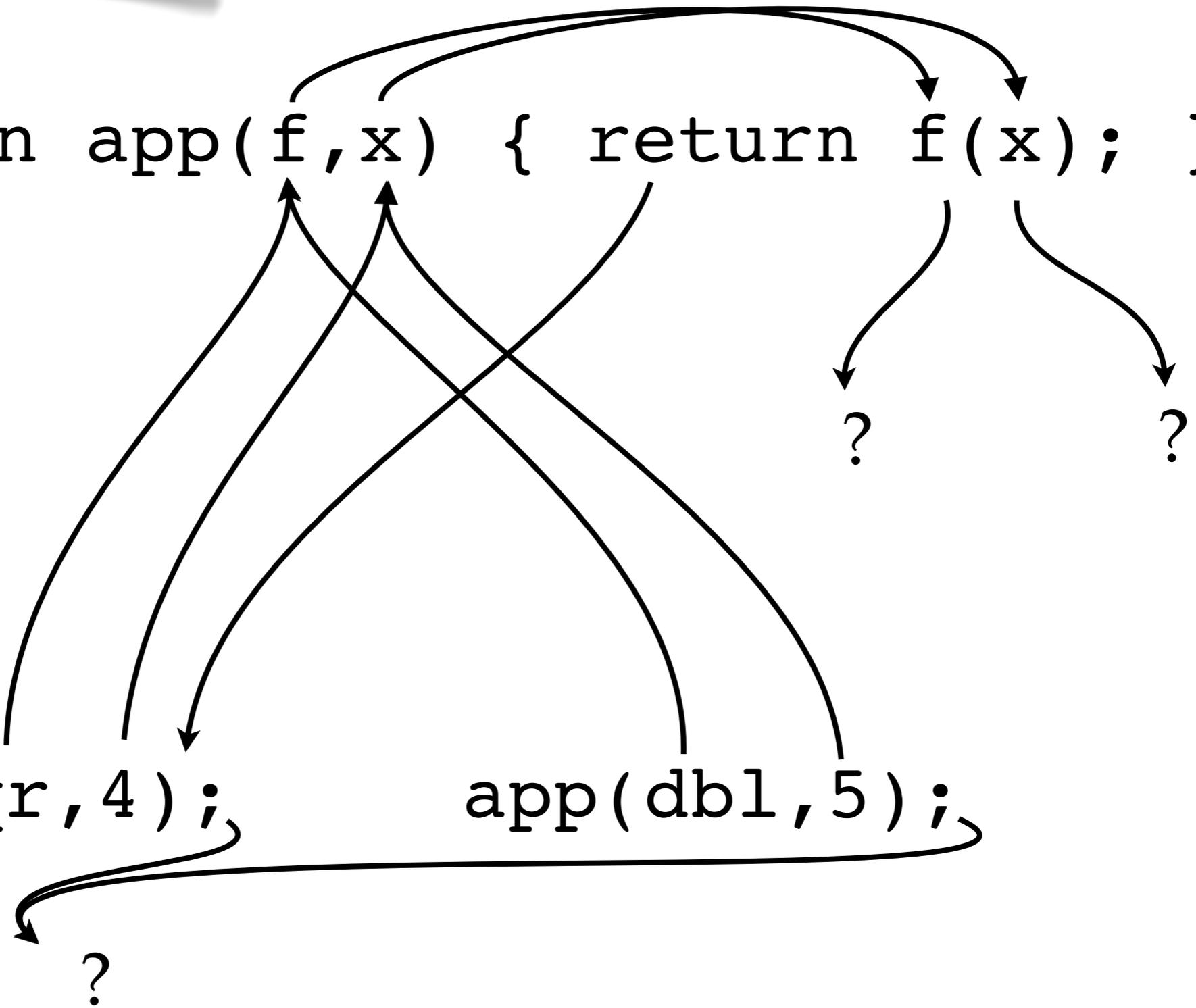
⋮

Whatever

```
function app(f, x) { return f(x); };
```

```
app(sqr, 4);
```

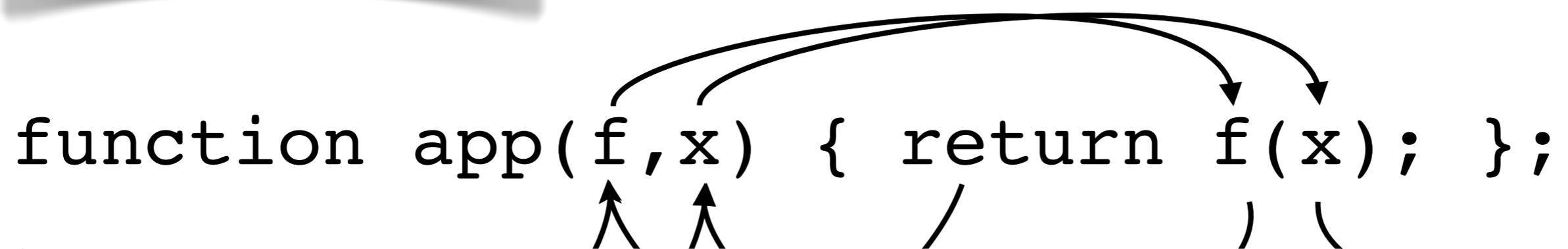
```
app(dbl, 5);
```



Whatever

SAS'08

```
function app(f, x) { return f(x); };
```

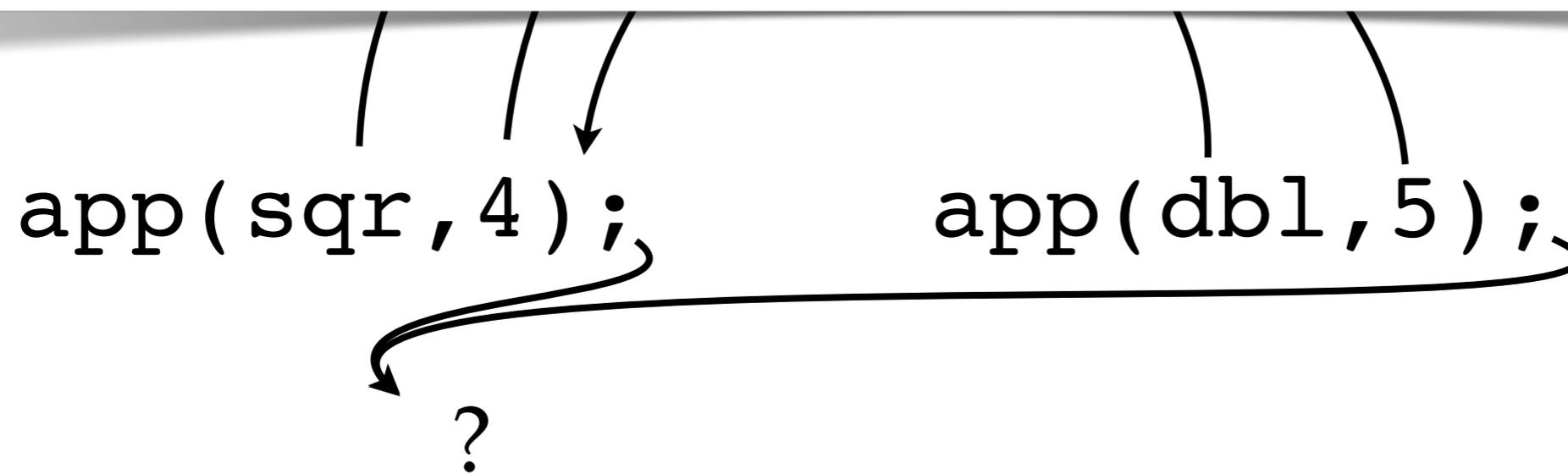


Theorem: They're all complete for PTIME.

```
app(sqr, 4);
```

```
app(db1, 5);
```

?



Precision



0CFA

Simple closure

Sub0CFA

⋮

Precision



1CFA

0CFA

Simple closure

Sub0CFA

⋮

1CFA

```
function app(f, x) { return f(x); };
```

{sqr}

{4}

```
app(sqr, 4);
```

```
app(db1, 5);
```

{sqr(4)}

1CFA

```
function app(f, x) { return f(x); };
```

{sqr}

{4}

```
app(sqr, 4);
```

```
app(db1, 5);
```

{sqr(4)}

1CFA

```
function app(f, x) { return f(x); };
```

{sqr} {4}

{dbl} {5}

```
app(sqr, 4);
```

```
app(dbl, 5);
```

{sqr(4)}

1CFA

```
function app(f, x) { return f(x); };
```

{sqr} {4}

{dbl} {5}

```
app(sqr, 4);
```

```
app(dbl, 5);
```

{sqr(4)}

{dbl(5)}

1CFA

```
function app(f, x) { return f(x); };
```

{sqr} {4}

{dbl} {5}

```
app(sqr, 4);
```

```
app(dbl, 5);
```

{sqr(4)}

{dbl(5)}

```
function app(f, x) { return f(x); };
```

Theorem: 1CFA is complete for EXPTIME.

```
app(sqr, 4);
```

```
{sqr(4)}
```

```
app(db1, 5);
```

```
{db1(5)}
```

Precision



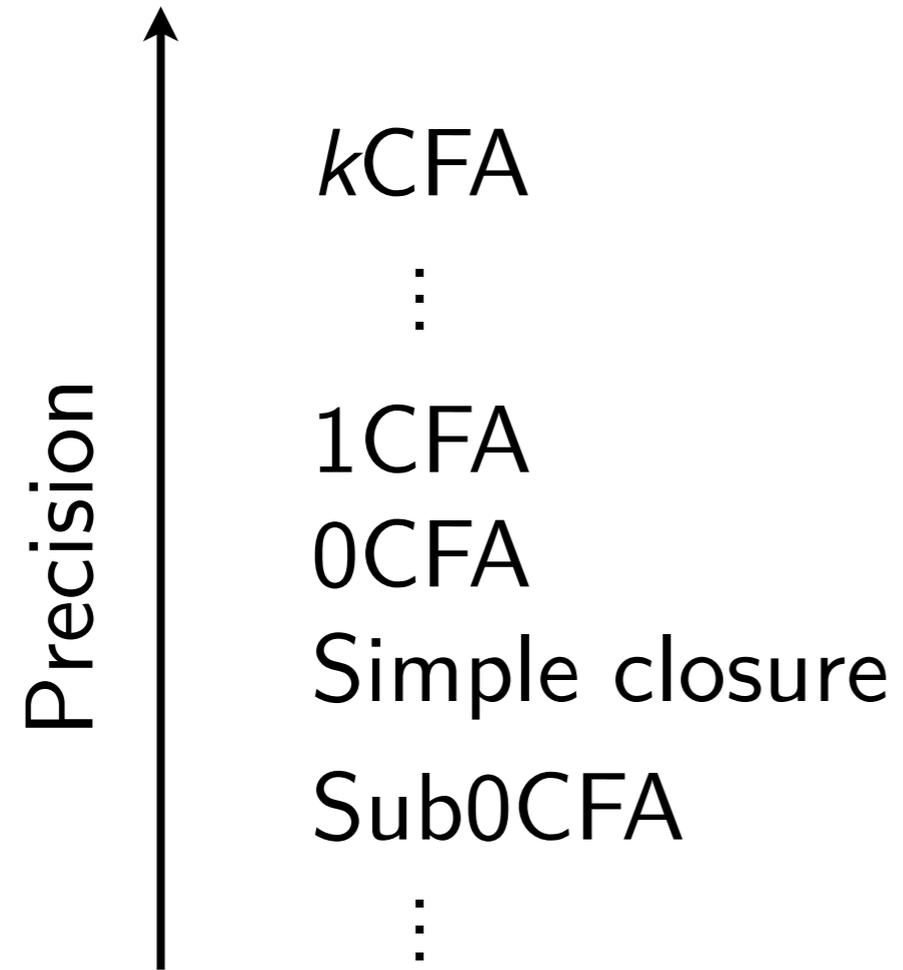
1CFA

0CFA

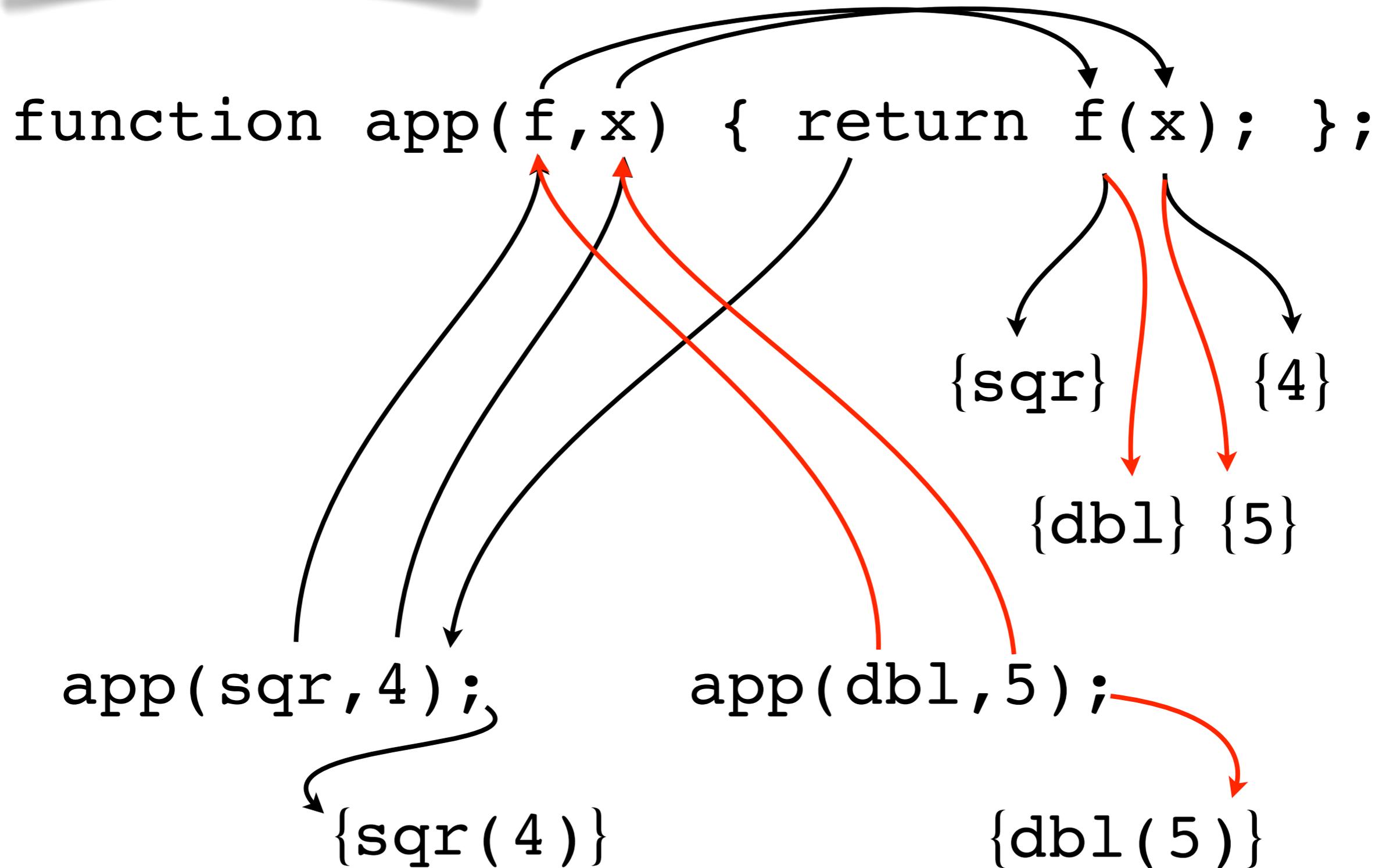
Simple closure

Sub0CFA

⋮



kCFA



```
function app(f, x) { return f(x); };
```

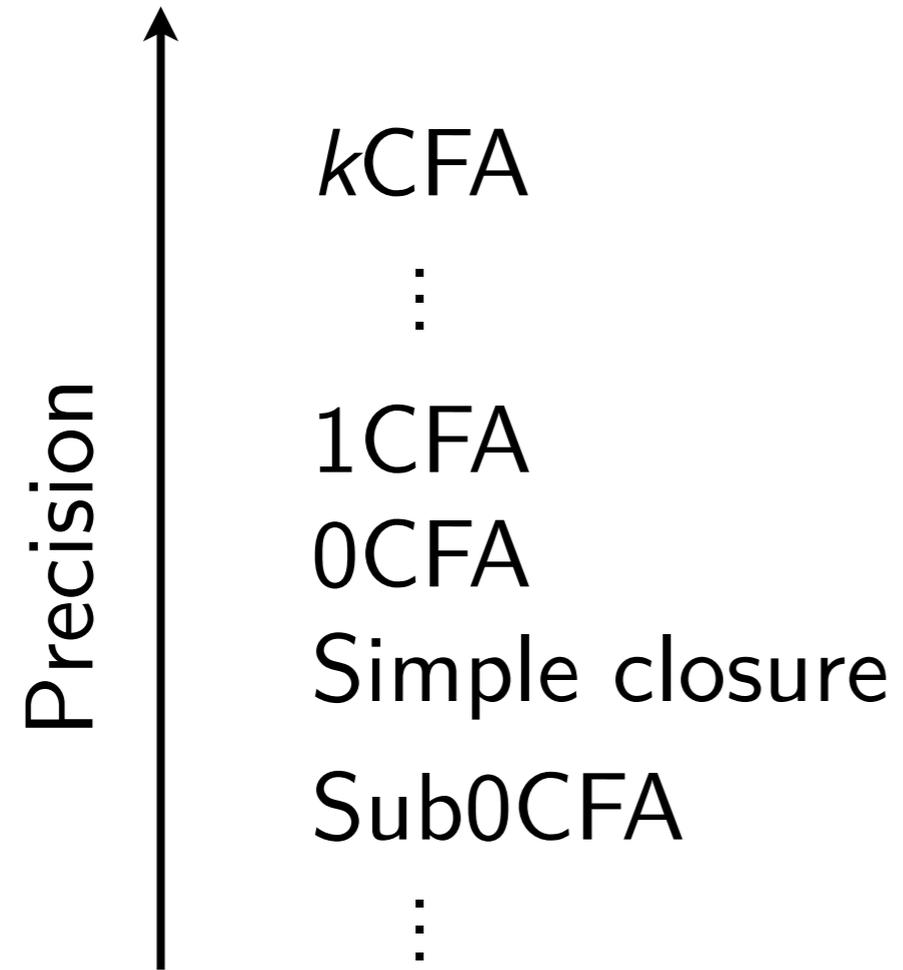
Theorem: *k*CFA is complete for EXPTIME.

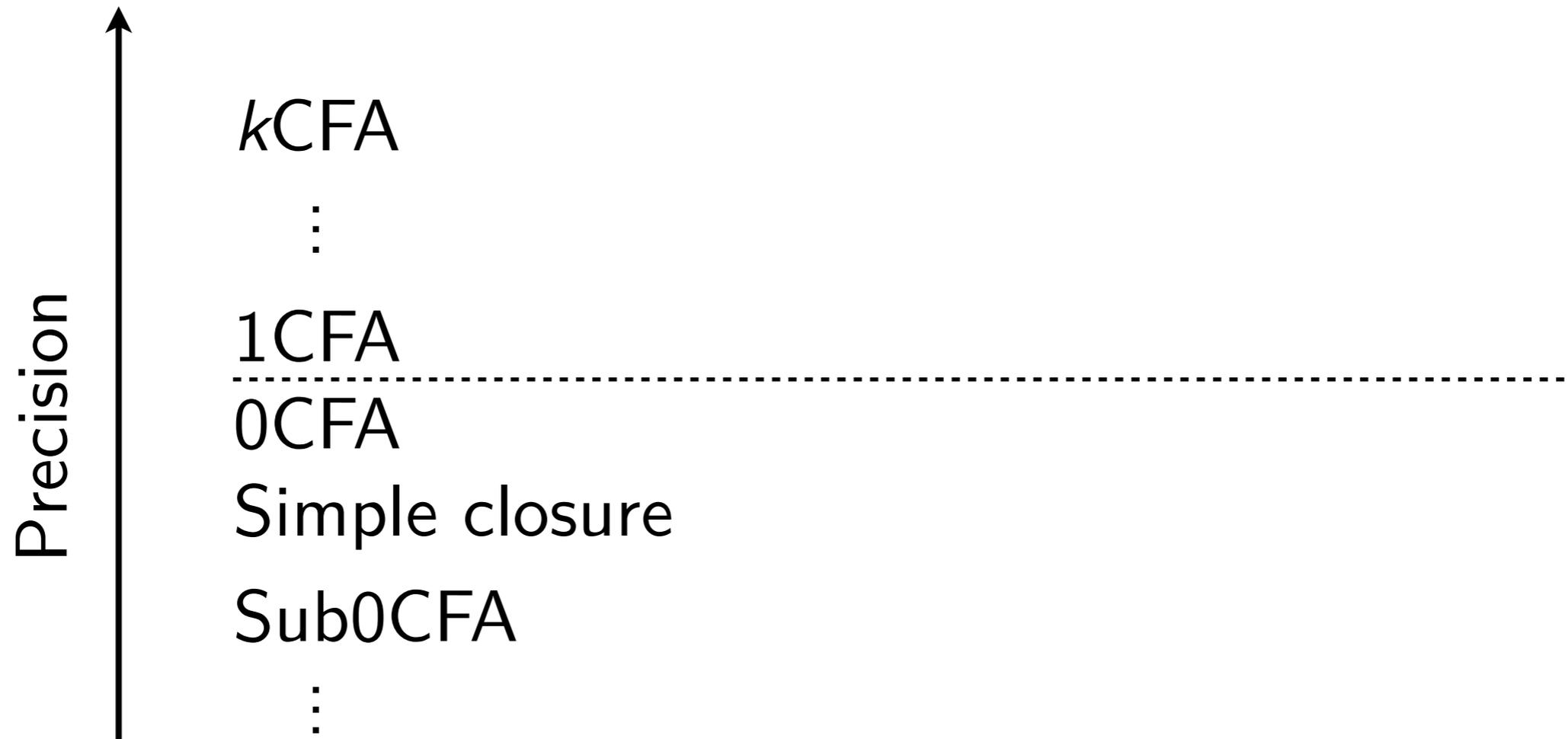
```
app(sqr, 4);
```

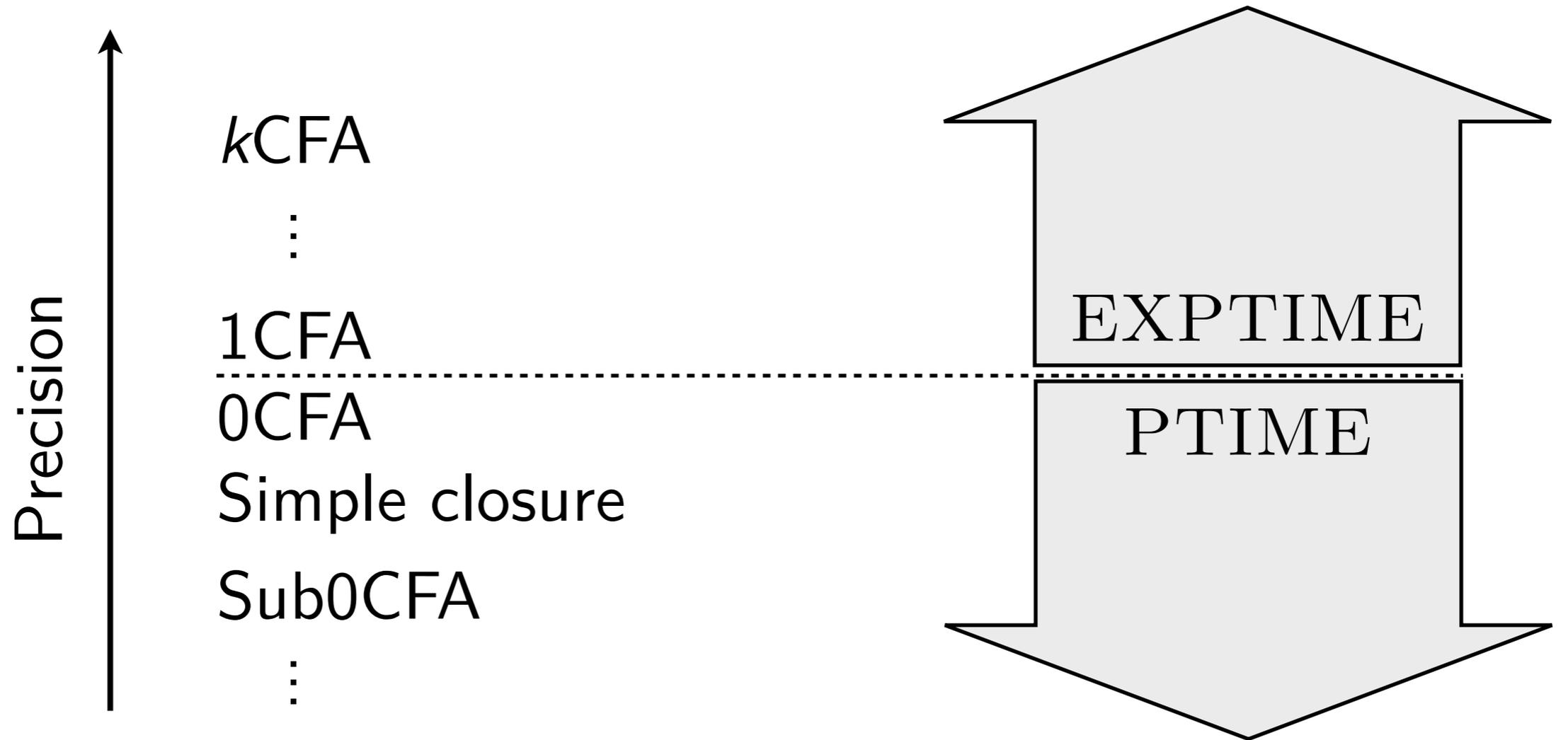
```
{sqr(4)}
```

```
app(db1, 5);
```

```
{db1(5)}
```



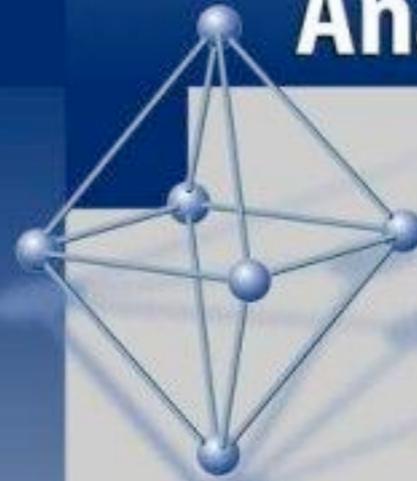




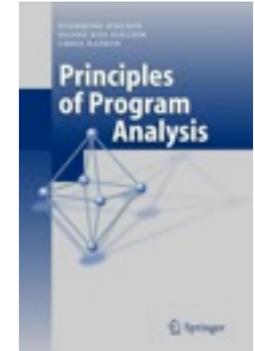
**Rigor (mortis) of
existing analyses**

FLEMMING NIELSON
HANNE RIIS NIELSON
CHRIS HANKIN

Principles of Program Analysis



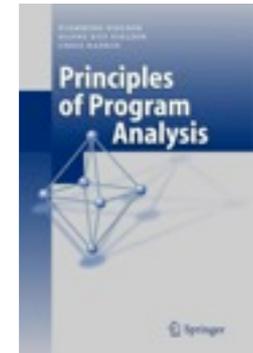
 Springer



| | |
|-------|---|
| [con] | $(\widehat{C}, \widehat{\rho}) \models c^\ell$ always |
| [var] | $(\widehat{C}, \widehat{\rho}) \models x^\ell$ iff $\widehat{\rho}(x) \subseteq \widehat{C}(\ell)$ |
| [fn] | $(\widehat{C}, \widehat{\rho}) \models (\text{fn } x \Rightarrow e_0)^\ell$ iff $\{\text{fn } x \Rightarrow e_0\} \subseteq \widehat{C}(\ell)$ |
| [fun] | $(\widehat{C}, \widehat{\rho}) \models (\text{fun } f x \Rightarrow e_0)^\ell$ iff $\{\text{fun } f x \Rightarrow e_0\} \subseteq \widehat{C}(\ell)$ |
| [app] | $(\widehat{C}, \widehat{\rho}) \models (t_1^{\ell_1} t_2^{\ell_2})^\ell$ iff $(\widehat{C}, \widehat{\rho}) \models t_1^{\ell_1} \wedge (\widehat{C}, \widehat{\rho}) \models t_2^{\ell_2} \wedge$ $(\forall (\text{fn } x \Rightarrow t_0^{\ell_0}) \in \widehat{C}(\ell_1) :$ $\quad (\widehat{C}, \widehat{\rho}) \models t_0^{\ell_0} \wedge$ $\quad \widehat{C}(\ell_2) \subseteq \widehat{\rho}(x) \wedge \widehat{C}(\ell_0) \subseteq \widehat{C}(\ell) \wedge$ $(\forall (\text{fun } f x \Rightarrow t_0^{\ell_0}) \in \widehat{C}(\ell_1) :$ $\quad (\widehat{C}, \widehat{\rho}) \models t_0^{\ell_0} \wedge$ $\quad \widehat{C}(\ell_2) \subseteq \widehat{\rho}(x) \wedge \widehat{C}(\ell_0) \subseteq \widehat{C}(\ell) \wedge$ $\quad \{\text{fun } f x \Rightarrow t_0^{\ell_0}\} \subseteq \widehat{\rho}(f))$ |
| [if] | $(\widehat{C}, \widehat{\rho}) \models (\text{if } t_0^{\ell_0} \text{ then } t_1^{\ell_1} \text{ else } t_2^{\ell_2})^\ell$ iff $(\widehat{C}, \widehat{\rho}) \models t_0^{\ell_0} \wedge$ $\quad (\widehat{C}, \widehat{\rho}) \models t_1^{\ell_1} \wedge (\widehat{C}, \widehat{\rho}) \models t_2^{\ell_2} \wedge$ $\quad \widehat{C}(\ell_1) \subseteq \widehat{C}(\ell) \wedge \widehat{C}(\ell_2) \subseteq \widehat{C}(\ell)$ |
| [let] | $(\widehat{C}, \widehat{\rho}) \models (\text{let } x = t_1^{\ell_1} \text{ in } t_2^{\ell_2})^\ell$ iff $(\widehat{C}, \widehat{\rho}) \models t_1^{\ell_1} \wedge (\widehat{C}, \widehat{\rho}) \models t_2^{\ell_2} \wedge$ $\quad \widehat{C}(\ell_1) \subseteq \widehat{\rho}(x) \wedge \widehat{C}(\ell_2) \subseteq \widehat{C}(\ell)$ |
| [op] | $(\widehat{C}, \widehat{\rho}) \models (t_1^{\ell_1} \text{ op } t_2^{\ell_2})^\ell$ iff $(\widehat{C}, \widehat{\rho}) \models t_1^{\ell_1} \wedge (\widehat{C}, \widehat{\rho}) \models t_2^{\ell_2}$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

the Semantic Gap



| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \in \bar{c}(l)$ |
| [bi] | $(\bar{c}, \bar{\rho}) \models (t_1 x \Rightarrow e_2)' \text{ iff } (t_1 x \Rightarrow e_2) \subseteq \bar{c}(l)$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun f x \Rightarrow e_2)' \text{ iff } (fun f x \Rightarrow e_2) \subseteq \bar{c}(l)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (t_1' e_2)'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $(\forall (t_1 x \Rightarrow e_2) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l) \wedge$ $(\forall (fun f x \Rightarrow e_2) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l) \wedge$ $\quad (fun f x \Rightarrow e_2) \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (if e_1 then e_2' else e_3)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge$ $(\bar{c}, \bar{\rho}) \models e_2' \wedge (\bar{c}, \bar{\rho}) \models e_3' \wedge$ $\bar{c}(l_2) \subseteq \bar{c}(l) \wedge \bar{c}(l_3) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (let x = e_1' in e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (t_1' \# e_2)'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

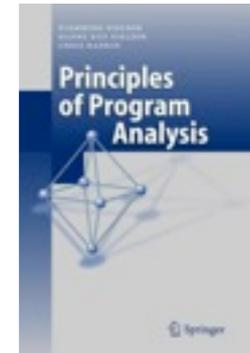


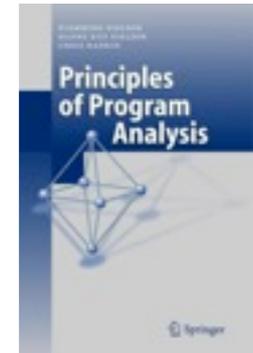
Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

$$\begin{array}{l}
 [\text{con}] \quad (\mathcal{C}, \rho) \vdash c' \text{ always} \\
 [\text{var}] \quad (\mathcal{C}, \rho) \vdash x' \text{ iff } \rho(x) \in \mathcal{C}(l) \\
 [\text{in}] \quad (\mathcal{C}, \rho) \vdash (t_1 x \Rightarrow e_0)' \text{ iff } (t_1 x \Rightarrow e_0) \in \mathcal{C}(l) \\
 [\text{fun}] \quad (\mathcal{C}, \rho) \vdash (\text{fun } f x \Rightarrow e_0)' \text{ iff } (\text{fun } f x \Rightarrow e_0) \in \mathcal{C}(l) \\
 [\text{app}] \quad (\mathcal{C}, \rho) \vdash (e_1 e_2)'\text{ iff } \\
 \quad \text{iff } (\mathcal{C}, \rho) \vdash e_1' \wedge (\mathcal{C}, \rho) \vdash e_2' \wedge \\
 \quad \quad (\forall (t_1 x \Rightarrow e_0) \in \mathcal{C}(l_1): \\
 \quad \quad \quad (\mathcal{C}, \rho) \vdash e_0' \wedge \\
 \quad \quad \quad \mathcal{C}(l_1) \subseteq \rho(x) \wedge \mathcal{C}(l_0) \subseteq \mathcal{C}(l) \wedge \\
 \quad \quad \quad (\forall (\text{fun } f x \Rightarrow e_0) \in \mathcal{C}(l_1): \\
 \quad \quad \quad \quad (\mathcal{C}, \rho) \vdash e_0' \wedge \\
 \quad \quad \quad \quad \mathcal{C}(l_1) \subseteq \rho(x) \wedge \mathcal{C}(l_0) \subseteq \mathcal{C}(l) \wedge \\
 \quad \quad \quad \quad (\text{fun } f x \Rightarrow e_0) \in \rho(f)) \\
 [\text{if}] \quad (\mathcal{C}, \rho) \vdash (\text{if } e_1 \text{ then } e_2 \text{ else } e_3)'\text{ iff } \\
 \quad \text{iff } (\mathcal{C}, \rho) \vdash e_1' \wedge \\
 \quad \quad (\mathcal{C}, \rho) \vdash e_2' \wedge (\mathcal{C}, \rho) \vdash e_3' \wedge \\
 \quad \quad \mathcal{C}(l_1) \subseteq \mathcal{C}(l) \wedge \mathcal{C}(l_2) \subseteq \mathcal{C}(l) \\
 [\text{let}] \quad (\mathcal{C}, \rho) \vdash (\text{let } x = e_1 \text{ in } e_2)'\text{ iff } \\
 \quad \text{iff } (\mathcal{C}, \rho) \vdash e_1' \wedge (\mathcal{C}, \rho) \vdash e_2' \wedge \\
 \quad \quad \mathcal{C}(l_1) \subseteq \rho(x) \wedge \mathcal{C}(l_2) \subseteq \mathcal{C}(l) \\
 [\text{op}] \quad (\mathcal{C}, \rho) \vdash (e_1 \text{ op } e_2)'\text{ iff } (\mathcal{C}, \rho) \vdash e_1' \wedge (\mathcal{C}, \rho) \vdash e_2'
 \end{array}$$

$$\begin{array}{l}
 [\text{var}] \quad \rho \vdash x^\ell \rightarrow v^\ell \text{ if } x \in \text{dom}(\rho) \text{ and } v = \rho(x) \\
 [\text{fn}] \quad \rho \vdash (\text{fn } x \Rightarrow e_0)^\ell \rightarrow (\text{close } (\text{fn } x \Rightarrow e_0) \text{ in } \rho_0)^\ell \\
 \quad \text{where } \rho_0 = \rho \upharpoonright FV(\text{fn } x \Rightarrow e_0) \\
 [\text{fun}] \quad \rho \vdash (\text{fun } f x \Rightarrow e_0)^\ell \rightarrow (\text{close } (\text{fun } f x \Rightarrow e_0) \text{ in } \rho_0)^\ell \\
 \quad \text{where } \rho_0 = \rho \upharpoonright FV(\text{fun } f x \Rightarrow e_0) \\
 [\text{app}_1] \quad \frac{\rho \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (ie_1 ie_2)^\ell \rightarrow (ie_1' ie_2)^\ell} \\
 [\text{app}_2] \quad \frac{\rho \vdash ie_2 \rightarrow ie_2'}{\rho \vdash (v_1^{\ell_1} ie_2)^\ell \rightarrow (v_1^{\ell_1} ie_2')^\ell} \\
 [\text{app}_{fn}] \quad \rho \vdash ((\text{close } (\text{fn } x \Rightarrow e_1) \text{ in } \rho_1)^{\ell_1} v_2^{\ell_2})^\ell \rightarrow \\
 \quad (\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)^\ell \\
 [\text{app}_{fun}] \quad \rho \vdash ((\text{close } (\text{fun } f x \Rightarrow e_1) \text{ in } \rho_1)^{\ell_1} v_2^{\ell_2})^\ell \rightarrow \\
 \quad (\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)^\ell \\
 \quad \text{where } \rho_2 = \rho_1[f \mapsto \text{close } (\text{fun } f x \Rightarrow e_1) \text{ in } \rho_1] \\
 [\text{bind}_1] \quad \frac{\rho_1 \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)^\ell \rightarrow (\text{bind } \rho_1 \text{ in } ie_1')^\ell} \\
 [\text{bind}_2] \quad \rho \vdash (\text{bind } \rho_1 \text{ in } v_1^{\ell_1})^\ell \rightarrow v_1^\ell
 \end{array}$$

Table 3.2: The Structural Operational Semantics of FUN (part 1).

the Semantic Gap



| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [fn] | $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)' \text{ iff } (fn\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)' \text{ iff } (fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (e_1' e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $(\forall (fn\ x \Rightarrow e_0) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $(\forall (fun\ f\ x \Rightarrow e_0) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $\quad (fun\ f\ x \Rightarrow e_0) \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (if\ e_1' \text{ then } e_2' \text{ else } e_3)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge$ $(\bar{c}, \bar{\rho}) \models e_2' \wedge (\bar{c}, \bar{\rho}) \models e_3' \wedge$ $\bar{c}(l_1) \subseteq \bar{c}(l) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (let\ x = e_1' \text{ in } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (e_1' \text{ op } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

| | |
|-----------------------|---|
| [var] | $\rho \vdash x' \rightarrow v'$ if $x \in \text{dom}(\rho)$ and $v = \rho(x)$ |
| [fn] | $\rho \vdash (fn\ x \Rightarrow e_0)' \rightarrow (\text{close } (fn\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \upharpoonright FV(fn\ x \Rightarrow e_0)$ |
| [fun] | $\rho \vdash (fun\ f\ x \Rightarrow e_0)' \rightarrow (\text{close } (fun\ f\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \upharpoonright FV(fun\ f\ x \Rightarrow e_0)$ |
| [app ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (ie_1\ ie_2)' \rightarrow (ie_1'\ ie_2)'}'$ |
| [app ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2'}{\rho \vdash (v_1' ie_2)' \rightarrow (v_1' ie_2)'}'$ |
| [app _{fn}] | $\rho \vdash ((\text{close } (fn\ x \Rightarrow e_1) \text{ in } \rho_1)'^{ie_1'} v_2')' \rightarrow$ $(\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)'$ |
| [app _{fun}] | $\rho \vdash ((\text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1)'^{ie_1'} v_2')' \rightarrow$ $(\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)'$ where $\rho_2 = \rho_1[f \mapsto \text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1]$ |
| [bind ₁] | $\frac{\rho_1 \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)' \rightarrow (\text{bind } \rho_1 \text{ in } ie_1)'}'$ |
| [bind ₂] | $\rho \vdash (\text{bind } \rho_1 \text{ in } v_1')' \rightarrow v_1'$ |

Table 3.2: The Structural Operational Semantics of FUN (part 1).

the Semantic Gap

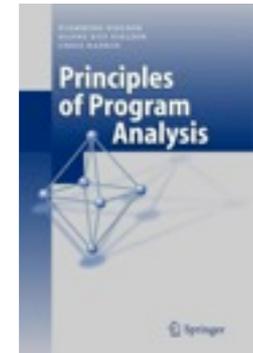


Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 to 3.1.4)

[con] $(\bar{c}, \bar{\rho}) \models c'$ always

[var] $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$

[fn] $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)' \text{ iff } (fn\ x \Rightarrow e_0) \subseteq \bar{c}(l)$

[fun] $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)' \text{ iff } (fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l)$

[app] $(\bar{c}, \bar{\rho}) \models (e_1\ e_2)'$
 iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$
 $(\forall (fn\ x \Rightarrow e_0) \in \bar{c}(l_1) :$
 $(\bar{c}, \bar{\rho}) \models e_0' \wedge$
 $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) /$
 $(\forall (fun\ f\ x \Rightarrow e_0) \in \bar{c}(l_1) :$
 $(\bar{c}, \bar{\rho}) \models e_0' \wedge$
 $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$
 $(fun\ f\ x \Rightarrow e_0) \subseteq \bar{\rho}(f))$

[if] $(\bar{c}, \bar{\rho}) \models (if\ e_0\ then\ e_1\ else\ e_2)'$
 iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge$
 $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$
 $\bar{c}(l_0) \subseteq \bar{c}(l) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$

[let] $(\bar{c}, \bar{\rho}) \models (let\ x = e_1\ in\ e_2)'$
 iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$
 $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l)$

[op] $(\bar{c}, \bar{\rho}) \models (e_1\ op\ e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$

Table 3.3: The Structural Operational Semantics of FUN (part 2).

[if₁]
$$\frac{\rho \vdash ie_0 \rightarrow ie'_0}{\rho \vdash (\text{if } ie_0 \text{ then } e_1 \text{ else } e_2)^\ell \rightarrow (\text{if } ie'_0 \text{ then } e_1 \text{ else } e_2)^\ell}$$

[if₂]
$$\rho \vdash (\text{if true}^{\ell_0} \text{ then } t_1^{\ell_1} \text{ else } t_2^{\ell_2})^\ell \rightarrow t_1^\ell$$

[if₃]
$$\rho \vdash (\text{if false}^{\ell_0} \text{ then } t_1^{\ell_1} \text{ else } t_2^{\ell_2})^\ell \rightarrow t_2^\ell$$

[let₁]
$$\frac{\rho \vdash ie_1 \rightarrow ie'_1}{\rho \vdash (\text{let } x = ie_1 \text{ in } e_2)^\ell \rightarrow (\text{let } x = ie'_1 \text{ in } e_2)^\ell}$$

[let₂]
$$\rho \vdash (\text{let } x = v^{\ell_1} \text{ in } e_2)^\ell \rightarrow (\text{bind } \rho_0[x \mapsto v] \text{ in } e_2)^\ell$$

 where $\rho_0 = \rho \upharpoonright FV(e_2)$

[op₁]
$$\frac{\rho \vdash ie_1 \rightarrow ie'_1}{\rho \vdash (ie_1 \text{ op } ie_2)^\ell \rightarrow (ie'_1 \text{ op } ie_2)^\ell}$$

[op₂]
$$\frac{\rho \vdash ie_2 \rightarrow ie'_2}{\rho \vdash (v_1^{\ell_1} \text{ op } ie_2)^\ell \rightarrow (v_1^{\ell_1} \text{ op } ie'_2)^\ell}$$

[op₃]
$$\rho \vdash (v_1^{\ell_1} \text{ op } v_2^{\ell_2})^\ell \rightarrow v^\ell \quad \text{if } v = v_1 \text{ op } v_2$$

Table 3.2: The Structural Operational Semantics of FUN (part 1).

[var] ρ

[fn] ρ

[fun] ρ

[app₁] $\bar{\rho}$

[app₂]
$$\frac{}{\rho \vdash (v_1^{\ell_1} \text{ op } v_2^{\ell_2})^\ell \rightarrow (v_1^{\ell_1} \text{ op } v_2^{\ell_2})^\ell}$$

[app_{fn}]
$$\rho \vdash ((\text{close } (fn\ x \Rightarrow e_1) \text{ in } \rho_1)^{\ell_1} v_2^{\ell_2})^\ell \rightarrow$$

 $(\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)^\ell$

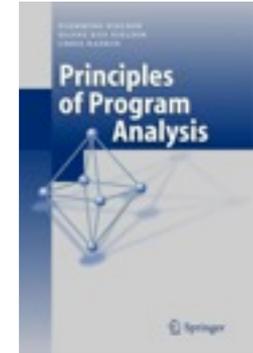
[app_{fun}]
$$\rho \vdash ((\text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1)^{\ell_1} v_2^{\ell_2})^\ell \rightarrow$$

 $(\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)^\ell$
 where $\rho_2 = \rho_1 \upharpoonright f \mapsto \text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1$

[bind₁]
$$\frac{\rho_1 \vdash ie_1 \rightarrow ie'_1}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)^\ell \rightarrow (\text{bind } \rho_1 \text{ in } ie'_1)^\ell}$$

[bind₂]
$$\rho \vdash (\text{bind } \rho_1 \text{ in } v_1^{\ell_1})^\ell \rightarrow v_1^\ell$$

the Semantic Gap



| | |
|-------|---|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x'$ iff $\bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [bi] | $(\bar{c}, \bar{\rho}) \models (fx \Rightarrow e_0)'$ iff $(fx \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (\text{fun } f \ x \Rightarrow e_0)'$ iff $(\text{fun } f \ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (e_1' e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $(\forall (fx \Rightarrow e_0) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$ $(\forall (\text{fun } f \ x \Rightarrow e_0) \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$ $\quad (\text{fun } f \ x \Rightarrow e_0) \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (\text{if } e_0' \text{ then } e_1' \text{ else } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge$ $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\bar{c}(l_0) \subseteq \bar{c}(l) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (\text{let } x = e_0' \text{ in } e_1)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge (\bar{c}, \bar{\rho}) \models e_1' \wedge$ $\bar{c}(l_0) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (e_1' \text{ op } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

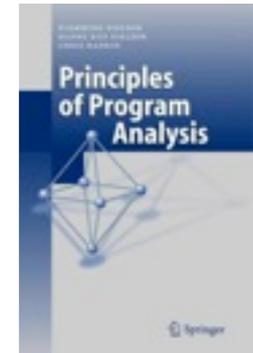
| | |
|-----------------------|--|
| [var] | $\rho \vdash x' \rightarrow v'$ if $x \in \text{dom}(\rho)$ and $v = \rho(x)$ |
| [fn] | $\rho \vdash (fx \Rightarrow e_0)' \rightarrow (\text{close } (fx \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \upharpoonright \text{FV}(fx \Rightarrow e_0)$ |
| [fun] | $\rho \vdash (\text{fun } f \ x \Rightarrow e_0)' \rightarrow (\text{close } (\text{fun } f \ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \upharpoonright \text{FV}(\text{fun } f \ x \Rightarrow e_0)$ |
| [app ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1 \ ie_2)' \rightarrow (ie_1' \ ie_2)'}{\rho \vdash (ie_1 \ ie_2)' \rightarrow (ie_1' \ ie_2)'}$ |
| [app ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1' \ ie_2)' \rightarrow (v_1' \ ie_2)'}{\rho \vdash (v_1' \ ie_2)' \rightarrow (v_1' \ ie_2)'}$ |
| [app _{fn}] | $\rho \vdash ((\text{close } (fx \Rightarrow e_1) \text{ in } \rho_1)' \ v_2')' \rightarrow$ $(\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)'$ |
| [app _{fun}] | $\rho \vdash ((\text{close } (\text{fun } f \ x \Rightarrow e_1) \text{ in } \rho_1)' \ v_2')' \rightarrow$ $(\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)'$ where $\rho_2 = \rho_1 \upharpoonright f \mapsto \text{close } (\text{fun } f \ x \Rightarrow e_1) \text{ in } \rho_1$ |
| [bind ₁] | $\frac{\rho_1 \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)' \rightarrow (\text{bind } \rho_1 \text{ in } ie_1)'}'$ |
| [bind ₂] | $\rho \vdash (\text{bind } \rho_1 \text{ in } v_1')' \rightarrow v_1'$ |

Table 3.2: The Structural Operational Semantics of FUN (part 1).

| | |
|---------------------|--|
| [if ₁] | $\frac{\rho \vdash ie_0 \rightarrow ie_0'}{\rho \vdash (\text{if } ie_0 \text{ then } e_1 \text{ else } e_2)' \rightarrow (\text{if } ie_0' \text{ then } e_1 \text{ else } e_2)'}$ |
| [if ₂] | $\rho \vdash (\text{if } \text{true}^{e_0} \text{ then } e_1' \text{ else } e_2')' \rightarrow e_1'$ |
| [if ₃] | $\rho \vdash (\text{if } \text{false}^{e_0} \text{ then } e_1' \text{ else } e_2')' \rightarrow e_2'$ |
| [let ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{let } x = ie_1 \text{ in } e_2)' \rightarrow (\text{let } x = ie_1' \text{ in } e_2)'}$ |
| [let ₂] | $\rho \vdash (\text{let } x = v^{e_1} \text{ in } e_2)' \rightarrow (\text{bind } \rho_0[x \mapsto v] \text{ in } e_2)'$ where $\rho_0 = \rho \upharpoonright \text{FV}(e_2)$ |
| [op ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1 \ \text{op} \ ie_2)' \rightarrow (ie_1' \ \text{op} \ ie_2)'}{\rho \vdash (ie_1 \ \text{op} \ ie_2)' \rightarrow (ie_1' \ \text{op} \ ie_2)'}$ |
| [op ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1' \ \text{op} \ ie_2)' \rightarrow (v_1' \ \text{op} \ ie_2)'}{\rho \vdash (v_1' \ \text{op} \ ie_2)' \rightarrow (v_1' \ \text{op} \ ie_2)'}$ |
| [op ₃] | $\rho \vdash (v_1' \ \text{op} \ v_2')' \rightarrow v'$ if $v = v_1 \ \text{op} \ v_2$ |

Table 3.3: The Structural Operational Semantics of FUN (part 2).

the Semantic Gap



| | |
|-------|---|
| [con] | $(\hat{C}, \hat{\rho}) \models c^l$ always |
| [var] | $(\hat{C}, \hat{\rho}) \models x^l$ iff $\hat{\rho}(x) \subseteq \hat{C}(l)$ |
| [fn] | $(\hat{C}, \hat{\rho}) \models (fn\ x \Rightarrow e_0)^l$ iff $\{fn\ x \Rightarrow e_0\} \subseteq \hat{C}(l)$ |
| [fun] | $(\hat{C}, \hat{\rho}) \models (fun\ f\ x \Rightarrow e_0)^l$ iff $\{fun\ f\ x \Rightarrow e_0\} \subseteq \hat{C}(l)$ |
| [app] | $(\hat{C}, \hat{\rho}) \models (t_1^l\ t_2^l)^l$ iff $(\hat{C}, \hat{\rho}) \models t_1^l \wedge (\hat{C}, \hat{\rho}) \models t_2^l \wedge$ $(\forall (fn\ x \Rightarrow e_0^l) \in \hat{C}(l_1) :$ $\hat{C}(l_2) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_0) \subseteq \hat{C}(l) \wedge$ $(\forall (fun\ f\ x \Rightarrow e_0^l) \in \hat{C}(l_1) :$ $\hat{C}(l_2) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_0) \subseteq \hat{C}(l) \wedge$ $\{fun\ f\ x \Rightarrow e_0^l\} \subseteq \hat{\rho}(f))$ |
| [if] | $(\hat{C}, \hat{\rho}) \models (if\ t_0^l\ then\ t_1^l\ else\ t_2^l)^l$ iff $(\hat{C}, \hat{\rho}) \models t_0^l \wedge$ $(\hat{C}, \hat{\rho}) \models t_1^l \wedge (\hat{C}, \hat{\rho}) \models t_2^l \wedge$ $\hat{C}(l_2) \subseteq \hat{C}(l) \wedge \hat{C}(l_0) \subseteq \hat{C}(l)$ |
| [let] | $(\hat{C}, \hat{\rho}) \models (let\ x = t_1^l\ in\ t_2^l)^l$ iff $(\hat{C}, \hat{\rho}) \models t_1^l \wedge (\hat{C}, \hat{\rho}) \models t_2^l \wedge$ $\hat{C}(l_1) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_0) \subseteq \hat{C}(l)$ |
| [op] | $(\hat{C}, \hat{\rho}) \models (t_1^l\ op\ t_2^l)^l$ iff $(\hat{C}, \hat{\rho}) \models t_1^l \wedge (\hat{C}, \hat{\rho}) \models t_2^l$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

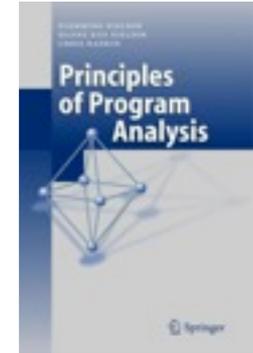
| | |
|-------|---|
| [con] | $(\hat{C}, \hat{\rho}) \models_s c^l$ always |
| [var] | $(\hat{C}, \hat{\rho}) \models_s x^l$ iff $\hat{\rho}(x) \subseteq \hat{C}(l)$ |
| [fn] | $(\hat{C}, \hat{\rho}) \models_s (fn\ x \Rightarrow e_0)^l$ iff $\{fn\ x \Rightarrow e_0\} \subseteq \hat{C}(l) \wedge$ $(\hat{C}, \hat{\rho}) \models_s e_0$ |
| [fun] | $(\hat{C}, \hat{\rho}) \models_s (fun\ f\ x \Rightarrow e_0)^l$ iff $\{fun\ f\ x \Rightarrow e_0\} \subseteq \hat{C}(l) \wedge$ $(\hat{C}, \hat{\rho}) \models_s e_0 \wedge \{fun\ f\ x \Rightarrow e_0\} \subseteq \hat{\rho}(f)$ |
| [app] | $(\hat{C}, \hat{\rho}) \models_s (t_1^{l_1}\ t_2^{l_2})^l$ iff $(\hat{C}, \hat{\rho}) \models_s t_1^{l_1} \wedge (\hat{C}, \hat{\rho}) \models_s t_2^{l_2} \wedge$ $(\forall (fn\ x \Rightarrow t_0^{l_0}) \in \hat{C}(l_1) :$ $\hat{C}(l_2) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_0) \subseteq \hat{C}(l) \wedge$ $(\forall (fun\ f\ x \Rightarrow t_0^{l_0}) \in \hat{C}(l_1) :$ $\hat{C}(l_2) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_0) \subseteq \hat{C}(l))$ |
| [if] | $(\hat{C}, \hat{\rho}) \models_s (if\ t_0^{l_0}\ then\ t_1^{l_1}\ else\ t_2^{l_2})^l$ iff $(\hat{C}, \hat{\rho}) \models_s t_0^{l_0} \wedge$ $(\hat{C}, \hat{\rho}) \models_s t_1^{l_1} \wedge (\hat{C}, \hat{\rho}) \models_s t_2^{l_2} \wedge$ $\hat{C}(l_1) \subseteq \hat{C}(l) \wedge \hat{C}(l_2) \subseteq \hat{C}(l)$ |
| [let] | $(\hat{C}, \hat{\rho}) \models_s (let\ x = t_1^{l_1}\ in\ t_2^{l_2})^l$ iff $(\hat{C}, \hat{\rho}) \models_s t_1^{l_1} \wedge (\hat{C}, \hat{\rho}) \models_s t_2^{l_2} \wedge$ $\hat{C}(l_1) \subseteq \hat{\rho}(x) \wedge \hat{C}(l_2) \subseteq \hat{C}(l)$ |
| [op] | $(\hat{C}, \hat{\rho}) \models_s (t_1^{l_1}\ op\ t_2^{l_2})^l$ iff $(\hat{C}, \hat{\rho}) \models_s t_1^{l_1} \wedge (\hat{C}, \hat{\rho}) \models_s t_2^{l_2}$ |

Table 3.5: Syntax directed Control Flow Analysis.

| | |
|-----------------------|---|
| [var] | $\rho \vdash x^l \rightarrow v^l$ if $x \in do$ |
| [fn] | $\rho \vdash (fn\ x \Rightarrow e_0)^l \rightarrow (c$ where ρ_0 |
| [fun] | $\rho \vdash (fun\ f\ x \Rightarrow e_0)^l \rightarrow$ where ρ_0 |
| [app ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1^l}{\rho \vdash (ie_1\ ie_2)^l \rightarrow (ie_1^l\ i}$ |
| [app ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2^l}{\rho \vdash (v_1^l\ ie_2)^l \rightarrow (v_1^l\ i}$ |
| [app _{fn}] | $\rho \vdash ((close\ (fn\ x \Rightarrow e$ (b1 |
| [app _{fun}] | $\rho \vdash ((close\ (fun\ f\ x \Rightarrow$ (b1 where ρ_2 |
| [bind ₁] | $\frac{\rho_2 \vdash ie_1}{\rho \vdash (bind\ \rho_1\ in\ ie_1)^l}$ |
| [bind ₂] | $\rho \vdash (bind\ \rho_1\ in\ v_1^l)^l$ |

Table 3.2: The Structural Operational Semantics of FUN (part 1).

the Semantic Gap



| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [fn] | $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)' \text{ iff } (fn\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)' \text{ iff } (fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (e_1' e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $(\forall (fn\ x \Rightarrow e_0) \in \bar{c}(l_1):$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$ $\quad (\forall (fun\ f\ x \Rightarrow e_0) \in \bar{c}(l_1):$ $\quad \quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$ $\quad \quad (fun\ f\ x \Rightarrow e_0) \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (\text{if } e_0' \text{ then } e_1' \text{ else } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad (\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\quad \bar{c}(l_0) \subseteq \bar{c}(l) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (\text{let } x = e_0' \text{ in } e_1)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge (\bar{c}, \bar{\rho}) \models e_1' \wedge$ $\quad \bar{c}(l_0) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (e_1' \text{ op } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [fn] | $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)'$ iff $(fn\ x \Rightarrow e_0) \subseteq \bar{c}(l) \wedge$ $\quad (\bar{c}, \bar{\rho}) \models e_0$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)'$ iff $(fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l) \wedge$ $\quad (\bar{c}, \bar{\rho}) \models e_0 \wedge (fun\ f\ x \Rightarrow e_0) \subseteq \bar{\rho}(f)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (e_1' e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\quad (\forall (fn\ x \Rightarrow e_0) \in \bar{c}(l_1):$ $\quad \quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l) \wedge$ $\quad \quad (\forall (fun\ f\ x \Rightarrow e_0) \in \bar{c}(l_1):$ $\quad \quad \quad \bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_0) \subseteq \bar{c}(l))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (\text{if } e_0' \text{ then } e_1' \text{ else } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad (\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2' \wedge$ $\quad \bar{c}(l_0) \subseteq \bar{c}(l) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (\text{let } x = e_0' \text{ in } e_1)'$ iff $(\bar{c}, \bar{\rho}) \models e_0' \wedge (\bar{c}, \bar{\rho}) \models e_1' \wedge$ $\quad \bar{c}(l_0) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_1) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (e_1' \text{ op } e_2)'$ iff $(\bar{c}, \bar{\rho}) \models e_1' \wedge (\bar{c}, \bar{\rho}) \models e_2'$ |

Table 3.5: Syntax directed Control Flow Analysis.

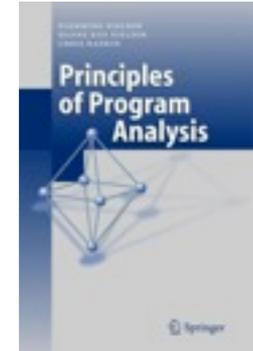
| | |
|-----------------------|--|
| [var] | $\rho \vdash x' \rightarrow v' \text{ if } x \in \text{dom}(\rho) \text{ and } v = \rho(x)$ |
| [fn] | $\rho \vdash (fn\ x \Rightarrow e_0)' \rightarrow (\text{close } (fn\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \mid FV(fn\ x \Rightarrow e_0)$ |
| [fun] | $\rho \vdash (fun\ f\ x \Rightarrow e_0)' \rightarrow (\text{close } (fun\ f\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \mid FV(fun\ f\ x \Rightarrow e_0)$ |
| [app ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1\ ie_2)' \rightarrow (ie_1'\ ie_2)'}{\rho \vdash (ie_1\ ie_2)' \rightarrow (ie_1'\ ie_2)'}'$ |
| [app ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1^i\ ie_2)' \rightarrow (v_1^i\ ie_2')'}{\rho \vdash (v_1^i\ ie_2)' \rightarrow (v_1^i\ ie_2')}'$ |
| [app _{rho}] | $\rho \vdash ((\text{close } (fn\ x \Rightarrow e_1) \text{ in } \rho_1)^{i_1}\ v_2^i)' \rightarrow$ $\quad (\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)'$ |
| [app _{fun}] | $\rho \vdash ((\text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1)^{i_1}\ v_2^i)' \rightarrow$ $\quad (\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)'$ where $\rho_2 = \rho_1 \mid f \mapsto \text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1$ |
| [bind ₁] | $\frac{\rho_1 \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)' \rightarrow (\text{bind } \rho_1 \text{ in } ie_1')}'$ |
| [bind ₂] | $\rho \vdash (\text{bind } \rho_1 \text{ in } v_1^i)' \rightarrow v_1^i$ |

Table 3.2: The Structural Operational Semantics of FUN (part 1).

| | |
|---------------------|--|
| [if ₁] | $\frac{\rho \vdash ie_0 \rightarrow ie_0'}{\rho \vdash (\text{if } ie_0 \text{ then } e_1 \text{ else } e_2)' \rightarrow (\text{if } ie_0' \text{ then } e_1 \text{ else } e_2)'}'$ |
| [if ₂] | $\rho \vdash (\text{if } true^{i_0} \text{ then } e_1^i \text{ else } e_2^i)' \rightarrow e_1^i$ |
| [if ₃] | $\rho \vdash (\text{if } false^{i_0} \text{ then } e_1^i \text{ else } e_2^i)' \rightarrow e_2^i$ |
| [let ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{let } x = ie_1 \text{ in } e_2)' \rightarrow (\text{let } x = ie_1' \text{ in } e_2)'}'$ |
| [let ₂] | $\rho \vdash (\text{let } x = v^{i_1} \text{ in } e_2)' \rightarrow (\text{bind } \rho_0[x \mapsto v] \text{ in } e_2)'$ where $\rho_0 = \rho \mid FV(e_2)$ |
| [op ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1\ op\ ie_2)' \rightarrow (ie_1'\ op\ ie_2)'}{\rho \vdash (ie_1\ op\ ie_2)' \rightarrow (ie_1'\ op\ ie_2)'}'$ |
| [op ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1^i\ op\ ie_2)' \rightarrow (v_1^i\ op\ ie_2')'}{\rho \vdash (v_1^i\ op\ ie_2)' \rightarrow (v_1^i\ op\ ie_2')}'$ |
| [op ₃] | $\rho \vdash (v_1^i\ op\ v_2^i)' \rightarrow v'$ if $v = v_1 \text{ op } v_2$ |

Table 3.3: The Structural Operational Semantics of FUN (part 2).

the Semantic Gap



| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [fn] | $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)' \text{ iff } (fn\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)' \text{ iff } (fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (t_1' \ t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $(\forall (fn\ x \Rightarrow e_0)' \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $\quad (\forall (fun\ f\ x \Rightarrow e_0)' \in \bar{c}(l_1) :$ $\quad (\bar{c}, \bar{\rho}) \models e_0' \wedge$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(f) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $\quad (fun\ f\ x \Rightarrow e_0)' \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (\text{if } t_0' \text{ then } t_1' \text{ else } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_0' \wedge$ $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $\bar{c}(l_1) \subseteq \bar{c}(l) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (\text{let } x = t_1' \text{ in } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (t_1' \text{ op } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2'$ |

Table 3.1: Abstract Control Flow Analysis (Subsections 3.1.1 and 3.1.2).

| | |
|-------|--|
| [con] | $(\bar{c}, \bar{\rho}) \models c'$ always |
| [var] | $(\bar{c}, \bar{\rho}) \models x' \text{ iff } \bar{\rho}(x) \subseteq \bar{c}(l)$ |
| [fn] | $(\bar{c}, \bar{\rho}) \models (fn\ x \Rightarrow e_0)'$ iff $(fn\ x \Rightarrow e_0) \subseteq \bar{c}(l) \wedge$ $(\bar{c}, \bar{\rho}) \models e_0$ |
| [fun] | $(\bar{c}, \bar{\rho}) \models (fun\ f\ x \Rightarrow e_0)'$ iff $(fun\ f\ x \Rightarrow e_0) \subseteq \bar{c}(l) \wedge$ $(\bar{c}, \bar{\rho}) \models e_0 \wedge (fun\ f\ x \Rightarrow e_0) \subseteq \bar{\rho}(f)$ |
| [app] | $(\bar{c}, \bar{\rho}) \models (t_1' \ t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $(\forall (fn\ x \Rightarrow e_0)' \in \bar{c}(l_1) :$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $\quad (\forall (fun\ f\ x \Rightarrow e_0)' \in \bar{c}(l_1) :$ $\quad \bar{c}(l_2) \subseteq \bar{\rho}(f) \wedge \bar{c}(l_3) \subseteq \bar{c}(l) \wedge$ $\quad (fun\ f\ x \Rightarrow e_0)' \subseteq \bar{\rho}(f))$ |
| [if] | $(\bar{c}, \bar{\rho}) \models (\text{if } t_0' \text{ then } t_1' \text{ else } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_0' \wedge$ $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $\bar{c}(l_1) \subseteq \bar{c}(l) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [let] | $(\bar{c}, \bar{\rho}) \models (\text{let } x = t_1' \text{ in } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2' \wedge$ $\bar{c}(l_1) \subseteq \bar{\rho}(x) \wedge \bar{c}(l_2) \subseteq \bar{c}(l)$ |
| [op] | $(\bar{c}, \bar{\rho}) \models (t_1' \text{ op } t_2')'$ iff $(\bar{c}, \bar{\rho}) \models t_1' \wedge (\bar{c}, \bar{\rho}) \models t_2'$ |

Table 3.5: Syntax directed Control Flow Analysis.

| | |
|-------|--|
| [con] | $C_*[c'] = \emptyset$ |
| [var] | $C_*[x'] = \{r(x) \subseteq C(l)\}$ |
| [fn] | $C_*[(fn\ x \Rightarrow e_0)'] = \{(fn\ x \Rightarrow e_0) \subseteq C(l) \cup C_*[e_0]\}$ |
| [fun] | $C_*[(fun\ f\ x \Rightarrow e_0)'] = \{(fun\ f\ x \Rightarrow e_0) \subseteq C(l) \cup C_*[e_0] \cup \{(fun\ f\ x \Rightarrow e_0) \subseteq r(f)\}\}$ |
| [app] | $C_*[(t_1' \ t_2')'] = C_*[t_1'] \cup C_*[t_2'] \cup \{(t) \subseteq C(l_1) \Rightarrow C(l_2) \subseteq r(x) \mid t = (fn\ x \Rightarrow t_0') \in \text{Term}_*\} \cup \{(t) \subseteq C(l_1) \Rightarrow C(l_2) \subseteq C(l) \mid t = (fn\ x \Rightarrow t_0') \in \text{Term}_*\} \cup \{(t) \subseteq C(l_1) \Rightarrow C(l_2) \subseteq r(x) \mid t = (fun\ f\ x \Rightarrow t_0') \in \text{Term}_*\} \cup \{(t) \subseteq C(l_1) \Rightarrow C(l_2) \subseteq C(l) \mid t = (fun\ f\ x \Rightarrow t_0') \in \text{Term}_*\}$ |
| [if] | $C_*[(\text{if } t_0' \text{ then } t_1' \text{ else } t_2')'] = C_*[t_0'] \cup C_*[t_1'] \cup C_*[t_2'] \cup \{C(l_1) \subseteq C(l)\} \cup \{C(l_2) \subseteq C(l)\}$ |
| [let] | $C_*[(\text{let } x = t_1' \text{ in } t_2')'] = C_*[t_1'] \cup C_*[t_2'] \cup \{C(l_1) \subseteq r(x)\} \cup \{C(l_2) \subseteq C(l)\}$ |
| [op] | $C_*[(t_1' \text{ op } t_2')'] = C_*[t_1'] \cup C_*[t_2']$ |

Table 3.6: Constraint based Control Flow Analysis.

| | |
|-----------------------|--|
| [var] | $\rho \vdash x' \rightarrow v' \text{ if } x \in \text{dom}(\rho) \text{ and } v = \rho(x)$ |
| [fn] | $\rho \vdash (fn\ x \Rightarrow e_0)' \rightarrow (\text{close } (fn\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \mid \text{FV}(fn\ x \Rightarrow e_0)$ |
| [fun] | $\rho \vdash (fun\ f\ x \Rightarrow e_0)' \rightarrow (\text{close } (fun\ f\ x \Rightarrow e_0) \text{ in } \rho_0)'$ where $\rho_0 = \rho \mid \text{FV}(fun\ f\ x \Rightarrow e_0)$ |
| [app ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1 \ ie_2)' \rightarrow (ie_1' \ ie_2)'}{\rho \vdash (ie_1 \ ie_2)' \rightarrow (ie_1' \ ie_2)'}$ |
| [app ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1' \ ie_2)' \rightarrow (v_1' \ ie_2)'}{\rho \vdash (v_1' \ ie_2)' \rightarrow (v_1' \ ie_2)'}$ |
| [app _{fn}] | $\rho \vdash ((\text{close } (fn\ x \Rightarrow e_1) \text{ in } \rho_1)'^{t_1'} \ v_2')' \rightarrow$ $(\text{bind } \rho_1[x \mapsto v_2] \text{ in } e_1)'$ |
| [app _{fun}] | $\rho \vdash ((\text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1)'^{t_1'} \ v_2')' \rightarrow$ $(\text{bind } \rho_2[x \mapsto v_2] \text{ in } e_1)'$ where $\rho_2 = \rho_1 \mid f \mapsto \text{close } (fun\ f\ x \Rightarrow e_1) \text{ in } \rho_1$ |
| [bind ₁] | $\frac{\rho_1 \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{bind } \rho_1 \text{ in } ie_1)' \rightarrow (\text{bind } \rho_1 \text{ in } ie_1)'}$ |
| [bind ₂] | $\rho \vdash (\text{bind } \rho_1 \text{ in } v_1')' \rightarrow v_1'$ |

Table 3.2: The Structural Operational Semantics of FUN (part 1).

| | |
|---------------------|--|
| [if ₁] | $\frac{\rho \vdash ie_0 \rightarrow ie_0'}{\rho \vdash (\text{if } ie_0 \text{ then } e_1 \text{ else } e_2)' \rightarrow (\text{if } ie_0' \text{ then } e_1 \text{ else } e_2)'}$ |
| [if ₂] | $\rho \vdash (\text{if } \text{true}^{e_0} \text{ then } t_1' \text{ else } t_2')' \rightarrow t_1'$ |
| [if ₃] | $\rho \vdash (\text{if } \text{false}^{e_0} \text{ then } t_1' \text{ else } t_2')' \rightarrow t_2'$ |
| [let ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1'}{\rho \vdash (\text{let } x = ie_1 \text{ in } e_2)' \rightarrow (\text{let } x = ie_1' \text{ in } e_2)'}$ |
| [let ₂] | $\rho \vdash (\text{let } x = v^{e_1} \text{ in } e_2)' \rightarrow (\text{bind } \rho_0[x \mapsto v] \text{ in } e_2)'$ where $\rho_0 = \rho \mid \text{FV}(e_2)$ |
| [op ₁] | $\frac{\rho \vdash ie_1 \rightarrow ie_1' \quad \rho \vdash (ie_1 \text{ op } ie_2)' \rightarrow (ie_1' \text{ op } ie_2)'}{\rho \vdash (ie_1 \text{ op } ie_2)' \rightarrow (ie_1' \text{ op } ie_2)'}$ |
| [op ₂] | $\frac{\rho \vdash ie_2 \rightarrow ie_2' \quad \rho \vdash (v_1' \text{ op } ie_2)' \rightarrow (v_1' \text{ op } ie_2)'}{\rho \vdash (v_1' \text{ op } ie_2)' \rightarrow (v_1' \text{ op } ie_2)'}$ |
| [op ₃] | $\rho \vdash (v_1' \text{ op } v_2')' \rightarrow v'$ if $v = v_1 \text{ op } v_2$ |

Table 3.3: The Structural Operational Semantics of FUN (part 2).

My challenge to ICFP:

Develop a program analysis for reasoning about:

Space-consumption in a lazy language

State and control in a language with effects

Security in a language with stack inspection

Blame in a language with behavioral contracts

Safe parallelism in a language with futures

My cl ICFP:

Develop a progr

Spac

Stat

Secu

Blan

Safe



ut:

lage

th effects

nspection

al contracts

l futures

Modularity of existing analyses

Three approaches:

Three approaches:

Do nothing (analyze whole programs only)

Three approaches:

Do nothing (analyze whole programs only)

Hemorrhage precision (black hole approach)

Three approaches:

Do nothing (analyze whole programs only)

Hemorrhage precision (black hole approach)

Do something really complicated

Modular Set-Based Analysis from Contracts

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Abstract

In PLT Scheme, programs consist of modules with contracts. The latter describe the inputs and outputs of functions and objects via predicates. A run-time system enforces these predicates; if a predicate fails, the enforcer raises an exception that blames a specific module with an explanation of the fault.

In this paper, we show how to use such module contracts to turn set-based analysis into a fully modular parameterized analysis. Using this analysis, a static debugger can indicate for any given contract check whether the corresponding predicate is always satisfied, partially satisfied, or (potentially) completely violated. The static debugger can also predict the source of potential errors, i.e., it is sound with respect to the blame assignment of the contract system.

Categories and Subject Descriptors F.3.2 [Semantics of Programming Languages]: Program analysis; D.2.4 [Software / Program Verification]: Programming by contract

General Terms Languages, Reliability, Verification.

Keywords Static Debugging, Set-based Analysis, Modular Analysis, Runtime Contracts.

1. Modules, Contracts, and Static Debugging

A static debugger helps programmers find errors via program analyses. It uses the invariants of the programming language to analyze the program and determines whether the program may violate one of them during execution. For example, a static debugger can find expressions that may dereference null pointers. Some static debuggers use lightweight analyses, e.g., Flanagan et al.'s MrSpidey [11] relies on a variant of set-based analysis [10, 16, 21]; others use a deep abstract interpretation, e.g., Bourdoncle's Syntox [4]; and yet others employ theorem proving, e.g., Detlefs et al.'s ESC [7].

Experience with static debuggers shows that they work well for reasonably small programs. Using MrSpidey, we have routinely debugged or re-engineered programs of 2,000 to 5,000 lines of code in PLT Scheme. Flanagan has successfully analyzed the core of the interpreter, dubbed MrEd [13], a 40,000 line program. Existing static debuggers, however, suffer from a monolithic approach to program analysis. Because their analyses require the availability of the entire program, programmers cannot analyze their programs until they have everyone else's modules.

Over the past few years, we have added a first-order module system to PLT Scheme [12] and have equipped the module system with a contract system [8]. A contract is roughly a predicate on the inputs and outputs of (exported) functions, including object methods and higher-order functions. The contract system monitors the contracts during program execution. If a module violates a contract, the contract system pinpoints the guilty party and issues an explanatory message.

This paper makes five contributions to static debugging and software contracts. *First*, it explains how to construct a modular static debugger for programs with contracts, using those contracts in a dual role: one as a source of abstract values and one as a sink for abstract values. *Second*, we prove that our contract-based, whole-program analysis computes its results in a modular manner. That is, our contract-aware set-based analysis produces the same predictions for a given point in the program regardless of whether it analyzes the whole program or just the surrounding module. *Third*, for any given contract check, the system indicates whether the corresponding predicate is always satisfied, partially satisfied, or completely violated. *Fourth*, the static debugger can also predict the source of potential errors, i.e., it is sound with respect to the blame assignment of the contract system. *Fifth*, the analysis is parameterized over both a predicate approximation relation and a predicate domain function.

2. Overview

The paper presents a model of a modular static debugger. The model consists of two parts: a runtime contract system and a set-based analysis for modules with contracts. A correctness theorem ties the two parts together. Figure 1 provides an overview of these three pieces in graphical form. The vertical column on the left represents the runtime contract system. A contract compiler translates a collection of modules and a main expression into a suitably annotated form. During execution, which we naturally model via a reduction system, the contract system keeps track of the contract obligations; if something goes wrong it blames a specific module.

The first horizontal row of Figure 1 depicts the analysis process, which consists of three stages. First, it partitions the program into module-like pieces by lifting expressions with contract annotations out of the main program. Second, the resulting collection of program pieces is analyzed with a parameterized set-based analysis. This step yields both sets of abstract values and sets of potential errors, including explanations that blame the guilty party; we call the latter *blame sets*. Third, the former are summarized as set-of-values descriptions, dubbed *types*.

The rest of the grid in Figure 1 explains our proof technique for the correctness theorem. Since each reduction step creates a complete program, the correctness proof can proceed via subject reduction. We re-apply the analysis after each reduction step. The proof then shows that the reductions preserve the types and the blame

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POPL'06 January 11–13, 2006, Charleston, South Carolina, USA.
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Abstract

In PLT Scheme, programs
latter describe the inputs
via predicates. A run-time
a predicate fails, the entire
specific module with an error.

In this paper, we show
set-based analysis into a
finding this analysis, a static
contract check whether the contract
partially satisfied, or (potentially)
debugger can also predict
sound with respect to the

**Categories and Subject
gramming Languages]: Program
Verification]: Program**

General Terms Languages

Keywords Static Debugging,
Analysis, Runtime Contracts.

1. Modules, Contracts

A static debugger helps
programs. It uses the invariants
the program and determines
of them during execution.
expressions that may dereference
gers use lightweight analysis
relies on a variant of set-based
deep abstract interpretation
others employ theorem proving.
Experience with static
reasonably small programs
debugged or re-engineered
in PLT Scheme. Flanagan
the interpreter, dubbed Mini-
static debuggers, however,
program analysis. Because
of the entire program, programs
until they have everyone else

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| Source \ Sink | $\text{int}_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 \text{int}_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ | $\text{any}_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 \text{any}_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ |
|---|------------------------------|---|------------------------------|---|
| $n_{e_1 \dots}^{l_n}$ | | $\left. \begin{array}{l} \{l_n\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_n\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{int}_f^{l_1^+ l_1^-}$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\langle \dots e_1 \text{int}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{any}_f^{l_1^+ l_1^-}$ | | | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\langle \dots e_1 \text{any}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(\lambda x^\beta. e^\ell)_{e_1 \dots}^{l_\lambda}$ | | $\{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_5^+) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l) \subseteq \varphi(l_5^-) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-}$ | | | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_5^+) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_5^-) \end{array} \right\}$ |
| $\langle \dots e_3 (c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-} \rangle_f^{l_4^+ l_4^-}$ | | $\{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \\ e_3 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |

| Source \ Sink | $(e^{l_5} e^{l_6})_{l_a}$ | $(c_i^{l_7^+ l_7^-} \rightarrow c_h^{l_8^+ l_8^-})_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 (c_i^{l_7^+ l_7^-} \rightarrow c_h^{l_8^+ l_8^-})_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ |
|---|---|---|---|
| $n_{e_1 \dots}^{l_n}$ | $\{l_n\} \subseteq \varphi(l_5) \Rightarrow \{\langle \lambda, \mathcal{R} \rangle\} \subseteq \psi(l_a)$ | | $\{l_n\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{int}_f^{l_1^+ l_1^-}$ | | | |
| $\langle \dots e_1 \text{int}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | $\{l_1^+\} \subseteq \varphi(l_5) \Rightarrow \{\langle \lambda, \mathcal{R} \rangle\} \subseteq \psi(l_a)$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{any}_f^{l_1^+ l_1^-}$ | | | |
| $\langle \dots e_1 \text{any}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | | |
| $(\lambda x^\beta. e^\ell)_{e_1 \dots}^{l_\lambda}$ | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_6) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5) \Rightarrow \varphi(l) \subseteq \varphi(l_a) \end{array} \right\}$ | | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_7^+) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l) \subseteq \varphi(l_8^-) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-}$ | | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_7^+) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_8^-) \end{array} \right\}$ |
| $\langle \dots e_3 (c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-} \rangle_f^{l_4^+ l_4^-}$ | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_6) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_a) \end{array} \right\}$ | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \\ e_3 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |

Table 1. Constraints creation for source-sink pairs.

N.

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Abstract

In PLT Scheme, programs
latter describe the inputs
via predicates. A run-time
predicate fails, the entire
specific module with an error.

In this paper, we show
set-based analysis into a
finding this analysis, a static
contract check whether the contract
partially satisfied, or (potentially)
debugger can also predict
sound with respect to the

Categories and Subject
gramming Languages]: Program
Verification]: Program

General Terms Language

Keywords Static Debugger,
Analysis, Runtime Contracts.

1. Modules, Contracts

A static debugger helps
programs. It uses the invariants
the program and determines
of them during execution.
expressions that may dereference
use lightweight analysis
relies on a variant of set-based
deep abstract interpretation
others employ theorem proving.
Experience with static
reasonably small programs
debugged or re-engineered
in PLT Scheme. Flanagan
the interpreter, dubbed Mini-
static debuggers, however,
program analysis. Because
of the entire program, programs
until they have everyone else

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| Source \ Sink | $\text{int}_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 \text{int}_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ | $\text{any}_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 \text{any}_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ |
|---|------------------------------|---|------------------------------|---|
| $n_{e_1 \dots}^{l_n}$ | | $\left. \begin{array}{l} \{l_n\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_n\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{int}_f^{l_1^+ l_1^-}$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\langle \dots e_1 \text{int}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{any}_f^{l_1^+ l_1^-}$ | | | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $\langle \dots e_1 \text{any}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_1^+\} \subseteq \varphi(l_5^-) \\ e_1 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(\lambda x^\beta. e^\ell)_{e_1 \dots}^{l_\lambda}$ | | $\{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_5^+) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l) \subseteq \varphi(l_5^-) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-}$ | | | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_5^+) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_5^-) \end{array} \right\}$ |
| $\langle \dots e_3 (c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-} \rangle_f^{l_4^+ l_4^-}$ | | $\{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \\ e_3 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |

| Source \ Sink | $(e^{l_5} e^{l_6})_{l_a}$ | $(c_i^{l_7^+ l_7^-} \rightarrow c_h^{l_8^+ l_8^-})_h^{l_5^+ l_5^-}$ | $\langle \dots e_5 (c_i^{l_7^+ l_7^-} \rightarrow c_h^{l_8^+ l_8^-})_h^{l_5^+ l_5^-} \rangle_h^{l_6^+ l_6^-}$ |
|---|---|---|---|
| $n_{e_1 \dots}^{l_n}$ | $\{l_n\} \subseteq \varphi(l_5) \Rightarrow \{\langle \lambda, \mathcal{R} \rangle\} \subseteq \psi(l_a)$ | | $\{l_n\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{int}_f^{l_1^+ l_1^-}$ | | | |
| $\langle \dots e_1 \text{int}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | $\{l_1^+\} \subseteq \varphi(l_5) \Rightarrow \{\langle \lambda, \mathcal{R} \rangle\} \subseteq \psi(l_a)$ | | $\{l_1^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{R} \rangle\} \subseteq \psi(l_5^-)$ |
| $\text{any}_f^{l_1^+ l_1^-}$ | | | |
| $\langle \dots e_1 \text{any}_f^{l_1^+ l_1^-} \rangle_f^{l_2^+ l_2^-}$ | | | |
| $(\lambda x^\beta. e^\ell)_{e_1 \dots}^{l_\lambda}$ | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_6) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5) \Rightarrow \varphi(l) \subseteq \varphi(l_a) \end{array} \right\}$ | | $\left. \begin{array}{l} \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_7^+) \subseteq \varphi(\beta) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l) \subseteq \varphi(l_8^-) \\ \{l_\lambda\} \subseteq \varphi(l_5^-) \\ e_1 \dots \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |
| $(c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-}$ | | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_7^+) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5^-) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_8^-) \end{array} \right\}$ |
| $\langle \dots e_3 (c_g^{l_1^+ l_1^-} \rightarrow c_f^{l_2^+ l_2^-})_f^{l_3^+ l_3^-} \rangle_f^{l_4^+ l_4^-}$ | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_6) \subseteq \varphi(l_1^-) \\ \{l_3^+\} \subseteq \varphi(l_5) \Rightarrow \varphi(l_2^+) \subseteq \varphi(l_a) \end{array} \right\}$ | | $\left. \begin{array}{l} \{l_3^+\} \subseteq \varphi(l_5^-) \\ e_3 \not\sqsubseteq e_5 \end{array} \right\} \Rightarrow \{\langle h, \mathcal{O} \rangle\} \subseteq \psi(l_5^-)$ |

Table 1. Constraints creation for source-sink pairs.

Higher-order Program Analysis is Alive and Well.

(I have a way forward.)

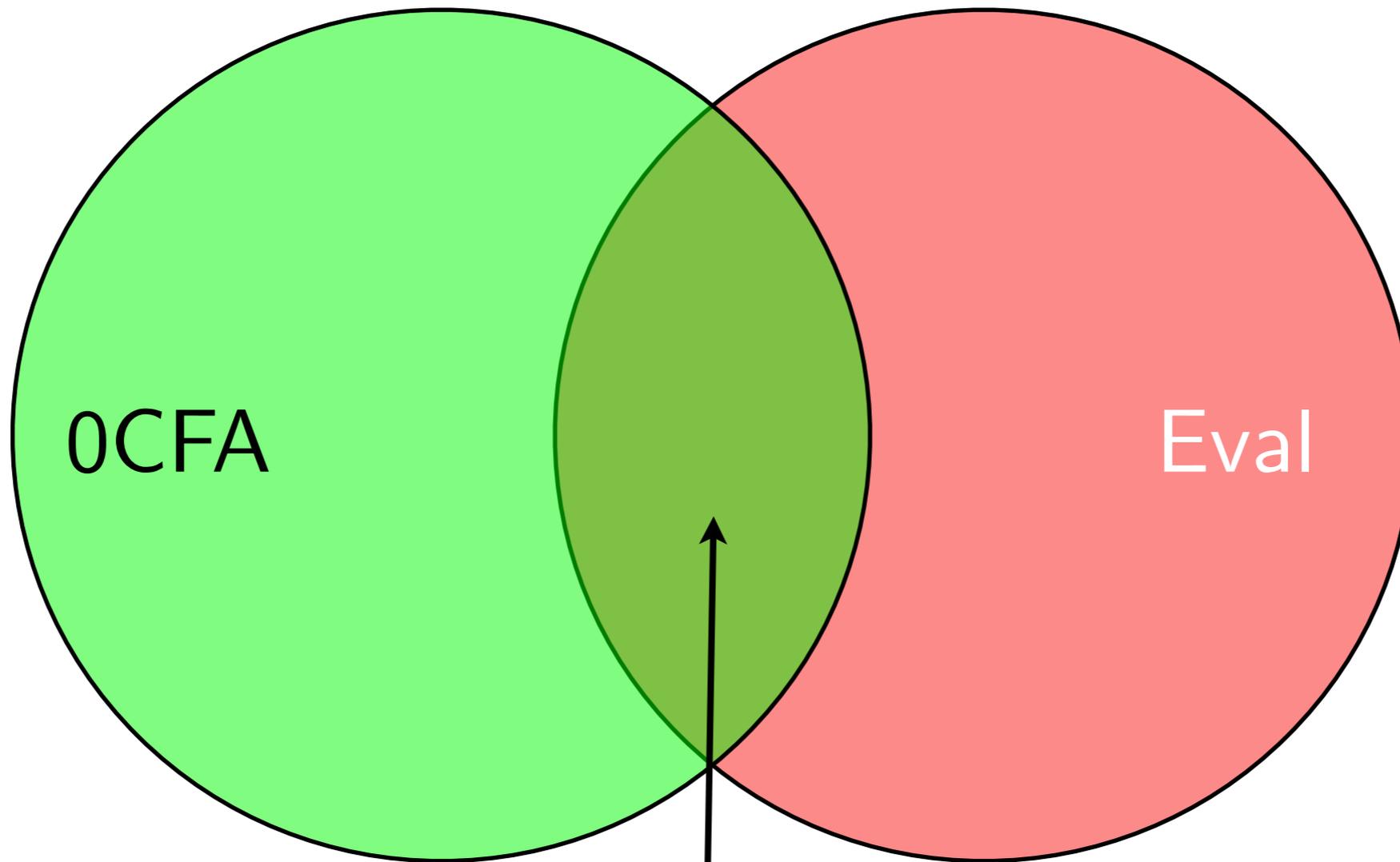
A Way Forward

Scalability

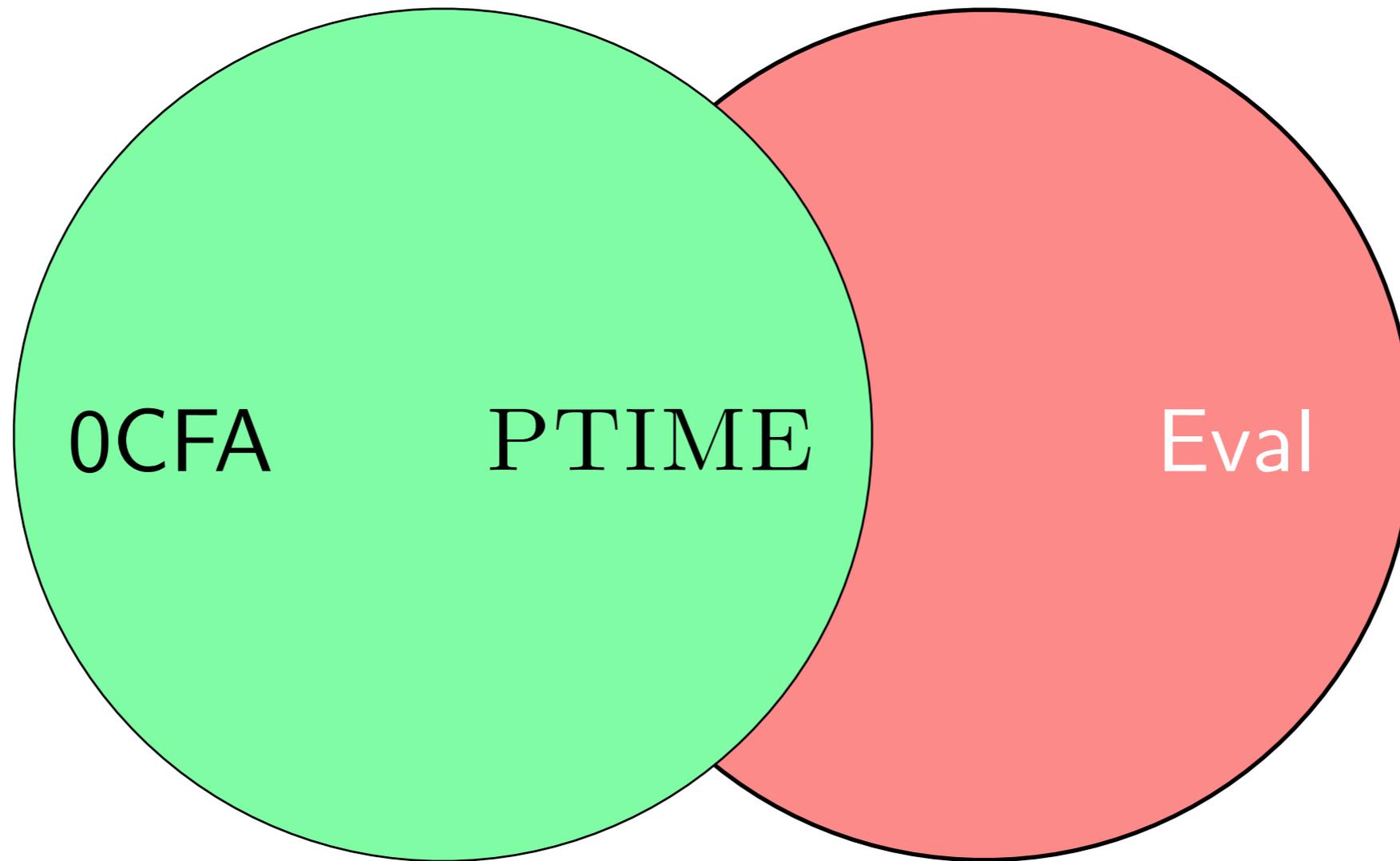


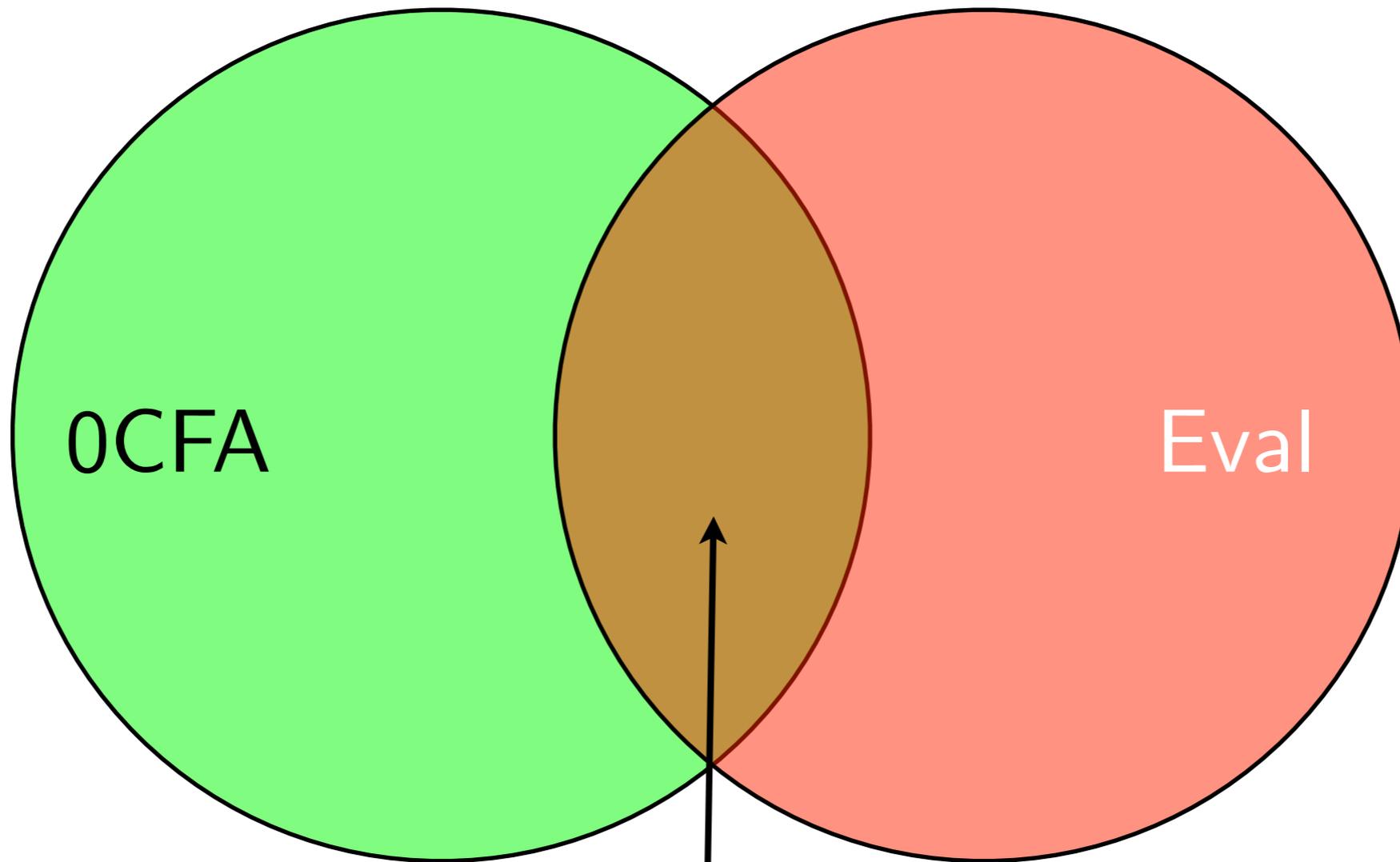
- Complexity
- Maintenance
- Verification
- Expressivity
- Modularity

**Key insight:
analysis is a kind of
evaluation**

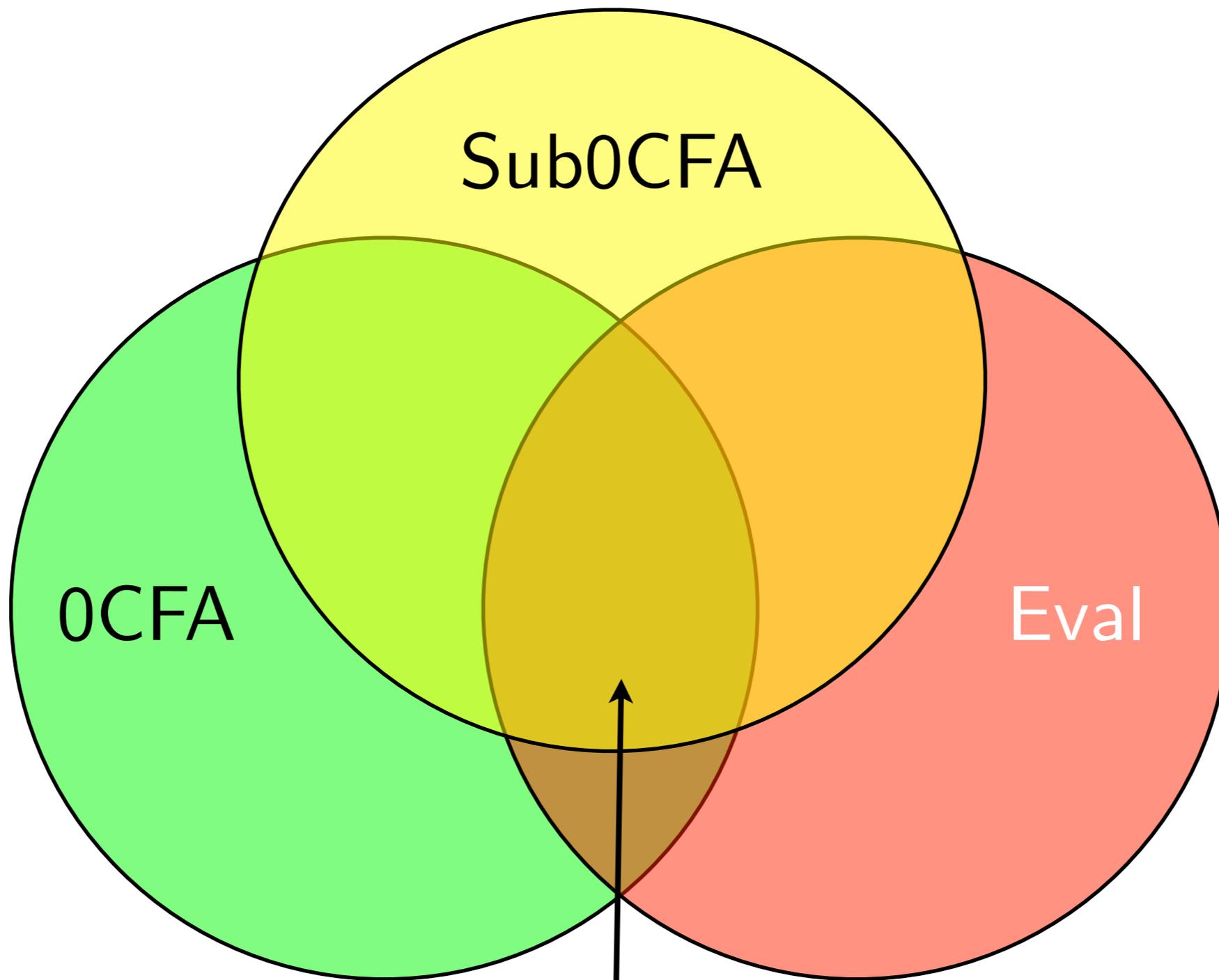


Every variable occurs once.

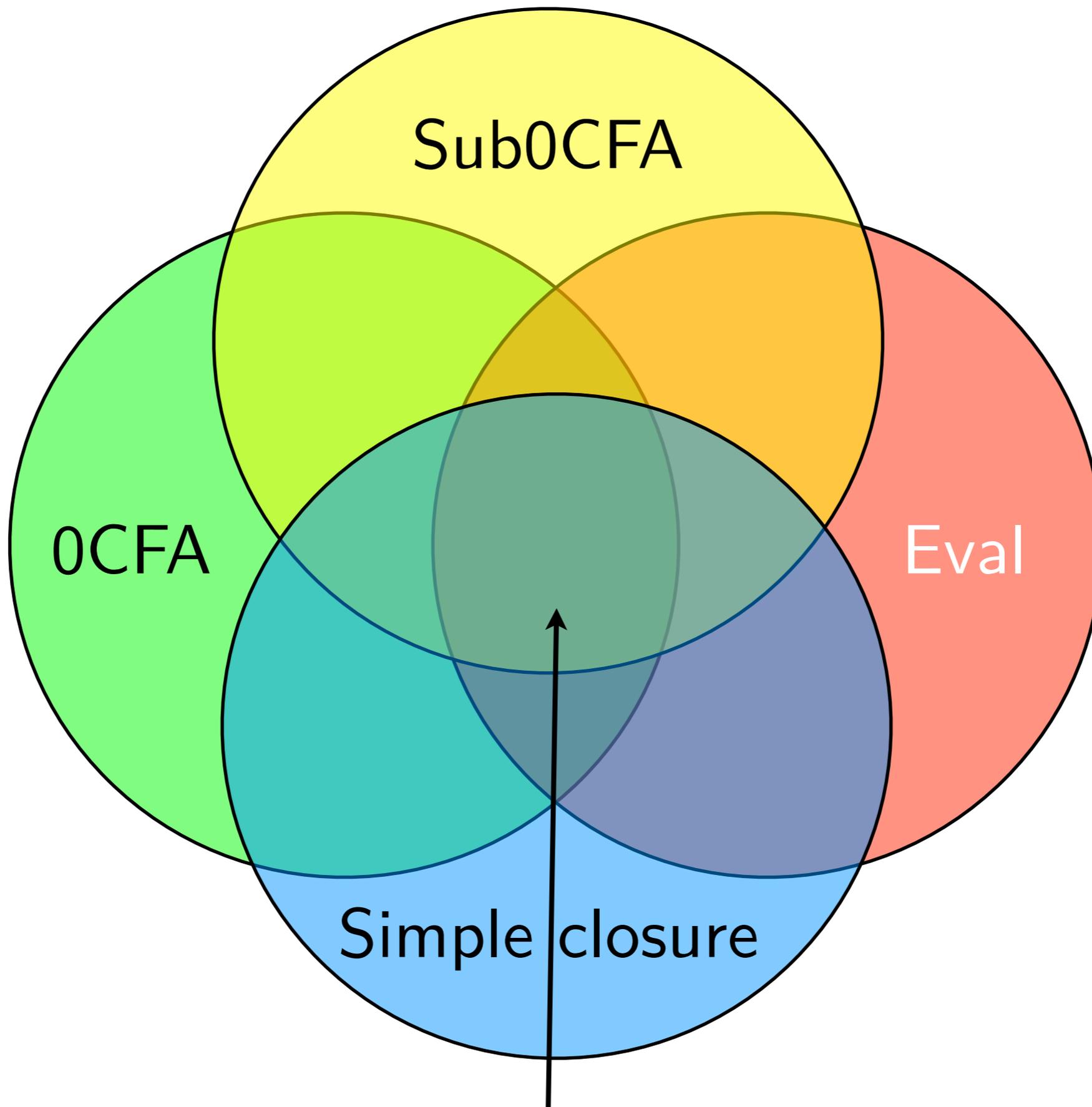




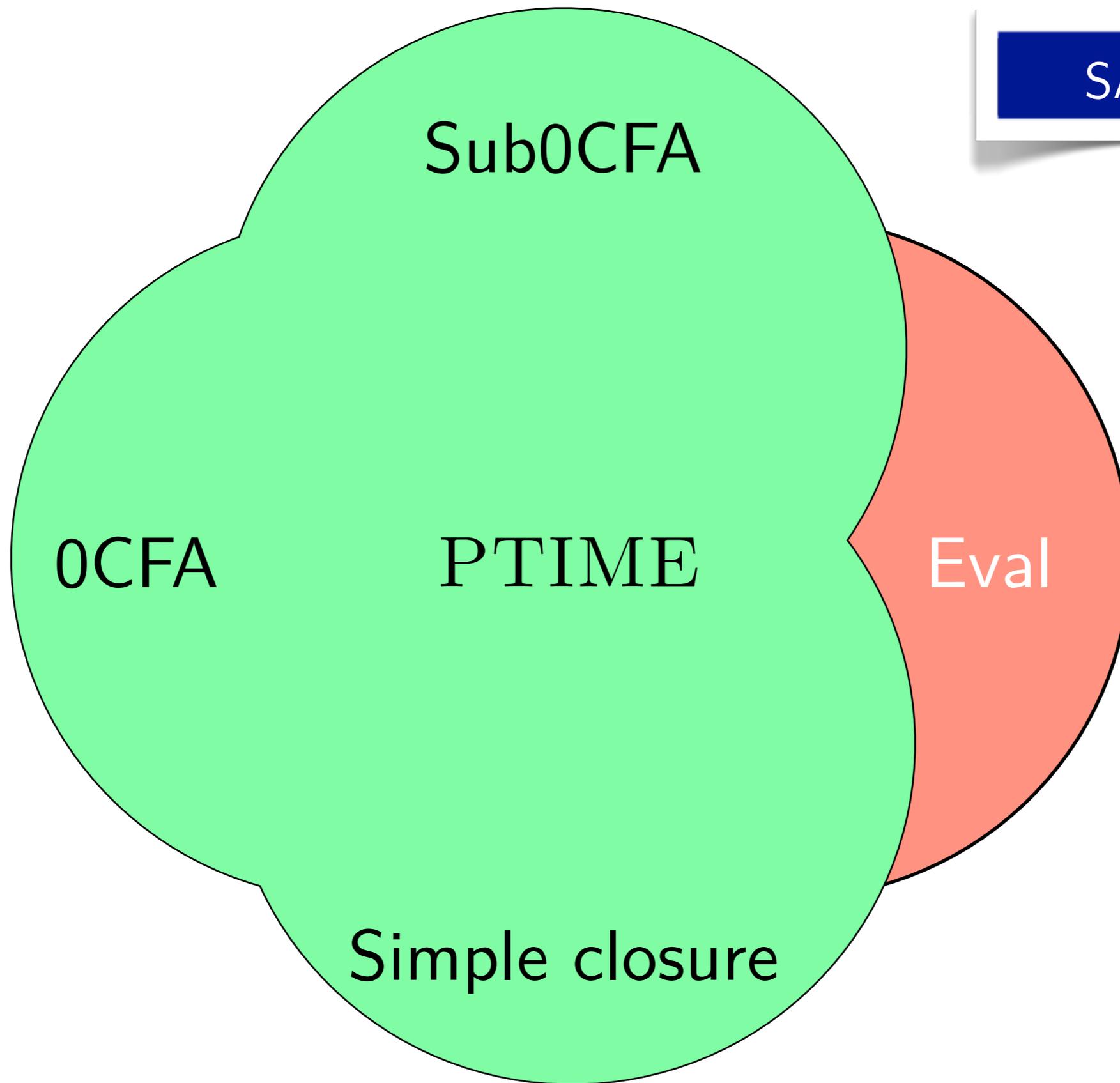
Every variable occurs once.

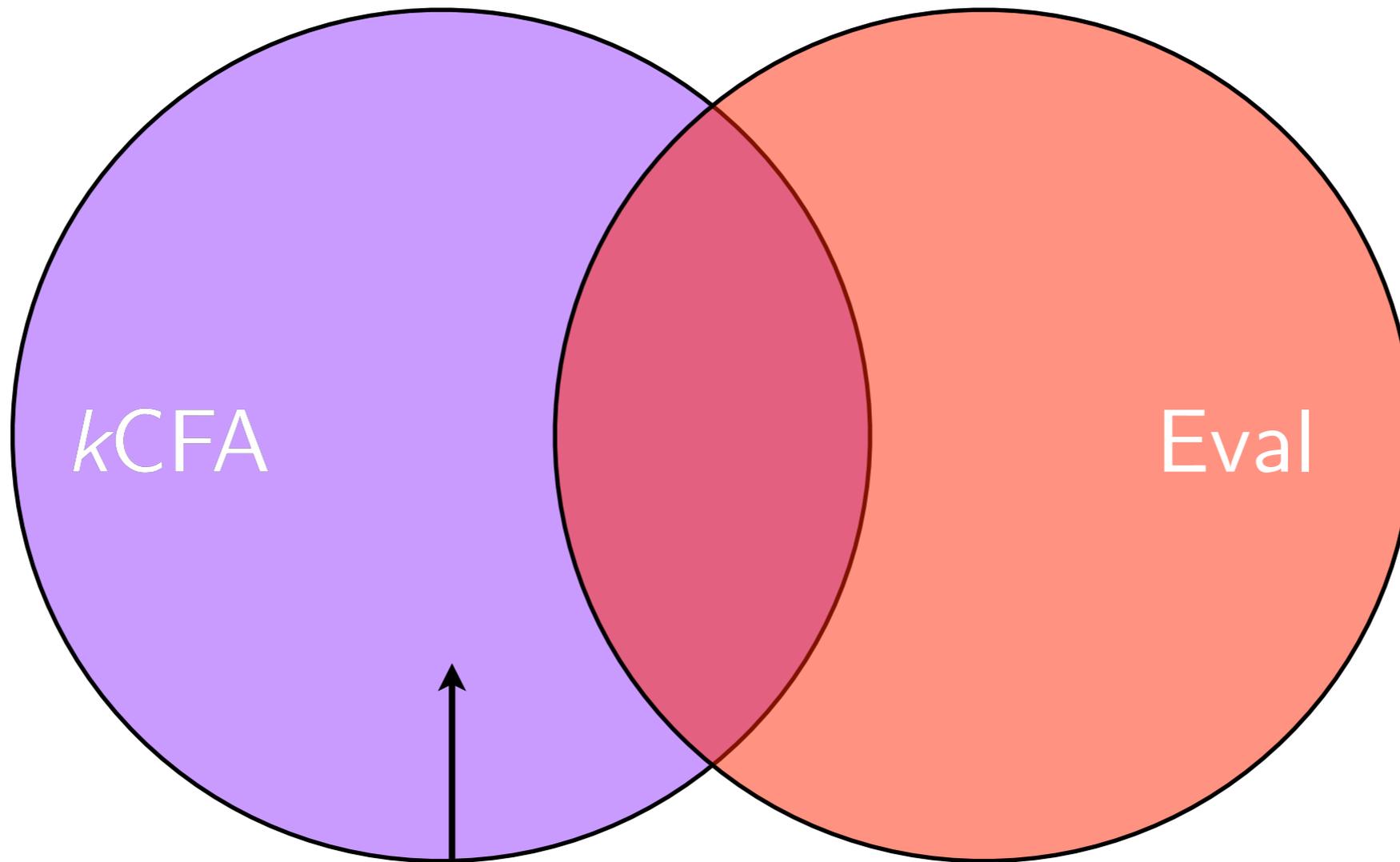


Every variable occurs once.

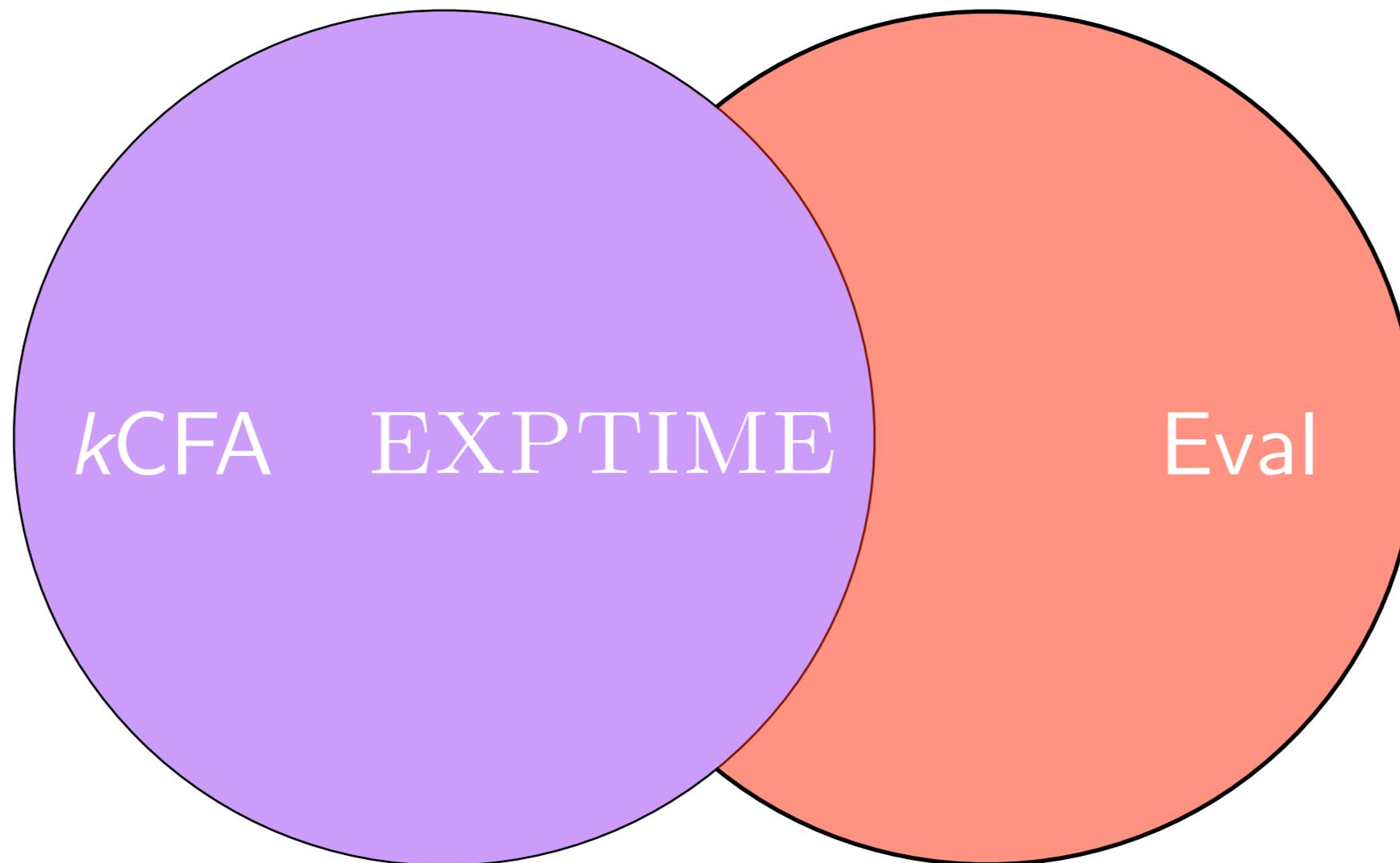


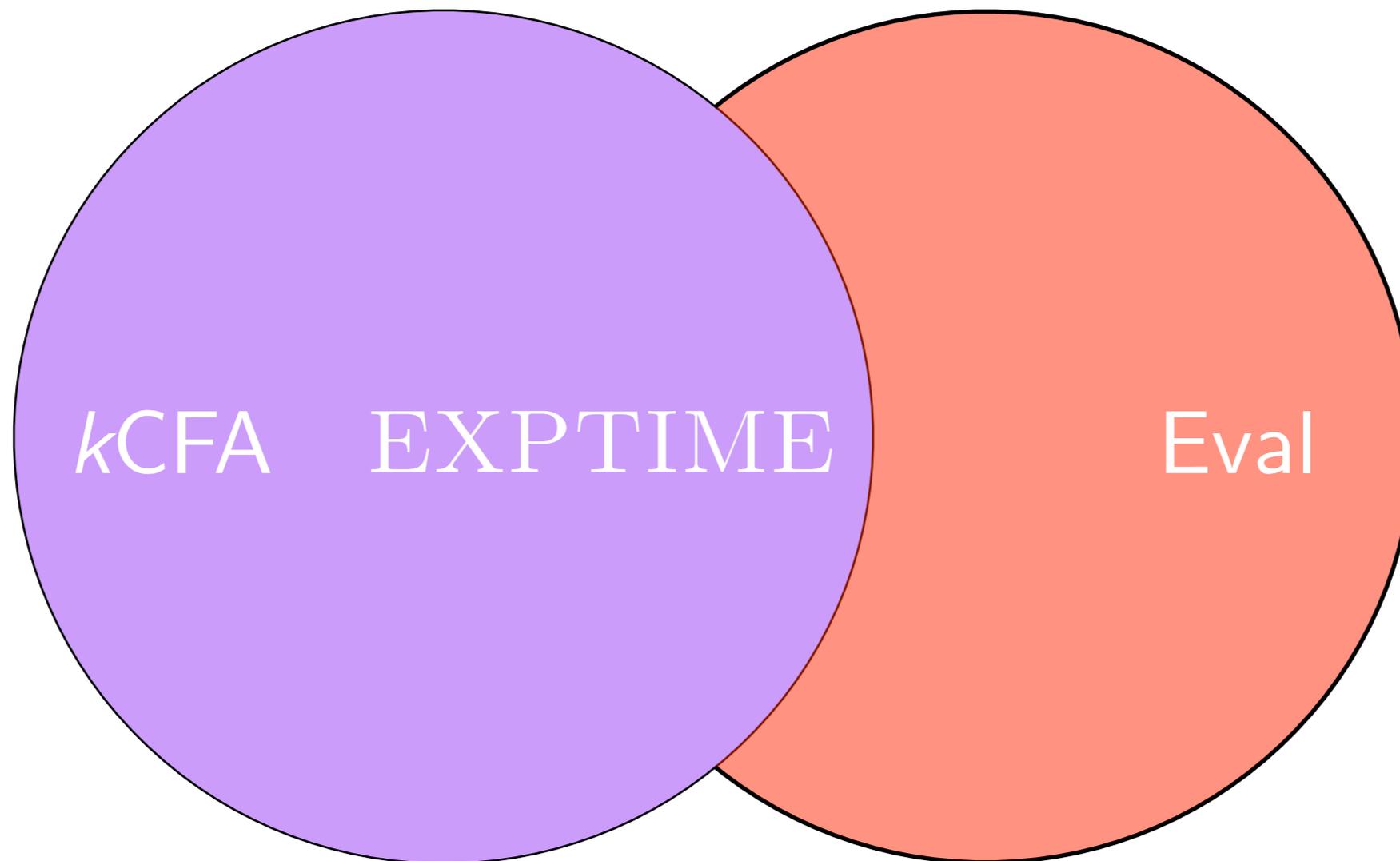
Every variable occurs once.

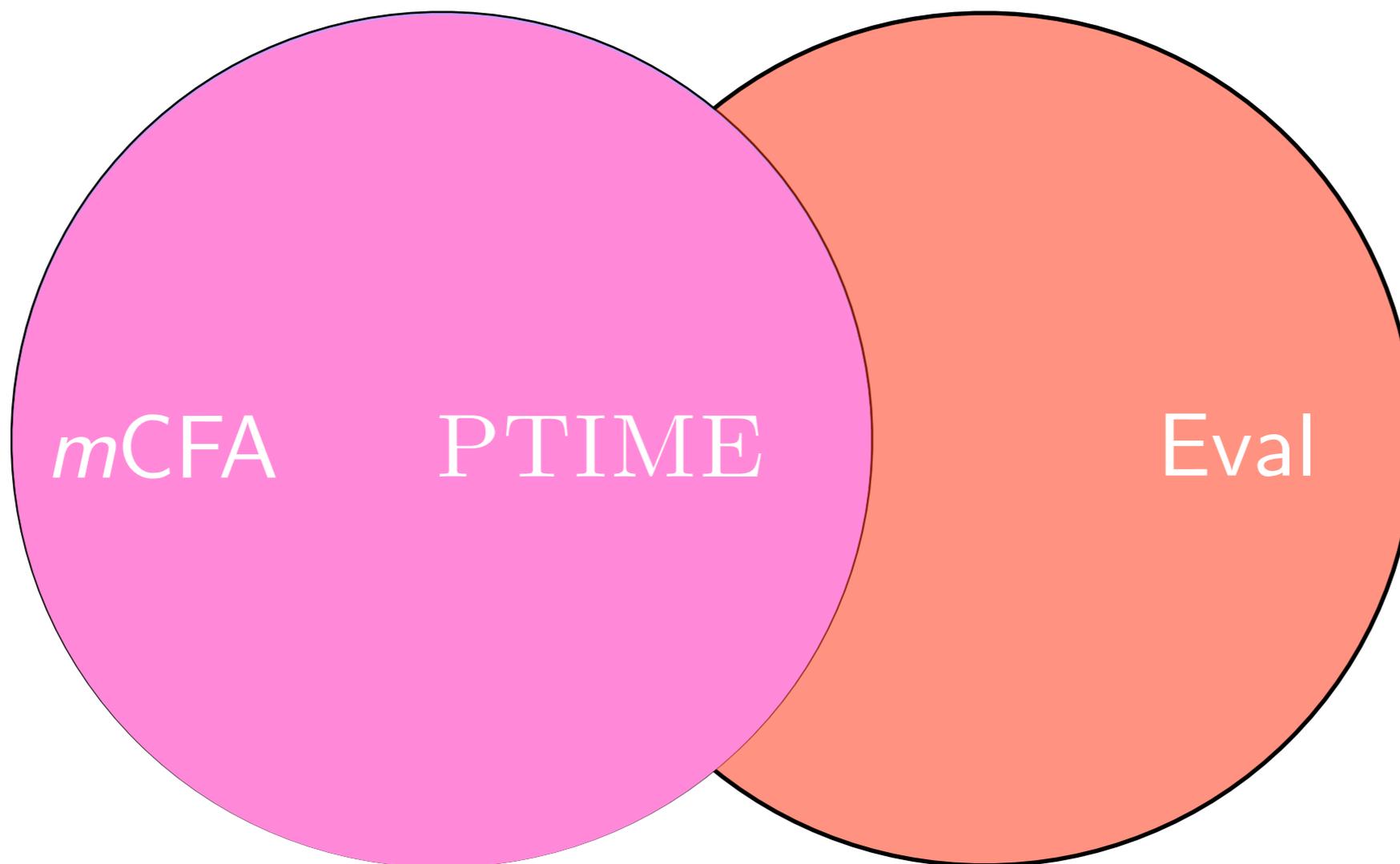




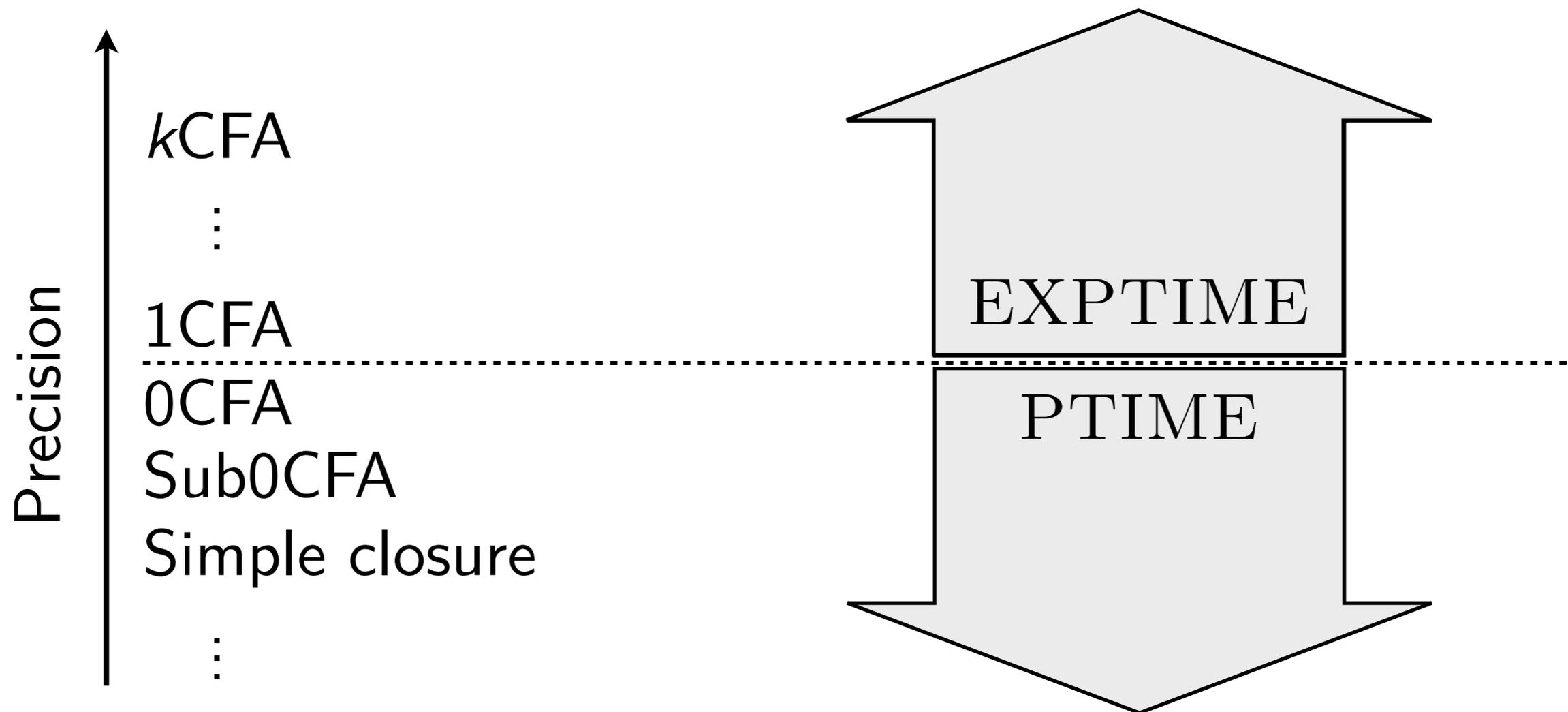
Datalog-style programming with analysis.

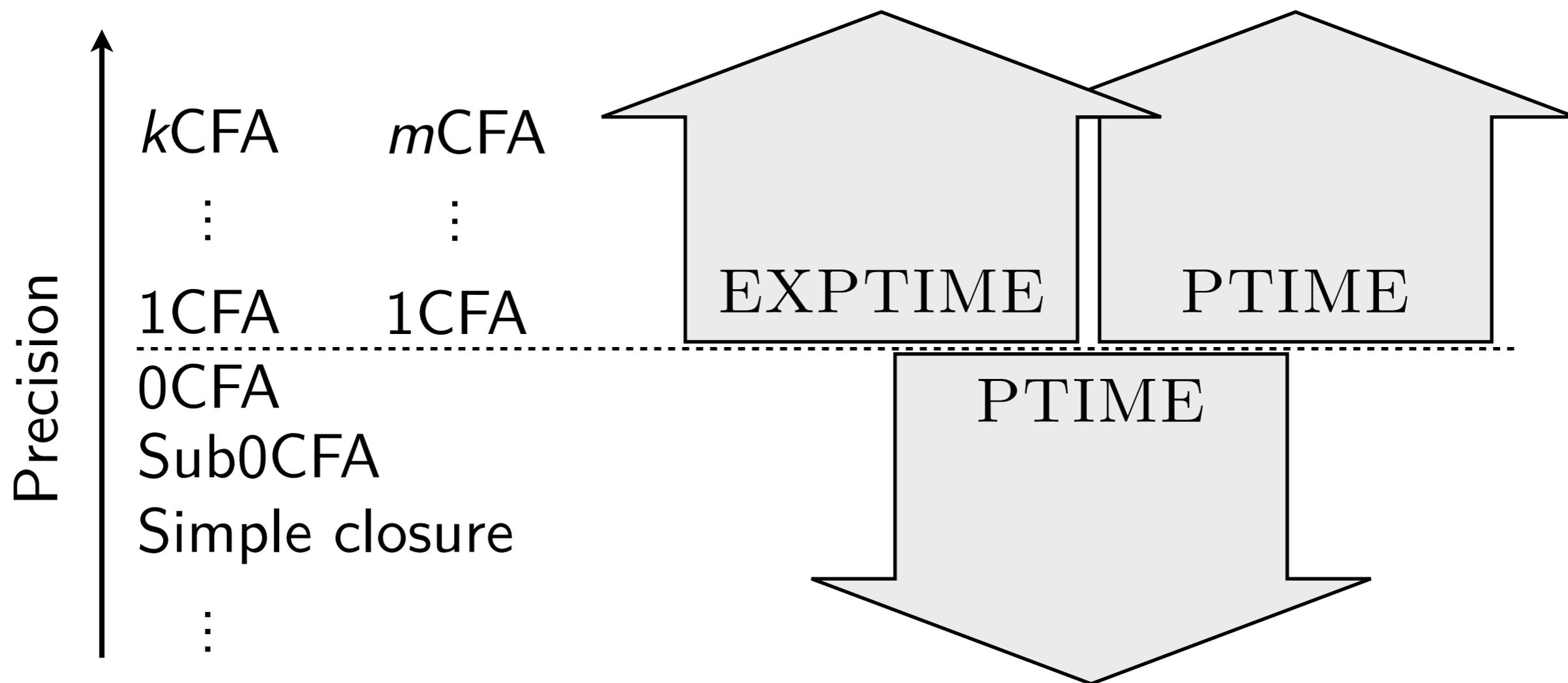






Similar precision, better performance



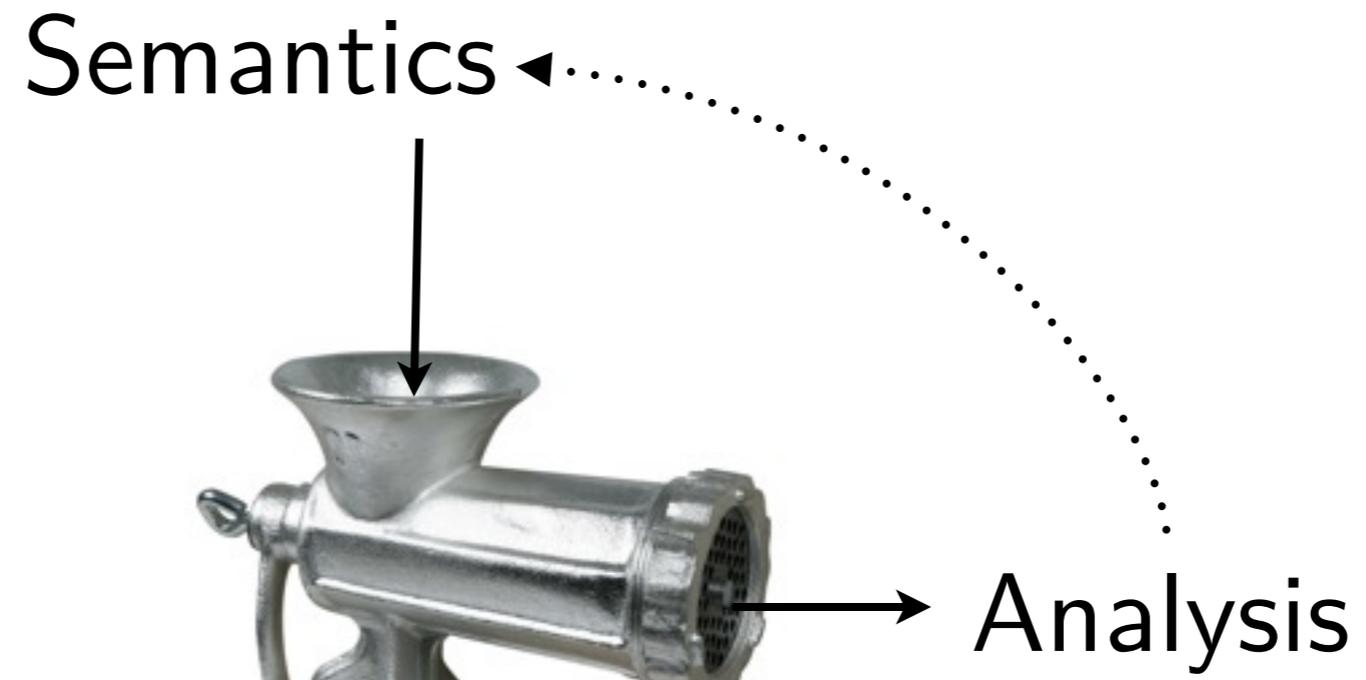


A Systematic Approach to Program Analysis Design

Semantics



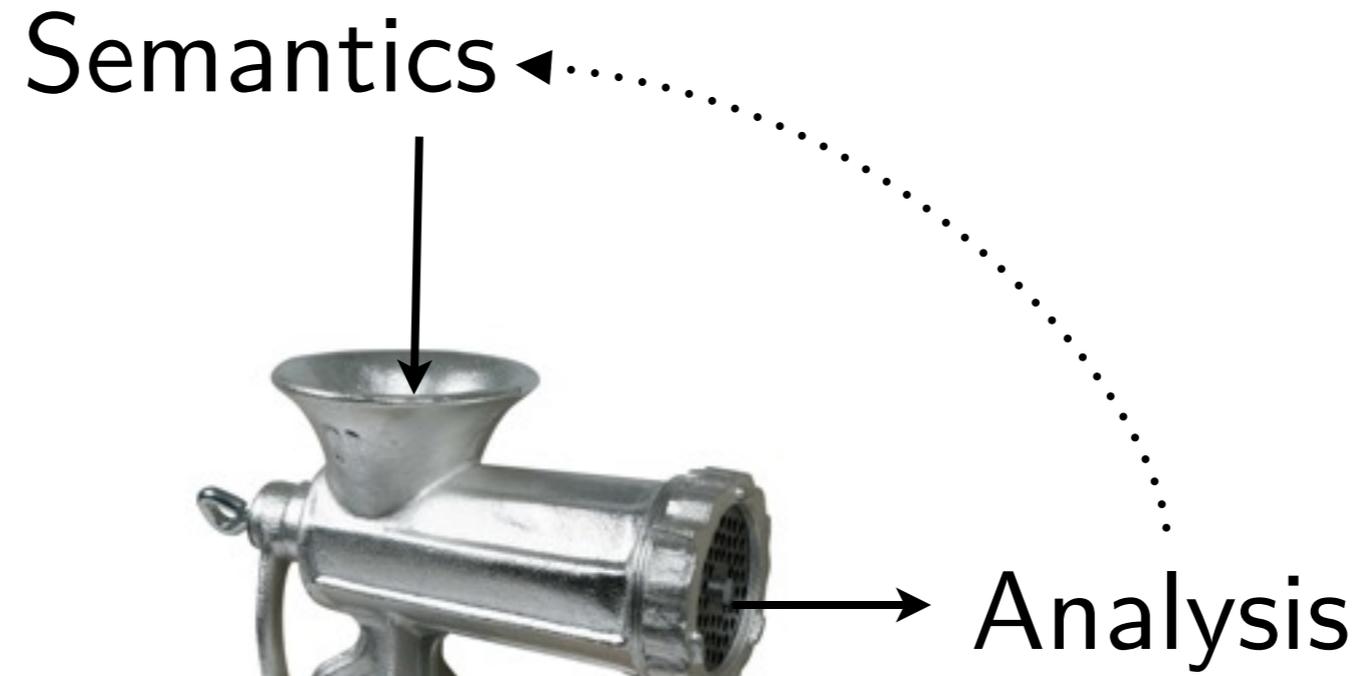
Analysis



Semantics



Analysis



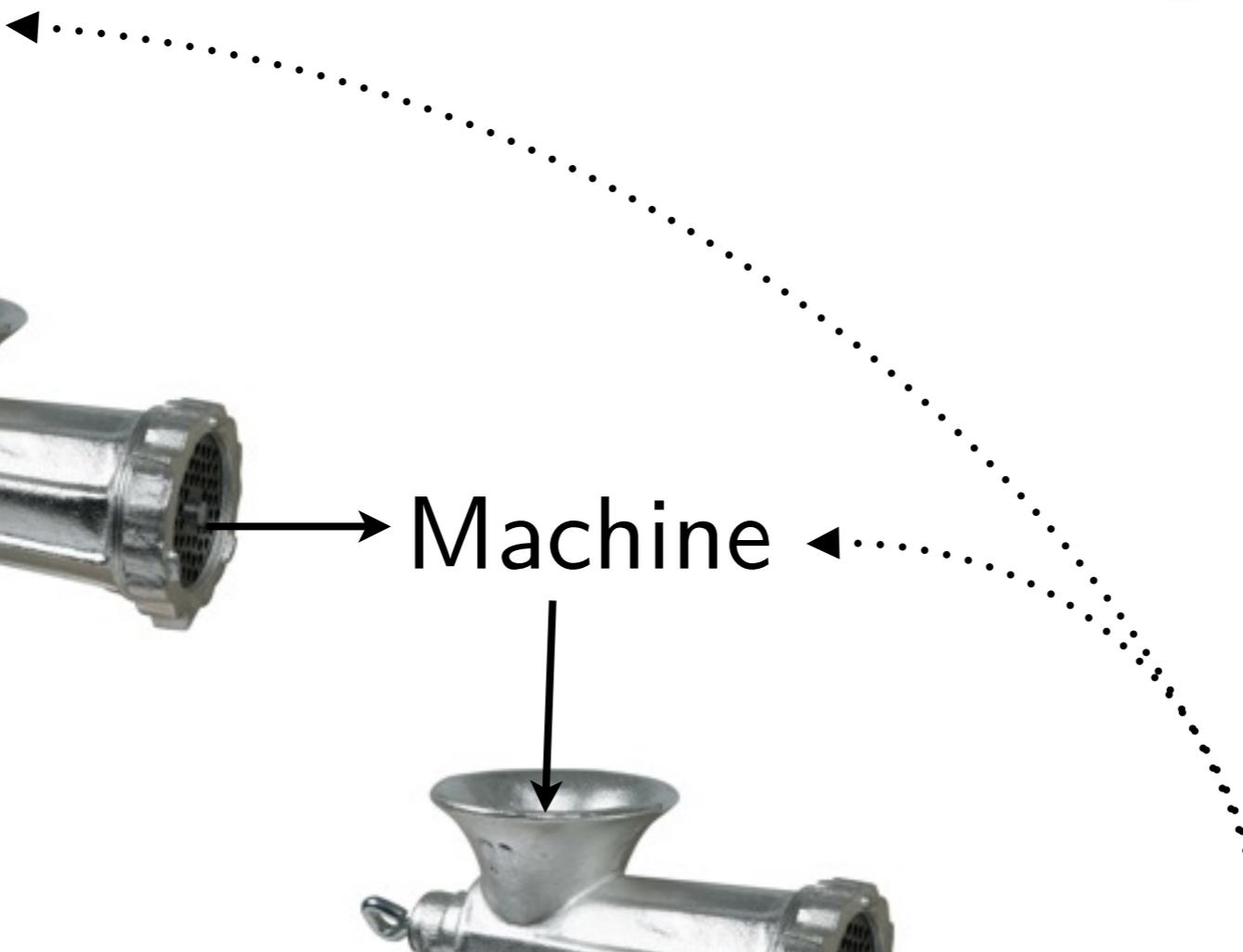
Semantics



Machine

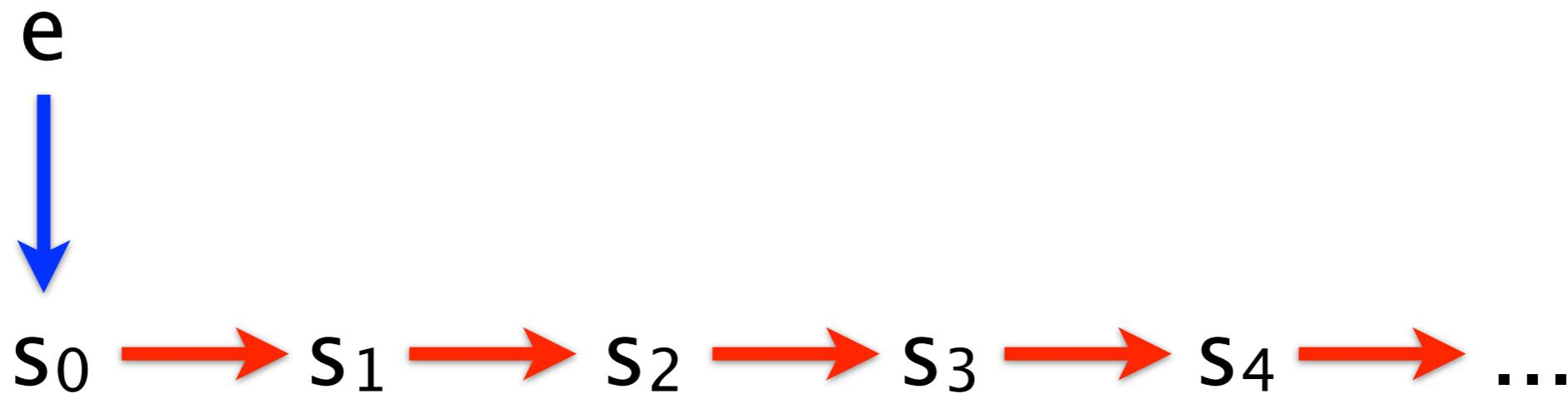


Analysis



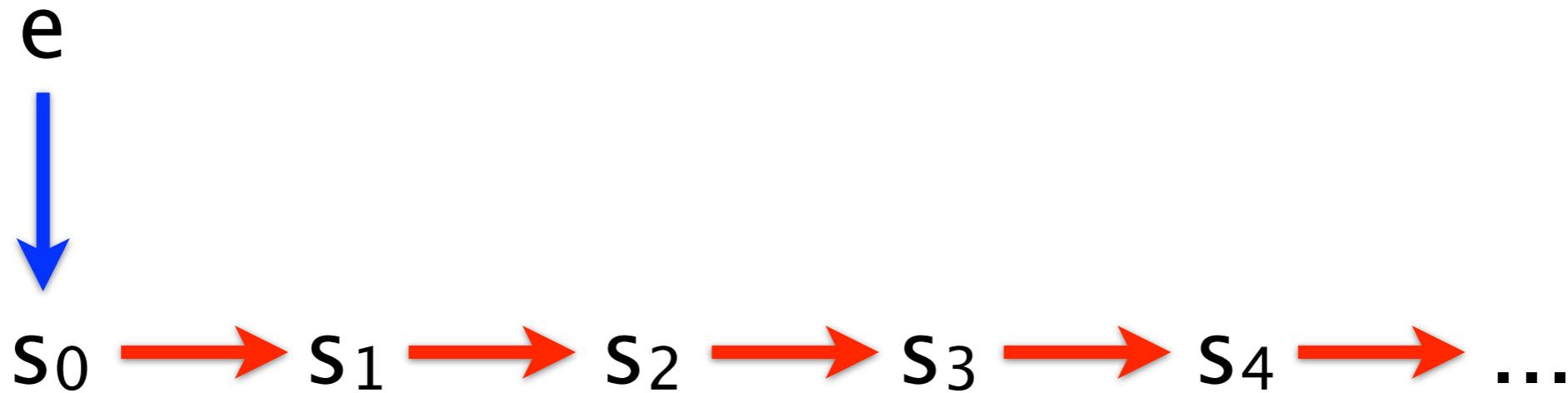
Analysis machine

ICFP'10/CACM'11



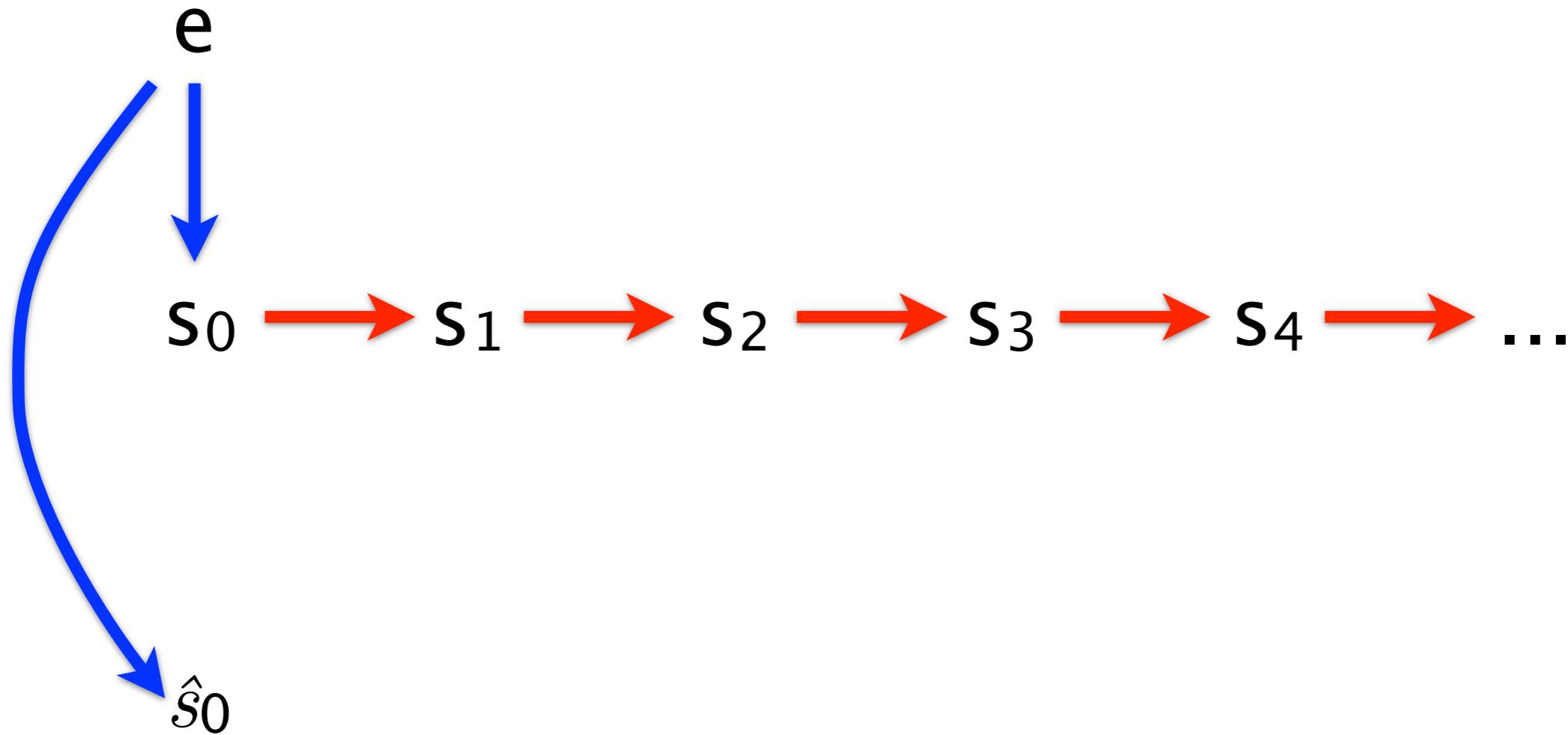
Analysis machine

ICFP'10/CACM'11



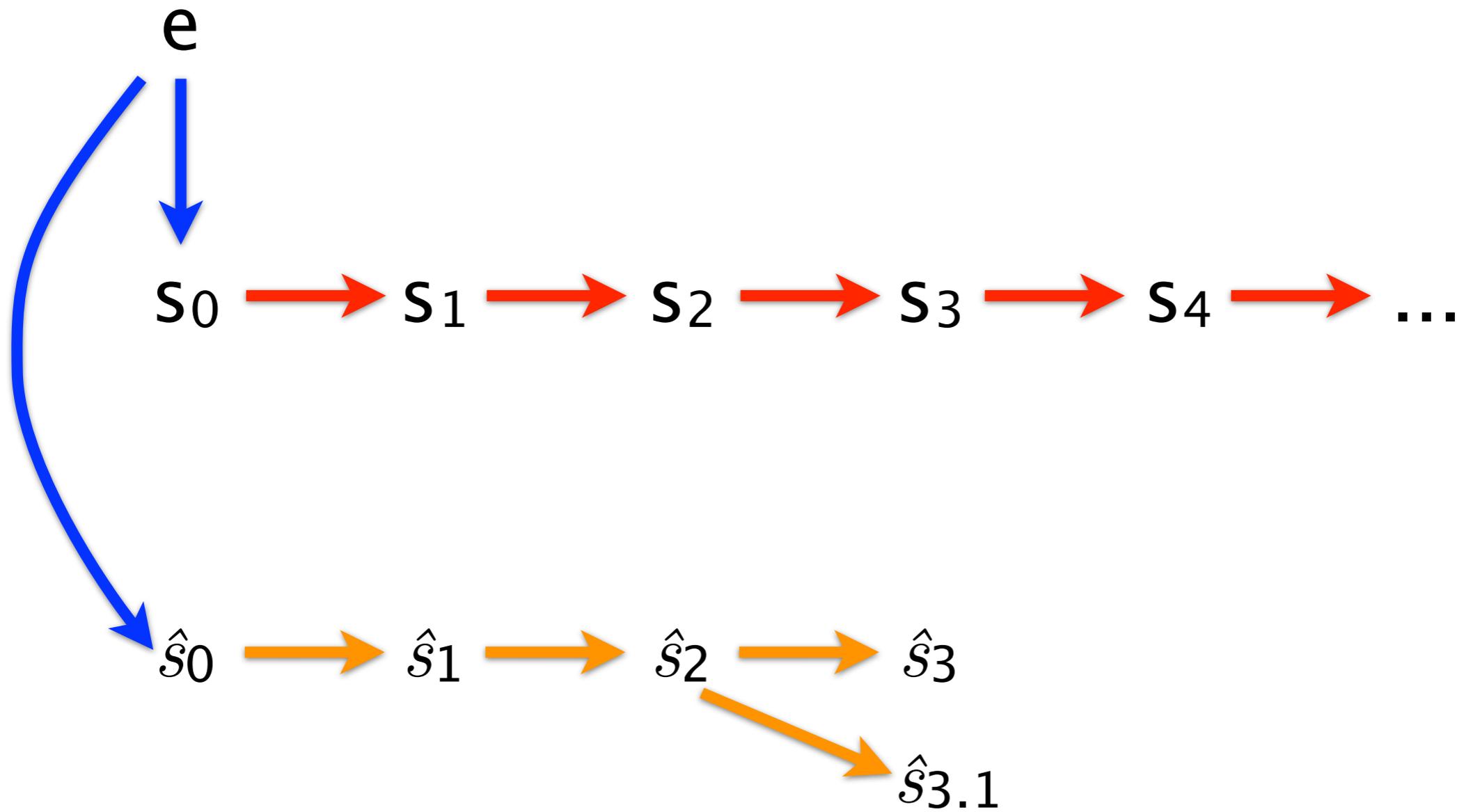
Analysis machine

ICFP'10/CACM'11



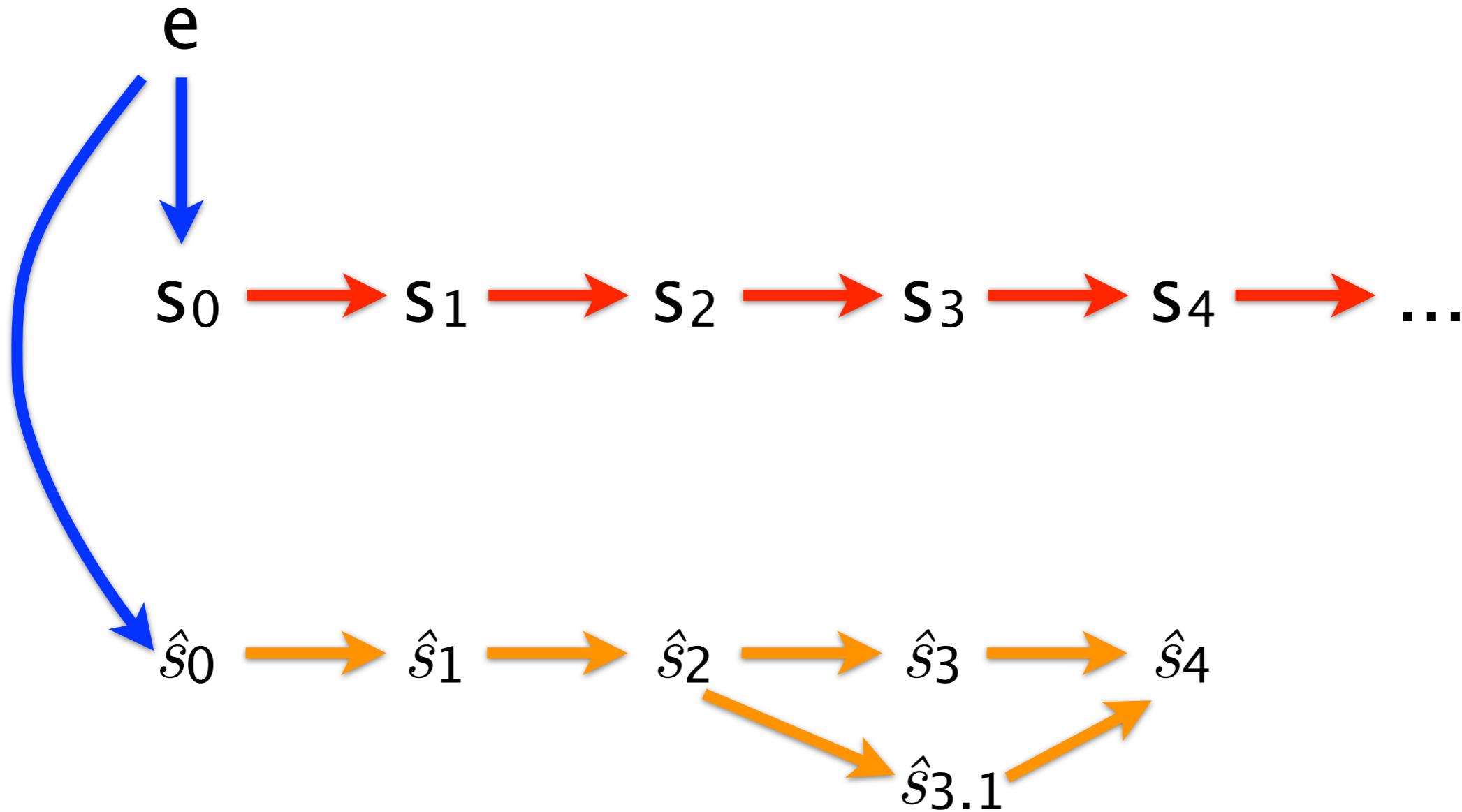
Analysis machine

ICFP'10/CACM'11



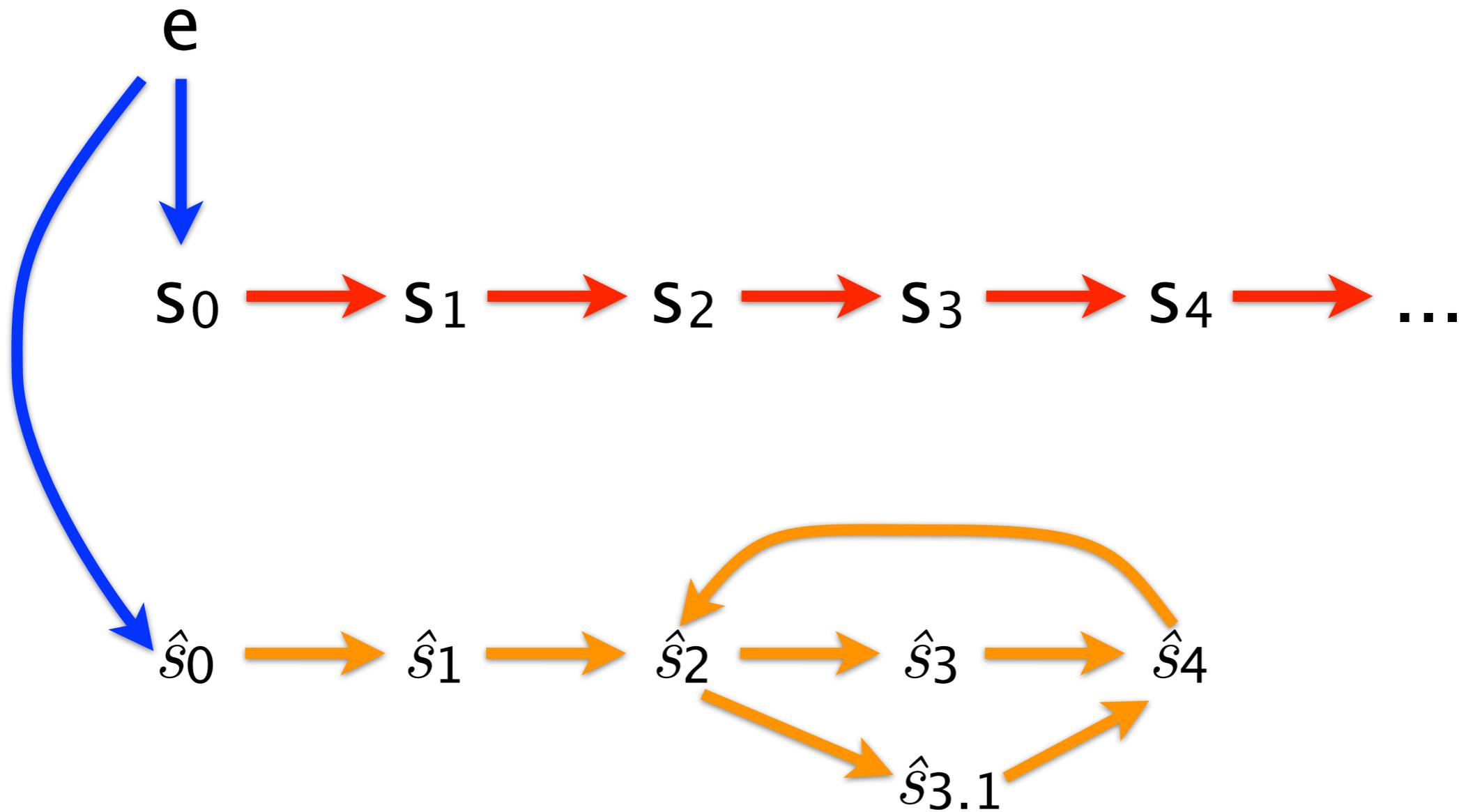
Analysis machine

ICFP'10/CACM'11



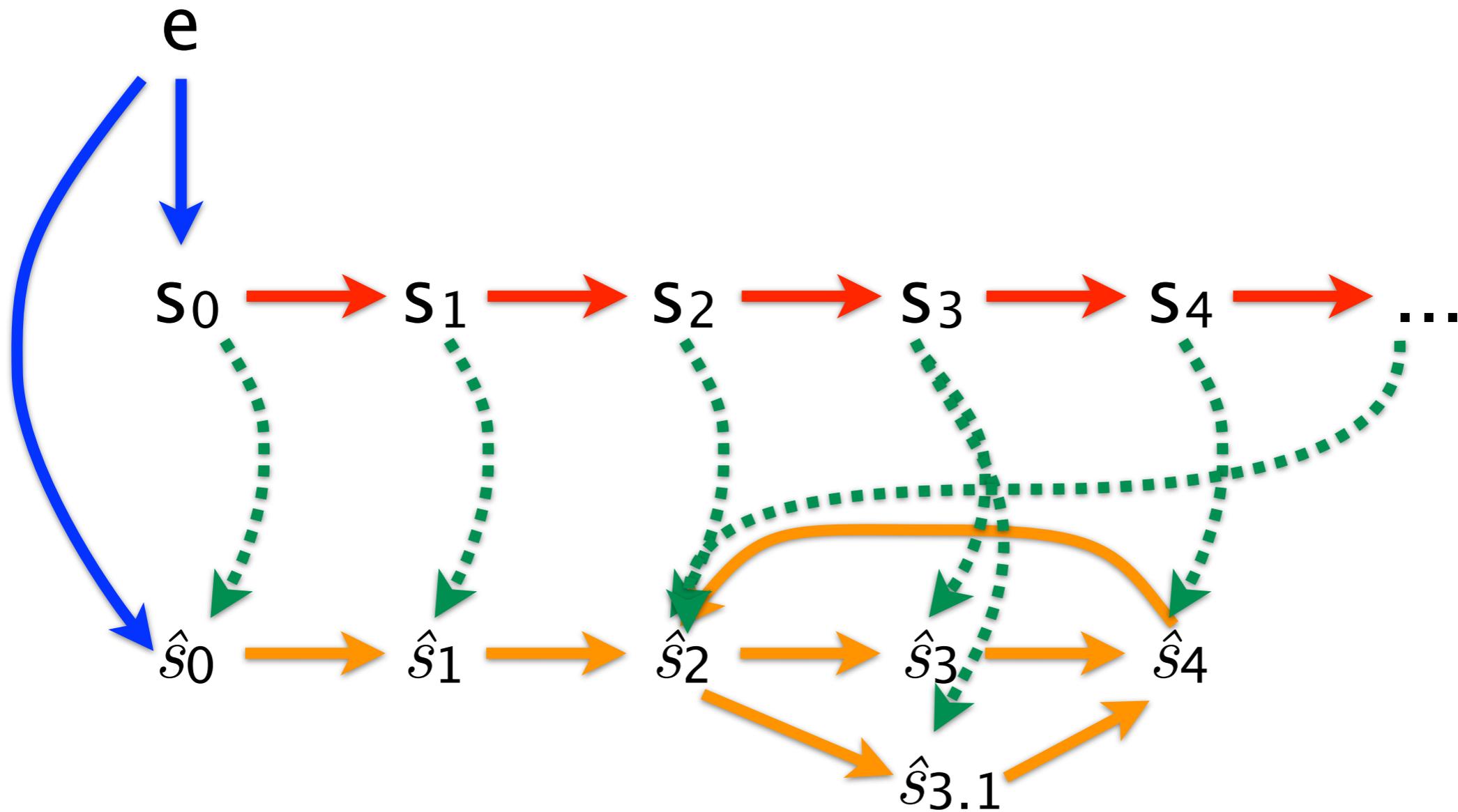
Analysis machine

ICFP'10/CACM'11



Analysis machine

ICFP'10/CACM'11



Theorem: The analysis simulates the machine.

Key idea:

**Deterministic state transition system
with an infinite state space.**



**Non-deterministic state transition system
with a **finite** state space.**

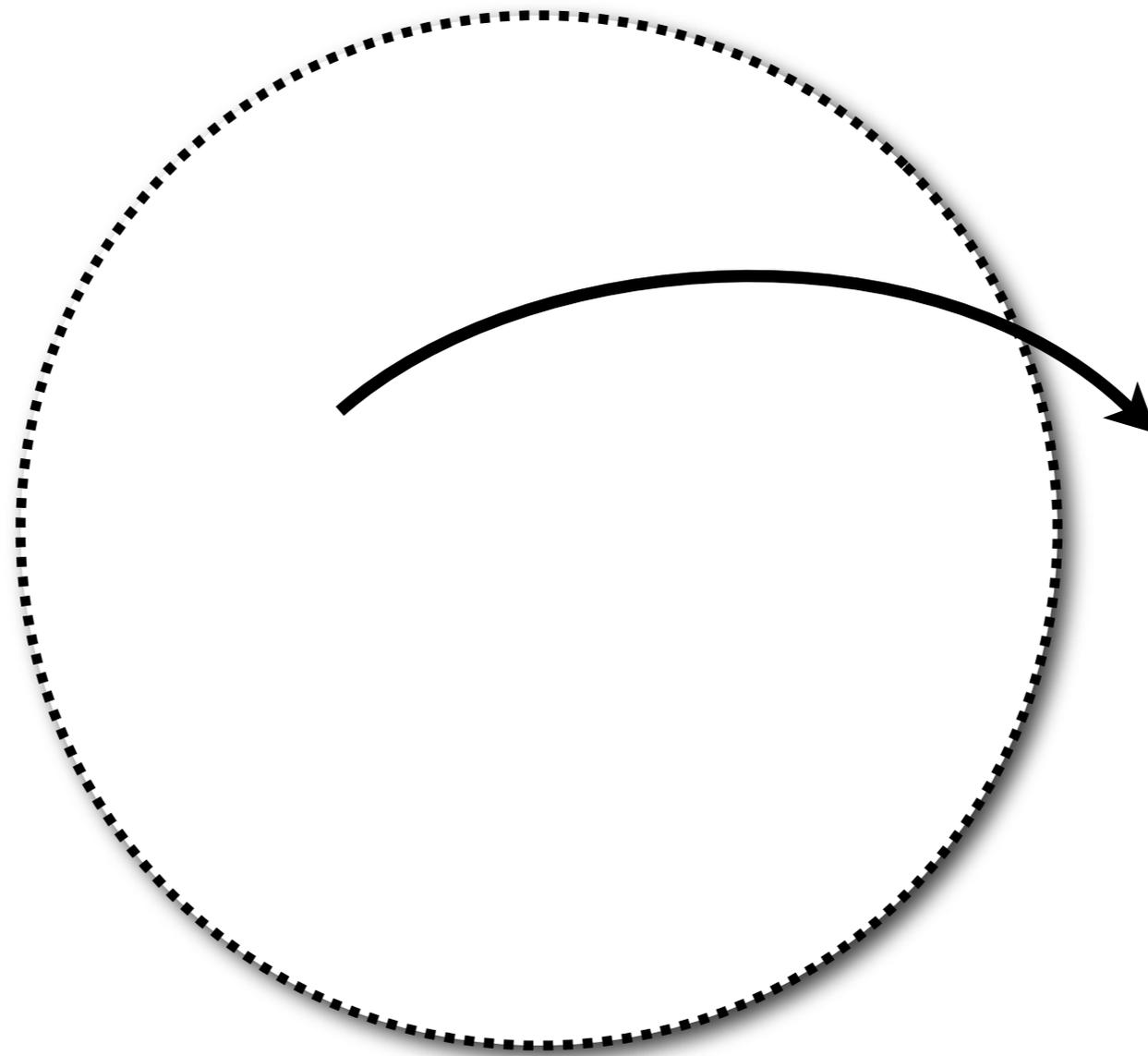
Key idea:

**Deterministic state transition system
with an infinite state space.**



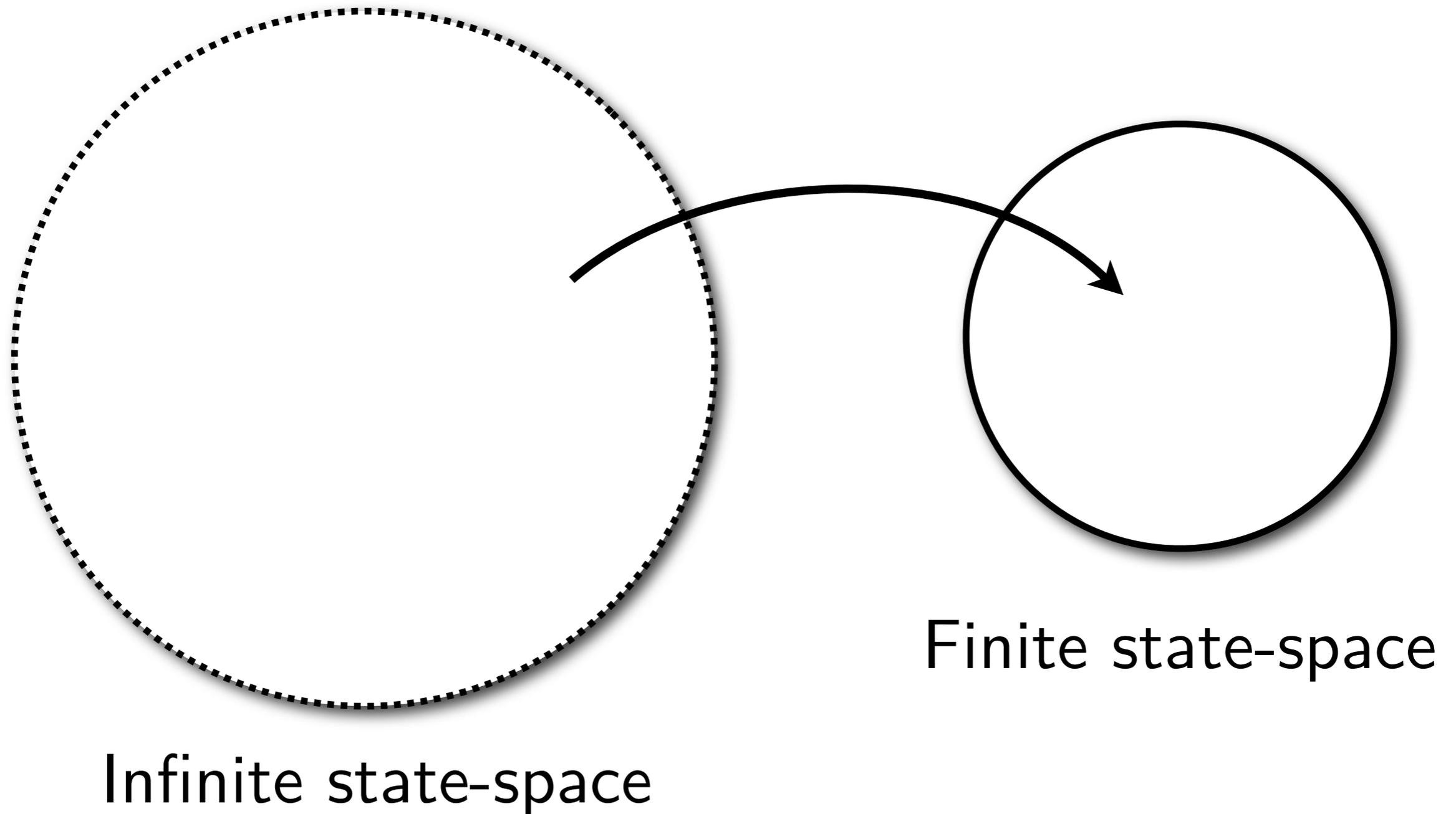
**Non-deterministic state transition system
with a **finite** state space.**

Program analysis...



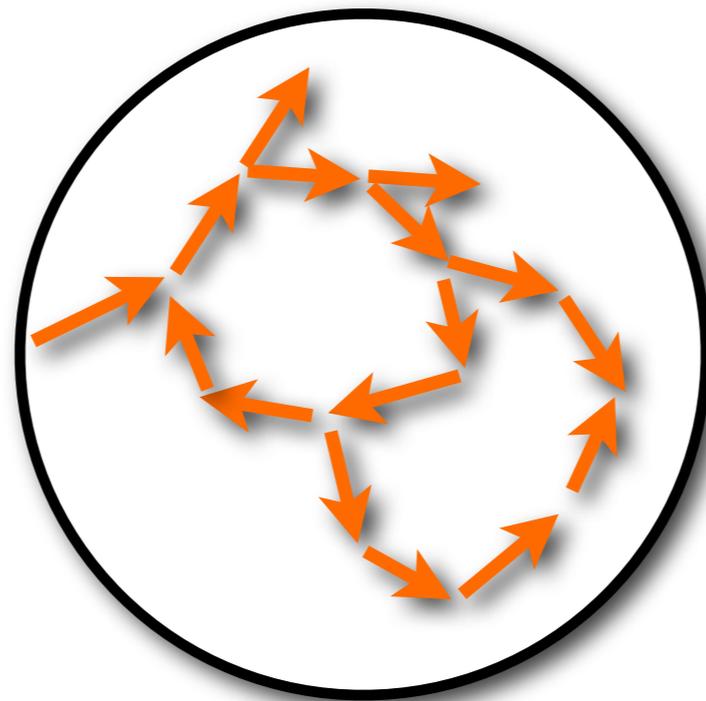
Infinite state-space

Program analysis...



...is bounded graph search.

...is bounded graph search.



Finite state-space

Semantics



Machine



A Closer Look



Analysis



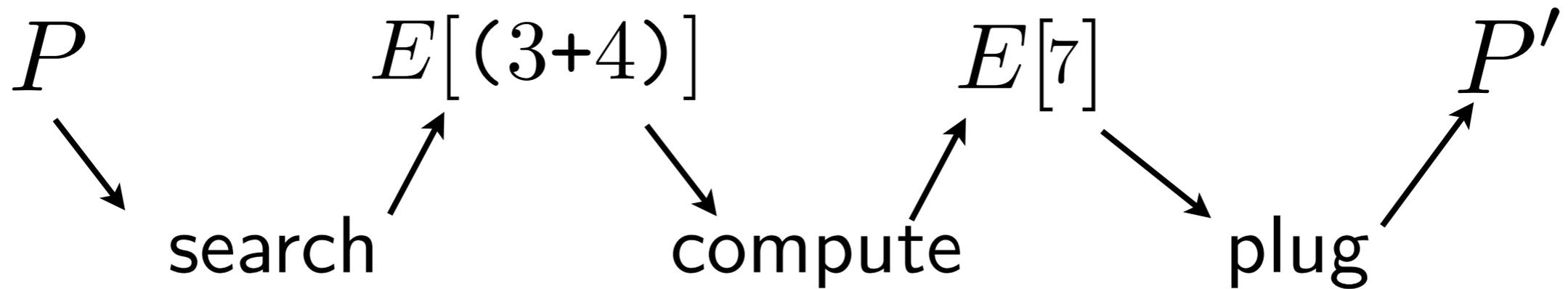
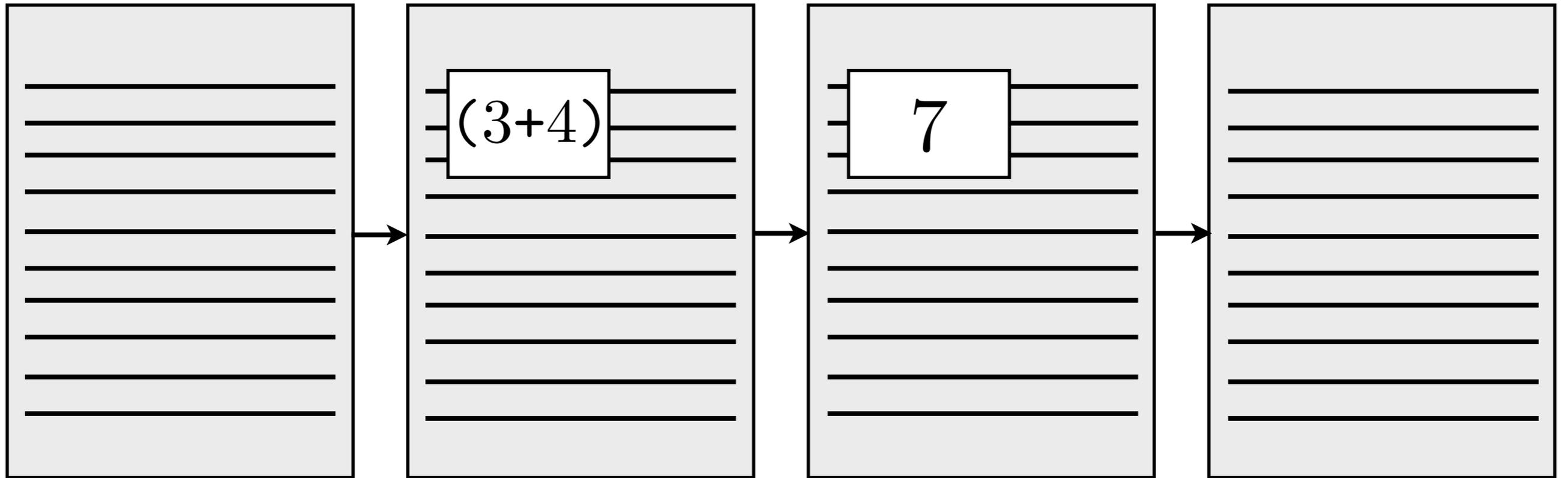
Reduction semantics:

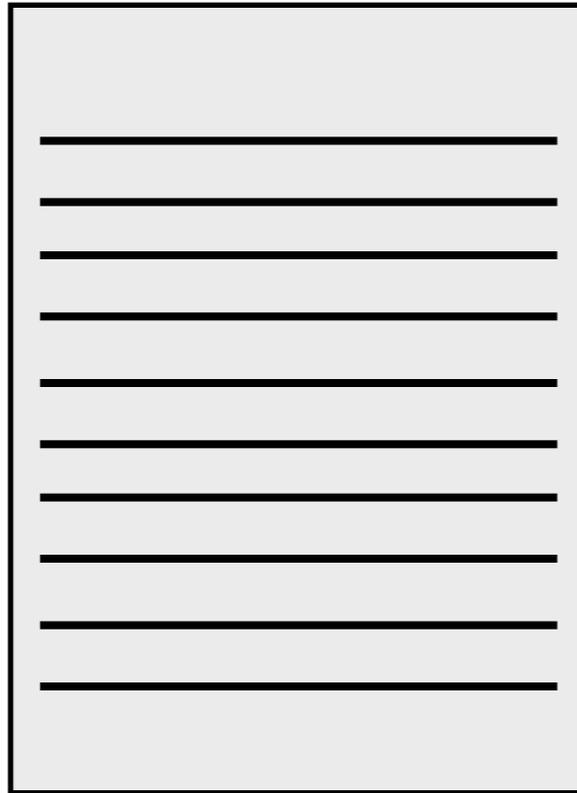
Syntax: $e ::= n \mid x \mid (e+e)$

Reduction: $(n+m) \rightarrow n + m$
 $x \rightarrow n$ where $\rho(x) = n$

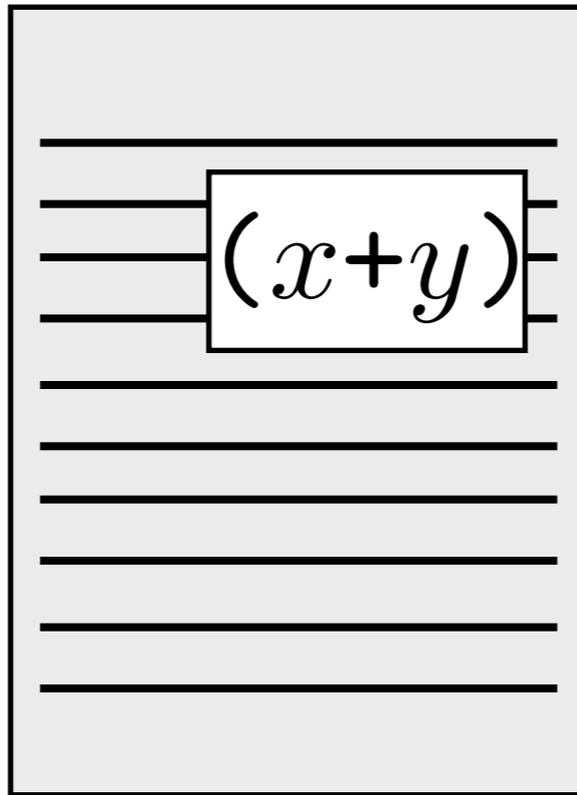
Eval. Contexts: $E ::= [] \mid (E+e) \mid (n+E)$

Reduction semantics:

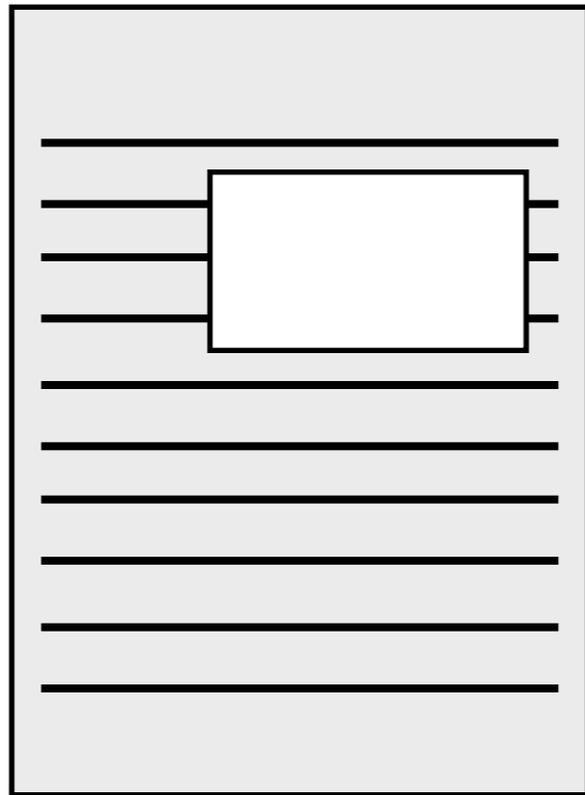




P



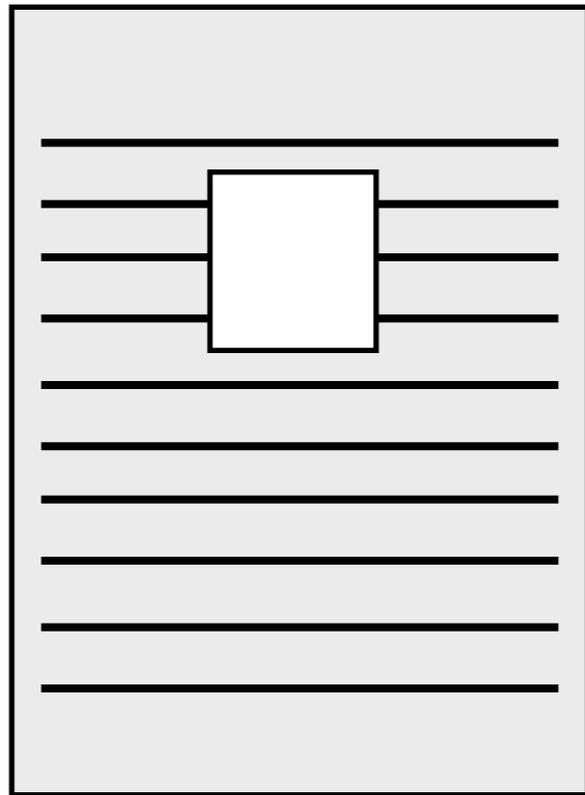
$$E[(x+y)]$$



$E[]$

$(x+y)$

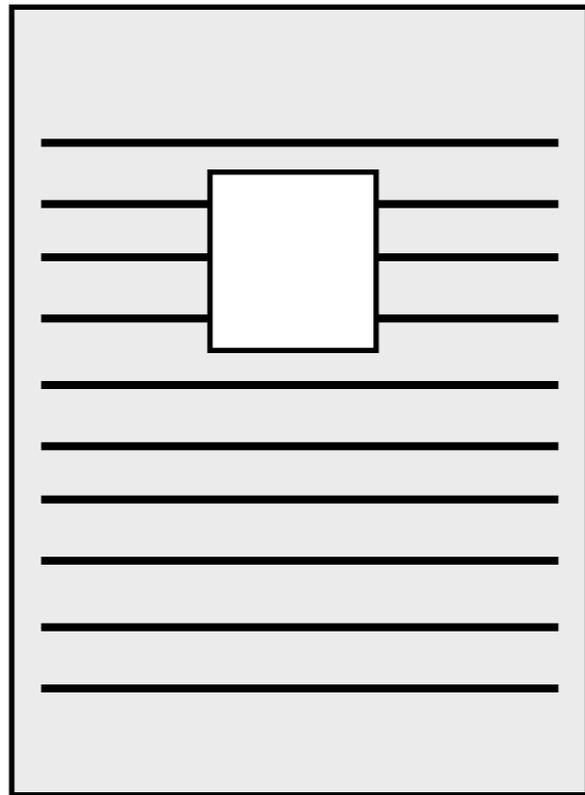
$(x+y)$



x

$$E[([]+y)]$$

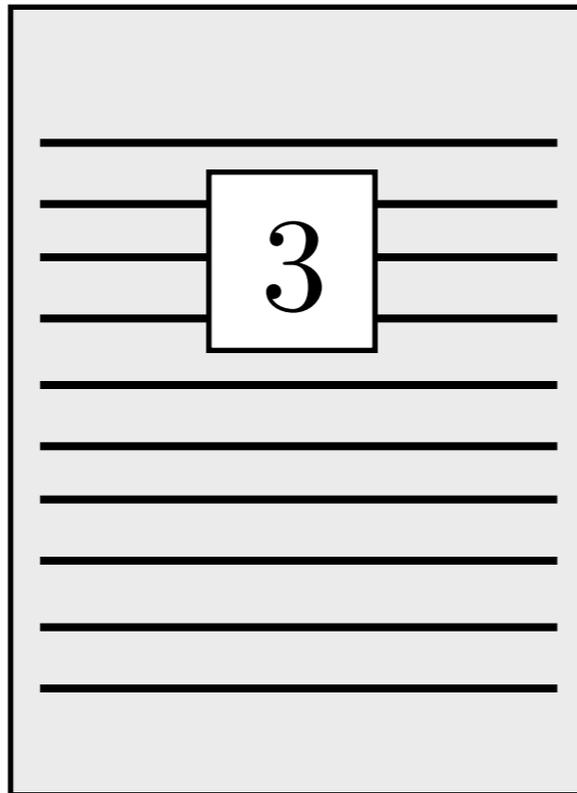
$$x \rightarrow 3$$



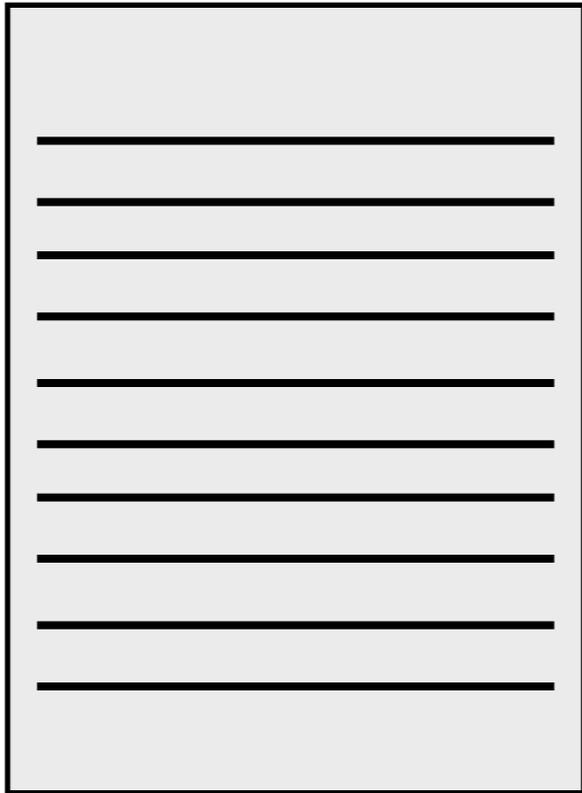
3

$$E[(\quad + y)]$$

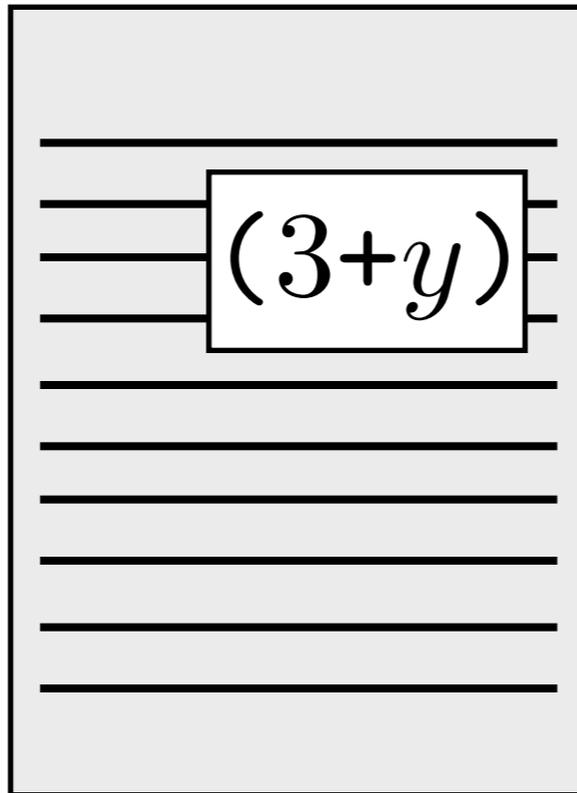
$$x \rightarrow 3$$



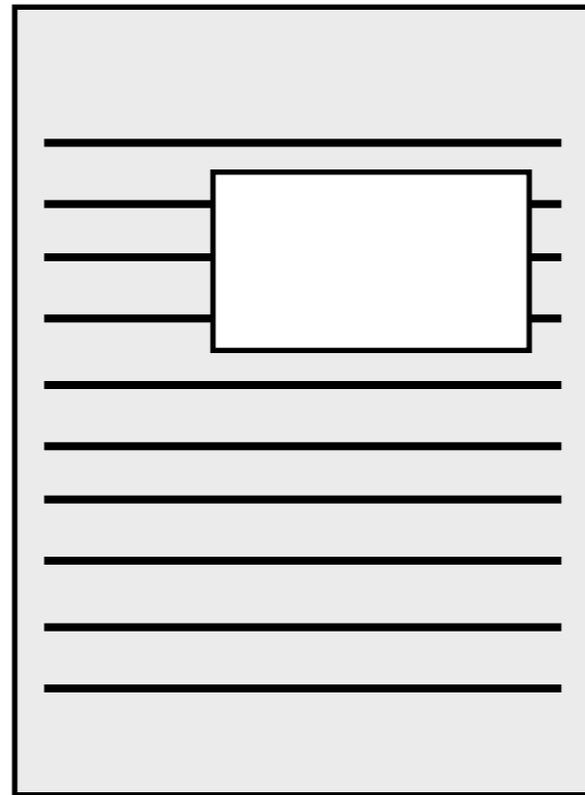
$$E[([3] + y)]$$



P'



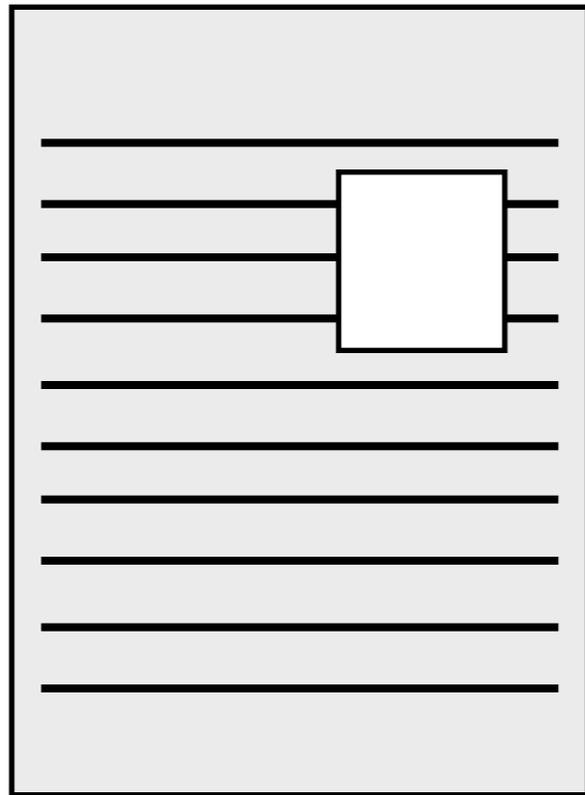
$$E[(3+y)]$$



$(3+y)$

$E[]$

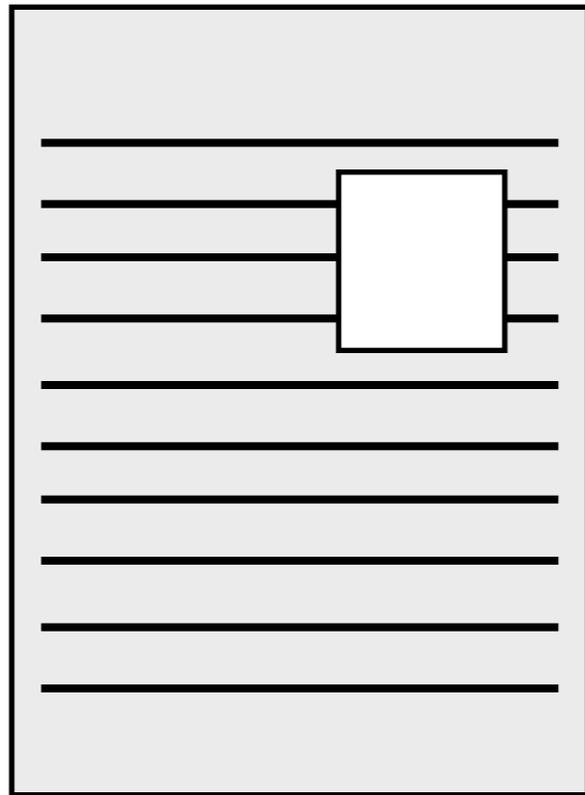
$(3+y)$



y

$$E[(3+[])]$$

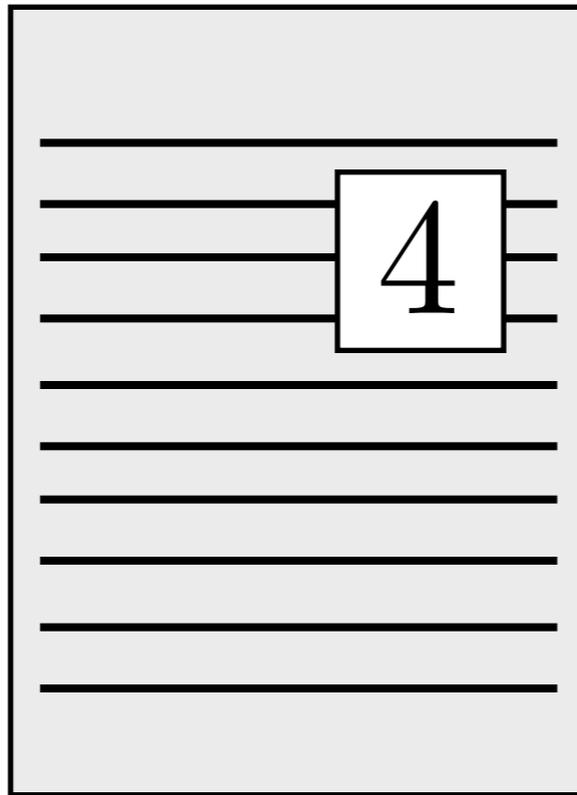
$$y \rightarrow 4$$



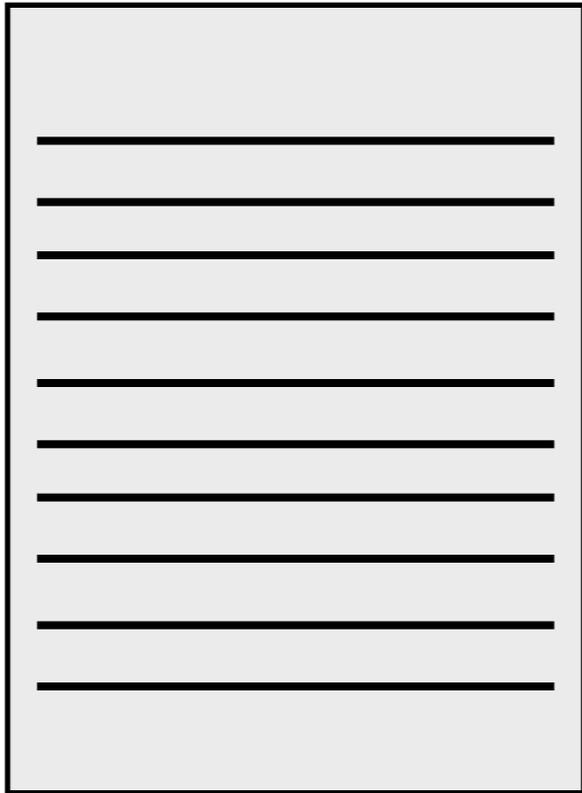
4

$$E[(3+[])]$$

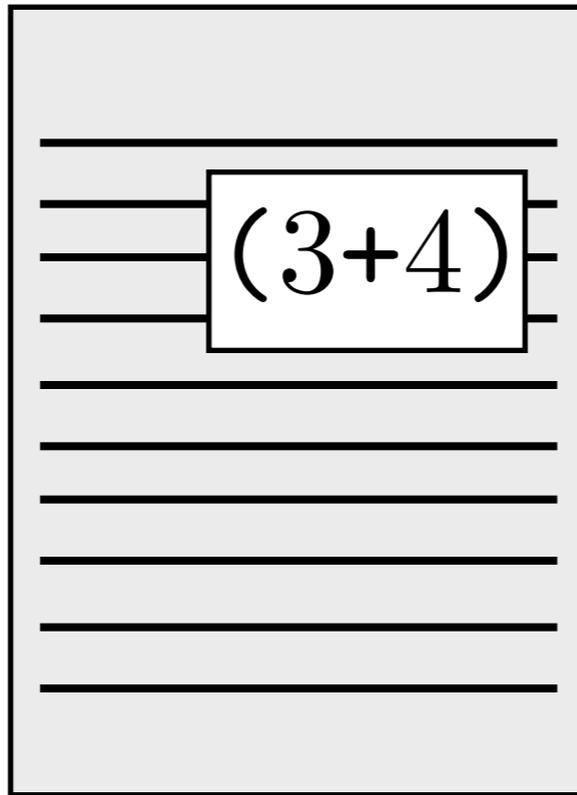
$$y \rightarrow 4$$



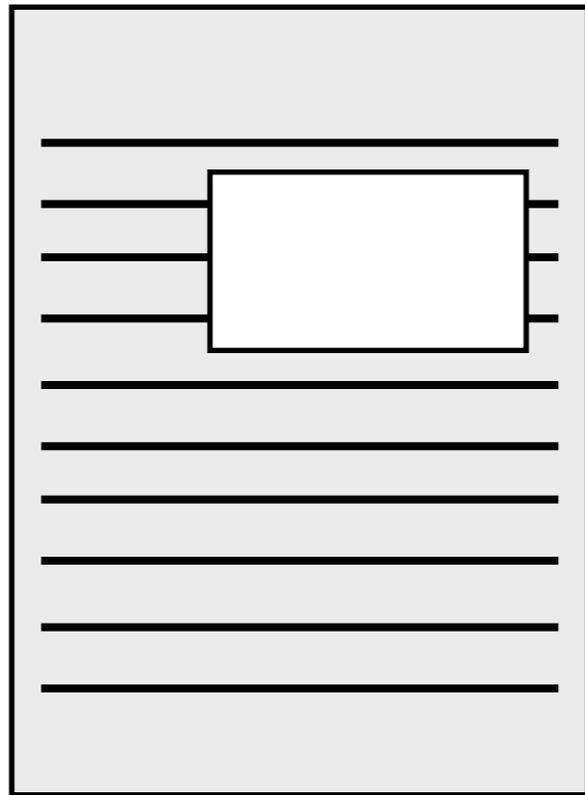
$$E[(3 + [4])]$$



P''



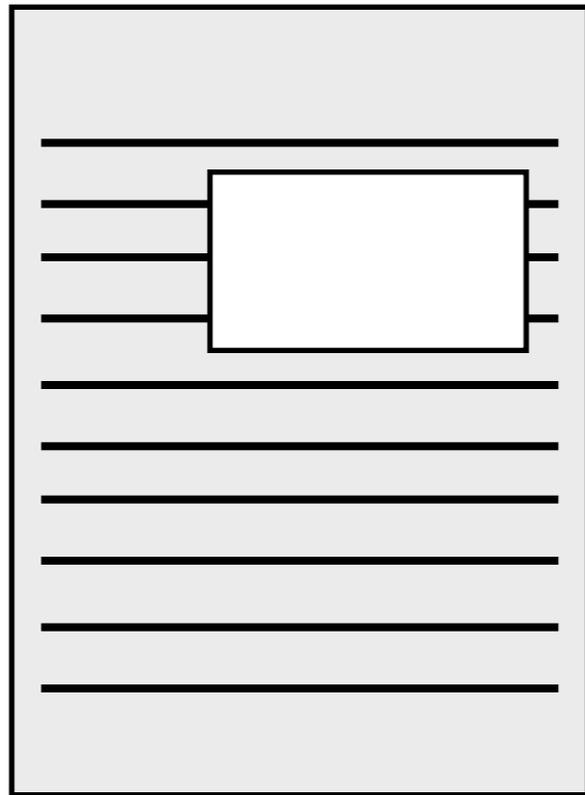
$$E[(3+4)]$$



$E[]$

$(3+4)$

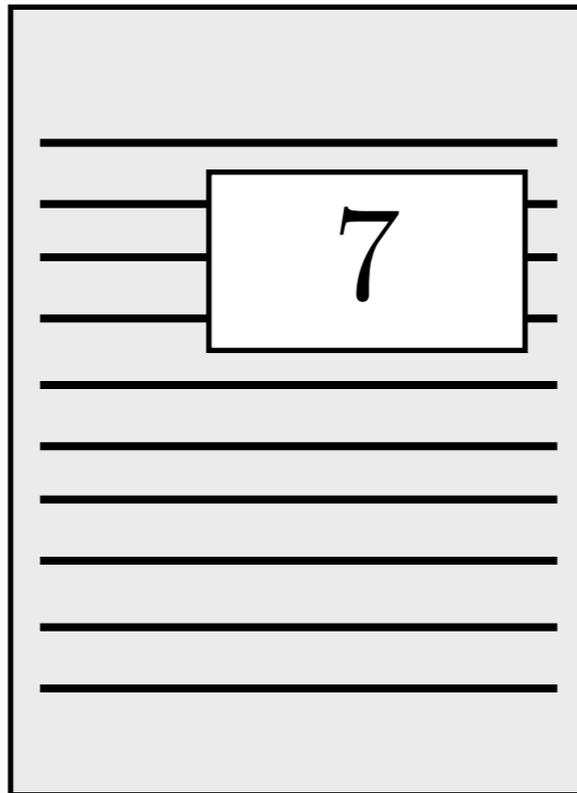
$(3+4) \rightarrow 7$



$E[]$

7

$(3+4) \rightarrow 7$



$E[7]$

Reduction semantics:

Syntax: $e ::= n \mid x \mid (e+e)$

Reduction: $(n+m) \rightarrow n + m$
 $x \rightarrow n$ where $\rho(x) = n$

Eval. Contexts: $E ::= [] \mid (E+e) \mid (n+E)$

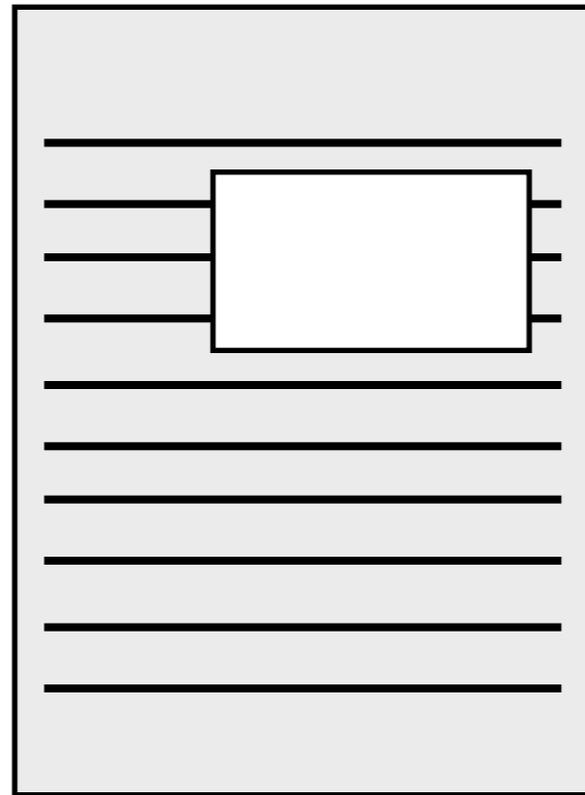
Reduction semantics:

Syntax: $e ::= n \mid x \mid (e+e)$

Reduction: $(n+m) \rightarrow n + m$
 $x \rightarrow n$ where $\rho(x) = n$

Eval. Contexts: $E ::= [] \mid (E+e) \mid (n+E)$

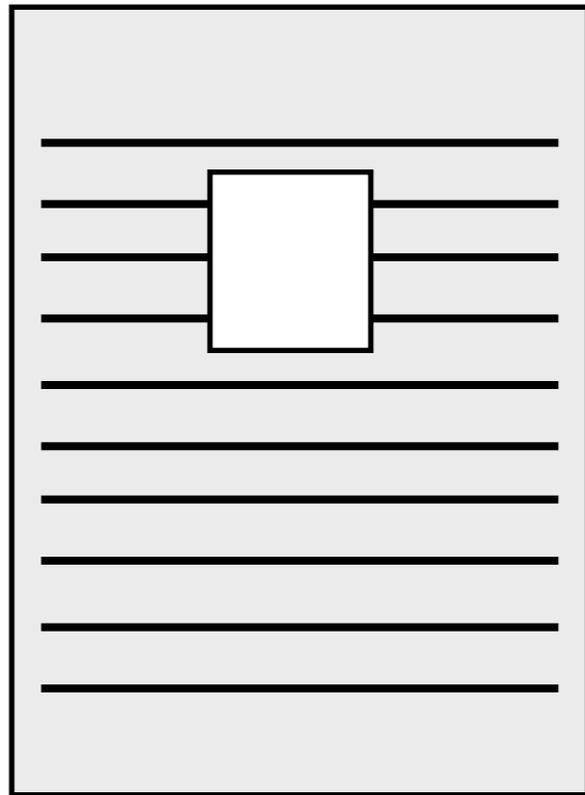
Continuations: $C ::= \mathbf{c}_0 \mid \mathbf{c}_1(e, C) \mid \mathbf{c}_2(n, C)$



C

$(x+y)$

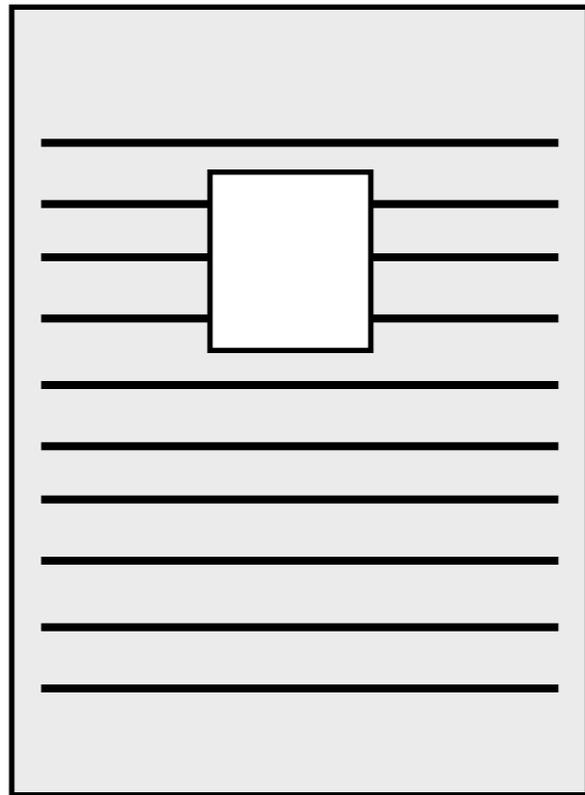
$(x+y)$



$\mathbf{c}_1(C, y)$

x

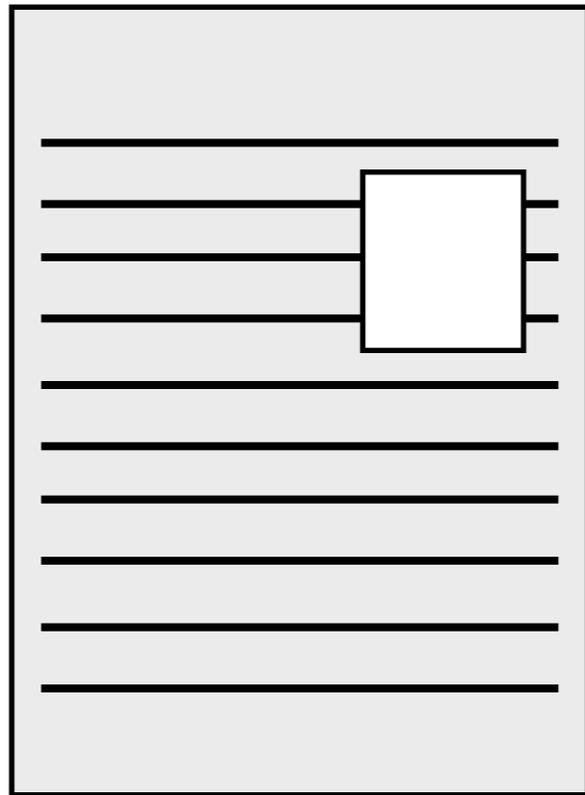
$x \rightarrow 3$



$\mathbf{c}_1(C, y)$

3

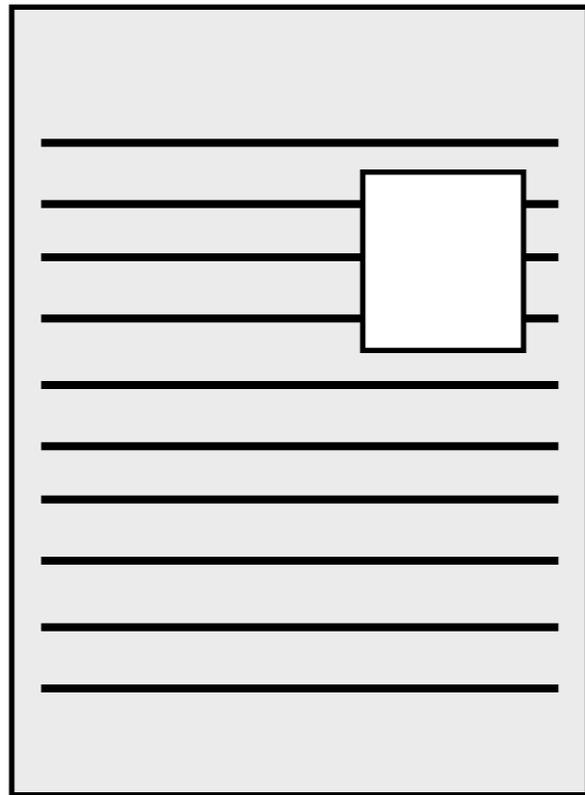
$x \rightarrow 3$



$\mathbf{c}_2(C, 3)$

y

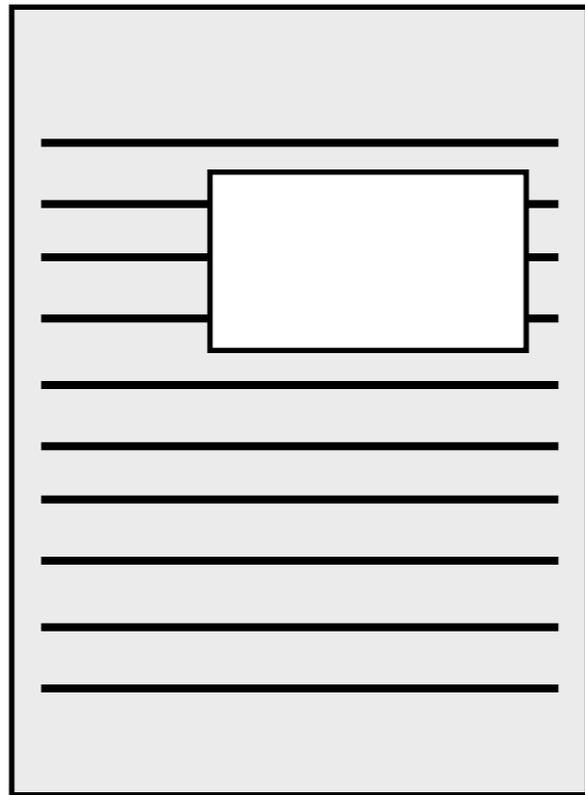
$y \rightarrow 4$



$\mathbf{c}_2(C, 3)$

4

$y \rightarrow 4$



C

$(3+4)$

$(3+4) \rightarrow 7$

Stack machine:

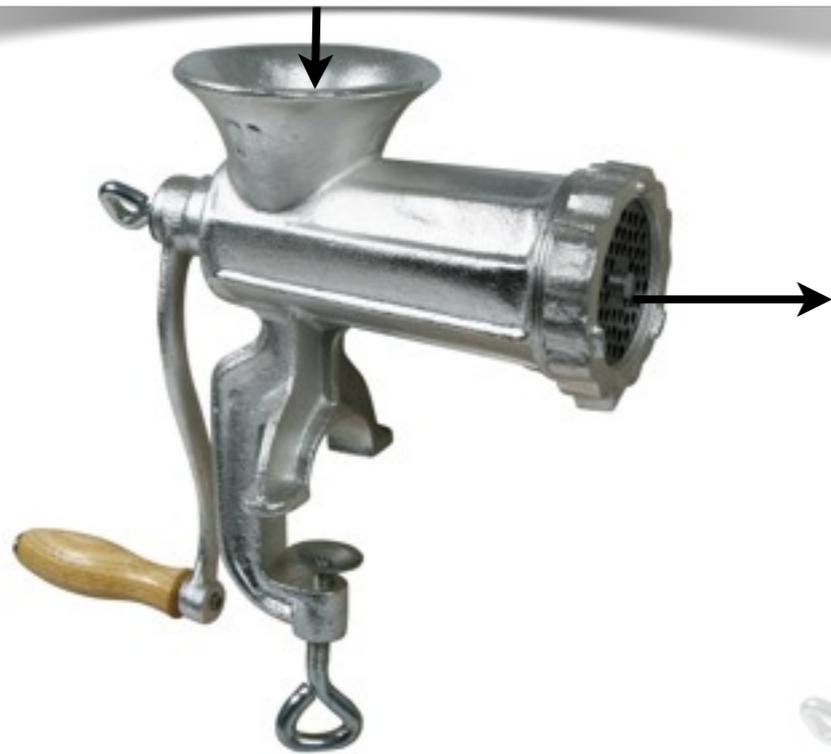
$$\begin{aligned} \langle (e_1+e_2), C \rangle &\rightarrow \langle e_1, \mathbf{c}_1(C, e_2) \rangle \\ \langle x, C \rangle &\rightarrow \langle n, C \rangle && \text{where } \rho(x) = n \\ \langle n, \mathbf{c}_1(C, e) \rangle &\rightarrow \langle e, \mathbf{c}_2(n, C) \rangle \\ \langle m, \mathbf{c}_2(n, C) \rangle &\rightarrow \langle n + m, C \rangle \end{aligned}$$

Correctness:

$$P \rightarrow^* n \iff \langle P, \mathbf{c}_0 \rangle \rightarrow^* \langle n, \mathbf{c}_0 \rangle$$

$$e ::= n \mid x \mid (e+e)$$
$$(n+m) \rightarrow n + m$$
$$x \rightarrow n \text{ where } \rho(x) = n$$
$$E ::= [] \mid (E+e) \mid (n+E)$$

A Closer Look


$$\begin{aligned} \langle (e_1+e_2), C \rangle &\rightarrow \langle e_1, \mathbf{c}_1(C, e_2) \rangle \\ \langle x, C \rangle &\rightarrow \langle n, C \rangle \\ \langle n, \mathbf{c}_1(C, e) \rangle &\rightarrow \langle e, \mathbf{c}_2(n, C) \rangle \\ \langle m, \mathbf{c}_2(n, C) \rangle &\rightarrow \langle n + m, C \rangle \end{aligned}$$


Analysis

Syntax:

$$c ::= \textit{num} \mid \textit{str} \mid \textit{bool} \mid \textit{undefined} \mid \textit{null}$$
$$v ::= c \mid \textit{func}(\vec{x}) \{ \textit{return } e \} \mid \{ \textit{str}.v \dots \}$$
$$p ::= \textit{str} : e$$
$$e ::= x \mid v \mid \{ \vec{p} \} \mid \textit{let } (x = e) e \mid e(\vec{e}) \\ \mid e[e] \mid e[e] = e \mid \textit{del } e[e]$$

Reductions:

$$\text{let } (x = v) e \rightarrow [v/x]e$$

$$(\text{func } (\vec{x}) \{ \text{return } e \}) (\vec{v}) \rightarrow [\vec{v}/\vec{x}]e$$

$$\{ \dots str_i.v \dots \} [str_i] \rightarrow v$$

$$\frac{str_x \notin (str_1 \dots)}{\{ str_1.v_1 \dots \} [str_x] \rightarrow \text{undefined}}$$

$$\{ \dots str_i.v_i \dots \} [str_i] = v \rightarrow \{ \dots str_i.v \dots \}$$

$$\frac{str_x \notin (str_1 \dots)}{\{ str_1.v_1 \dots \} [str_x] = v \rightarrow \{ str_x.v, str_1.v_1 \dots \}}$$

$$\text{del } \{ \dots str_i.v_i \dots \} [str_i] \rightarrow \{ \dots \}$$

$$\frac{str_x \notin (str_1 \dots)}{\text{del } \{ str_1.v_1 \dots \} [str_x] \rightarrow \{ str_1.v_1 \dots \}}$$

Eval. Contexts:

$$\begin{array}{l}
 E ::= [] \\
 | \text{let } (x = E) e \\
 | E(\vec{e}) \\
 | v(e \dots E, v \dots) \\
 | \{ str : v \dots str : E, \vec{p} \} \\
 | E[e] \\
 | v[E] \\
 | E[e] = e \\
 | v[E] = e \\
 | v[v] = E \\
 | \text{del } E[e] \\
 | \text{del } v[E]
 \end{array}$$

Continuations:

$$\begin{array}{l}
 C ::= \mathbf{c}_1 \\
 | \mathbf{c}_2(x, e, \rho, C) \\
 | \mathbf{c}_3(\vec{e}, \rho, C) \\
 | \mathbf{c}_4(c, \vec{c}, \vec{e}, \rho, C) \\
 | \mathbf{c}_5(str, \vec{q}, \vec{p}, \rho, C) \\
 | \mathbf{c}_6(e, \rho, C) \\
 | \mathbf{c}_7(c, C) \\
 | \mathbf{c}_8(e, e, \rho, C) \\
 | \mathbf{c}_9(c, e, \rho, C) \\
 | \mathbf{c}_{10}(c, c, C) \\
 | \mathbf{c}_{11}(e, \rho, C) \\
 | \mathbf{c}_{12}(c, C)
 \end{array}$$

Machine:

| | | |
|---|---|------------------------------------|
| $\langle\langle x, \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle c, \sigma, C \rangle$ | where $\sigma(\rho(x)) = c$ |
| $\langle c, \sigma, \mathbf{c}_2(x, e, \rho, C) \rangle$ | $\rightarrow \langle\langle e, \rho[x \mapsto a] \rangle, \sigma[a \mapsto c], C \rangle$ | where a is fresh |
| $\langle c, \sigma, \mathbf{c}_4(\langle \text{func}(\vec{x}) \{ \text{return } e \}, \rho \rangle, c_n \dots c_0, \rho', C) \rangle$ | $\rightarrow \langle\langle e, \rho[\vec{x} \mapsto \vec{a}] \rangle, \sigma[\vec{a} \mapsto c_0 \dots c_n c], C \rangle$ | where \vec{a} are fresh |
| $\langle\langle str_i, \rho \rangle, \sigma, \mathbf{c}_7(\{ \dots str_i.c_i \dots \}, C) \rangle$ | $\rightarrow \langle c_i, \sigma, C \rangle$ | |
| $\langle\langle str_x, \rho \rangle, \sigma, \mathbf{c}_7(\{ str_1.c_1 \dots \}, C) \rangle$ | $\rightarrow \langle \text{undefined}, \sigma, C \rangle$ | where $str_x \notin (str_1 \dots)$ |
| $\langle c, \sigma, \mathbf{c}_{10}(\{ \dots str_i.c_i \dots \}, \langle str_i, \rho \rangle, C) \rangle$ | $\rightarrow \langle \{ \dots str_i.c \dots \}, \sigma, C \rangle$ | |
| $\langle c, \sigma, \mathbf{c}_{10}(\{ str_1.c_1 \dots \}, \langle str_x, \rho \rangle, C) \rangle$ | $\rightarrow \langle \{ str_x.c, str_1.c_1 \dots \}, \sigma, C \rangle$ | where $str_x \notin (str_1 \dots)$ |
| $\langle\langle str_i, \rho \rangle, \sigma, \mathbf{c}_{12}(\{ \dots str_i.c_i \dots \}, C) \rangle$ | $\rightarrow \langle \{ \dots \}, \sigma, C \rangle$ | |
| $\langle\langle str_x, \rho \rangle, \sigma, \mathbf{c}_{12}(\{ str_1.c_1 \dots \}, C) \rangle$ | $\rightarrow \langle \{ str_1.c_1 \dots \}, \sigma, C \rangle$ | where $str_x \notin (str_1 \dots)$ |
| $\langle c, \sigma, \mathbf{c}_3(e\vec{e}, \rho, C) \rangle$ | $\rightarrow \langle\langle e, \rho \rangle, \sigma, \mathbf{c}_4(c, \vec{e}, \rho, C) \rangle$ | |
| $\langle\langle \text{func}() \{ \text{return } e \}, \rho \rangle, \sigma, \mathbf{c}_3(\rho', C) \rangle$ | $\rightarrow \langle\langle e, \rho \rangle, \sigma, C \rangle$ | |
| $\langle c, \sigma, \mathbf{c}_5(str, \vec{q}, \rho, C) \rangle$ | $\rightarrow \langle \{ str:c, \vec{q} \}, C \rangle$ | |
| $\langle c, \sigma, \mathbf{c}_5(str, \vec{q}, str_1:e_1\vec{p}, \rho, C) \rangle$ | $\rightarrow \langle\langle e_1, \rho \rangle, \sigma, \mathbf{c}_5(str_1, str:c\vec{q}, \vec{p}, \rho, C) \rangle$ | |
| $\langle\langle \text{let } (x = e_0) e_1, \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_2(x, e_1, \rho, C) \rangle$ | |
| $\langle\langle e(), \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e, \rho \rangle, \sigma, C \rangle$ | |
| $\langle\langle e_0(e\vec{e}), \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_3(e\vec{e}, \rho, C) \rangle$ | |
| $\langle\langle \{ \}, \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle \{ \}, \sigma, C \rangle$ | |
| $\langle\langle \{ str_0:e_0\vec{p} \}, \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_5(str_0, \vec{p}, \rho, C) \rangle$ | |
| $\langle\langle e_0[e_1], \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_6(e_1, \rho, C) \rangle$ | |
| $\langle\langle e_0[e_1] = e_2, \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_8(e_1, e_2, \rho, C) \rangle$ | |
| $\langle\langle \text{del } e_0[e_1], \rho \rangle, \sigma, C \rangle$ | $\rightarrow \langle\langle e_0, \rho \rangle, \sigma, \mathbf{c}_{11}(e_1, \rho, C) \rangle$ | |

$\langle e, C \rangle$

Var \rightarrow Addr

Addr \rightarrow Value

$\langle e, \rho, \sigma, C \rangle$

Semantics



Machine



A Closer Look



Analysis



Semantics

A Closer Look



Machine



Analysis

Key idea:

**Deterministic state transition system
with an infinite state space.**



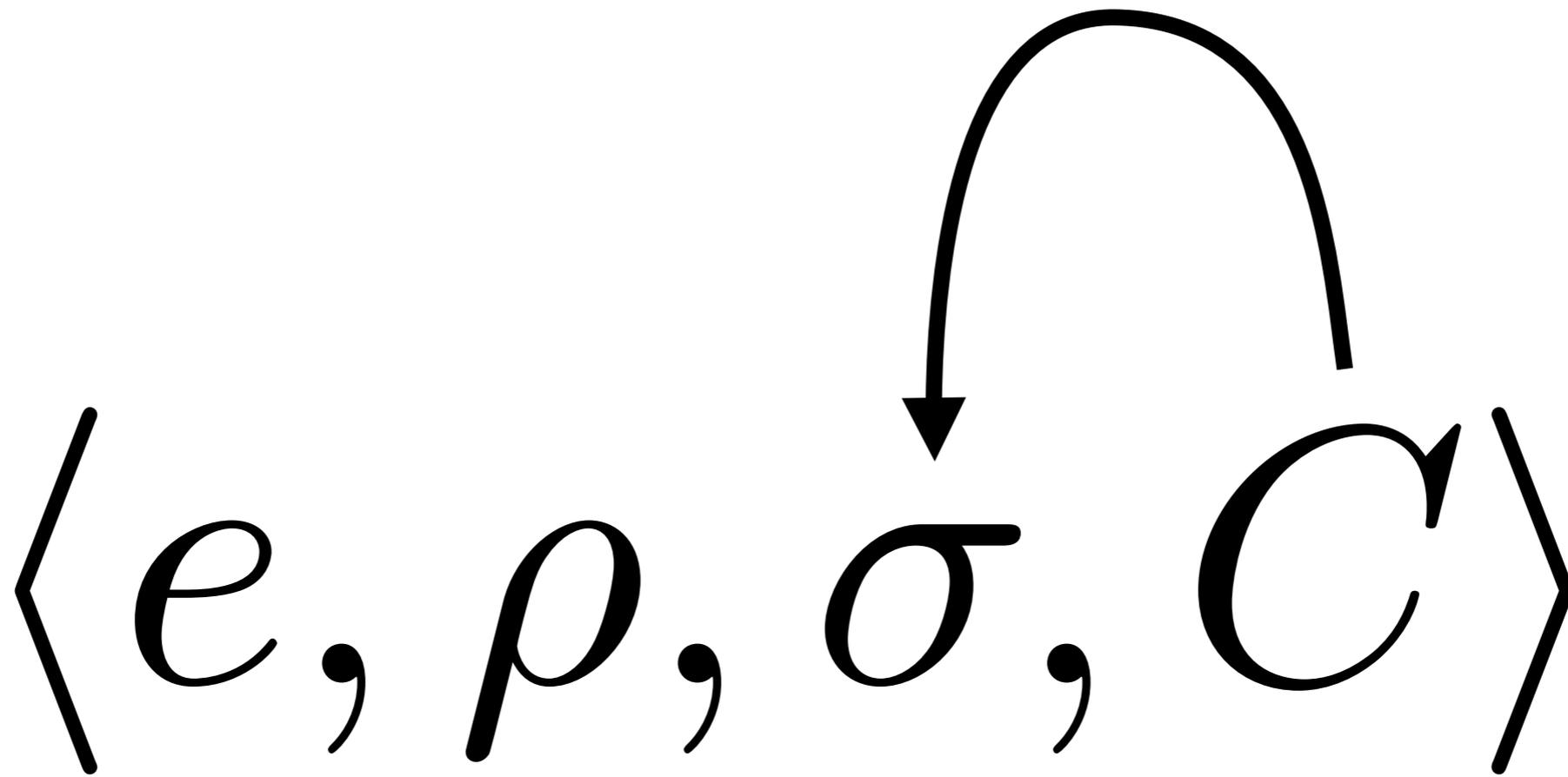
**Non-Deterministic state transition system
with a **finite** state space.**

Step 1:

$$\langle e, \rho, \sigma, C \rangle$$

Move continuations into heap.

Step 1:



Move continuations into heap.

Step 1:

$$\langle e, \rho, \sigma, a \rangle$$

$$\sigma(a) = C$$

Step 1:

Var \rightarrow Addr

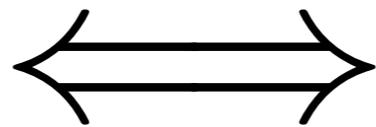
Addr \rightarrow Value + Cont

$\langle e, \rho, \sigma, a \rangle$

$$\sigma(a) = C$$

Step 1:

$$\langle (e_1 + e_2), \rho, \sigma, C \rangle \rightarrow \langle e_1, \rho, \sigma, \mathbf{c}_1(C, e_2) \rangle$$



$$\langle (e_1 + e_2), \rho, \sigma, a \rangle \rightarrow \langle e_1, \rho, \sigma [a' \mapsto \mathbf{c}_1(a, e_2)], a' \rangle$$

Step 2:

$$\langle e, \rho, \hat{\sigma}, a \rangle$$

$$\hat{\sigma}(a) \ni C$$

Step 2:

Var \rightarrow Addr

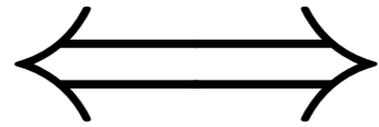
Addr \rightarrow \wp (Value + Cont)

$\langle e, \rho, \hat{\sigma}, a \rangle$

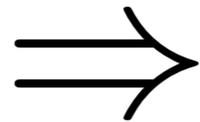
$\hat{\sigma}(a) \ni C$

Step 1:

$$\langle (e_1 + e_2), \rho, \sigma, C \rangle \rightarrow \langle e_1, \rho, \sigma, \mathbf{c}_1(C, e_2) \rangle$$

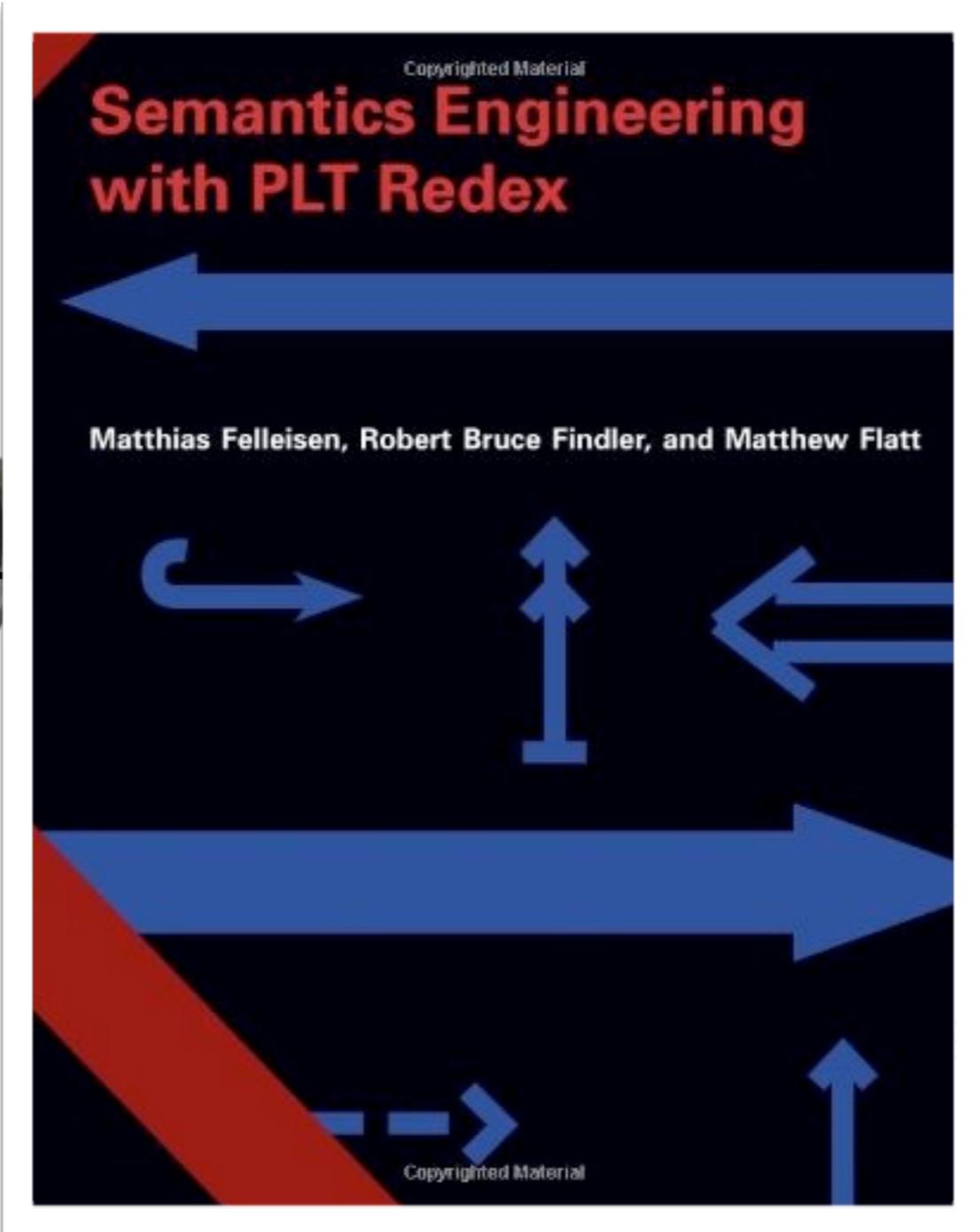


$$\langle (e_1 + e_2), \rho, \sigma, a \rangle \rightarrow \langle e_1, \rho, \sigma[a' \mapsto \mathbf{c}_1(a, e_2)], a' \rangle$$

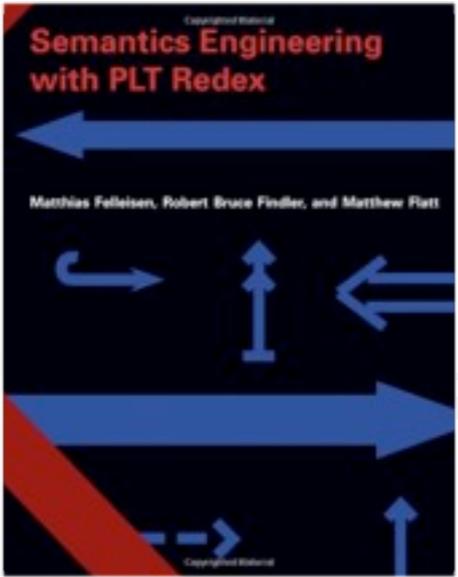


$$\langle (e_1 + e_2), \rho, \hat{\sigma}, a \rangle \rightarrow \langle e_1, \rho, \hat{\sigma} \sqcup [a' \mapsto \mathbf{c}_1(a, e_2)], a' \rangle$$

Semantics ←.....



.....
Analysis



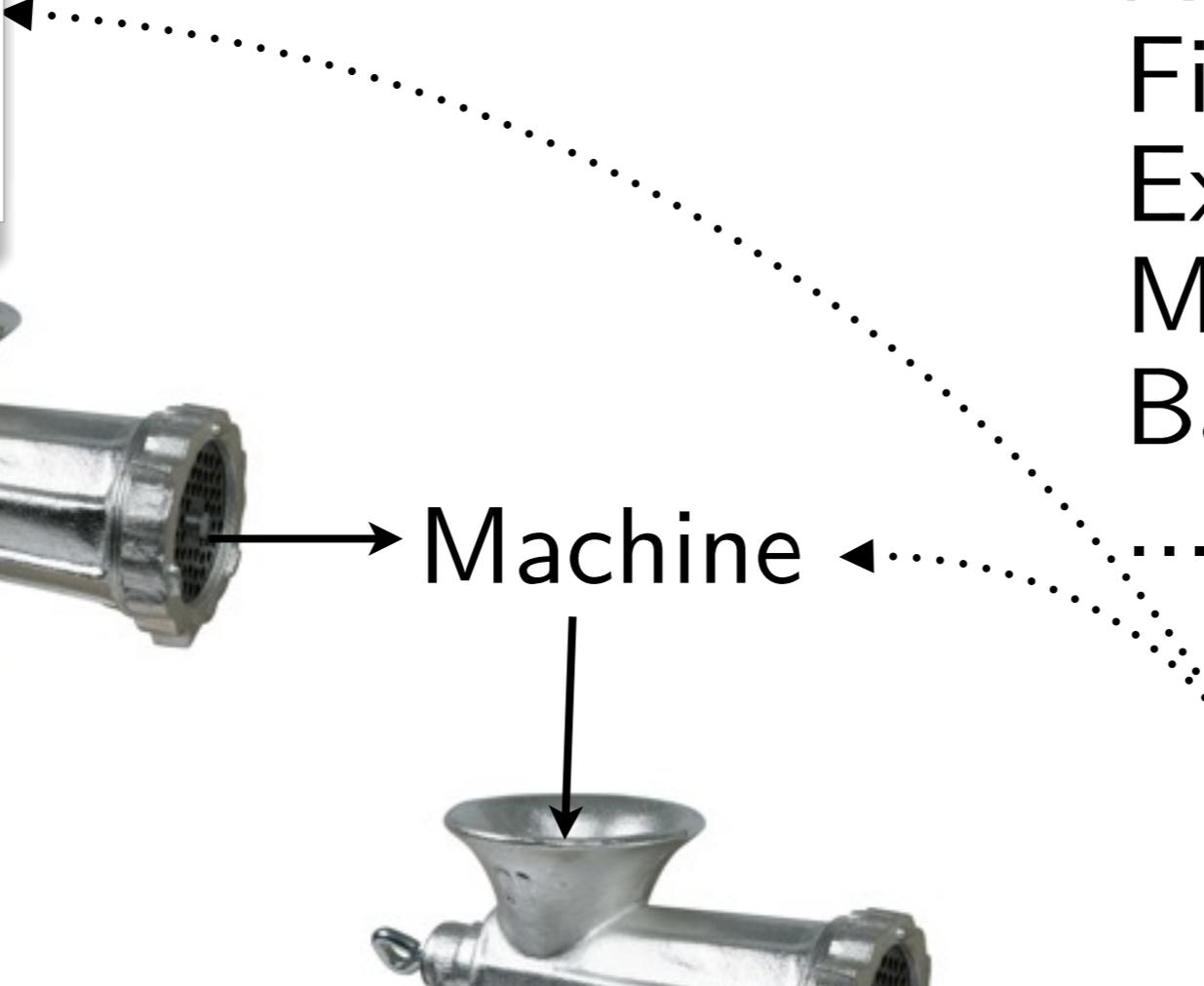
Analysis of:
First-class control
Exceptions
Mutation
Base values



Machine



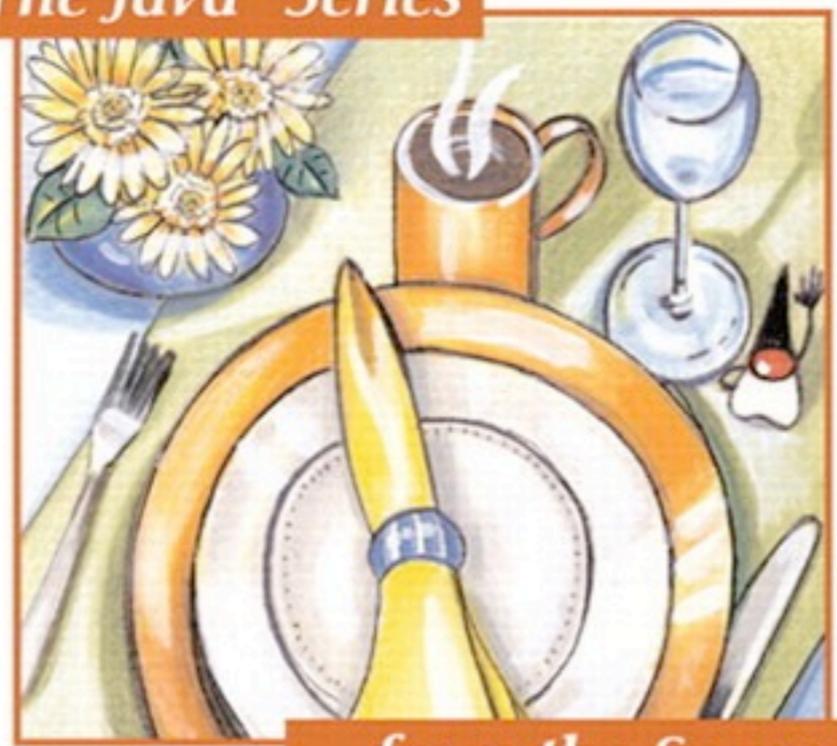
Analysis



James Gosling • Bill Joy • Guy Steele • Gilad Bracha ↕

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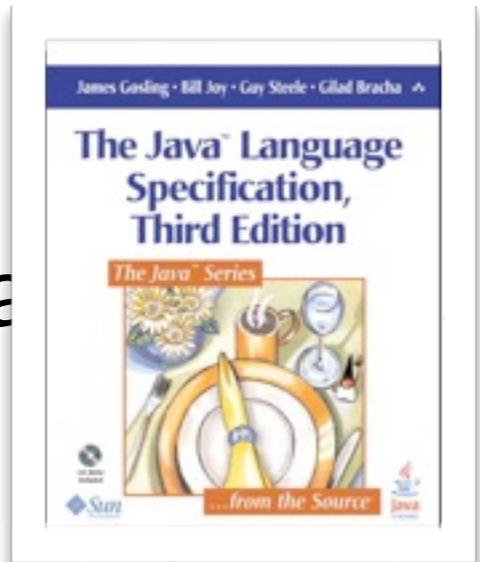


Semanti



...
analysis

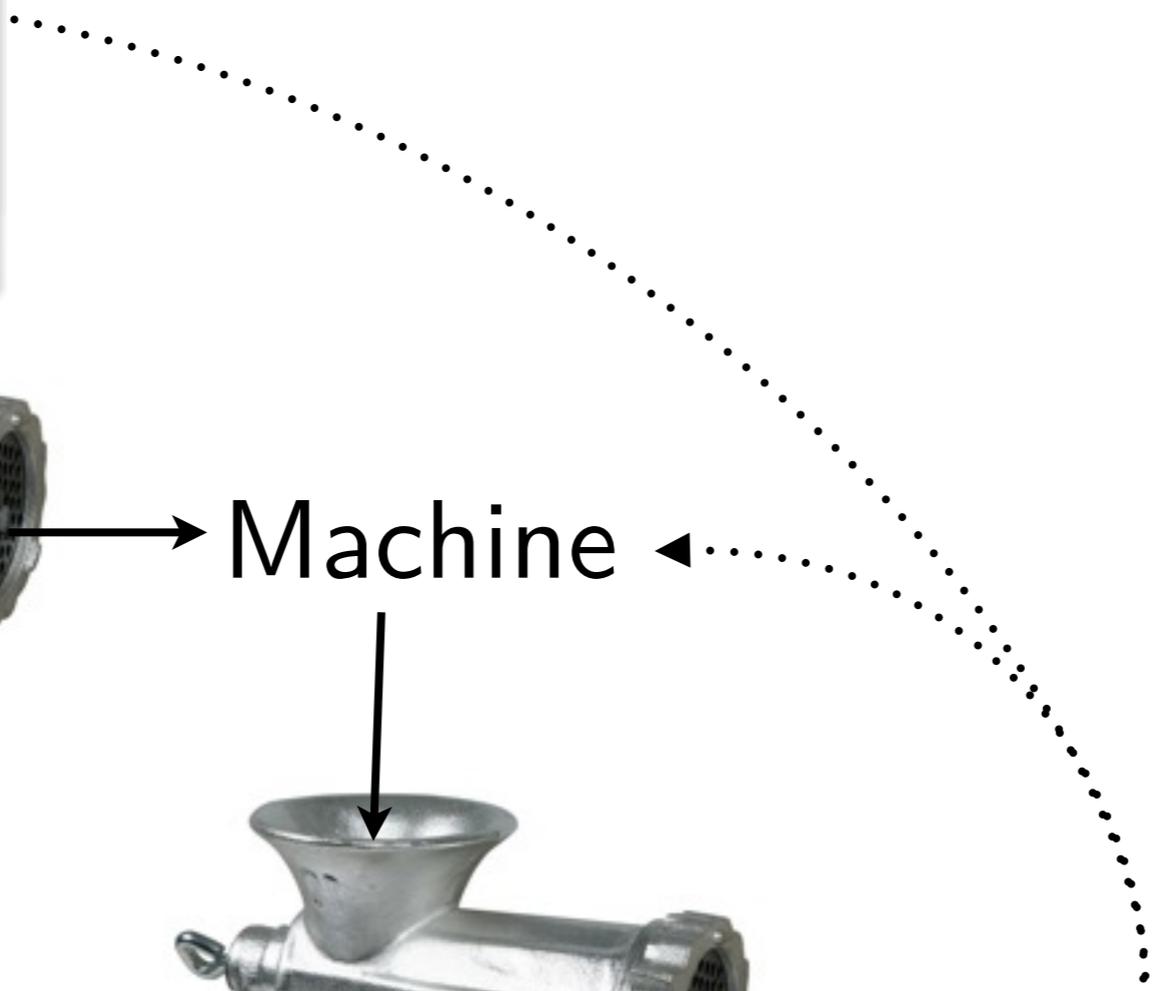
Sema



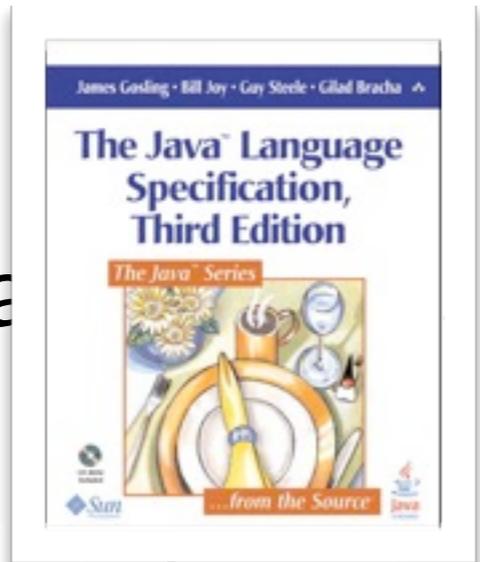
Machine



Analysis



Sema



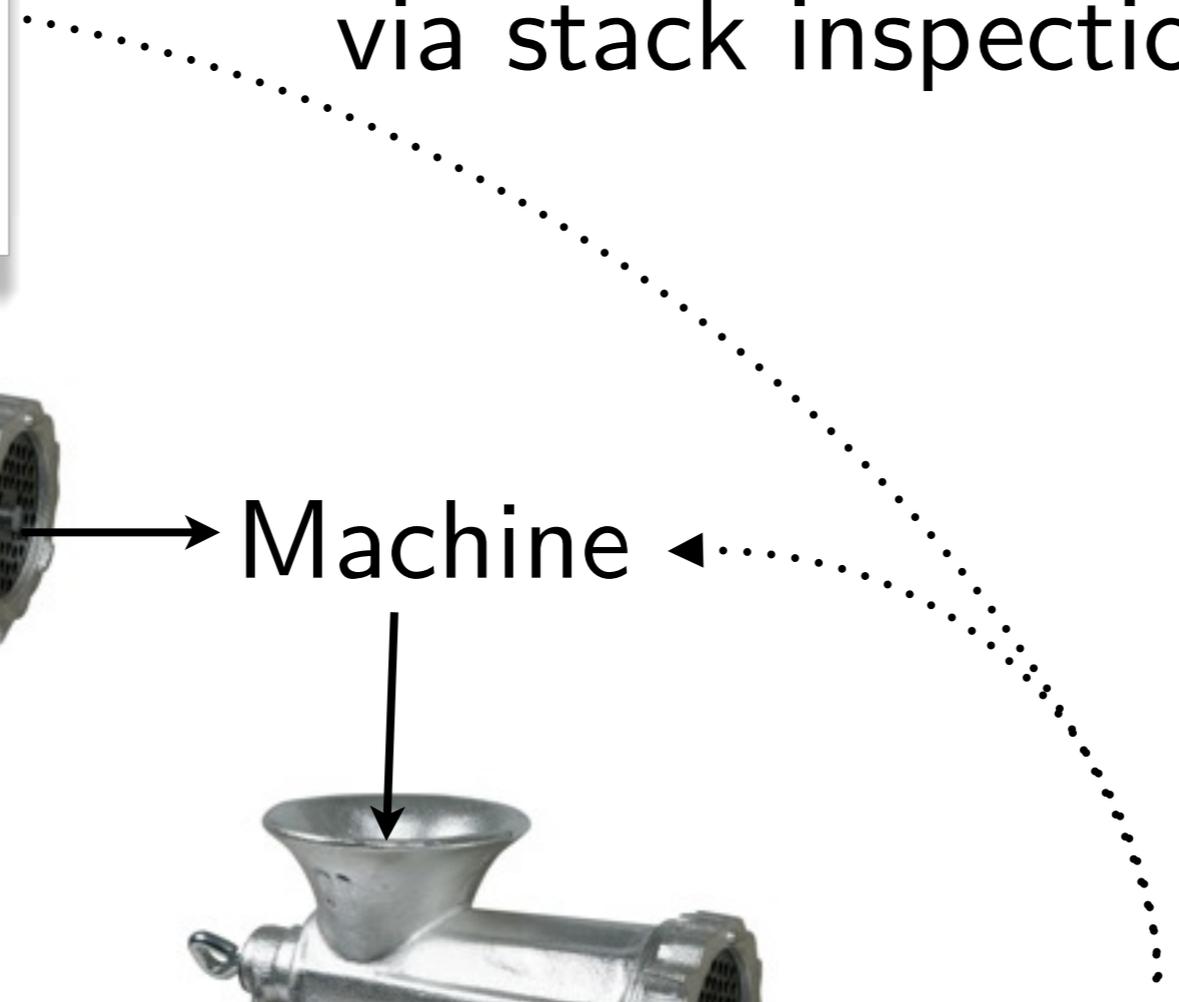
Static verification of security via stack inspection



Machine



Analysis



Abstract Models of Memory Management*

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Abstract

Most specifications of garbage collectors concentrate on the low-level algorithmic details of *how* to find and preserve accessible objects. Often, they focus on bit-level manipulations such as “scanning stack frames,” “marking objects,” “tagging data,” *etc.* While these details are important in some contexts, they often obscure the more fundamental aspects of memory management: *what* objects are garbage and *why*?

We develop a series of calculi that are just low-level enough that we can express allocation and garbage collection, yet are sufficiently abstract that we may formally prove the correctness of various memory management strategies. By making the heap of a program syntactically apparent, we can specify memory actions as rewriting rules that allocate values on the heap and automatically dereference pointers to such objects when needed. This formulation permits the specification of garbage collection as a relation that removes portions of the heap without affecting the outcome of the evaluation.

Our high-level approach allows us to specify in a compact manner a wide variety of memory management techniques, including standard trace-based garbage collection (*i.e.*, the family of copying and mark/sweep collection algorithms), generational collection, and type-based, tag-free collection. Furthermore, since the definition of garbage is based on the *semantics* of the underlying language instead of the conservative approximation of inaccessibility, we are able to specify and prove the idea that type inference can be used to collect some objects that are accessible but never used.

*This work was sponsored in part by the Advanced Research Projects Agency (ARPA), CSTO, under the title “The Fox Project: Advanced Development of Systems Software,” ARPA Order No. 8313, issued by ESD/AVS under Contract No. F19628-91-C-0168, Wright Laboratory, Aeronautical Systems Center, Air Force Materiel Command, USAF, and ARPA grant No. F33615-93-1-1330. Views and conclusions contained in this document are those of the authors and should not be interpreted as necessarily representing official policies or endorsements, either expressed or implied, of Wright Laboratory or the United States Government.

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1 Memory Safety

Advanced programming languages manage memory allocation and deallocation automatically. Automatic memory managers, or garbage collectors, significantly facilitate the programming process because programmers can rely on the language implementation for the delicate tasks of finding and freeing unneeded objects. Indeed, the presence of a garbage collector ensures *memory safety* in the same way that a type system guarantees *type safety*: no program written in an advanced programming language will crash due to dangling pointer problems while allocation, access, and deallocation are transparent. However, in contrast to type systems, memory management strategies and particularly garbage collectors rarely come with a compact formulation and a formal proof of soundness. Since garbage collectors work on the machine representations of abstract values, the very idea of providing a proof of memory safety sounds unrealistic given the lack of simple models of memory operations.

The recently developed syntactic approaches to the specification of language semantics by Felleisen and Hieb [11] and Mason and Talcott [18, 19] are the first execution models that are intensional enough to permit the specification of memory management actions and yet are sufficiently abstract to permit compact proofs of important properties. Starting from the λ_v -S calculus of Felleisen and Hieb, we design compact specifications of a number of memory management ideas and prove several correctness theorems.

The basic idea underlying the development of our garbage collection calculi is the representation of a program’s run-time memory as a global series of syntactic declarations. The program evaluation rules allocate large objects in the global declaration, which represents the heap, and automatically dereference pointers to such objects when needed. As a result, garbage collection can be specified as any relation that removes portions of the current heap without affecting the result of a program’s execution.

In Section 2, we present a small functional programming language, λ_{gc} , with a rewriting semantics that makes allocation explicit. We define a semantic notion of garbage collection for λ_{gc} and prove that there is no *optimal* collection strategy that is computable. In Section 3, we specify the “free-variable” garbage collection rule which models trace-based collectors including mark/sweep and copying collectors. We prove that the free-variable rule is correct and provide two “implementations” at the syntactic level: the first corresponds to a copying collector, the second to a generational one.

In Section 4, we formalize so-called “tag-free” collection algorithms for explicitly-typed, monomorphic languages such as Pascal and Algol [7, 29, 8]. We show how to *recover*



Analysis



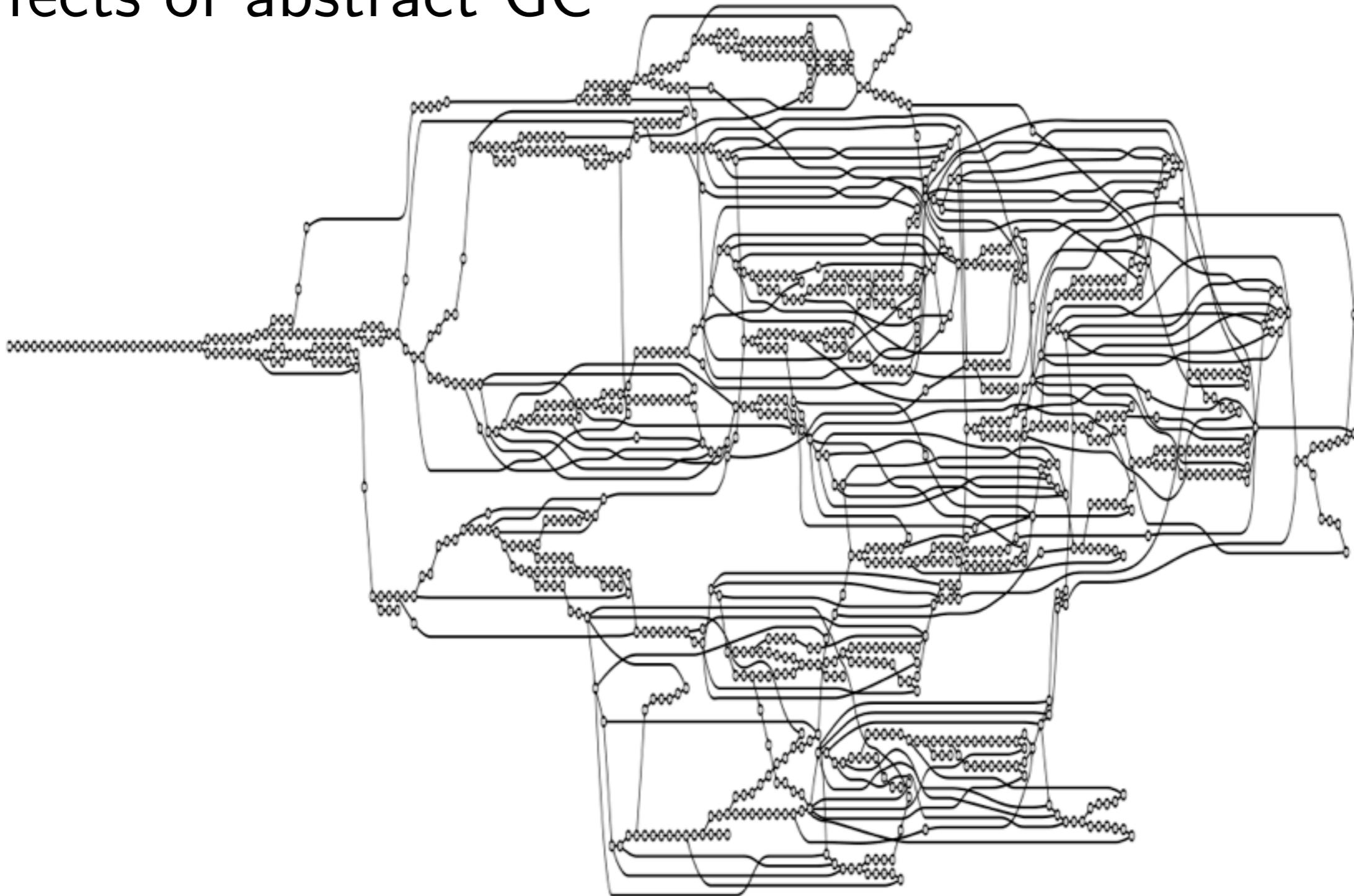
Improved precision and efficiency via abstract GC



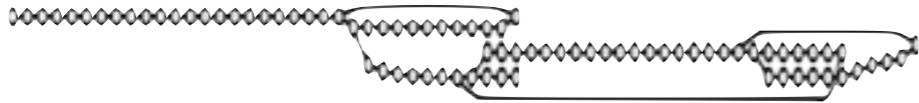
Analysis

Effects of abstract GC

Effects of abstract GC



Effects of abstract GC



My challenge to ICFP:

Develop a program analysis for reasoning about:

- ✓ Space-consumption in a lazy language
- ✓ State and control in a language with effects
- ✓ Security in a language with stack inspection
- ✓ Blame in a language with behavioral contracts
-  Safe parallelism in a language with futures



Space-consumption in a lazy language



State and control in a language with effects



Security in a language with stack inspection



Blame in a language with behavioral contracts



Safe parallelism in a language with futures



Garbage collection



Java

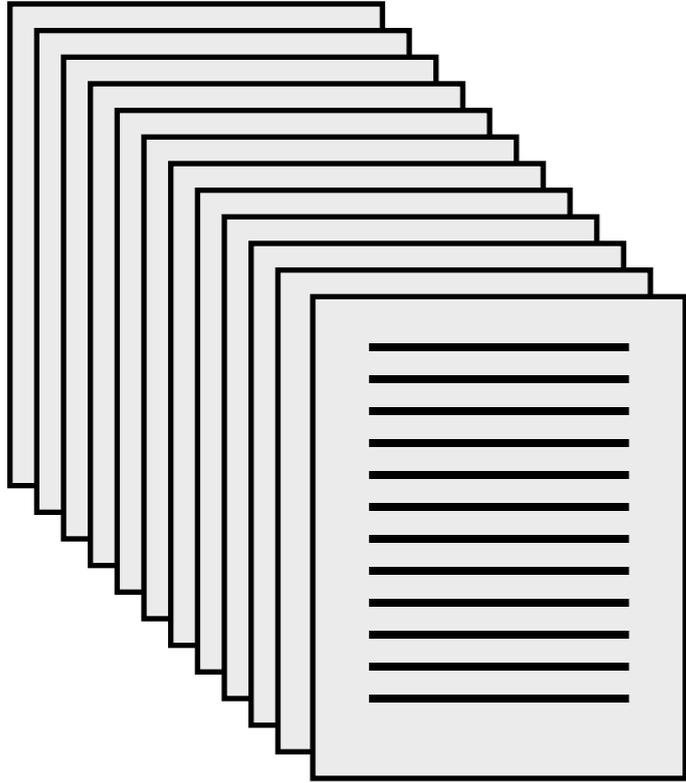


JavaScript



May happen in parallel for threads

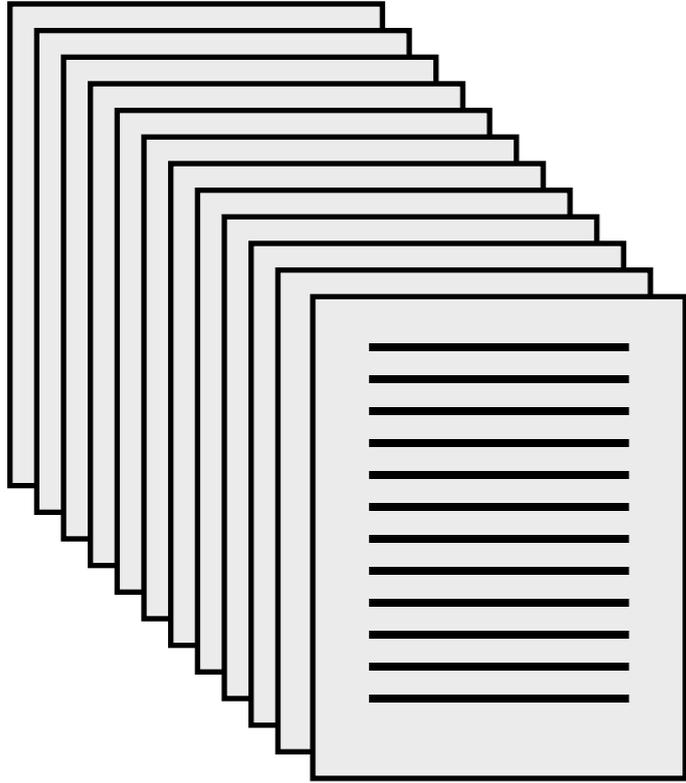
Complexity and Modularity



IM LOC

$$+ O(n^3) =$$

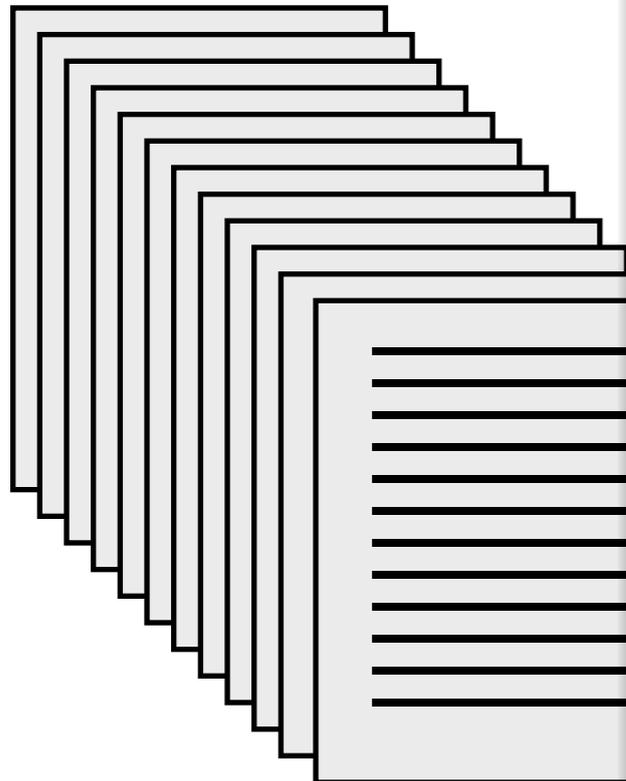




IM LOC

$$+ O(n^3) =$$





IM LOC

On the Cubic Bottleneck in Subtyping and Flow Analysis

Nevin Heintze*

David McAllester†

Abstract

We prove that certain data-flow and control-flow problems are 2NPDA-complete. This means that these problems are in the class 2NPDA and that they are hard for that class. The fact that they are in 2NPDA demonstrates the richness of the class. The fact that they are hard for 2NPDA can be interpreted as evidence they can not be solved in sub-cubic time — the cubic time decision procedure for an arbitrary 2NPDA problem has not been improved since its discovery in 1968.

1. Introduction

Cubic time complexity has become a common feature of algorithms for the automated analysis of computer programs. There is a general feeling that many of these algorithms are inherently cubic time — no sub-cubic procedure has been found. Such cubic time algorithms include Shivers' control flow analysis [17], the Palsberg and O'Keefe method of determining typability in the Amadio-Cardelli type system [15, 1], and various set-based analyses [5, 10, 11]. At an intuitive level the inherent cubic complexity in all these problems arises from the need to compute a dynamic transitive closure — one must compute the transitive closure of a directed graph while adding edges to the input graph as a consequence of edges derived for the output graph. Not only do these problems all seem inherently cubic, they all seem structurally similar and inherently cubic for the same reason.

In order to better understand the "cubic bottleneck" in flow analysis, Melski and Reps have investigated a simple data-flow reachability problem [13].¹ They relate this

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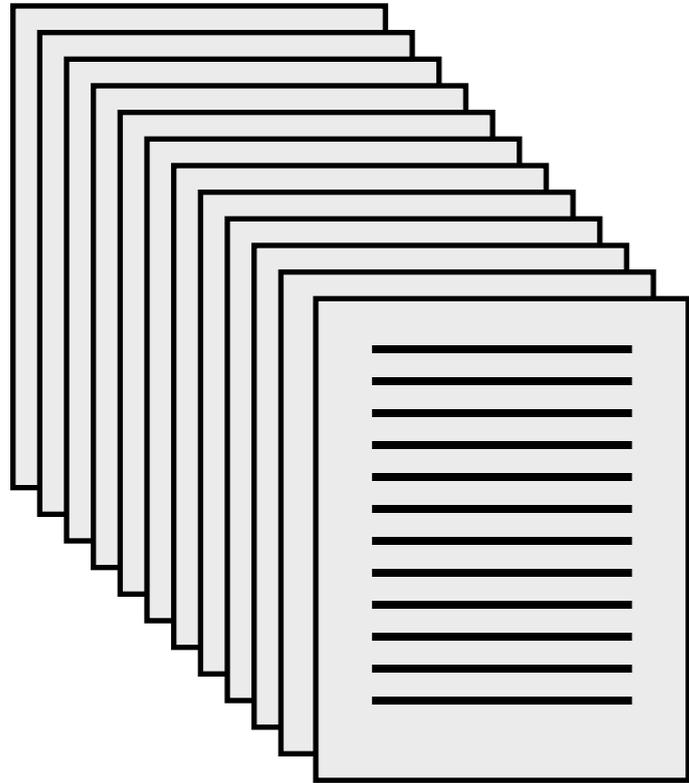
¹Following Heintze and Jaffar [4], Melski and Reps formulate this data-flow reachability problem as a set-constraint problem. We use the data-flow formulation here because it seems closer to applications.

data-flow reachability problem to the problem of context-free-language reachability (CFL-reachability). An instance of the CFL-reachability problem consists of a context free grammar and a directed graph where each arc is labeled with a symbol from the terminal alphabet. The problem is to determine whether there is a path between two given nodes such that the sequence of labels on the arcs in that path is a string in the language generated by the given grammar. The CFL-reachability problem can be solved in $O(|G|n^3)$ time where $|G|$ is the size of the grammar (the number of productions in a Chomsky normal form grammar) and n is the number of nodes in the graph. Melski and Reps give a linear time reduction from data-flow reachability to CFL-reachability. This reduction produces a grammar of size n , so the reduction appears to yield an $O(n^4)$ method of solving data-flow reachability. However, Melski and Reps show that the reduction produces problems with special structure and that the overall running time of solving a data-flow problem by reduction to CFL-reachability is $O(n^3)$. More significantly, Melski and Reps give a reduction of CFL-reachability to data-flow reachability which runs in $O(|G|n)$ time. For a fixed grammar this reduction is linear time. If the data-flow reachability problem could be solved in sub-cubic time then the CFL-reachability problem over a fixed grammar could also be solved in sub-cubic time.

Here we investigate the cubic bottleneck by relating it to the class 2NPDA. 2NPDA is the class of languages (or problems) definable by a two way nondeterministic push-down automata. In 1968 it was shown that any problem in the class 2NPDA can be solved in cubic time [2]. But no sub-cubic procedure for an arbitrary 2NPDA problem is known. Neal has shown that a certain 2NPDA problem — ground monadic rewriting reachability (GMR-reachability) — is 2NPDA complete [14].² In other words, this problem is both in the class 2NPDA and is 2NPDA-hard, i.e., if GMR-reachability can be solved in sub-cubic time then all 2NPDA problems can be solved in sub-cubic time. We review Neal's result here. We also show that data-flow reachability, control-flow reachability, and the complement of Amadio-

²Neal uses a "monotone closure" formulation of GMR-problem. We find the GMR formulation more natural.

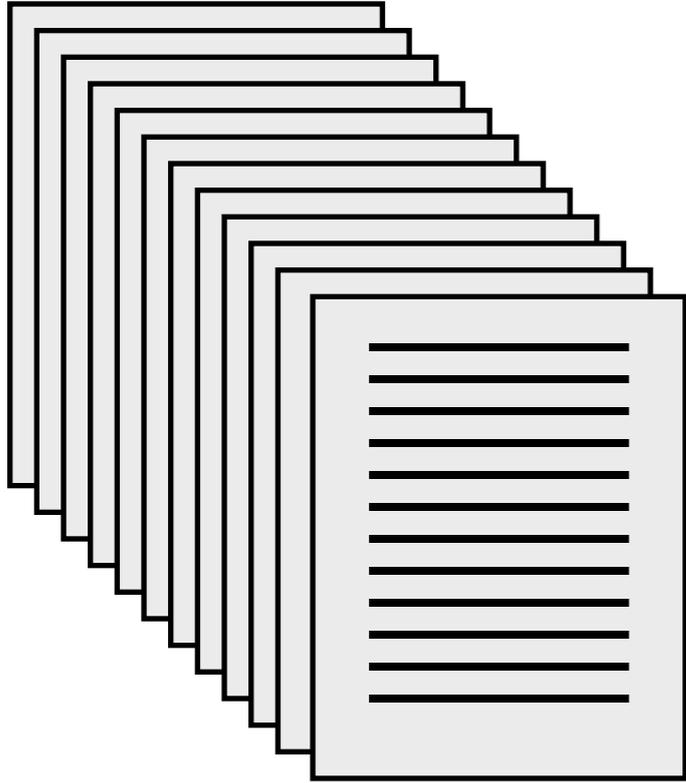




IM LOC

$$+ O(n^3 / \lg n) =$$



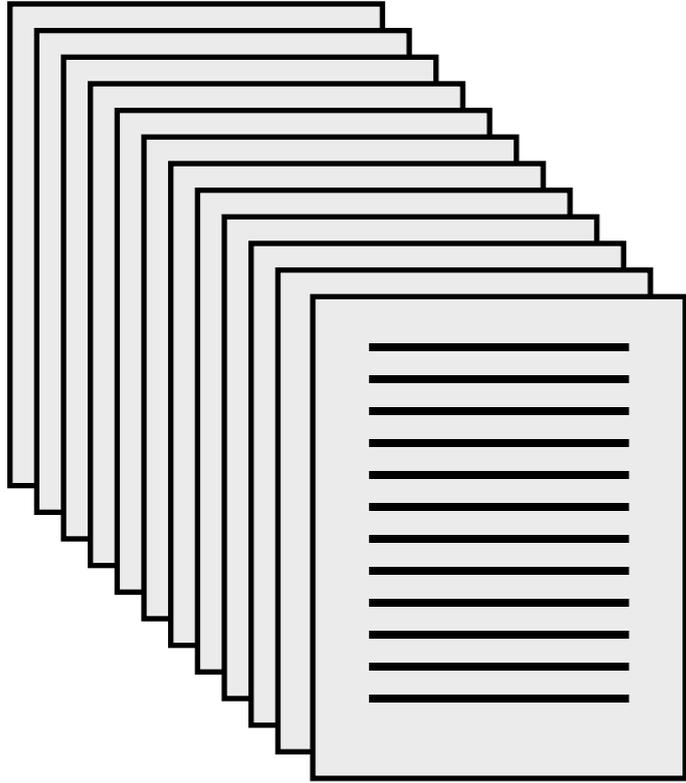


IM LOC

$$+ O(n^{2.9})$$

=



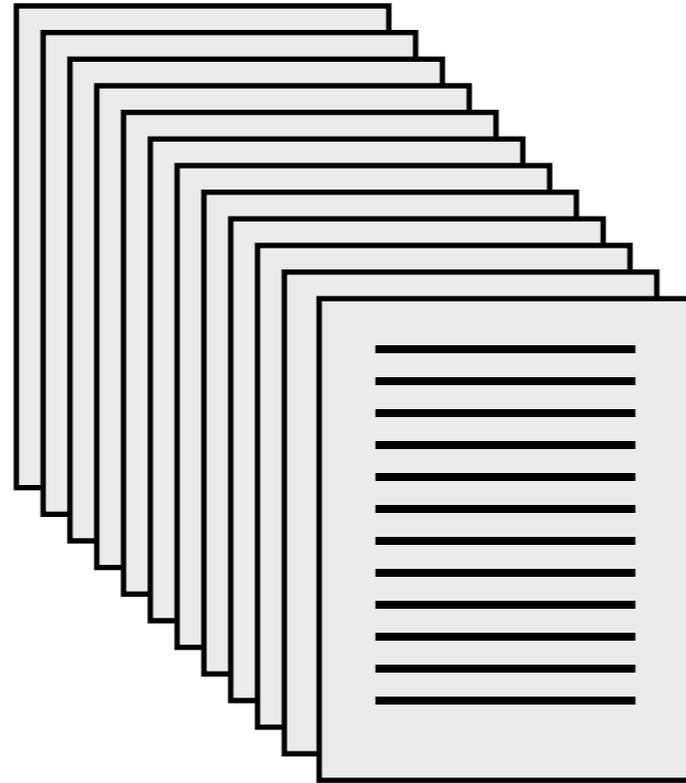


IM LOC

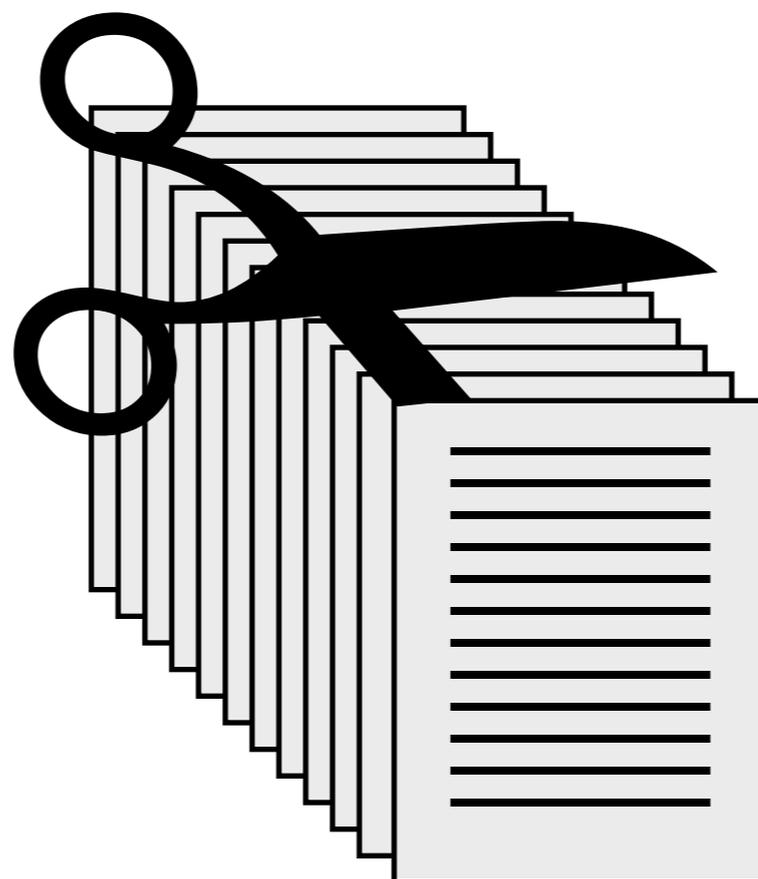
$$+ O(n^{2.9})$$

=

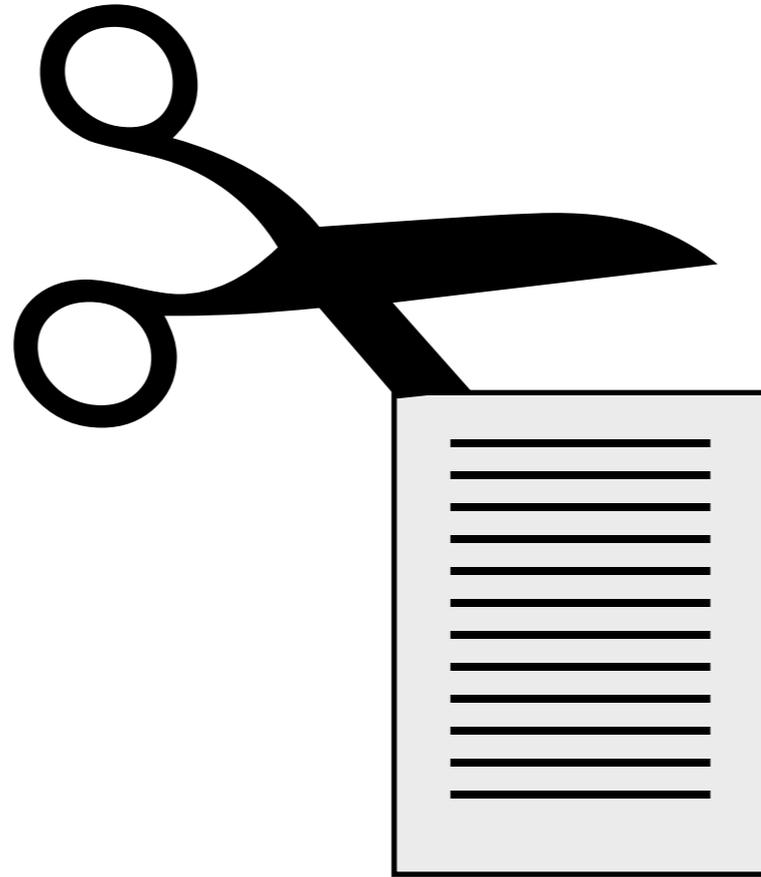




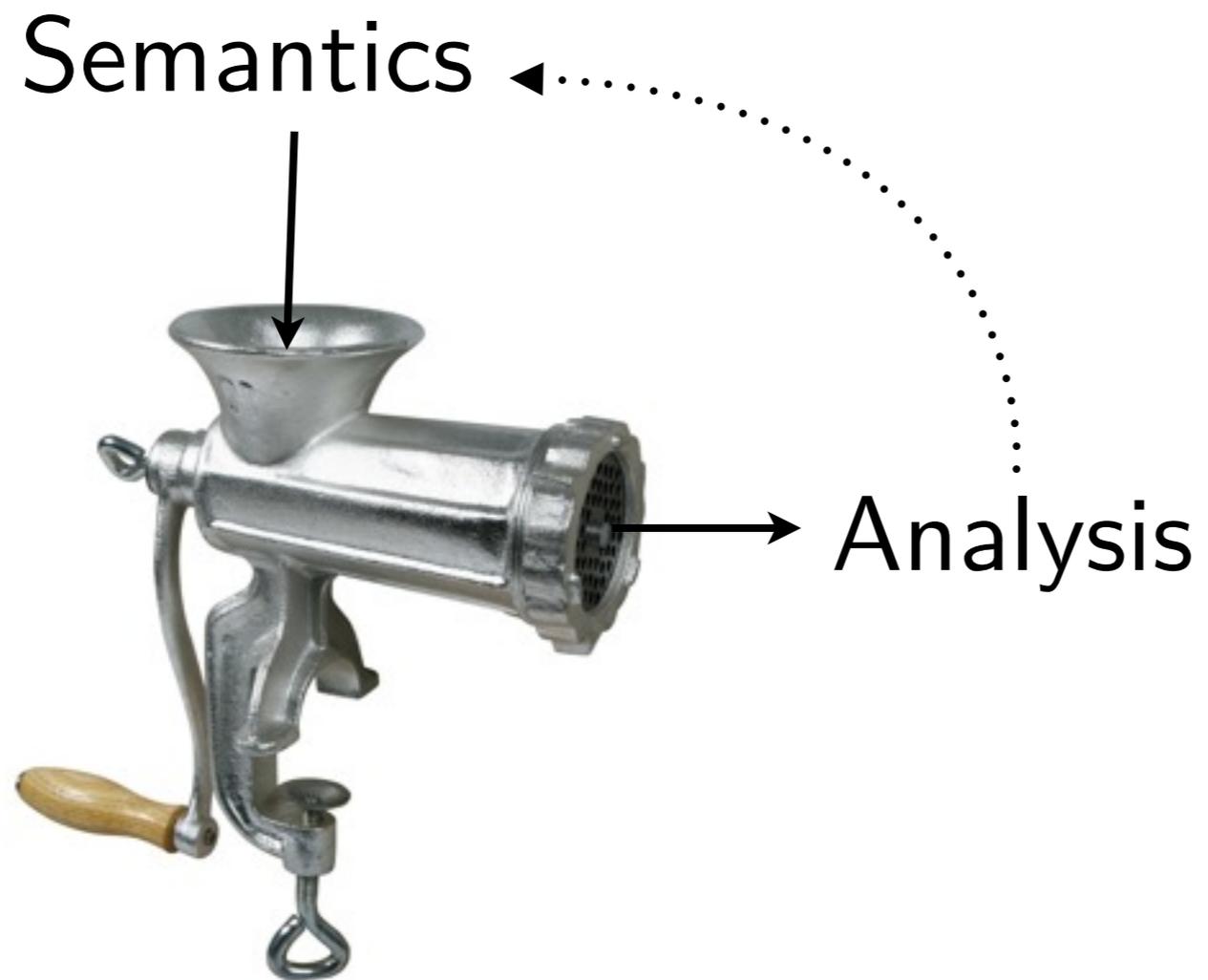
IM LOC



IM LOC



IK LOC



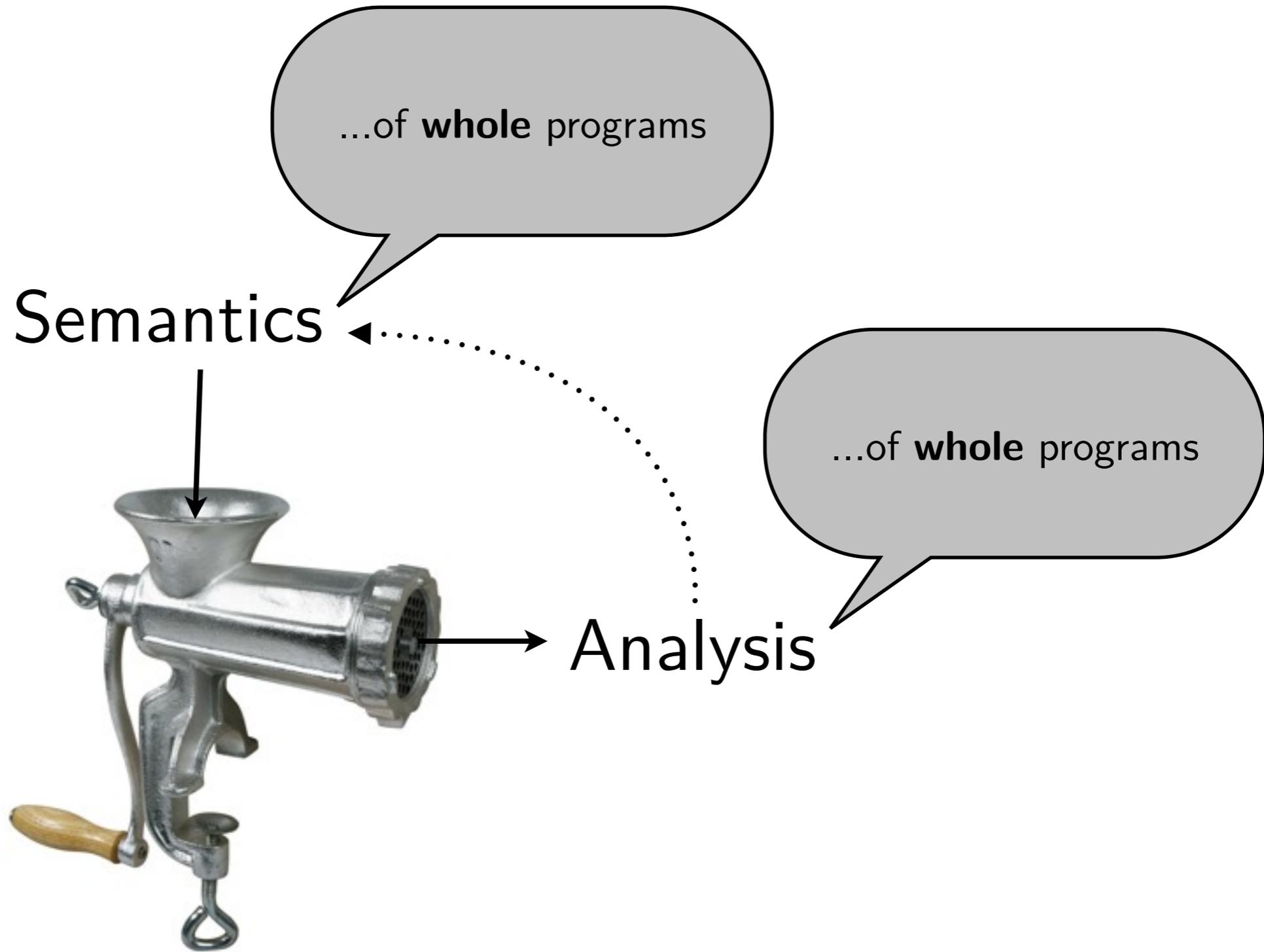
...of **whole** programs

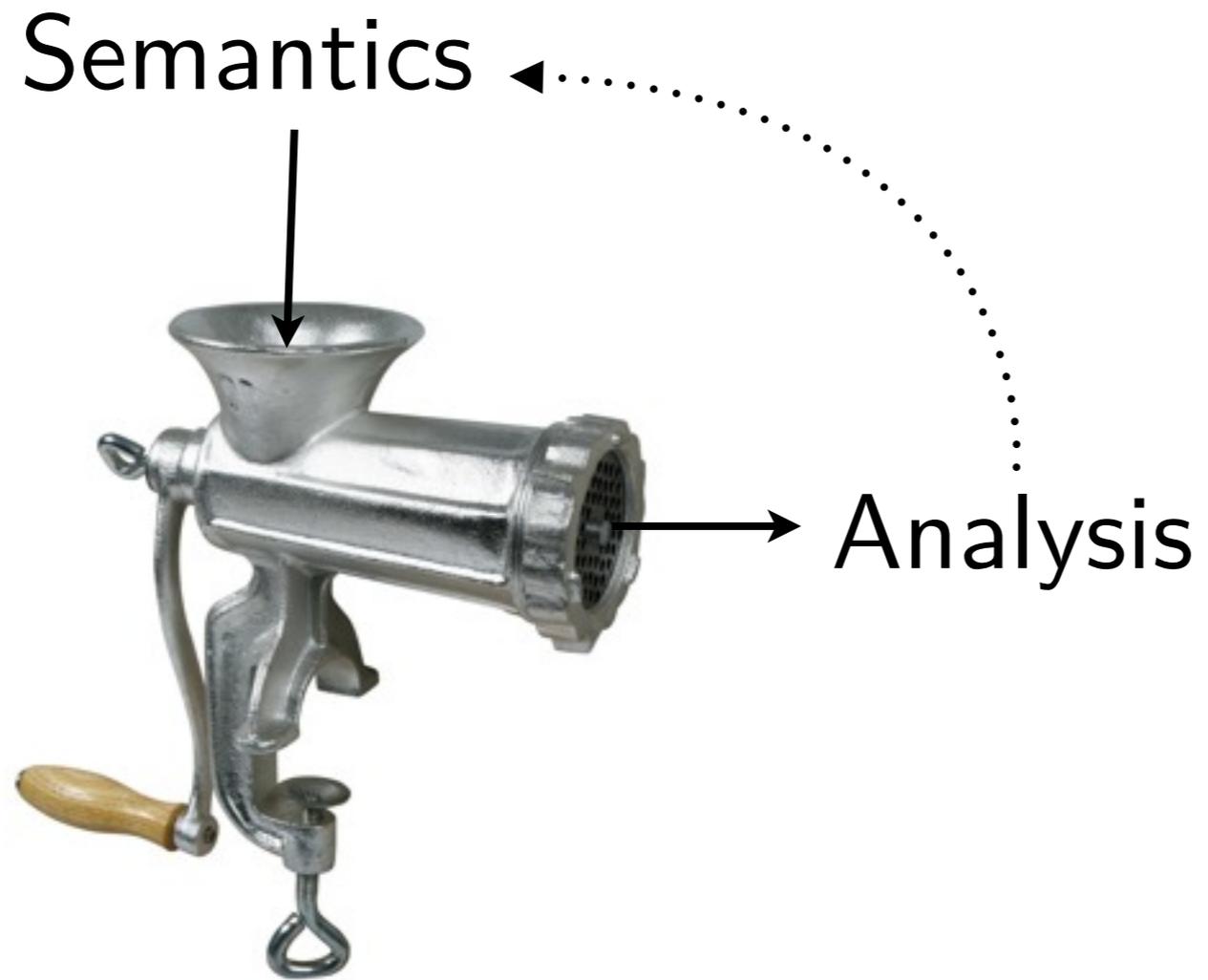
Semantics



Analysis





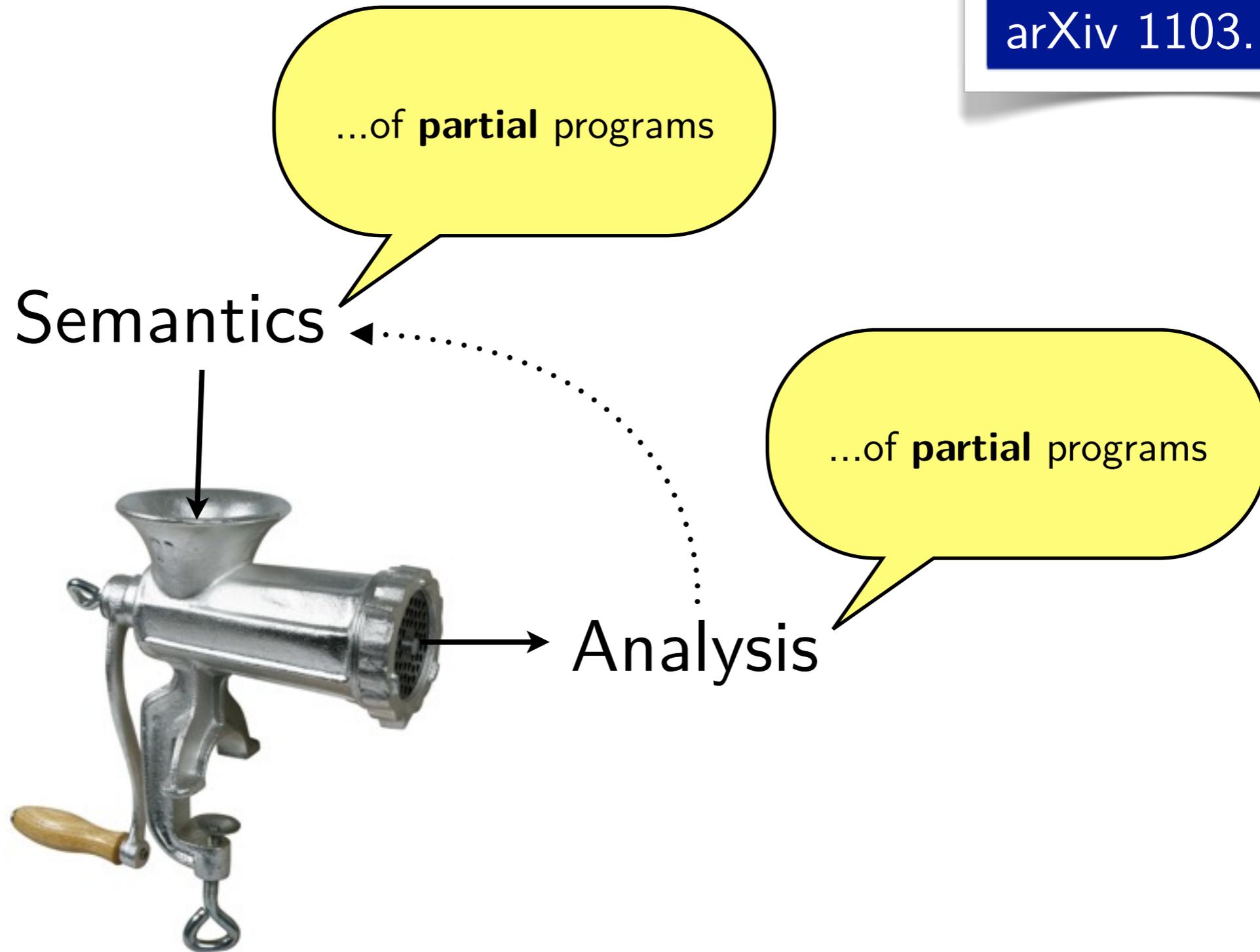


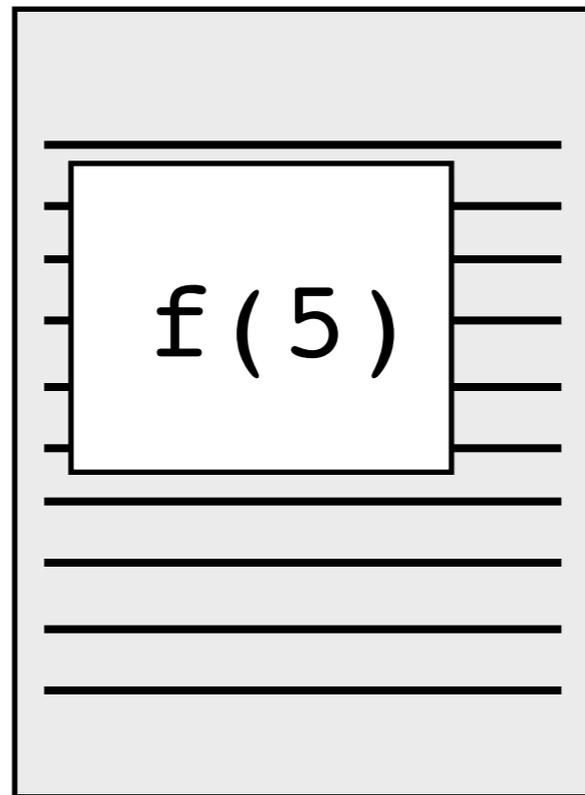
...of **partial** programs

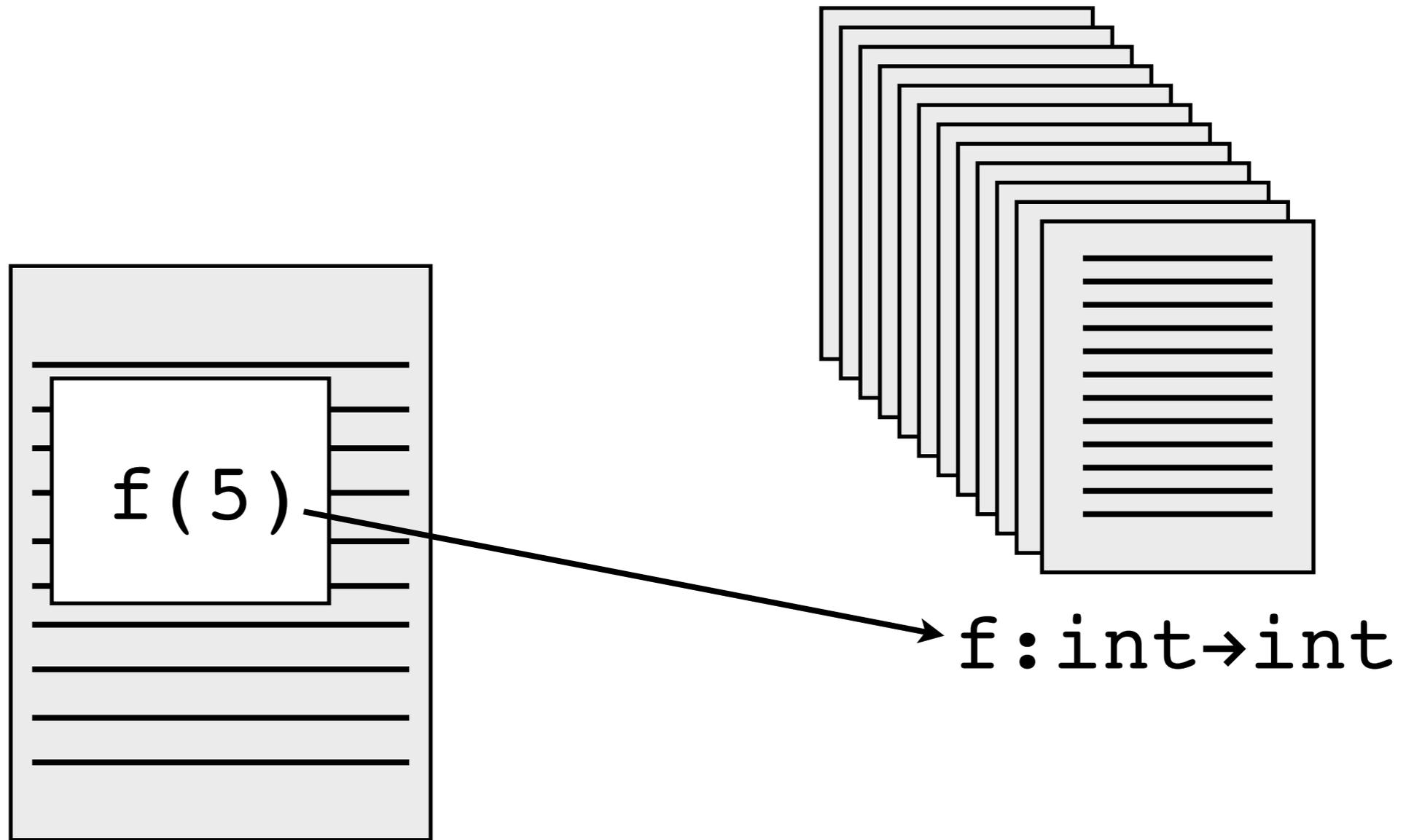
Semantics

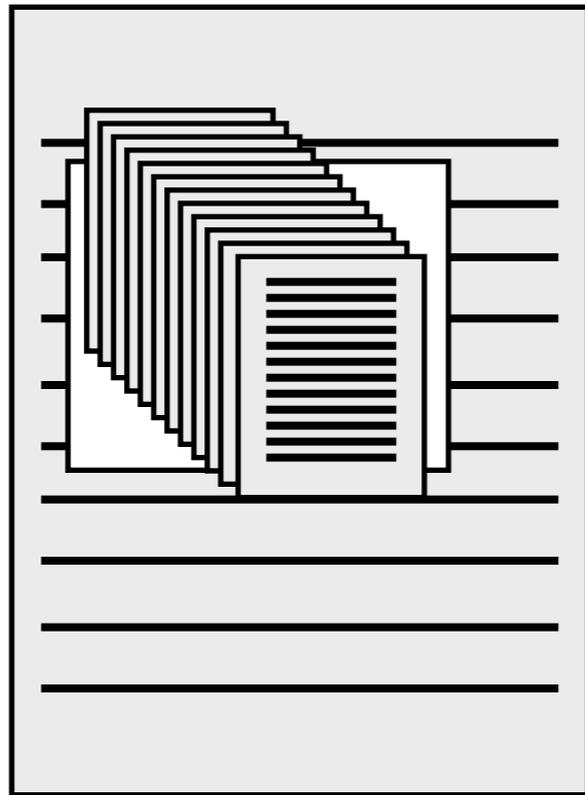


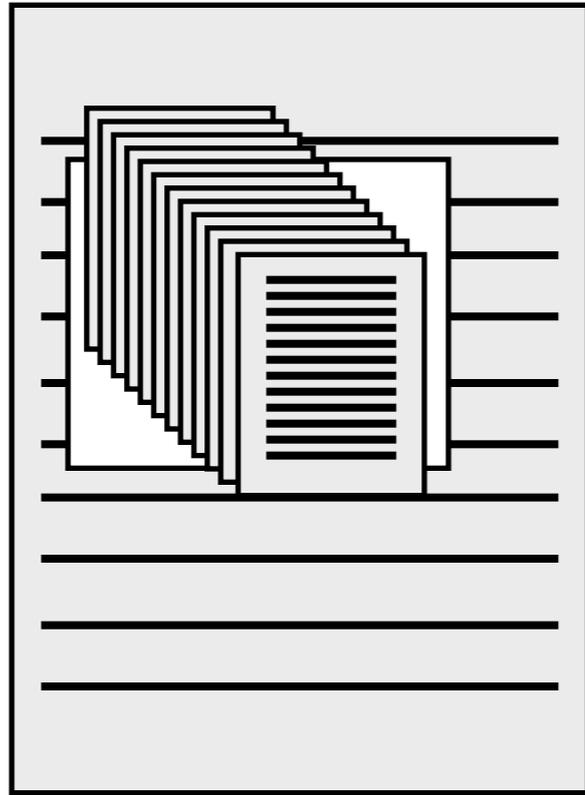
Analysis



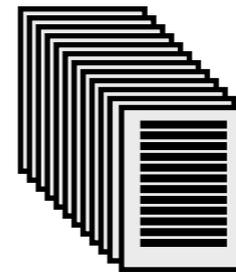
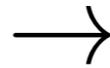


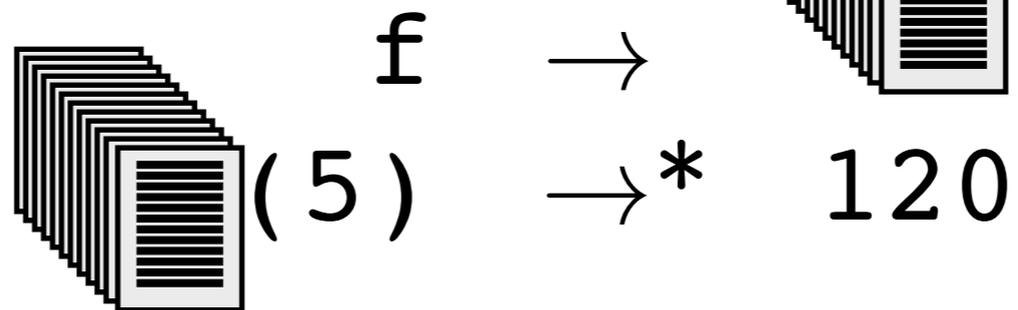
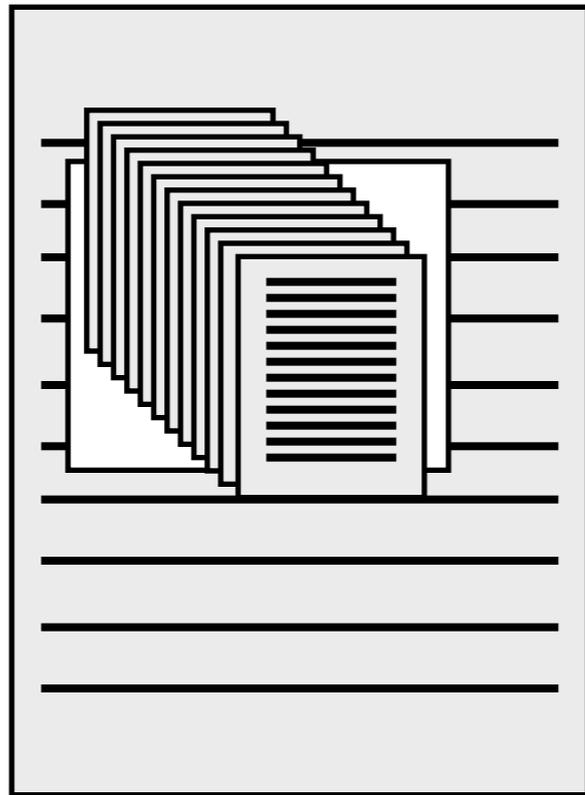


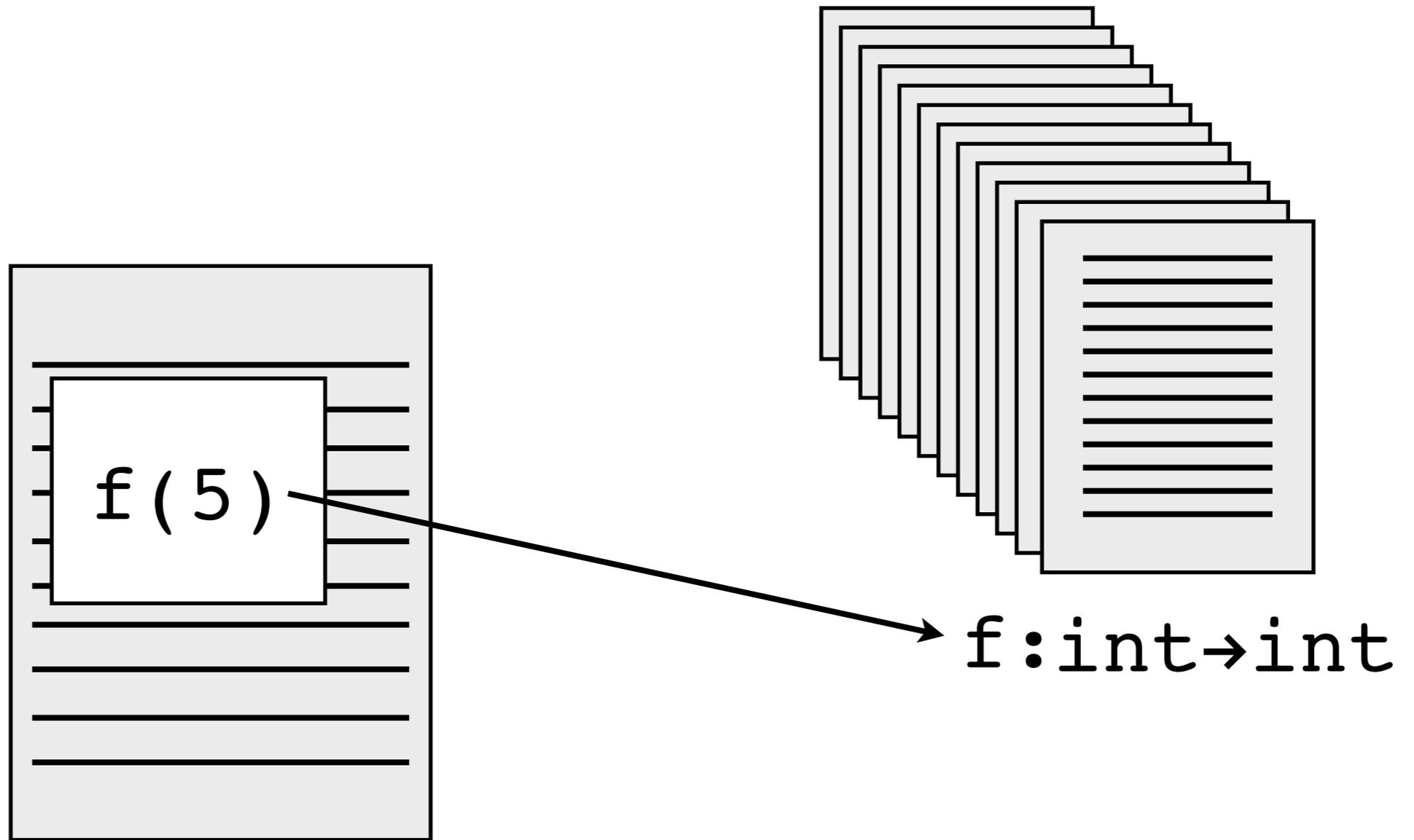


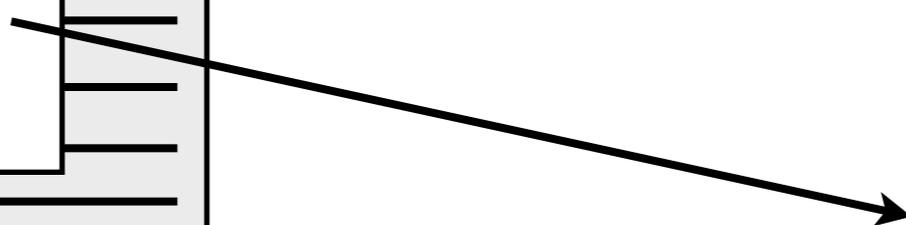
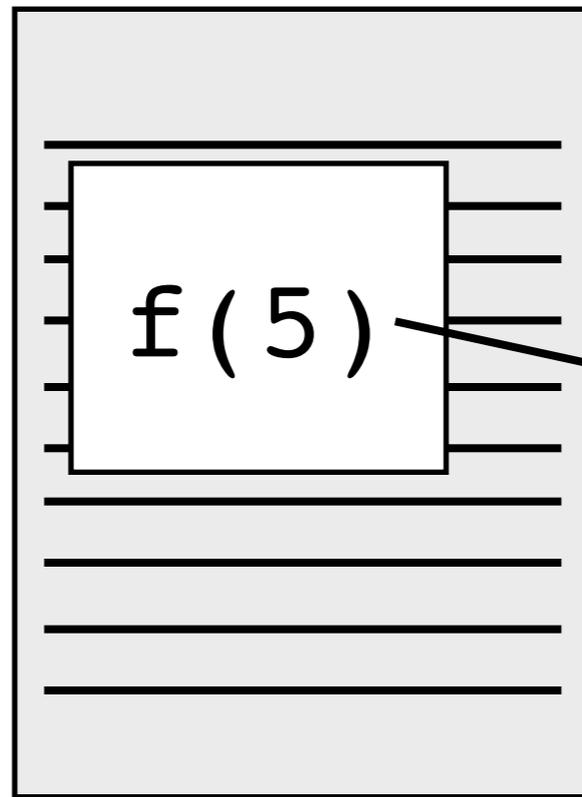


f

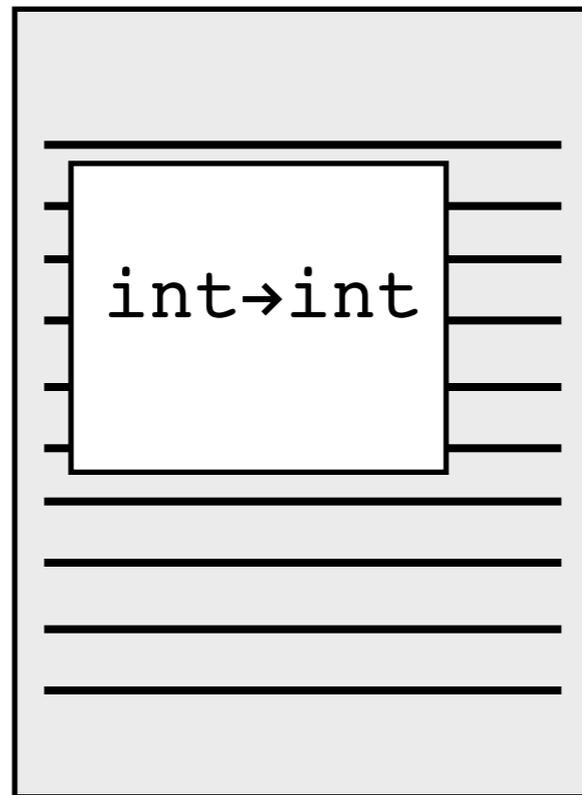


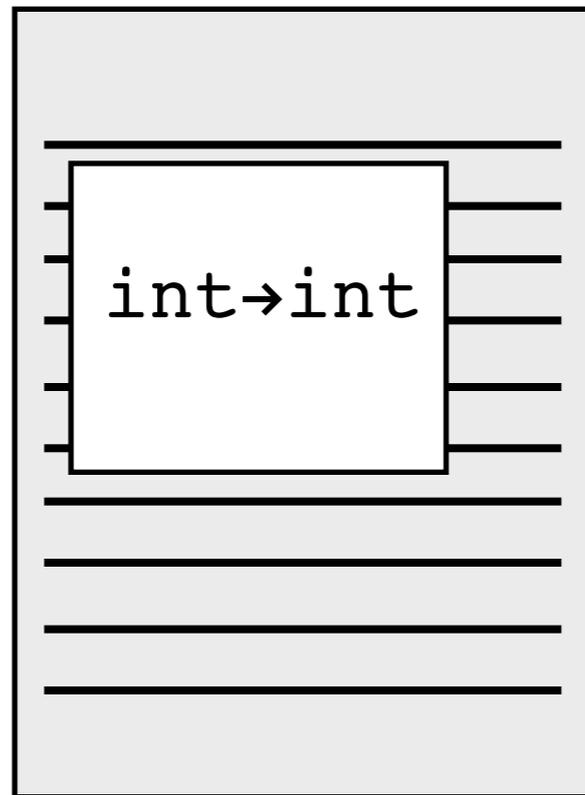




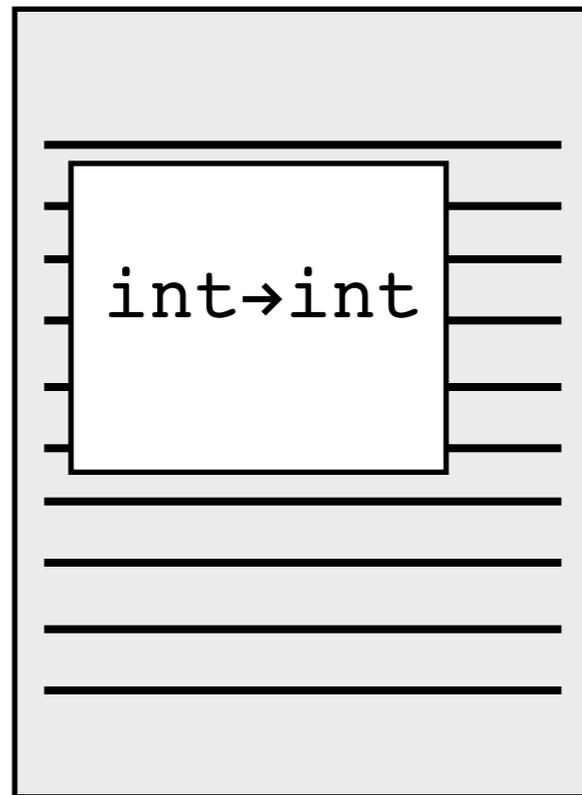


`f:int→int`





`f` → `(int→int)`



`f` \rightarrow `(int->int)`
`(int->int)(5)` \rightarrow `int`

Syntax:

$$e ::= v \mid x \mid (e+e)$$

$$v ::= n \mid \text{int}$$

Reduction:

$$(m+n) \rightarrow m + n$$

$$(\text{int}+v) \rightarrow \text{int}$$

$$(v+\text{int}) \rightarrow \text{int}$$

Eval. Contexts:

$$E ::= [] \mid (E+e) \mid (v+E)$$

Syntax: $e ::= \dots \mid (\text{if0 } e \ e \ e)$

Reduction: $(\text{if0 } 0 \ e_1 \ e_2) \rightarrow e_1$
 $(\text{if0 } n \ e_1 \ e_2) \rightarrow e_2$ where $n \neq 0$

Eval. Contexts:

$E ::= [] \mid (E+e) \mid (v+E) \mid (\text{if0 } E \ e \ e)$

Syntax: $e ::= \dots \mid (\text{if0 } e \ e \ e)$

Reduction:

$$\begin{aligned}(\text{if0 } 0 \ e_1 \ e_2) &\rightarrow e_1 \\(\text{if0 } n \ e_1 \ e_2) &\rightarrow e_2 \text{ where } n \neq 0 \\(\text{if0 int } e_1 \ e_2) &\rightarrow e_1 \\(\text{if0 int } e_1 \ e_2) &\rightarrow e_2\end{aligned}$$

Eval. Contexts:

$$E ::= [] \mid (E+e) \mid (v+E) \mid (\text{if0 } E \ e \ e)$$

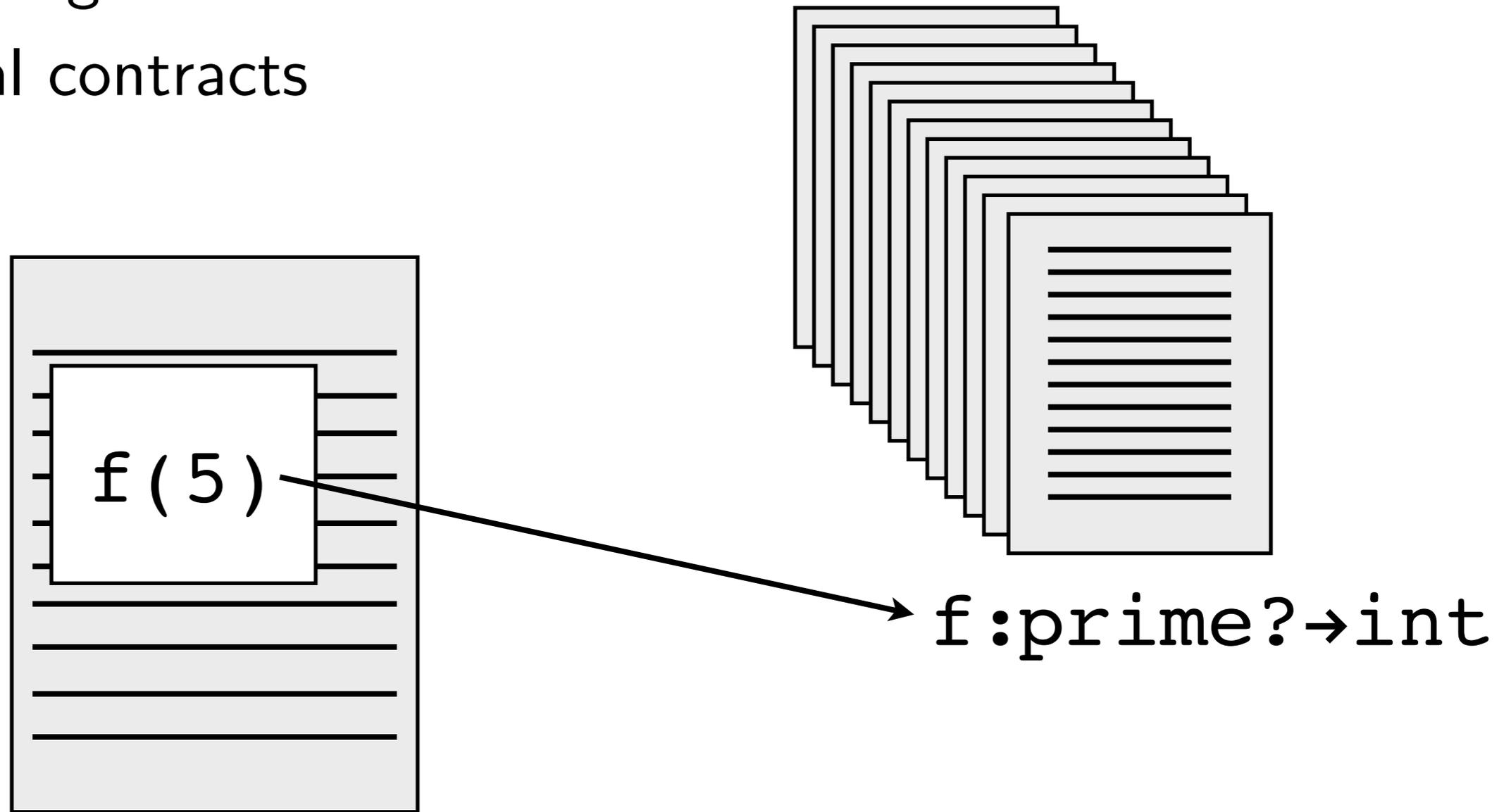
Key idea:

Non-deterministic state transition system
with an infinite state space.

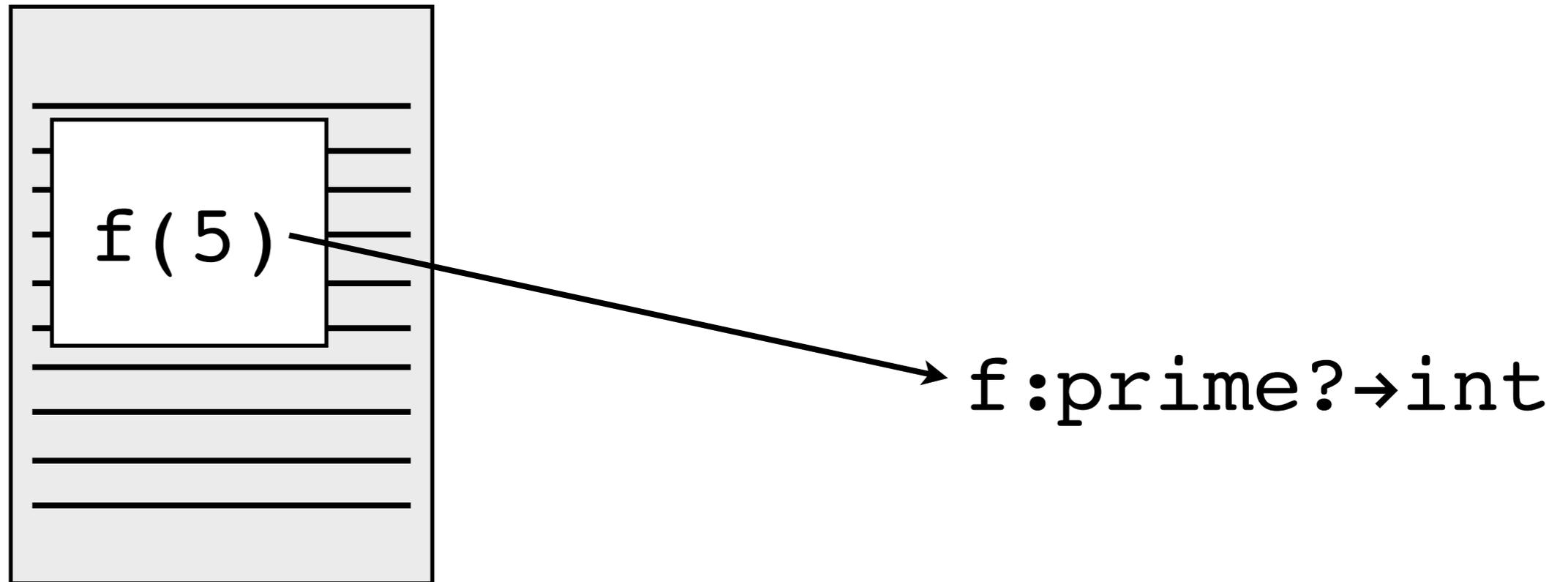


Non-deterministic state transition system
with a **finite** state space.

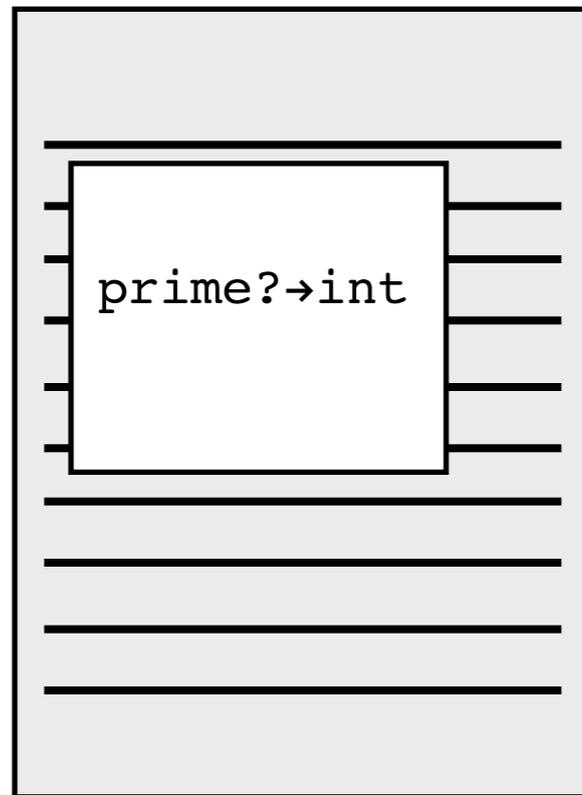
Scales to higher-order behavioral contracts



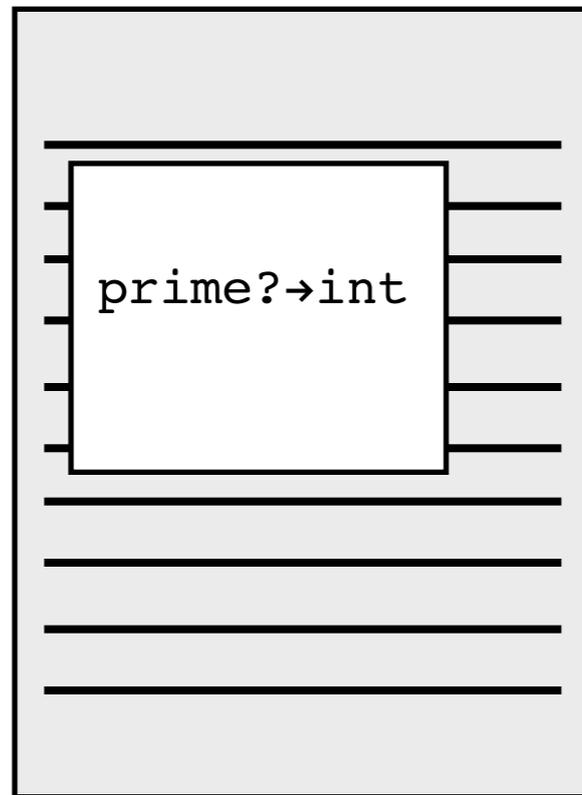
Scales to higher-order
behavioral contracts



Scales to higher-order behavioral contracts

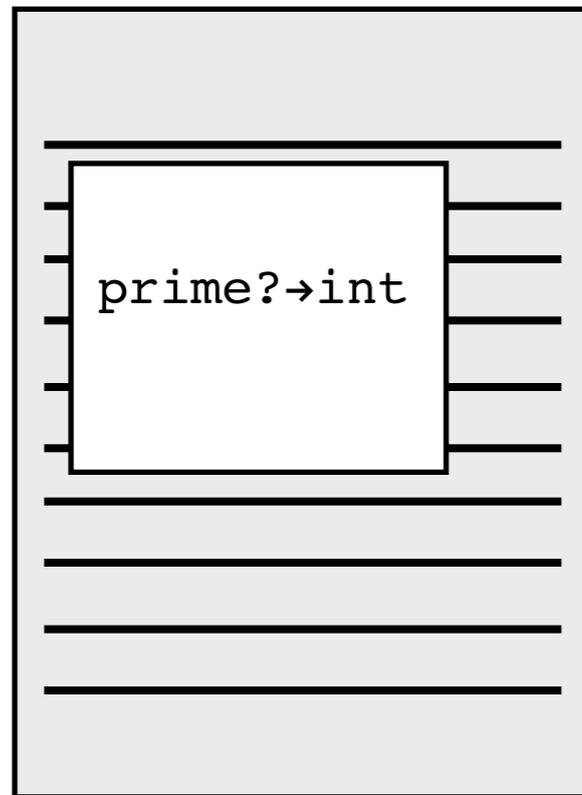


Scales to higher-order behavioral contracts



$f \rightarrow (\text{prime?} \rightarrow \text{int})$

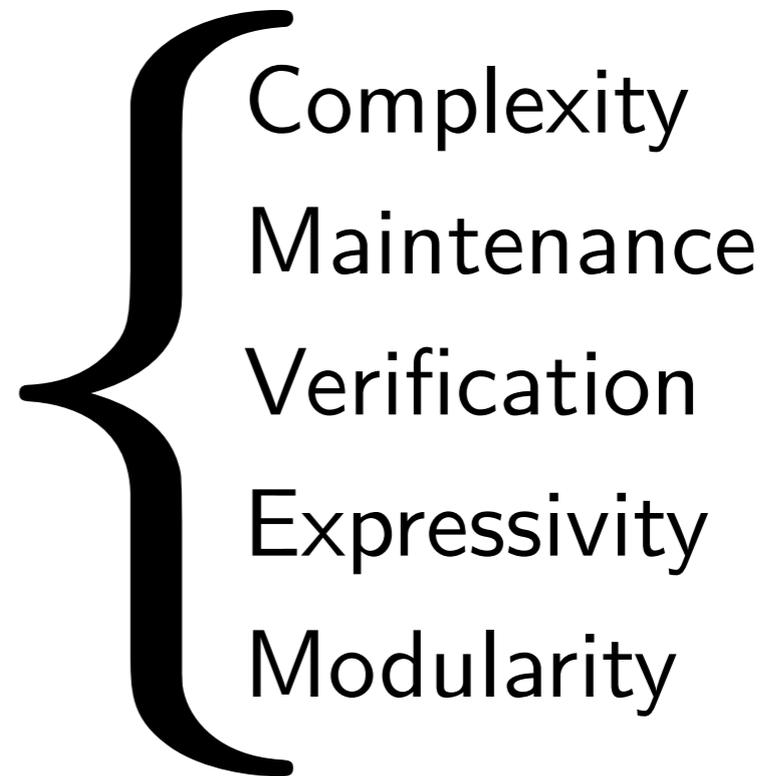
Scales to higher-order behavioral contracts



$f \rightarrow (\text{prime?} \rightarrow \text{int})$
 $(\text{prime?} \rightarrow \text{int}) (5) \rightarrow^* \text{int}$

A Way Forward

Scalability



Past

Complexity:

- ICFP'07: PTIME of context-insensitive CFA
- SAS'08: PTIME of sub-0CFAs
- ICFP'08: EXPTIME of context-sensitive
- HOSC'11: Subcubic bottleneck broken

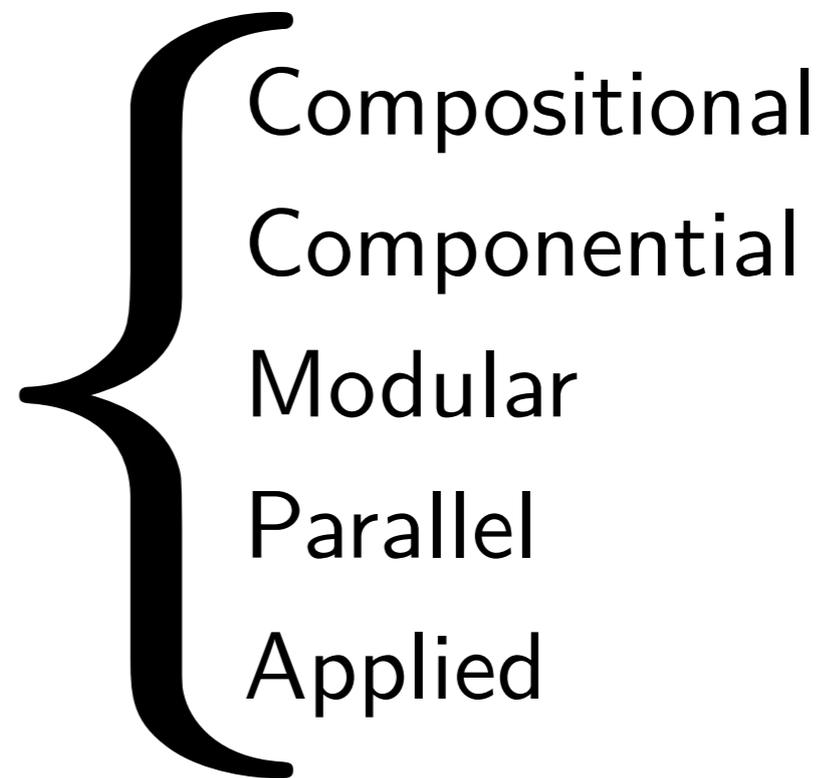
A Way Forward

Expressive, maintainable, verifiable, modular, performant:

- ICFP'10, CACM'11: Systematic approach analysis
- PLDI'10: Object-oriented, functional bridge
- SFP'10: Pushdown machine analysis
- 2011 (in prep): Modular reduction for modular analysis

Future

Scalability



Compositional

Composing analyses for mutual benefit

Componential analyses for separate analysis

Modular

Beyond types and contracts as specifications

Parallel

May happen in parallel for H.O. + threads

Futures and imperative H.O. languages

Context-sensitive analysis on a GPU

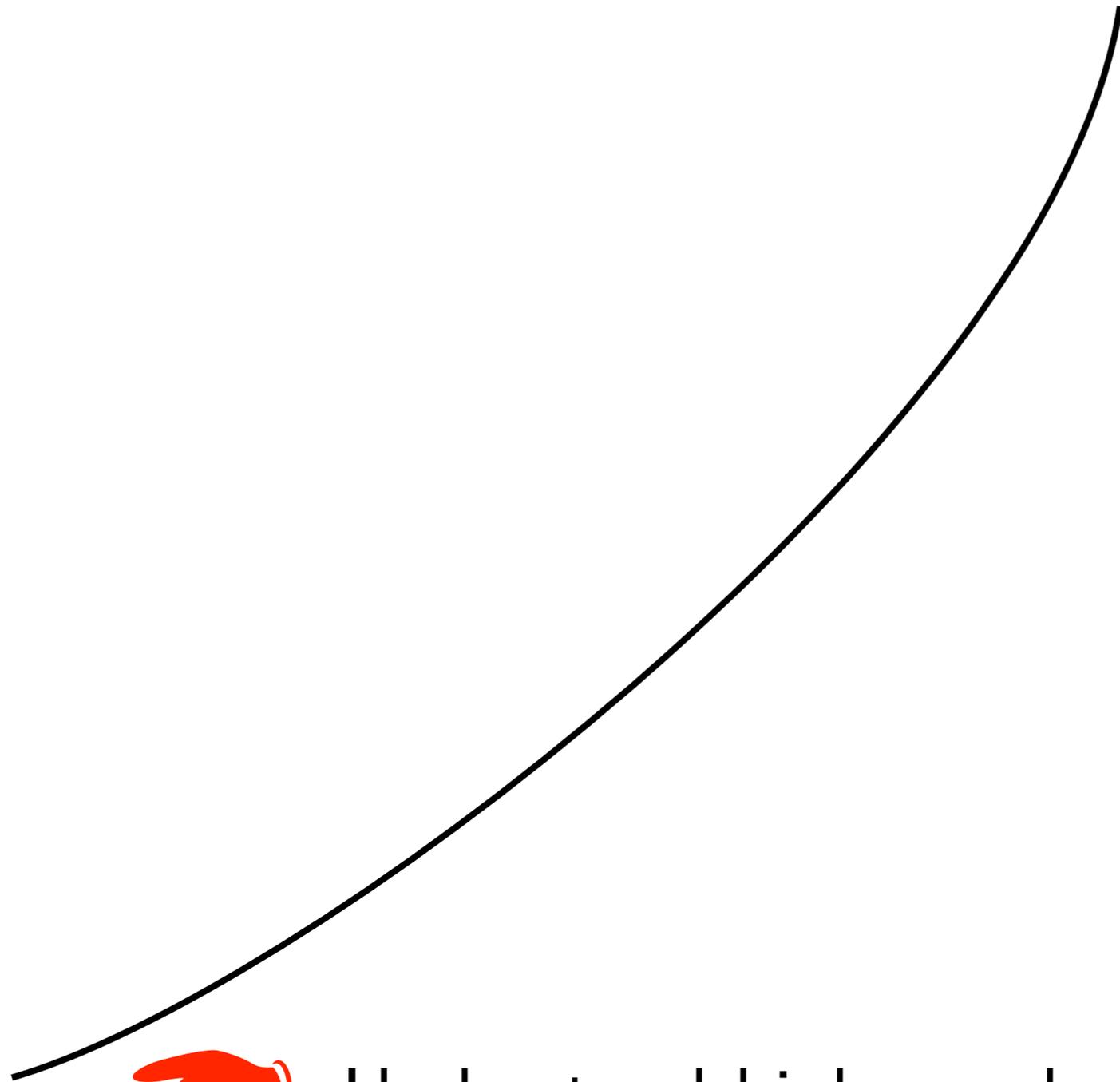
Applied

Scripts to programs via analysis

Analysis of the Racket Machine, X10

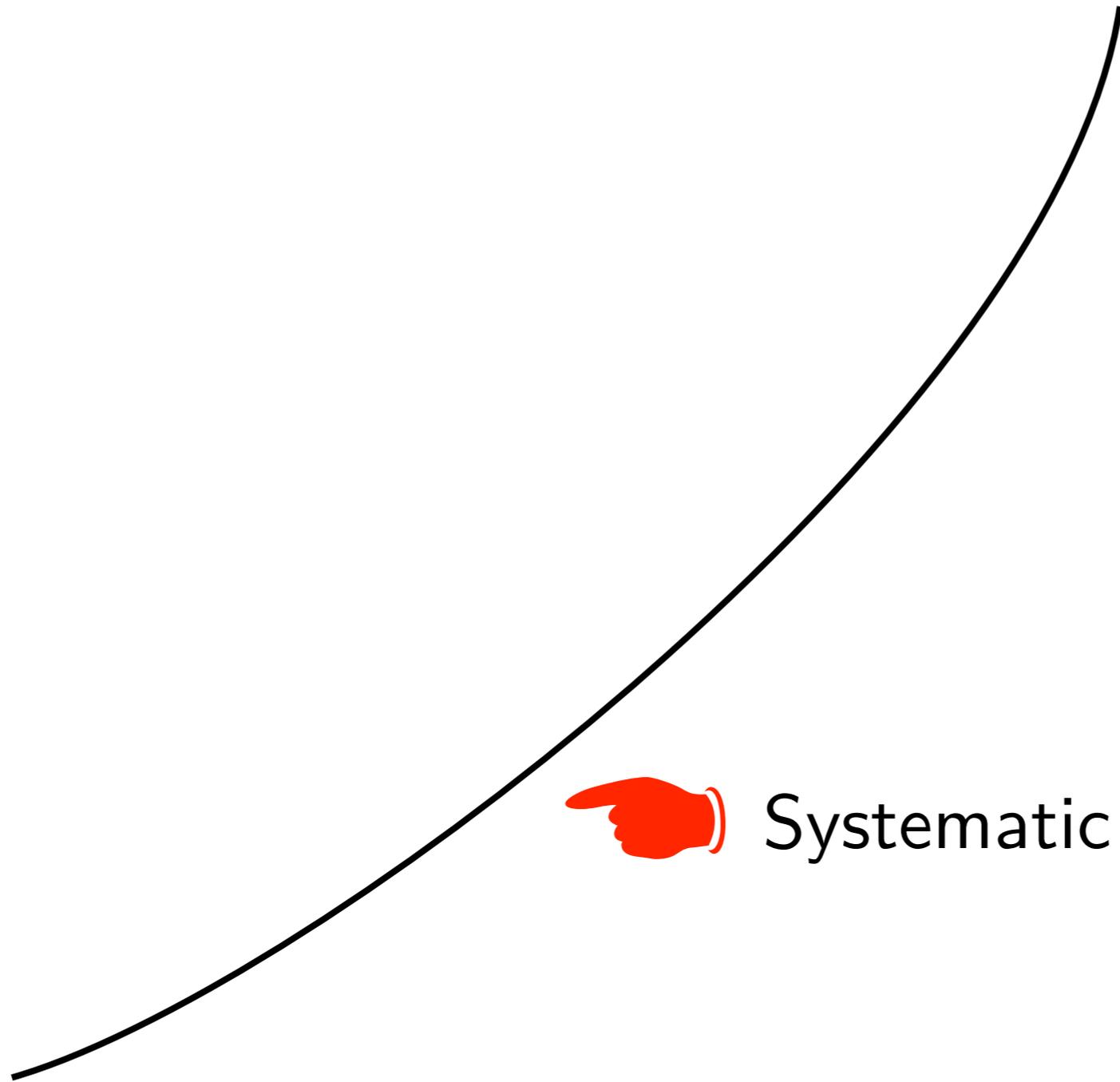
Contract verification of .5MLOC

vision



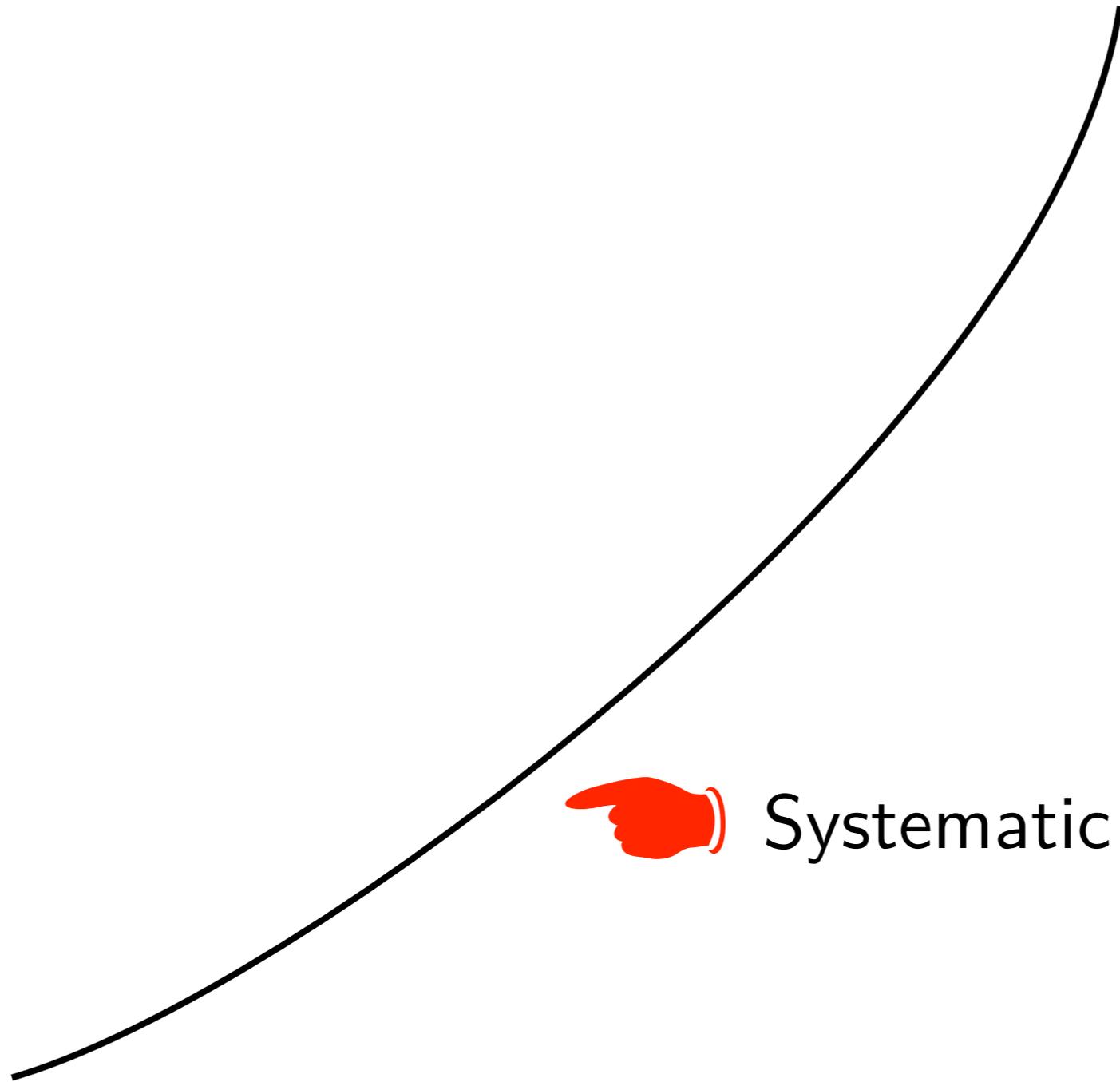
Understand higher-order program analysis

vision



Systematic approach that scales

vision



Systematic approach that scales

vision

Tools for reasoning about large-scale software written in expressive, modern languages.



vision

Tools for reasoning about large-scale software written in expressive, modern languages.



Thank you