CS4700/CS5700 Fundamentals of Computer Networks

Lecture 11: Intra-domain routing

Slides used with permissions from Edward W. Knightly, T. S. Eugene Ng, Ion Stoica, Hui Zhang

What is Routing?

- To ensure information is delivered to the correct destination at a reasonable level of performance
- Forwarding
 - Given a forwarding table, move information from input ports to output ports of a router
 - Local mechanical operations
- Routing
 - Acquires information in the forwarding tables
 - Requires knowledge of the network
 - Requires distributed coordination of routers

Viewing Routing as a Policy



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 Given multiple alternative paths, how to route information to destinations should be viewed as a policy decision



Viewing Routing as a Policy

- Given multiple alternative paths, how to route information to destinations should be viewed as a policy decision
- What are some possible policies?
 - Shortest path (RIP, OSPF)
 - Most load-balanced
 - QoS routing (satisfies app requirements)
 - etc



Internet Routing

- Internet topology roughly organized as a two level hierarchy
- First lower level autonomous systems (AS's)
 AS: region of network under a single administrative domain
- Each AS runs an intra-domain routing protocol
 - Distance Vector, e.g., Routing Information Protocol (RIP)
 - Link State, e.g., Open Shortest Path First (OSPF)
 - Possibly others
- Second level inter-connected AS's
- Between AS's runs inter-domain routing protocols, e.g., Border Gateway Routing (BGP)
 - De facto standard today, BGP-4



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- Different organizations may want different internal routing policies
- Allow organizations to hide their internal network configurations from outside
- Allow organizations to choose how to route across multiple organizations (BGP)
- Basically, easier to compute routes, more flexibility, more autonomy/independence

<u>Outline</u>

- Two intra-domain routing protocols
- Both try to achieve the "shortest path" routing policy
- Quite commonly used
- OSPF: Based on Link-State routing algorithm
- RIP: Based on Distance-Vector routing algorithm
- In Project 2, you will get to implement and play around with these algorithms!
 - Distributed coordination in action

Intra-domain Routing Protocols

- Based on unreliable datagram delivery
- Distance vector
 - Routing Information Protocol (RIP), based on Bellman-Ford algorithm
 - Each neighbor periodically exchange reachability information to its neighbors
 - Minimal communication overhead, but it takes long to converge, i.e., in proportion to the maximum path length
- Link state
 - Open Shortest Path First (OSPF), based on Dijkstra's algorithm
 - Each router periodically <u>floods immediate reachability</u> information to other routers
 - Fast convergence, but high communication and computation overhead

Routing on a Graph

- Goal: determine a "good" path through the network from source to destination
 - Good often means the shortest path
- Network modeled as a graph
 - Routers \rightarrow nodes
 - Link →edges
 - Edge cost: delay, congestion level,...



Link State Routing (OSPF): Flooding

- Each node knows its connectivity and cost to a direct neighbor
- Every node tells every other node this local connectivity/cost information
 - Via flooding
- In the end, every node learns the complete topology of the network
- E.g. A floods message

A connected to B cost 2 A connected to D cost 1 A connected to C cost 5



- Each node periodically generates Link State Packet (LSP) contains
 - ID of node created LSP
 - List of direct neighbors and costs
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- Receiving node flood LSP to all its neighbors except the neighbor where the LSP came from
- LSP is also generated when a link's state changes (failed or restored)









A Link State Routing Algorithm

Dijkstra's algorithm

- Net topology, link costs known to all nodes
 - Accomplished via "link state flooding"
 - All nodes have same info
- Compute least cost paths from one node ('source") to all other nodes
- Repeat for all sources

Notations

- C(i,j): link cost from node *i* to *j*; cost infinite if not direct neighbors
- D(v): current value of cost of path from source to node v
- p(v): predecessor node along path from source to v, that is next to v
- S: set of nodes whose least cost path definitively known

Dijsktra's Algorithm (A "Greedy" Algorithm)

1 Initialization:

2 S =
$$\{A\};$$

```
3 for all nodes v
```

```
4 if v adjacent to A
```

```
5 then D(v) = c(A,v);
```

```
6 else D(v) = \infty;
```

```
7
```

8 **Loop**

- 9 find w not in S such that D(w) is a minimum;
- 10 add w to S;
- 11 update D(v) for all v adjacent to w and not in S:

12
$$D(v) = min(D(v), D(w) + c(w,v));$$

// new cost to v is either old cost to v or known

- If shortest path cost to wplus cost from wto v
- 13 until all nodes in S;







St	ер	start S	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
	0	A	2,A	5,A	1,A	∞	∞
-	1	AD		4,D		2,D	∞
_	2						
	3						
_	4						
_	5						



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12 D(v) = min(D(v), D(w) + c(w,v));
13 until all nodes in S;

S	tep	start S	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
	0	А	2,A	5,A	1,A	∞	∞
	1	AD		4,D		2,D	∞
-	2	ADE		3,E			4,E
	3						
	4						
	5						



•••	
▶ 8	Loop
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	to w and not in S:
12	D(v) = min(D(v), D(w) + c(w,v));
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Step	start S	D(B),p(B)	D(C),p(C)	D(D),p(D)	D(E),p(E)	D(F),p(F)
0	А	2,A	5,A	1,A	∞	∞
1	AD		4,D		2,D	∞
2	ADE		3,E			4,E
→ 3	ADEB					
4						
5						



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	0	А	2,A	5,A	1,A	∞	∞
	1	AD		4,D		2,D	∞
	2	ADE		3,E			4,E
	3	ADEB					
-	4	ADEBC					
	-5						



→ 8	loon
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Distance Vector Routing (RIP)

- What is a distance vector?
 - Current best known cost to get to a destination
- Idea: Exchange distance vectors among neighbors to learn about lowest cost paths



Dest.	Cos
А	7
В	1
D	2
E	5
F	1
G	3

Note no vector entry for C itself

At the beginning, distance vector only has information about directly attached neighbors, all other dests have cost ∞

Eventually the vector is filled

Distance Vector Routing Algorithm

- Iterative: continues until no nodes exchange info
- Asynchronous: nodes need not exchange info/iterate in lock steps
- Distributed: each node communicates only with directlyattached neighbors
- Each router maintains
 - Row for each possible destination
 - Column for each directly-attached neighbor to node
 - Entry in row Y and column Z of node X → best known distance from X to Y, via Z as next hop
- Note: for simplicity in this lecture examples we show only the shortest distances to each destination

Distance Vector Routing

- Each local iteration caused by:
 - Local link cost change
 - Message from neighbor: its least cost path change from neighbor to destination
- Each node notifies neighbors only when its least cost path to any destination changes
 - Neighbors then notify their neighbors if necessary

Each node:

wait for (change in local link cost or msg from neighbor) *recompute* distance table if least cost path to any dest has changed, *notify* neighbors

Distance Vector Algorithm (cont'd)

1 Initialization:

- 2 for all nodes V do
- 3 if V adjacent to A

4
$$D(A, V, V) = c(A, V);$$
 /* Distance from A to V via neighbor V */

5 else

$$\mathsf{D}(A, V, *) = \infty;$$

loop:

9

- 8 wait (until A sees a link cost change to neighbor V
 - or until A receives update from neighbor V)
- 10 if (c(A, V) changes by d)
- 11 for all destinations Y through V do

2
$$D(A, Y, V) = D(A, Y, V) + d$$

13 **else if** (update D(V, Y) received from V) /* shortest path from V to some Y has changed */

14
$$D(A, Y, V) = c(A, V) + D(V, Y);$$

- 15 if (there is a new minimum for destination Y)
- 16 send D(A, Y) to all neighbors /* D(A, Y) denotes the min D(A, Y, *) */

17 forever

Example: Distance Vector Algorithm



Node	Α
------	---

Node C

Dest.	Cost	NextHop
В	2	В
С	7	С
D	8	-

Node B

Dest.	Cost	NextHo
А	2	А
С	1	С
D	3	D

1 Initialization:

- 2 for all nodes V do
- 3 **if** *V* adjacent to *A*

4
$$D(A, V, V) = c(A, V);$$

. . .

6
$$D(A, V, *) = \infty;$$

Dest.	Cost	NextHo
А	7	А
В	1	В
D	1	D

Node D

Dest.	Cost	NextHo
А	∞	-
В	3	В
С	1	С

Example: 1^{st} Iteration (C \rightarrow A)





loop:

7

else if (update D(V, Y) received from V) 13

14
$$D(A,Y,V) = c(A,V) + D(V, Y)$$

- if (there is a new min. for destination Y) 15
- send D(A, Y) to all neighbors 16

17 forever

De	st.	Cost	NextHo
A		7	A
В		1	В
D		1	D

Node	D
------	---

Dest.	Cost	NextHo
А	8	-
В	3	В
С	1	С

Example: End of 1st Iteration



Example: End of 2nd Iteration





Distance Vector: Link Cost Changes

7 **loop:**

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- 9 or until A receives update from neighbor V)
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- 13 else if (update D(V, Y) received from V)
- 14 D(A,Y,V) = c(A,V) + D(V, Y);
- 15 **if** (there is a new minimum for destination Y)
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17 forever





Distance Vector: Count to Infinity Problem

7 **loop:**

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- 9 or until A receives update from neighbor V)
- 10 if (c(A, V) changes by d)
- 11 for all destinations Y through V do

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$$D(A, Y, V) = D(A, Y, V) + d;$$

- 13 else if (update D(V, Y) received from V)
- 14 D(A, Y, V) = c(A, V) + D(V, Y);
- 15 **if** (there is a new minimum for destination Y)
- 16 **send** D(*A*, *Y*) to all neighbors

17 forever





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Distance Vector: Poisoned Reverse

- If C routes through B to get to A:
 - C tells B its (C's) distance to A is infinite (so B won't route to A via C)
 - Will this completely solve count to infinity problem?





Link State vs. Distance Vector

Per node message complexity

- LS: O(n*d) messages; n number of nodes; d – degree of node
- DV: O(d) messages; where d is node's degree

Complexity

- LS: O(n²) with O(n*d) messages (with naïve priority queue)
- DV: convergence time varies
 may be routing loops
 - count-to-infinity problem

Robustness: what happens if router malfunctions?

- LS:
 - node can advertise incorrect link cost
 - each node computes only its own table
- DV:
 - node can advertise incorrect path cost
 - each node's table used by others; error propagate through network