CS 3700 Networks and Distributed Systems

Lecture 14: Time + Logical Clocks

(Based off slides by Rik Sarkar at University of Edinburgh)

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Global time

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□ In practice, we act like there is a global notion of time

e.g., What time is it?

But, time is relative

- Einstein showed speed of light constant for all observers
- Leads to Relativity of Simultaneity

Basically, impossible to tell if two events are simultaneous

If events are separated by space

But, if events are causally connected, can preserve order

Global time in systems

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For human-scale systems, these differences don't matter

Rarely are we going near the speed of light

But these do come to play in computing systems

- Must consider relativity of time when designing systems
- **E.g., high-frequency trading systems**
 - Need to be able to declare who bought first
- Or, need to be able to merge multiple writes to single object



- Defining and measuring time
- Correcting clocks
- Logical clocks
- Vector clocks

Historic clocks

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 - Our units of time date from the Sumerians in 2000BC
 - Sexagesimal system based on hand counting
 - Humans used a variety of devices to measure time
 - Sundials
 - Astronomical clocks
 - Candle clocks
 - Hourglasses
 - Mechanical clocks developed in medieval ages
 - Typically maintained by monks (church bell tower)

Electronic clocks



- □ First developed in 1920s
 - Uses carefully shaped quartz crystal
 - Pass current, counts oscillations
- Most oscillate at 32,768/sec
 - Easy to count in hardware
 - Small enough to fit (~4mm)
- **Typical quartz clock quite accurate**
 - Within 15 sec/30 days (6e-6)
 - Can achieve 1e-7 accuracy in controlled lab conditions
 - Not good enough for today's applications



Atomic clocks

- Based on atomic physics
 - Cool atoms to near absolute zero
 - Bombard them with microwaves
 - Count transitions between energy levels



- Most accurate timekeeping devices today
 - Accurate to within 10⁻⁹ seconds per day
 - E.g., loses 1 second in 30 million years
- □ SI second now defined in terms of atomic oscillations
 - 9,192,631,770 transitions of cesium-133 atom

TAI

Atomic clocks used to define a number of time standards

TAI: International Atomic Time

- Avg. of 200 atomic clocks, corrected for time dilation
- Essentially, a count of the number of seconds passed

Measuring real-world time

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 - Originally, each town defined noon locally
 - Point at which sun highest in the sky
 - With growth of railroads, this became impractical
 - Continually have to re-set watches
 - Hard to set rail schedules
 - Notion of "time zones" developed
 - Regions where wall-clock time is the same
 - Now, need to synchronize clocks

GMT, UT1, and UTC

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- **GMT:** Greenwich Mean Time
 - Originally, mean solar time at o° longitude
 - This isn't really "noon" due to Earth's axial tilt
- **UT1:** Universal Time
 - Modernized version of GMT
 - Based on rotation of Earth, ~86,400 seconds/day
- **UTC:** Universal Coordinated Time
 - UT1 + leap seconds
 - Minutes can have 59-61 seconds
 - Since 1972, 25 leap seconds have been introduced

11 Outline

- Defining and measuring time
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- Vector clocks

Correctness

What does it mean for a clock to be correct?

- Relative to an "ideal" clock
- Clock skew is magnitude, clock drift is difference in rates

Say clock is correct within p if

 $(1{\text{-}}p)(t'{\text{-}}t) \le H(t') - H(t) \le (1{\text{+}}p)(t'{\text{-}}t)$

□ (t'-t) True length of interval

- \Box H(t') H(t) Measured length of interval
- \Box (1-*p*)(*t*'-*t*) Smallest acceptable measurement
- (1+p)(t'-t) Largest acceptable measurement

□ Monotonic property: $t < t' \Rightarrow H(t) < H(t')$

Monotonicity

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 - □ If a clock is running "slow" relative to real time
 - Can simply re-set the clock to real time
 - Doesn't break monotonicity
 - □ But, if a clock is running "fast", what to do?
 - Re-setting the clock back breaks monotonicity
 - Imagine programming with the same time occurring twice
 - Instead, "slow down" clock
 - Maintains monotonicity

Simple synchronization

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- □ If we know message delay *T*
 - □ A sends current time *t* to *B*, who sets time to *t*+*T*
- Typically, don't know exact delay
 - May know range on delay min < T < max</p>
 - □ B can then set time to t+(max-min)/2
 - Clocks are then within (max-min)/2 of each other
- Can general this protocol to many clocks
 Overall accuracy still ~(max-min)

But, don't generally have any bound on delay

Cristian's method



- No assumption of delay bound
- □ A sends request to B of current time
 - **B** responds with local time *T*
 - A measures RTT
 - A sets local time to T+RTT/2
- Assumes that delay is symmetric
 - □ Why?
- □ A can do this many times in a row, use overall min *RTT*
- Rough accuracy is RTT/2 min, with overall min min





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Synchronizing in the real world

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- Network Time Protocol (NTP) developed in 80s with goals
 - Keep machines synchronized to UTC
 - Deal with lengthly losses of connectivity
 - Enable clients to synchronized frequently (scalable)
 - Avoid security attacks

- NTP deployed widely today
 - Uses 64-bit value, epoch is 1/1/1900 (rollover in 2036)
 - LANs: Precision to 1ms
 - Internet: Precision to 10s of ms

NTP Hierarchy

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Based on hierarchy of accuracy, called *strata*

- **Stratum o:** High-precision atomic clocks
- **Stratum 1:** Hosts directly connected to atomic clocks
- **Stratum 2**: Hosts that run NTP with stratum 1 hosts
- **Stratum 3:** Hosts that run NTP with stratum 2 hosts

Stratum x hosts often synch with other stratum x hosts
 Provides redundancy

NTP strata

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NTP in practice

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- Run on UDP port 123
- Most Internet hosts support NTP
- Accuracy on general Intenet is ~10ms
 - Up to 1ms on local networks, ideal conditions
- Many networks run local NTP servers
 - E.g., time.ccs.neu.edu
- NTP has recently been a vector for DDoS attacks
 - Best practice is for servers to filter requests outside local network

21 Outline

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Logical ordering

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 - **Goal:** Be able to provide some synchronization of events
 - Recall, never able to do perfectly synchronize clocks
 - How to deal with this fact in the real world?
 - Create a new abstraction: Logical ordering
 - Remove real-world time from equation
 - Base ordering on causality
 - **Logical clocks are based on the simple principles:**
 - I. Events observed by a single process are ordered
 - 2. Any message must be sent before it is received

Example of logical ordering





- Each host can order all events it observes
 - B observes m1 received before m3 sent
- Can "interleave" timelines via messages
- Cannot make statement about all pairs of events
 E.g., m5 send and m1 receive can't be ordered

Happened-before relation





 \Box Formalize logical clocks via happened-before (\rightarrow) relation

- □ If e_1 precedes e_2 on single host, then $e_1 \rightarrow e_2$
- □ If e_1 and e_2 and send/receive of message, then $e_1 \rightarrow e_2$
- □ $e_1 \rightarrow e_2$ and $e_2 \rightarrow e_3$, then $e_1 \rightarrow e_3$

If neither e1 → e2 nor e2 → e1, then e1 and e2 are concurrent
 Say e1 || e2

Limits of happened-before

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Cannot capture external events

- Only considers message-passing; phone call?
- Two events may be concurrent in our system

□ If e1 || e2, it does not imply causality

- Potential causality is implied
- E.g., process may receive message before unrelated event

But, still pretty useful

How to implement logical ordering in a real system?

Logical clocks

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 - Lamport created way to create logical clock from ordering
 - Define logical clock to be a monotonically increasing value
 - Numeric abstraction
 - Meaningless value by itself
 - **Each host** *i* maintains internal logical clock *Lⁱ*
 - L_i is incremented after each event
 - L_i is piggy-backed on each message sent
 - **Upon receipt of message with** *t*
 - Set value to $max(L_i, t) + 1$

Example of logical clocks

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For each event e, timestamp is longest chain of events that happened-before e

Certain events cause "skipping" of clock
 A's clock skips from 1 to 5

No reverse implication

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□ We can observe that $e_1 \rightarrow e_2 \Rightarrow L(e_1) < L(e_2)$

- If e1 happened before e2, then logical clocks ordered
- But the reverse is not true
 - $\Box L(e_1) < L(e_2) \Rightarrow e_1 \rightarrow e_2$
- In example, L(e) < L(b), but e +> b
 In fact, e concurrent with all but f



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Vector clocks

- Developed to overcome lack of reverse implication
 - □ Want $L(e_1) < L(e_2) \Rightarrow e_1 \rightarrow e_2$

Processes keep local vector clock V_i

- Array of logical clocks of length N (# processes)
- Initially [0,0, ... 0]
- Similar update procedure to logical clocks
 - V_i[i] is incremented after each event
 - V_i is piggy-backed on each message sent
 - Upon receipt of message with vector clock V_k
 - $V_i[x] = max(V_i[x], V_k[x]) + 1$, for all x

Example of vector clocks



□ Invariant:

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V_i[j] is the number of events in process P_j that happened before the current state of process P_i

Comparing vector timestamps

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Given two vector timestamps V_i and V_j

$$\Box V_i = V_j \text{ iff } V_i[x] = V_j[x] \text{ for all } x$$

- \Box $V_i < V_j$ iff $V_i[x] < V_j[x]$ for all x
- □ For example, (2,4,1) < (3,5,9)

But, other pairs incomparable
E.g., (2,4,1) and (3,1,7)

□ As with logical clocks $e_1 \rightarrow e_2 \Rightarrow L(e_1) < L(e_2)$

□ And also $L(e_1) < L(e_2) \Rightarrow e_1 \rightarrow e_2$

Vector vs. logical clocks

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 - Vector clocks augment logical clocks
 - Use generalization of same mechanism
 - Cost: Larger messages, more complexity
 - Often don't know total number of processes
 - But, with both can say when certain events happened before each other

Also, can extent vector clocks to matrix clocks
 Your logical clock + others'