Lecture 4: Process communication

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Interprocess Communication

- Processes within a system may be **independent** or **cooperating**
- Cooperating process can affect or be affected by other processes, including sharing data
- Reasons for cooperating processes (instead of single process):
  - Information sharing
  - Computation speedup
  - Modularity
  - Convenience
- Cooperating processes need **interprocess communication (IPC)**
- Two models of IPC
  - Shared memory
  - Message passing
Communications Models

(a)

(b)
Producer-Consumer Problem

- Paradigm for cooperating processes, *producer* process produces information (repeatedly) that is consumed by a *consumer* process
  - *unbounded-buffer* places no practical limit on the size of the buffer
  - *bounded-buffer* assumes that there is a fixed buffer size

- How can we implement a producer and consumer using shared memory?
Bounded-Buffer — Shared-Memory Solution

• Shared data

```c
#define BUFFER_SIZE 10
typedef struct {
  ...
}
item;

item buffer[BUFFER_SIZE];
int produced = 0;
int consumed = 0;
```

• How to ensure that producer and consumer don’t overwrite each others’ updates?
  • Following solution is correct, but can only have BUFFER_SIZE-1 elements waiting to be consumed
Bounded-Buffer – Producer

Producer:

```c
while (true) {
    /* do nothing -- no free buffers */
    while (produced - consumed == BUFFER_SIZE) {};

    buffer[produced % BUFFER_SIZE] = produceItem();
    produced++;
}
```

Consumer:

```c
while (true) {
    while (produced - consumed == 0) {};

    consumeItem(buffer[consumed % BUFFER_SIZE]);
    consumed++;
}
```
Interprocess Communication – Message Passing

• Mechanism for processes to communicate and synchronize actions

• Message system – processes communicate with each other without resorting to shared variables

• IPC facility provides two operations:
  • send(message) – message size fixed or variable
  • receive(message)

• If P and Q wish to communicate, they need to:
  • establish a communication link between them
  • exchange messages via send/receive

• Implementation of communication link
  • physical (e.g., shared memory, hardware bus)
  • logical (e.g., logical properties)
Implementation Questions

• How are links established?
• Can a link be associated with more than two processes?
• How many links can there be between every pair of communicating processes?
• What is the capacity of a link?
• Is the size of a message that the link can accommodate fixed or variable?
• Is a link unidirectional or bi-directional?
Direct Communication

• Processes must name each other explicitly:
  • send \((P, message)\) – send a message to process P
  • receive \((Q, message)\) – receive a message from process Q

• Properties of communication link
  • Links are established automatically
  • A link is associated with exactly one pair of communicating processes
  • Between each pair there exists exactly one link
  • The link may be unidirectional, but is usually bi-directional
Indirect Communication

• Messages are directed and received from mailboxes (also referred to as ports)
  • Each mailbox has a unique id
  • Processes can communicate only if they share a mailbox

• Properties of communication link
  • Link established only if processes share a common mailbox
  • A link may be associated with many processes
  • Each pair of processes may share several communication links
  • Link may be unidirectional or bi-directional
Indirect Communication

• Operations
  • create a new mailbox
  • send and receive messages through mailbox
  • destroy a mailbox

• Primitives are defined as:
  send\((A, message)\) – send a message to mailbox A
  receive\((A, message)\) – receive a message from mailbox A
Synchronization

- Message passing may be either blocking or non-blocking

- **Blocking** is considered **synchronous**
  - **Blocking send** has the sender block until the message is received
  - **Blocking receive** has the receiver block until a message is available

- **Non-blocking** is considered **asynchronous**
  - **Non-blocking** send has the sender send the message and continue
  - **Non-blocking** receive has the receiver receive a valid message or null
Buffering

- Queue of messages attached to the link; implemented in one of three ways

1. Zero capacity – 0 messages
   Sender must wait for receiver (rendezvous)

2. Bounded capacity – finite length of $n$ messages
   Sender must wait if link full

3. Unbounded capacity – infinite length
   Sender never waits
Sockets

- A **socket** is defined as an *endpoint for communication*

- Concatenation of IP address and port

- The socket **161.25.19.8:1625** refers to port **1625** on host **161.25.19.8**

- Communication consists between a pair of sockets

- Will talk more about the network later in the course
Socket Communication

host $X$
(146.86.5.20)

socket
(146.86.5.20:1625)

web server
(161.25.19.8)

socket
(161.25.19.8:80)
Pipes

• Acts as a conduit allowing two processes to communicate

• Issues
  • Is communication unidirectional or bidirectional?
  • In the case of two-way communication, is it half or full-duplex?
  • Must there exist a relationship (i.e. parent-child) between the communicating processes?
  • Can the pipes be used over a network?
Ordinary Pipes

- **Ordinary Pipes** allow communication in standard producer-consumer style

- Producer writes to one end (the *write-end* of the pipe)

- Consumer reads from the other end (the *read-end* of the pipe)

- Ordinary pipes are therefore unidirectional

- Require parent-child relationship between communicating processes
Ordinary Pipes

![Diagram showing ordinary pipes with parent and child processes connected through pipes.](image-url)
Named Pipes

- Named Pipes are more powerful than ordinary pipes
- Communication is bidirectional
- No parent-child relationship is necessary between the communicating processes
- Several processes can use the named pipe for communication
- Provided on both UNIX and Windows systems